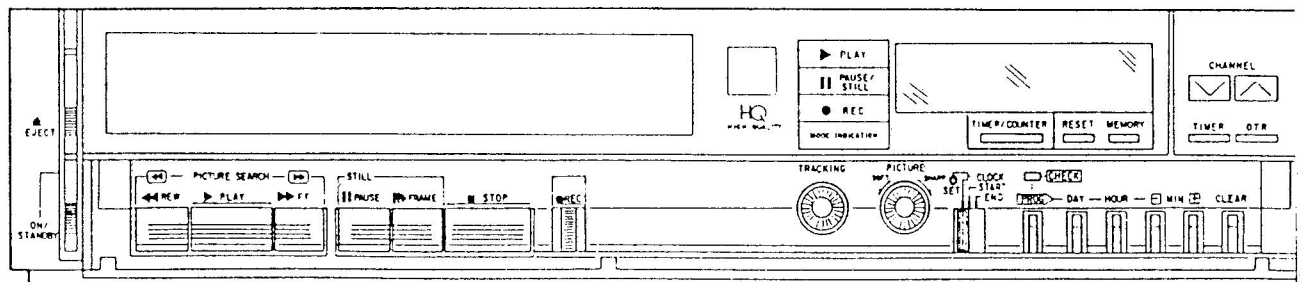


TOSHIBA

VIDEO CASSETTE RECORDER

V-83CZ

SERVICE TEXT



TOSHIBA CORPORATION

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1. OVERVIEW

1-1. VHS Format

The VHS format has been specified to assure correct operations of VHS type VTRs (Video Tape Recorder) and to maintain interchangeability between VHS type cassette tapes. The format has specifications as described below.

1-1-1. Magnetic tape pattern

The tape pattern in the VHS format features:

- * Guard bandless recording
- * Azimuth angle of ± 6 degrees, and
- * "H-alignment"

1. Since a guard bandless recording system is employed a signal on an adjacent track will be reproduced in addition to the signal on a desired track if a tracking deviation is caused by any reason in the playback mode, thus causing undesirable crosstalk signals. Of the crosstalk signals, higher frequency components of a luminance FM signal can be removed by making use of azimuth loss effect of the heads. However, lower frequency components of the luminance FM signal can not be removed sufficiently because of poor azimuth loss effect to the lower frequencies.

2. To compensate the poor azimuth loss effect in the lower frequency range, a line correlation between tape patterns is introduced to remove the lower frequency components of the crosstalks. That is, each horizontal sync pulse is recorded so that it is always aligned with other sync pulses on the adjacent tracks. This is called "H-alignment".

3. Under this condition, crosstalks have frequencies close to a playback FM frequency of the main signal and develop considerably lower interference signal when they are demodulated.

4. Moreover, with the "H-alignment" established, skew distortion, which is caused when a video head traces on two or more tracks in a mode such as Cue or Review, will cause almost no problem because of horizontal sync signals reproduced in the specific period.

* Fig. 1-1-1 shows magnetic tape patterns in the VHS format. Table 1-1-1 shows specifications for the patterns shown in Fig. 1-1-1.

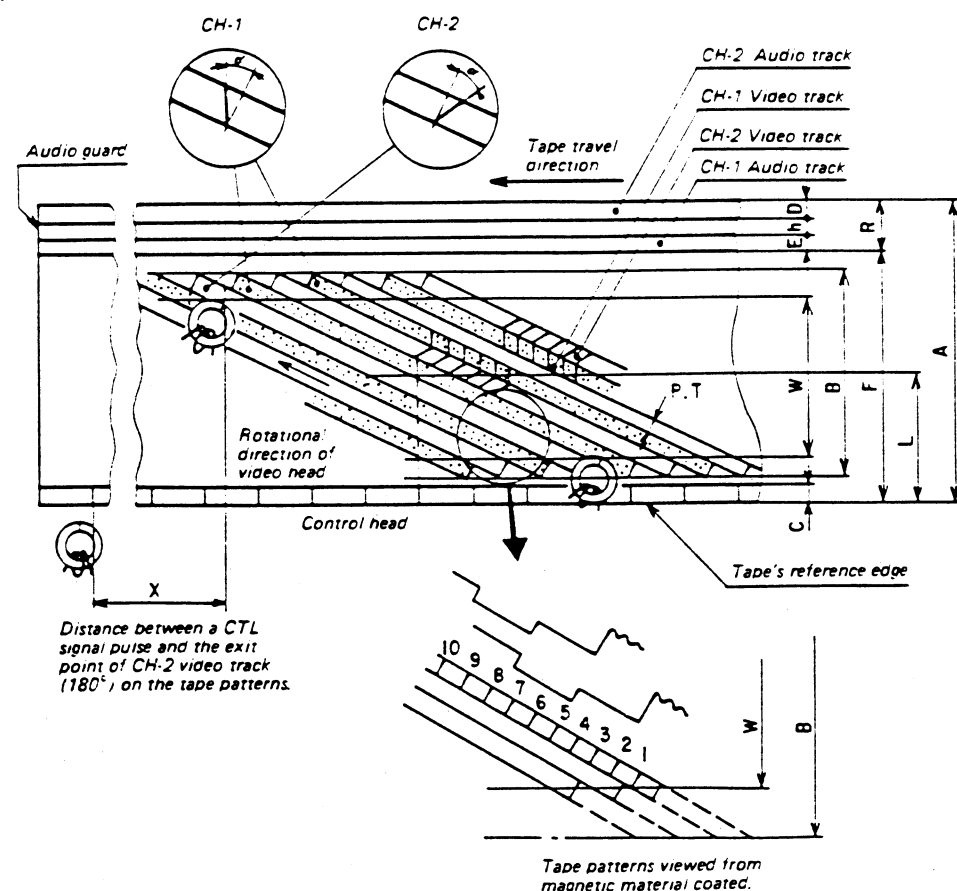


Fig. 1-1-1 Magnetic tape patterns

Table 1-1-1 VHF specifications

Items	Specifications	Note
1. (A) Tape width	mm 12.65 \pm 0.01	Upper cylinder
2. (Vt) Tape travel speed	mm/sec 23.39 \pm 0.5%	
3. (Φ) Cylinder diameter	mm 62 \pm 0.01	
4. (Vh) Relative speed	m/sec 4.85	
5. (P) Video track pitch	mm 0.049	Full reference edge of tape
6. (B) Video fullwidth	mm 10.60	
7. (W) Video width	mm 10.07	
8. (L) Video track center	mm 6.2	
9. (T) Video track width	mm 0.049	Single track
10. (C) Control track width	mm 0.75	
11. (R) Audio track width	mm 1.0	
12. (D) Audio track width	mm 0.35	
13. (E) Audio track width	mm 0.35	From reference edge of tape
14. (F) Audio track reference edge	mm 11.65	
15. (h) Audio track guard width	mm 0.3	During tape stopped
16. (θ_o) Video track angle	5° 56' 7.4"	
17. (θ) Video track angle	5° 57' 50.3"	During tape running
18. (α) Video head azimuth angle	6° \pm 10'	
19. (X) Position of audio and control heads	mm 79.244	Inside from lower end of W Beginning of tape wound cylinder entrance
20. Position of V-sync front porch	5 - 8H	
21. Back tension of tape	30 - 45g	

Tape Path

(This is not standardized, but shows a general arrangement in the VHS mechanism.)

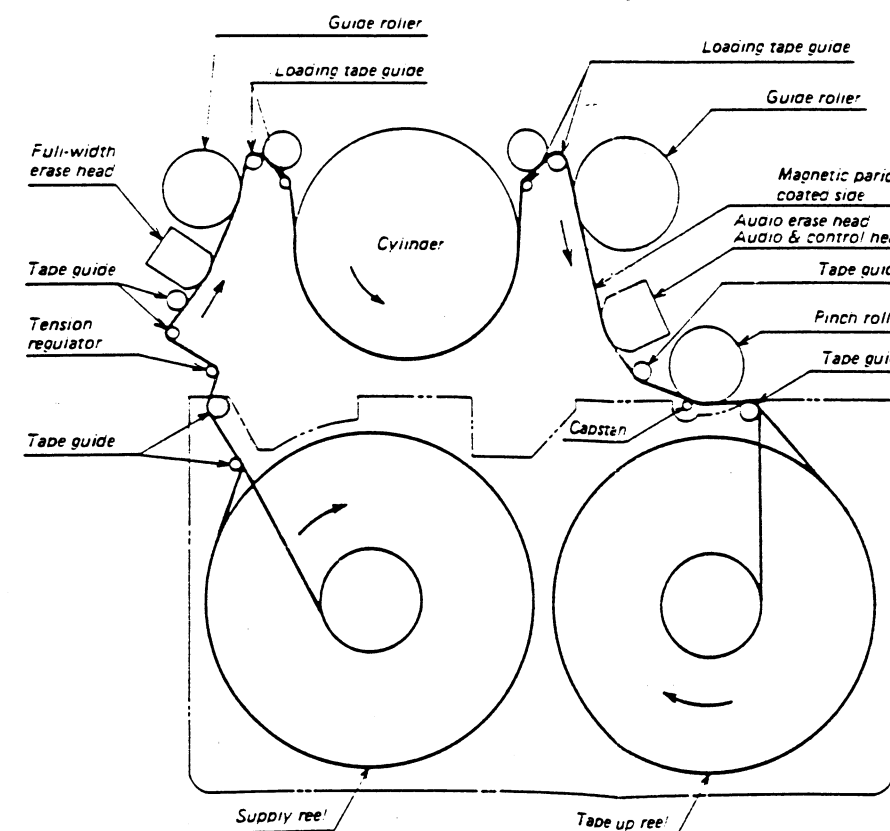


Fig. 1-1-2

1-1-2. Video cassette

VHS type video cassettes have specifications as follows:

1. Video tape

Length:

Determined by a length calculated by the following equation, depending upon nominal recording or playback time.

$$L = (1.42t + 2) + 3 - 0$$

Where L: Tape length (m)

t: Recording or playback time

L should be integer with all decimal points rounded-up

Width: $12.65 \pm 0.01\text{mm}$

Allowance of width: Less than $6\mu\text{m}$

Thickness: $19 \pm 1, -2\mu\text{m}$

Coercive force:

Optimum recording current for 600 oersted (nominal) class should not differ from that of the reference tape.

2. Leader tape and trailer tape

Length:

When recording or playback time exceeds 90 min.: $170 \pm 20\text{mm}$

not exceeds 90 min.: $150 \pm 20\text{mm}$

Width: $12.65 \pm 0.03\text{mm}$

Thickness: $40 - 5, -25\mu\text{m}$

Material: Polyester film

Light transmissivity:

Higher than 50%

Splicing length: $12 - 19\text{mm}$

Splicing clearance: $0 - 70\mu\text{m}$

Splicing strength:

Higher than 3 kg

3. Reel

Outside diameter: $89 \pm 0.2\text{mm}$

Hub diameter:

When recording or playback time exceeds 90 min.: $26 \pm 0.15\text{mm}$

not exceeds 90 min.: $62 \pm 0.2\text{mm}$

is less than 30 min.: $70 \pm 0.2\text{mm}$ allowable

Margin of wrapping:

More than 1.5mm

4. Types and indication

Types of blank cassette

Type	Record or Playback time	Length of video tape
E-240	240 min.	$343 \pm 3, 0\text{m}$
E-180	180 min.	$258 \pm 3, 0\text{m}$
E-150	150 min.	$215 \pm 3, 0\text{m}$
E-120	120 min.	$173 \pm 3, 0\text{m}$
E-90	90 min.	$130 \pm 3, 0\text{m}$
E-60	60 min.	$86 \pm 3, 0\text{m}$
E-30	30 min.	$45 \pm 3, 0\text{m}$

5. Shape and dimensions of cassette

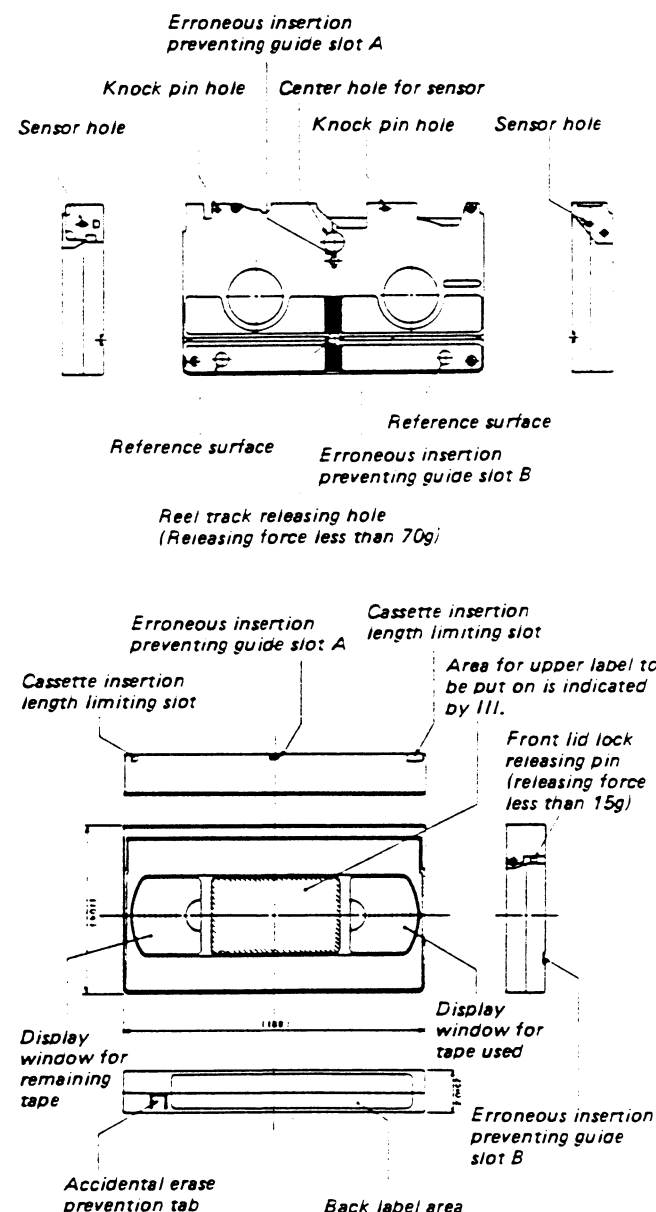


Fig. 1-1-3

6. Tape threading

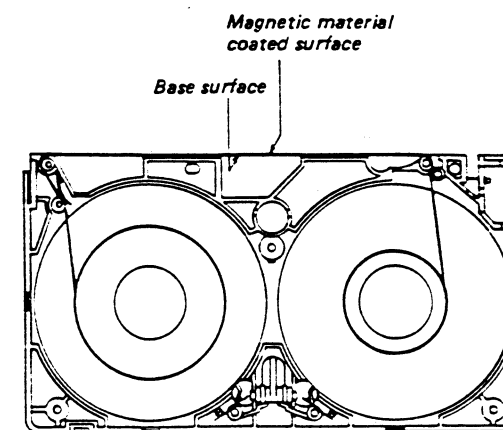


Fig. 1-1-4

1-1-3. Recording system

1. Video signal recording system

Recording signal: CCIR B/W and PAL, SECAM color TV signals.

Luminance signals for black & white and color signals:

FM recording

Carrier color signal: PAL: Down converted phase shifted direct recording.

2. Luminance signal record system

Pre-emphasis characteristic:

$$T = 1.3 \pm 0.05\mu\text{sec}$$

$$X = 4 \pm 0.3$$

FM carrier frequency:

WHITE PEAK $4.8 \pm 0.1\text{ MHz}$

SYNC TIP $3.8 \pm 0.1\text{ MHz}$

FM carrier frequency deviation:

$1 \pm 0.1\text{ MHz}$

White clip level:

$160 \pm 10\%, -5\%$ (from sync tip)

Dark clip level:

$40 \pm 10\%$ (from sync tip)

(100% is assured from sync tip to white peak.)

Recording current characteristics

FM signal record amplifier characteristic:

For frequencies more than 3.8 MHz . . .

saturated optimum record current.

For currents at 2 MHz and 1 MHz . . .

3 dB $\pm 1\text{ dB}$ and 6 dB $\pm 1.5\text{ dB}$ referred to

0 dB current of 3.8 MHz, and flat

response at frequencies less than 1 MHz.

Bandwidth of converted carrier color signal:

Constant current response

Head current of FM signal:

$\pm 1.5\text{ dB}$ within optimum record current at

4 MHz

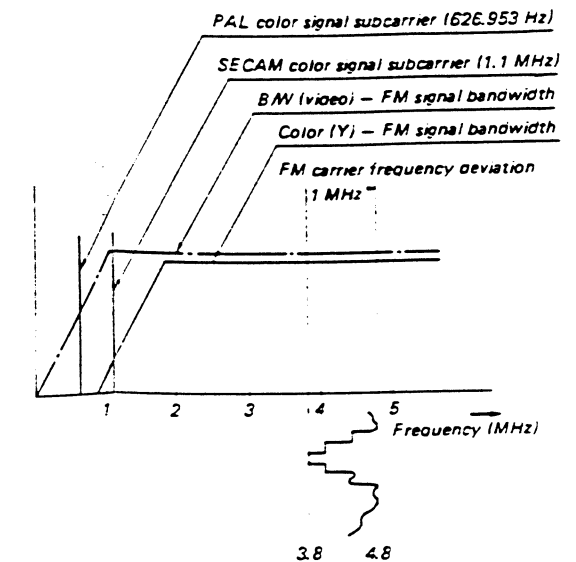
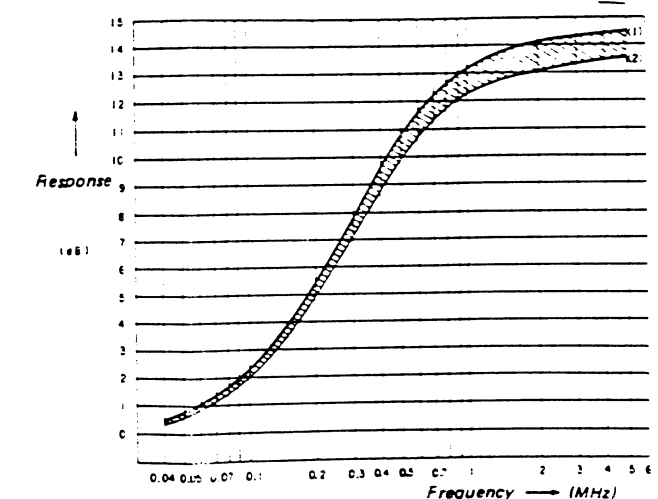


Fig. 1-1-5 Recording signal spectrum



$$T = C \cdot R_b = 1.3 \mu\text{sec} \pm 0.05 \mu\text{sec}$$

$$X = \frac{R_b}{R_c} = 4 \pm 0.3$$

$$T = 1.35 \mu\text{sec}$$

$$X = 4.3$$

$$T = 1.25 \mu\text{sec}$$

$$X = 3.7$$

Fig. 1-1-6 Pre-emphasis characteristic

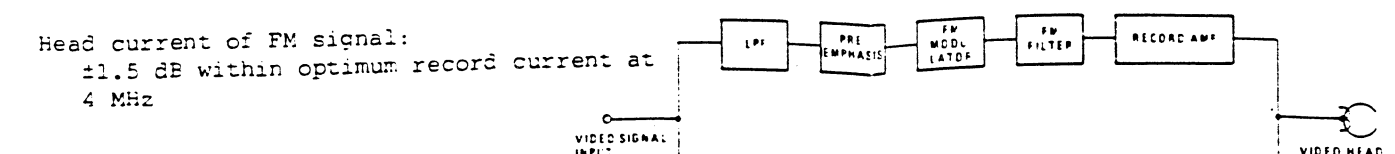


Fig. 1-1-7 Basic block diagram of recording system

3. Color signal recording system

Fig. 1-1-8 shows a block diagram of a color recording system in the VHS system.

Converted carrier color signal frequency:

$$f_c = 40 \times f_H + 1.953 \text{ Hz (626,953 Hz)}$$

(Where f_H stands for the horizontal sync frequency of an input video signal)

Record conversion carrier color signal phase:

CH-1: Constant (6 degrees rightward in head azimuth).

CH-2: phase is retarded by 90 degrees every one horizontal period. (6 degrees leftward in head azimuth).

Phase switching per line of the record carrier color signal is performed at a position equivalent to horizontal sync signal period or the front porch, and the burst phase should be free from any deterioration.

Recording level of converted carrier color signal:

-7 - -10 dB (in playback output level) from the saturation level.

Video head polarity:

Shall coincide between the channels.

Time difference between luminance signal and converted color signal:

Shall be less than 0.1μsec on video tape.

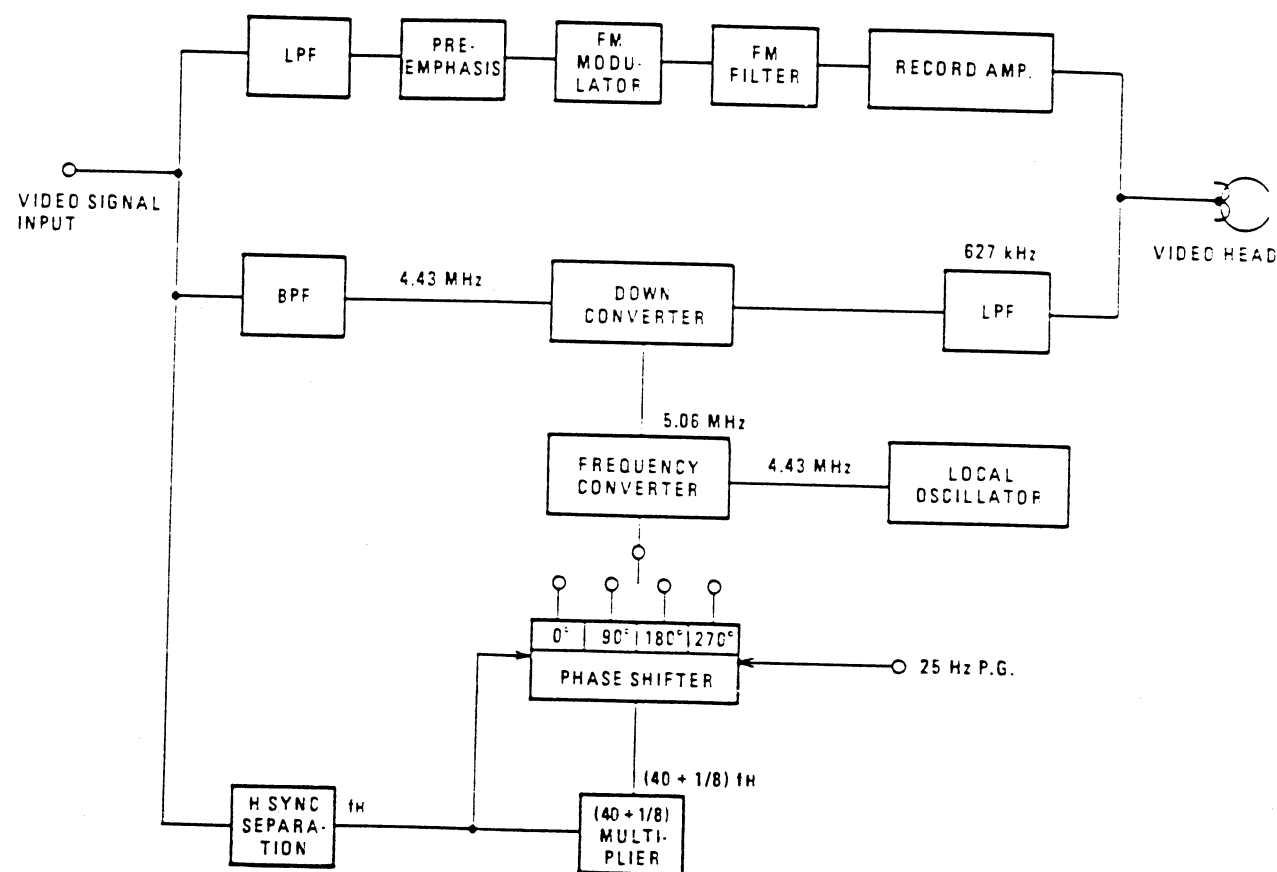


Fig. 1-1-8 Block diagram of PAL signal recording system

1-1-4. Recording format on control signal

Recording level:

The control signal should be recorded with a level higher than a saturation recording level on the control track.

Correlations among waveform, polarities of control signal and video heads should be as follows:

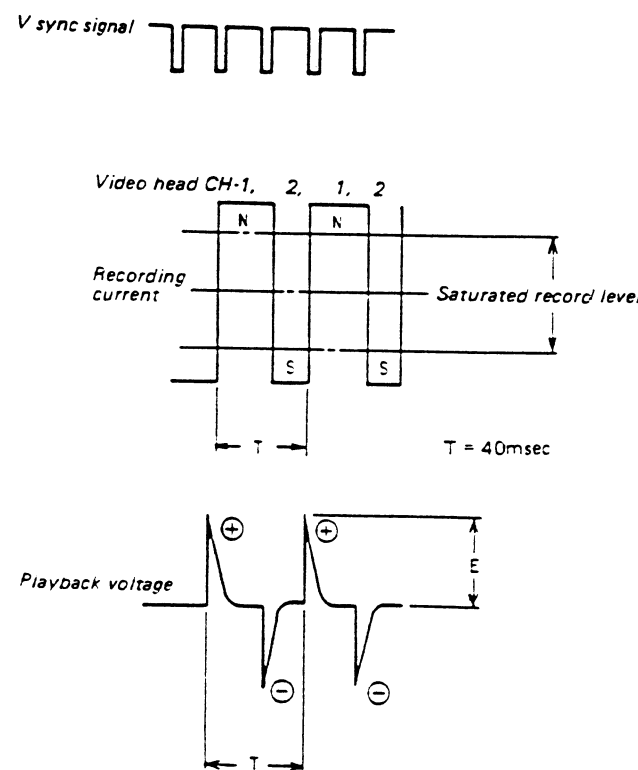


Fig. 1-1-9

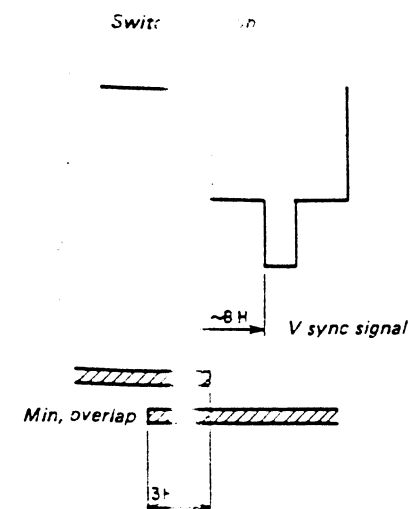


Fig. 1-1-10

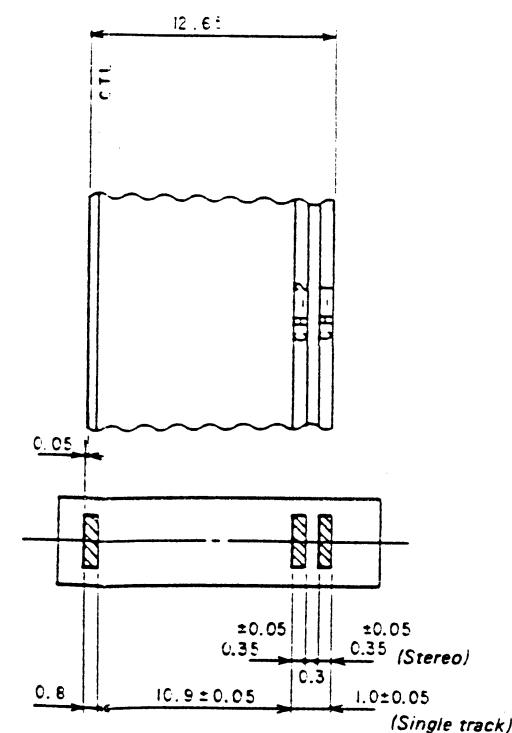


Fig. 1-1-11 Audio and control head

Note:

Gaps for a control head and an audio head should be aligned in line.

2. OPERATION THEORY, MECHANISM

2-1. Outline

2-1-1. Mechanism system configuration

Fig. 2-1-1 shows a diagram of mechanical system configuration consisting of functional blocks. In addition to this a tape transport adjusting mechanism is included.

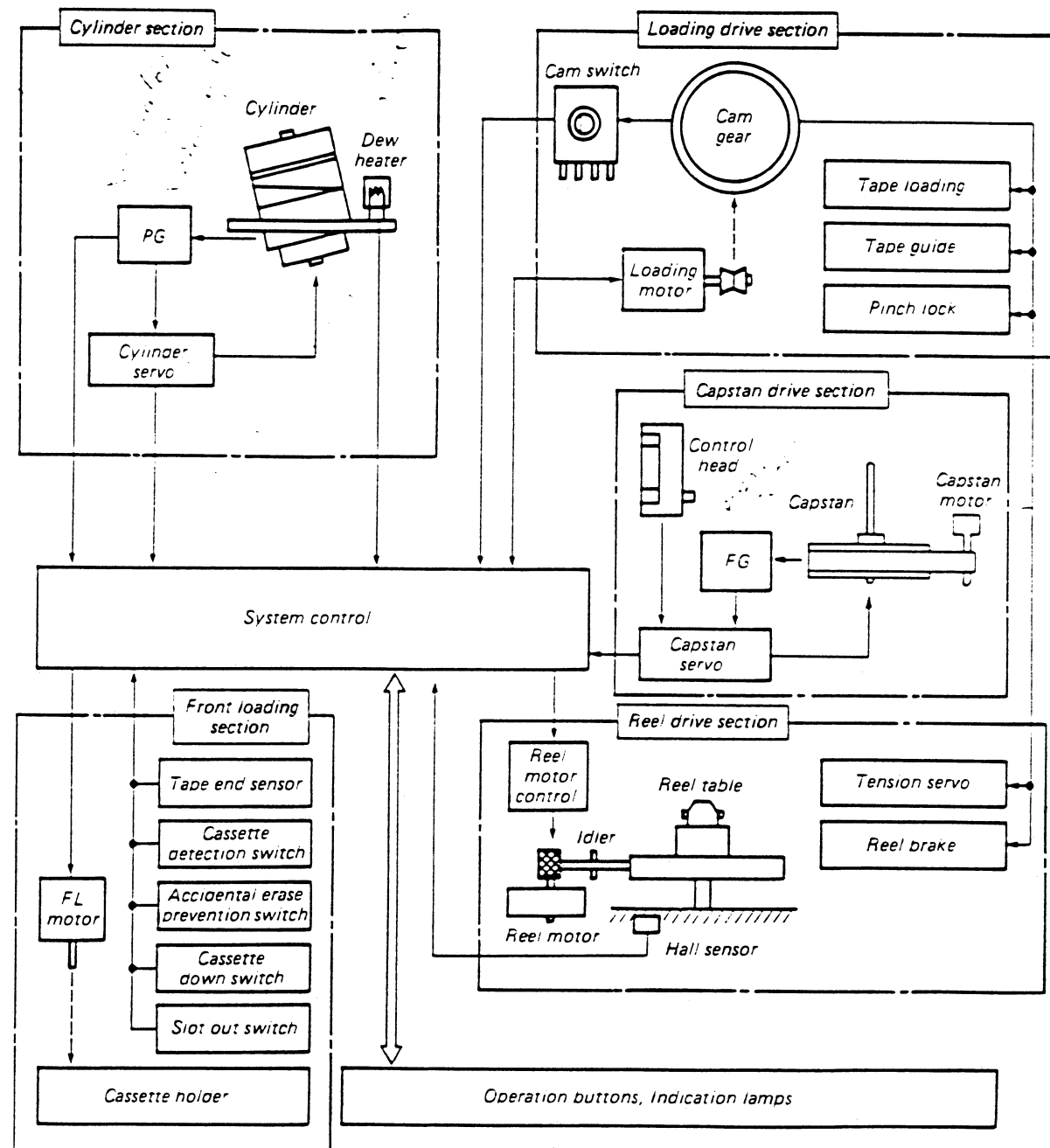


Fig. 2-1-1 Mechanical system block diagram

2-1-2. Description on each functional block

1. Front loading

The front loading mechanism consists of the following main parts.

Mechanical Parts
<ul style="list-style-type: none"> * Cassette holder * Guide bracket * Slot mechanism * Door control mechanism * Cassette dual insertion protection mechanism * Cassette lid opening mechanism
Electrical Parts
<ul style="list-style-type: none"> * FL motor * Cassette insertion detection switches (L, R) * Cassette down detection switch * Accidental erase prevention * Slot out detection switch * Tape end detection switch

2. Loading drive

Loading drive operations are performed in the following orders.

- The loading motor rotates the cam gear.
- The rotating cam gear moves the pinch lock lever, logic slider and the brake slider, thus setting each part of mechanisms to a specified mode.
- The loading motor also rotates the loading ring and moves the S-, T-sliders thereby wrapping a tape around the cylinder or unwrapping the tape from the cylinder.

3. Reel drive

- The reel motor rotates the T-reel table or the S-reel table through an idler. It is determined by swing direction of the idler (depending upon rotating direction of the reel motor) that which one of the reel tables is driven.
- In the playback mode, the reel motor is driven by a constant current source to develop a constant torque. The band brake which is wrapped around the S-reel table applies a specified tension to the tape.
- Detection of rotating reel tables is performed by magnets mounted under the T-reel table and hall sensor.

4. Capstan

A out drive system is employed in the capstan drive system.

Speed control in the playback mode is conducted by a FG servo system and a phase control circuit using control pulses.

5. Cylinder

The cylinder is driven by a built-in direct drive type motor.

Rotating speed control of the cylinder is conducted by detecting rotating speed of the rotor with a PG head.

To prevent dew condensation on the cylinder surface, a dew heater is provided. The heater operates when the main power is turned off and the cylinder is in stop.

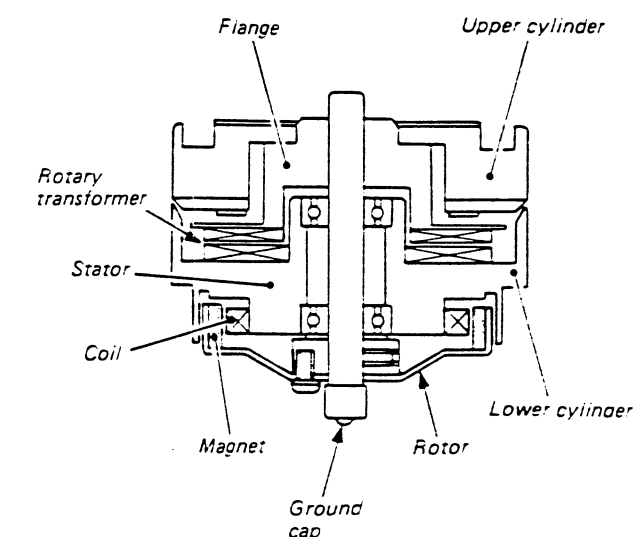


Fig. 2-1-2 Structure of cylinder

6. Tape transport adjustment mechanism

This adjustment mechanism consists of following parts:

- a. Nos. 3 and 8 guide posts
- b. S- and T-guide rollers
- c. FE and ACE heads

The purpose of the transport adjustment is as follows:

- * To obtain a playback RF signal envelope with fine linearity.
- * To adjust azimuth control position to assure good interchangeability of cassette tapes.

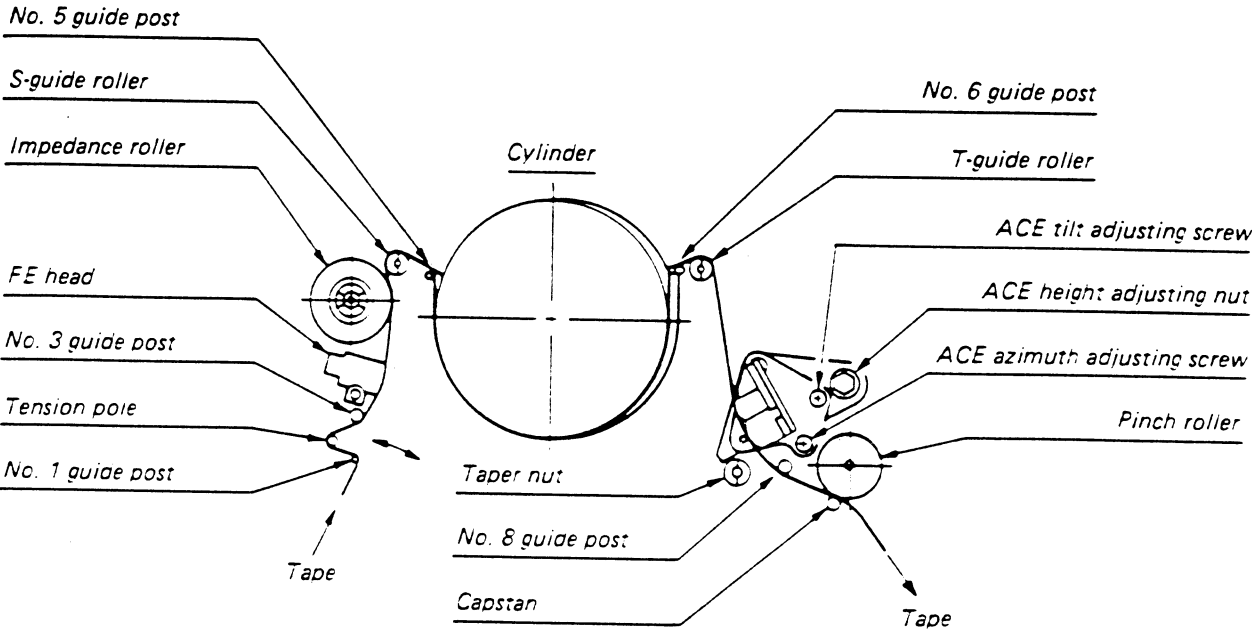


Fig. 2-1-3 Tape transport adjustment location

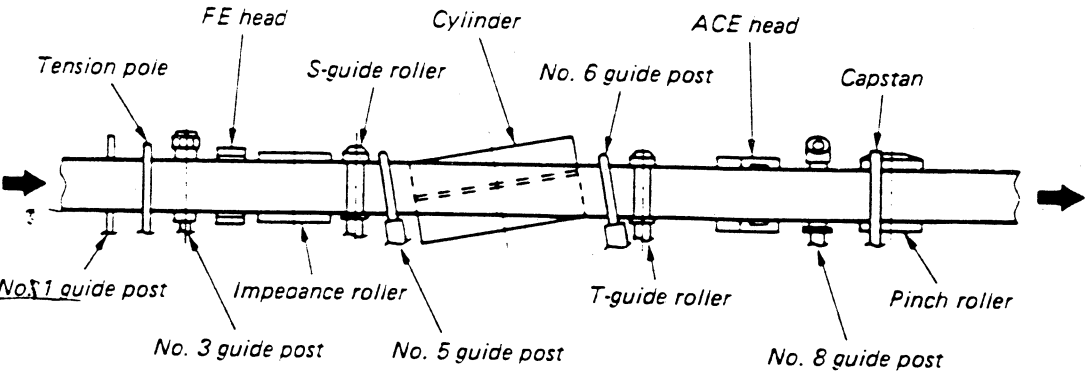


Fig. 2-1-4 Tape path diagram

2-2. Cam Gear Operation

2-2-1. Cam gear and operation of each mechanism

1. Four cams A - D are provided on one disc. (Fig. 2-2-3)
2. These cams control the main brakes, soft brakes, pinch roller, band brakes, etc. through the logic slider, brake slider, and the pinch lock lever. (Fig. 2-2-1)
3. The cam gear rotates the loading ring which in turn moves the S-, T-sliders. (Fig. 2-2-3)
4. Fig. 2-2-3 shows shapes of the cams and position for each mode of operation. Table 2-2-1 also shows operation modes and their timings.

Table 2-2-1 Timing table for cam gear and each mode

Mode	Operation guide	Positions		
		Slider	Cam	Cam SW
FF/REW	FF, FF Short Rewind	A	①	I
Stop	Stop, Cassette eject, Rewind short	A	②	II
Play	Play, Still, Rec, Frame	B	③	V
Cue/ Review	Cue/Review EDIT REW	B	④	VI
Pause	Timer operation standby REC → Stop, Pause	B	⑤	VII

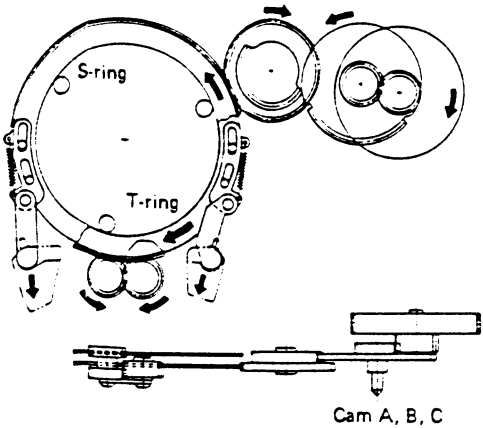


Fig. 2-2-1

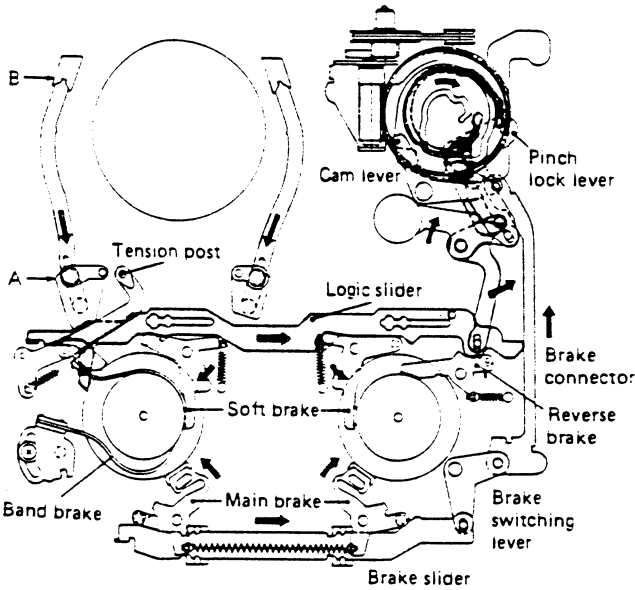
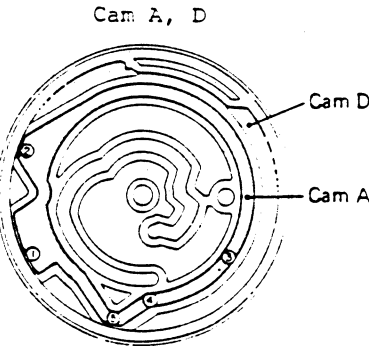


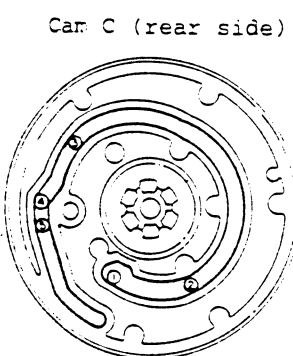
Fig. 2-2-2



Cam A and cam D control the main brakes through cam lever, brake connector, brake switching lever and brake slider.



Cam B controls pinch roller through pinch lock lever.



Cam C controls soft brakes, band brakes and reverse brakes through logic slider.

Fig. 2-2-3

2-2-2. Cam switch drive

1. Cam switches function to convert each mode of the mechanisms into electrical signals and transfer them to the microcomputer.
2. The cam switches are rotated in synchronization with the cam gear by the loading motor and each mode signal is created in relation to the angle of the cam rotated.
3. IC601 controls IC602 to drive the loading motor in forward or reverse direction for setting the cam to a desired mode position.

Fig. 2-2-4 shows forward rotation modes of the cam.

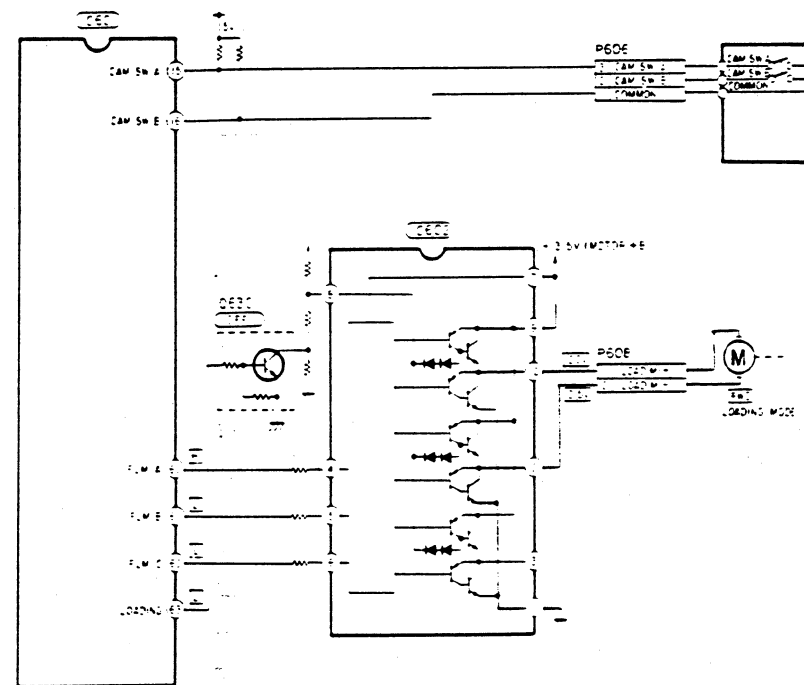


Fig. 2-2-4 Loading motor drive (FF rotation)

Mode	IC601, Pin No				Loading motor
	60	61	62	63	
Stop	H	H	H	L	Stop
Cam rotates forwardly (Loading)	H	L	L	L	FORWARD rotation (11.5V)
				H	FORWARD rotation (8.5V)
Cam rotates reversely (Unloading)	H	L	H	L	REVERSE rotation (11.5V)
				H	REVERSE rotation (8.5V)

2-2-3. Cam control

1. The loading motor rotates and moves the cam gear, thus setting a mechanical mode.
2. Cam gear positions corresponding to various modes, cam switches, and mechanical system operations are given in the cam control chart.

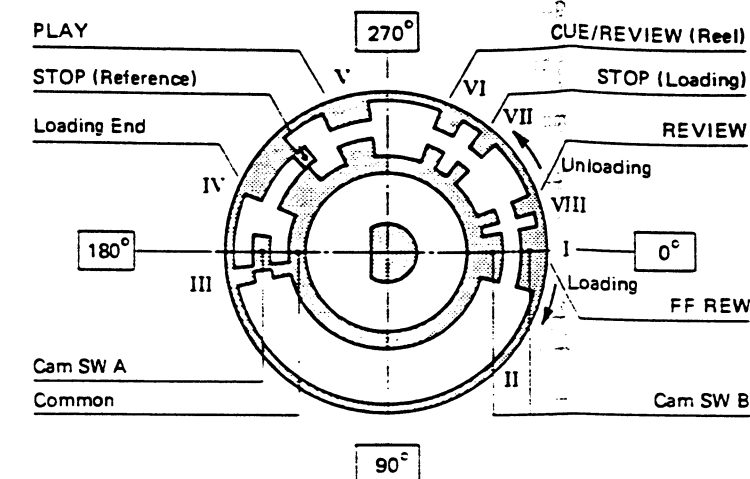


Fig. 2-2-5 Shape of cam switch

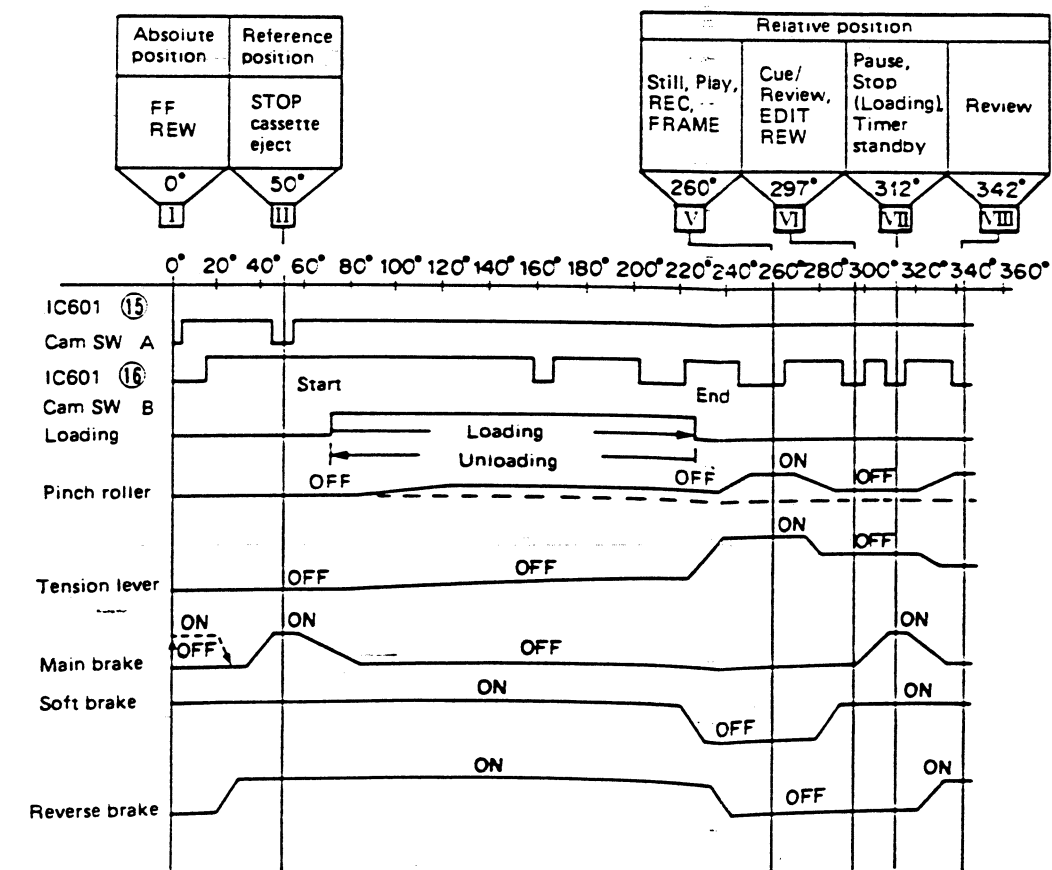


Fig. 2-2-6 Cam control chart

3. DESCRIPTION ON EACH MODE OPERATION

3-1. Front Loading

3-1-1. Slot-in operation

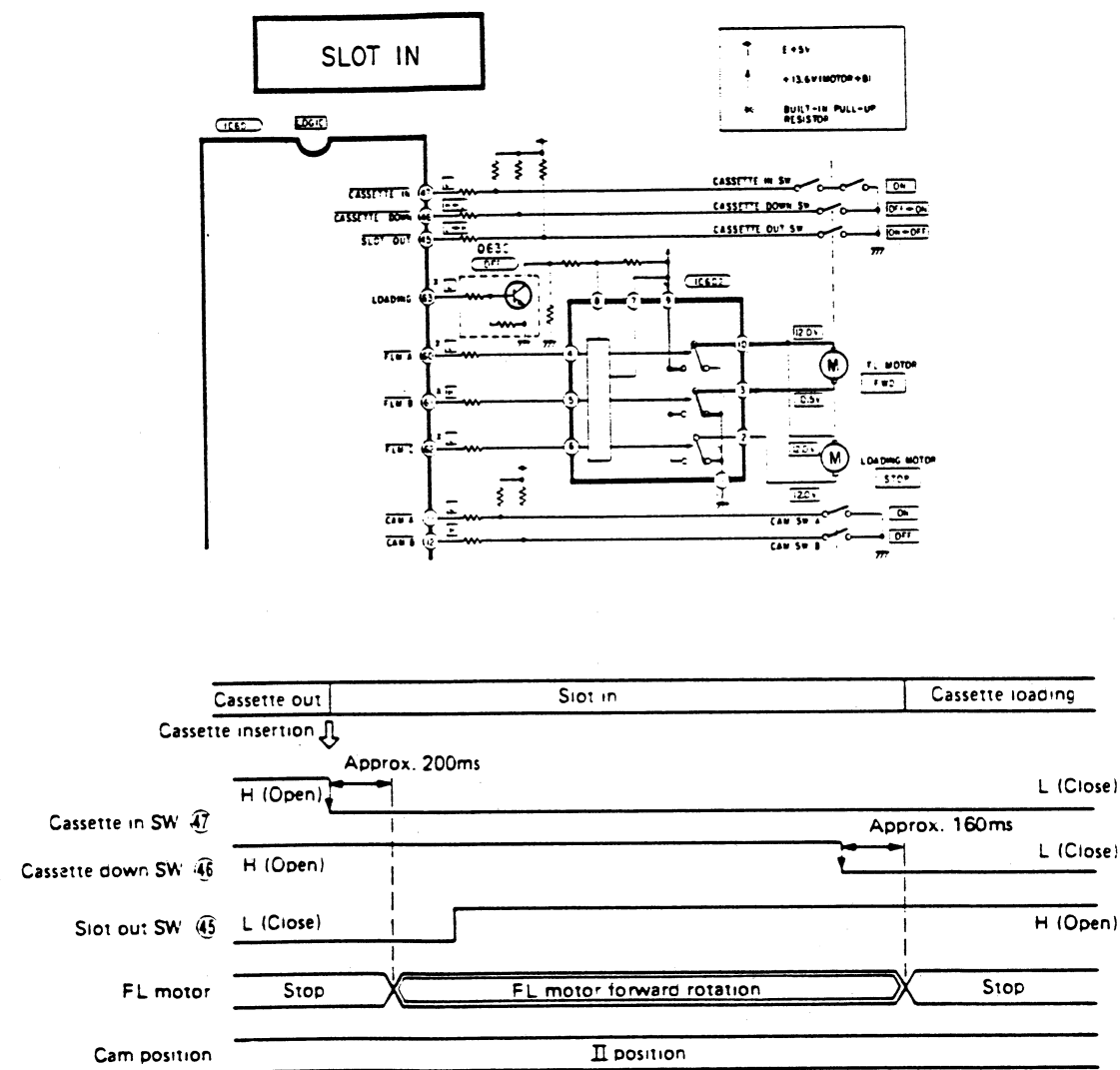


Fig. 3-1-1 Slot in operation

1. When a cassette is loaded into the cassette holder, two cassette detection switches mounted under the cassette holder are pressed by the bottom case of the cassette and closed. (IC601 controls IC602 to rotate the FL motor in forward direction.) (Fig. 3-1-2)
2. The motor rotates in direction shown by the arrow (clockwise direction viewed from front side) with the two left and right cassette detection switches in operation.

The rotational force of the motor is transferred to the arm gear L through the coupling, worm gear, worm wheel, arm gear R and the left and right drive gears, and the arm gear L moves the cassette holder horizontally. (Refer to Fig. 3-1-3)

Pressed by lower end of cassette and turned on.

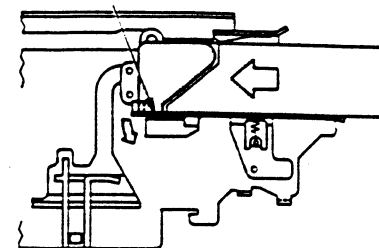


Fig. 3-1-2

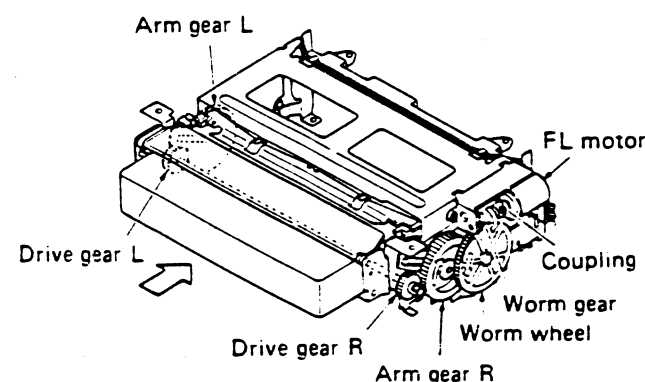


Fig. 3-1-3

3. The cassette loaded in the cassette holder is, first, held in a place by two cassette hold springs (strip) provided on left and right sides of the holder reinforcement plates, thus preventing the cassette from its positional deviation at the starting period. Motion of the cassette holder unlatches both left and right cassette levers from their hooks provided on the guide bracket and allows the cassette to rotate in the direction being pressed, thus holding the cassette more tightly and preventing positional deviation of the cassette due to the cassette lid opener. (Fig. 3-1-4)

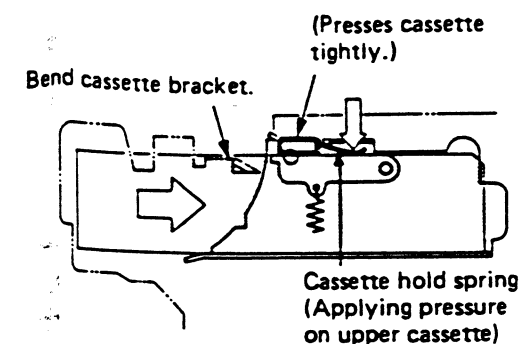


Fig. 3-1-4

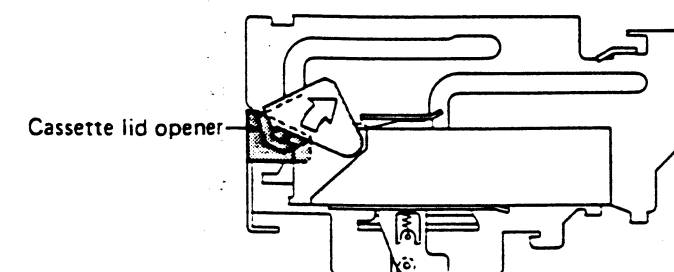


Fig. 3-1-5

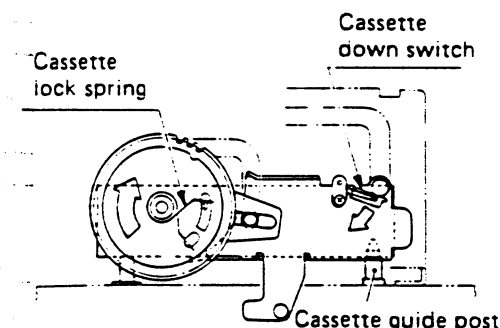


Fig. 3-1-6

4. In the last stage of the cassette holder's horizontal motion, the cassette lid is engaged with the cassette opener and opened widely as the cassette holder moves down.
5. When the cassette is mounted on the cassette guide posts, the cassette down switch turns on. The slot motor continues to rotate for approx. 160 msec after the above operation and the cassette is pressed by the left and right cassette lock springs and stopped. (Fig. 3-1-6)

3-1-2. Slot-out operation

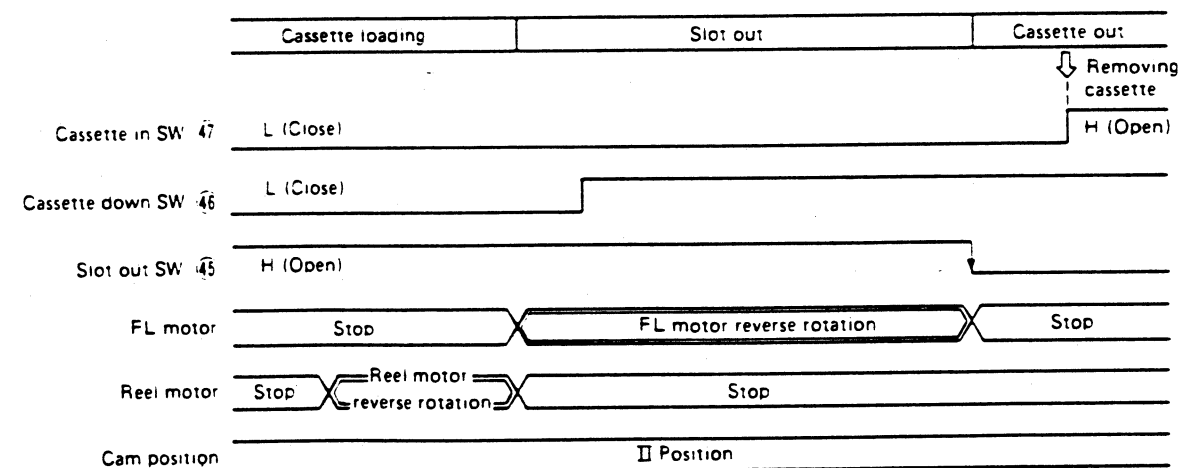
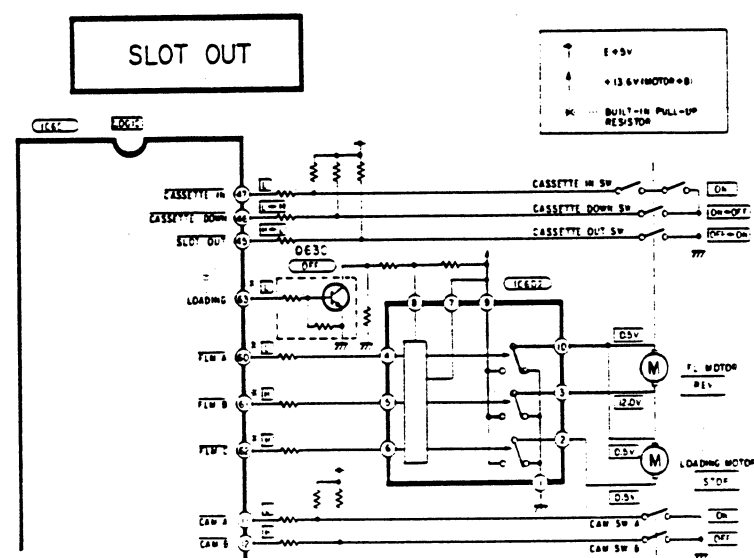


Fig. 3-1-7 Slot out operation

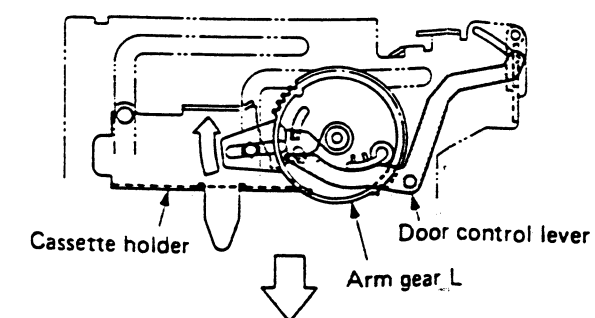


Fig. 3-1-8

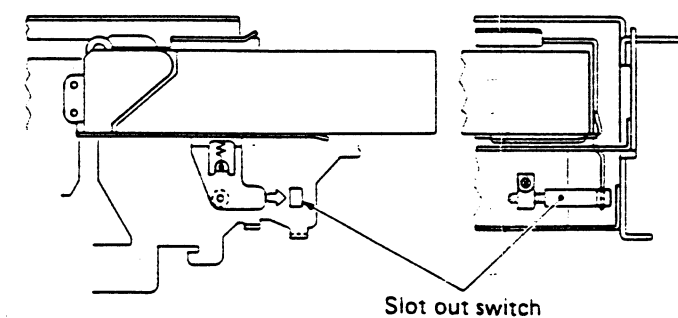


Fig. 3-1-9

1. The loading motor rotates and sets the cam gear to the stop mode (position II) and actuates the main brakes for the reel tables.
2. IC601 controls IC603 so that the reel motor rotates in opposite direction for approx. 1 sec to remove tape slack. Then, IC601 also controls IC603 and rotates the FL motor in reverse direction.
3. While the cassette holder is moving upward, the door control lever rotatively moves along the cam surface of the arm gear and the door opens. (Fig. 3-1-8)
4. The cassette holder horizontally moves and reaches close to the stop position, the slot-out switch is turned on by the lower end of the cassette holder. (Fig. 3-1-9)

3-2. Stop Mode

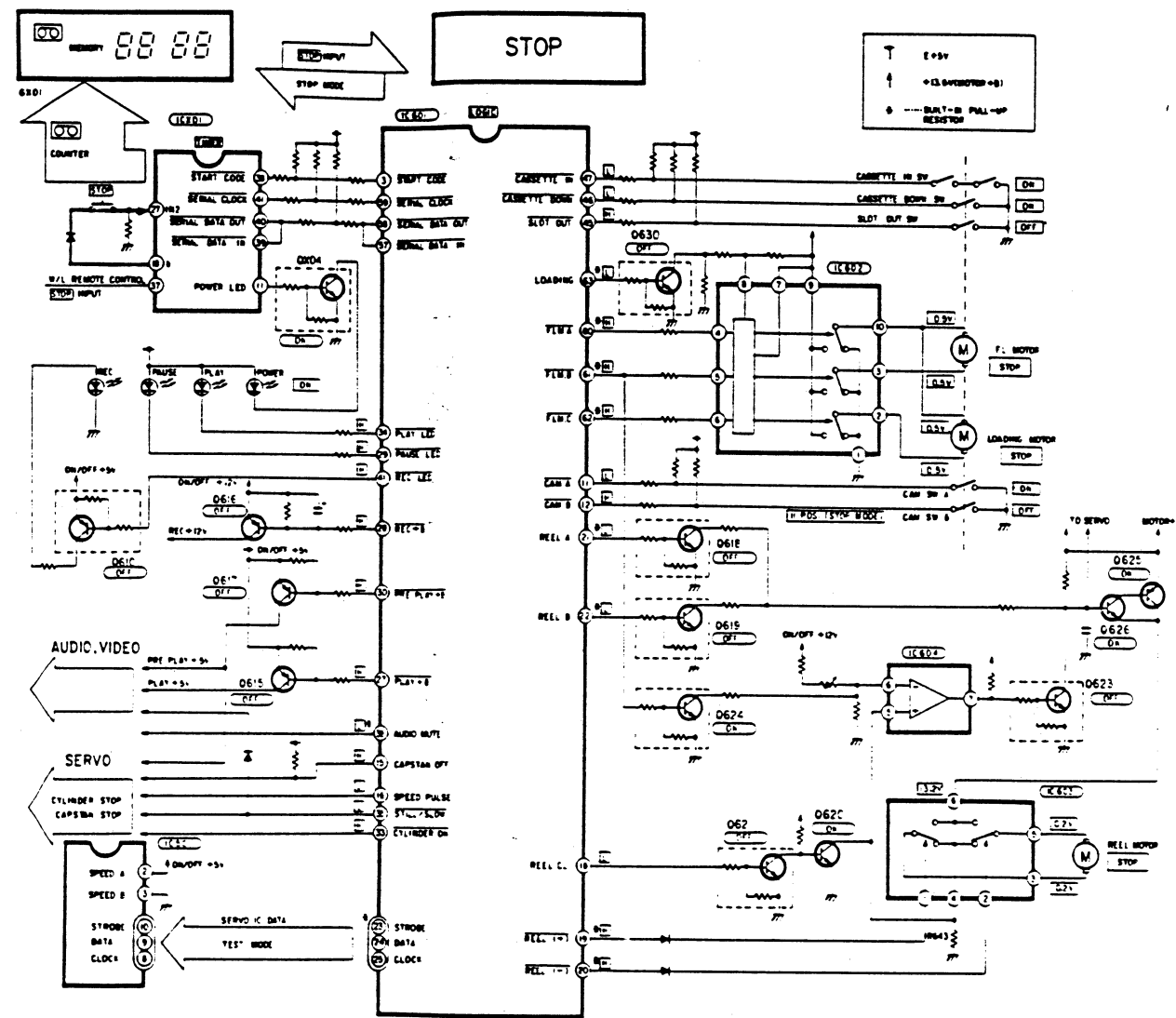


Fig. 3-2-1

1. The cam gear is in the stop mode (position II). Under this condition, the cylinder motor, capstan motor, and the reel motor are also stopped.
2. Each part the mechanism is set as follows:
 - a. The T- and S-sliders are set in unloading condition.
 - b. The pinch roller is away from the capstan.
 - c. The tension lever is stored on the reel table side. That is, the band brake is released and the back tension is released.
 - d. The T- and S-main brakes, T- and S-soft brakes and the reverse brakes are being actuated.

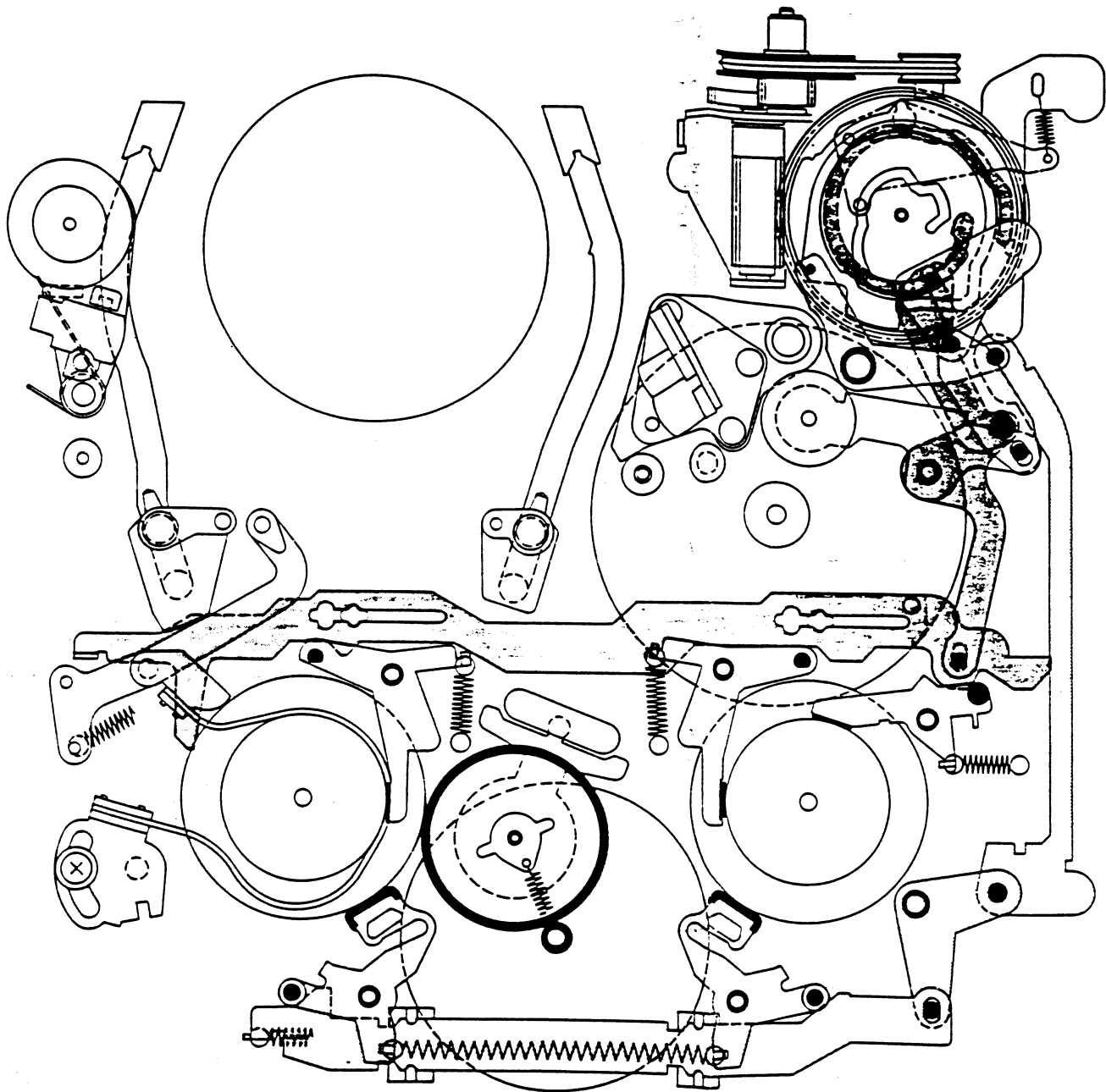


Fig. 3-2-2

3-3. FF/REW Mode (From Stop Mode)

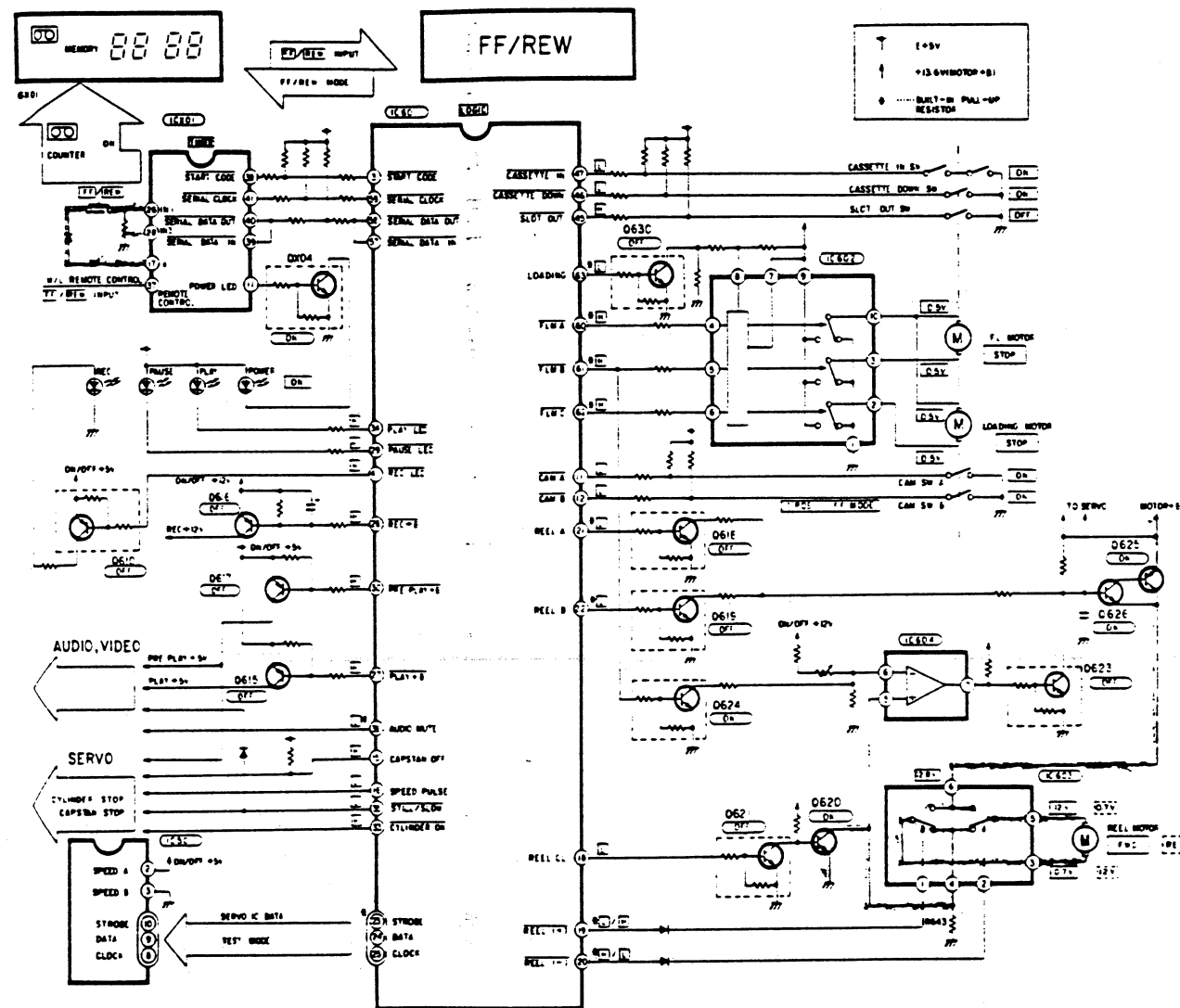


Fig. 3-3-1

1. When the FF button is pushed in the stop mode, ICX01 transfers the FF input signal serially to IC601 to set the FF mode.
2. IC601 controls IC602 and rotates the loading motor in reverse direction. (Direction Mode No. 1)
3. The cam gear rotates (Mode No. 2 to 6), the brake slider starts to move and releases the T- and S-main brakes (Mode No. 7 to 14). The logic slider also moves and releases the reverse brakes (Mode No. 15 to 22).
4. When the cam gear is set to the FF mode (position I), the loading motor stops. IC601 controls IC603 which in turn drives the reel motor with a constant voltage. Then the idler contacts the T-reel table and transfers rotational force, thus winding the tape.
5. In the REW mode, the reel motor rotates in reverse direction, and the idler contacts the S-reel table, thus rewinding the tape.
6. The cylinder motor and the capstan motor are in stop condition.

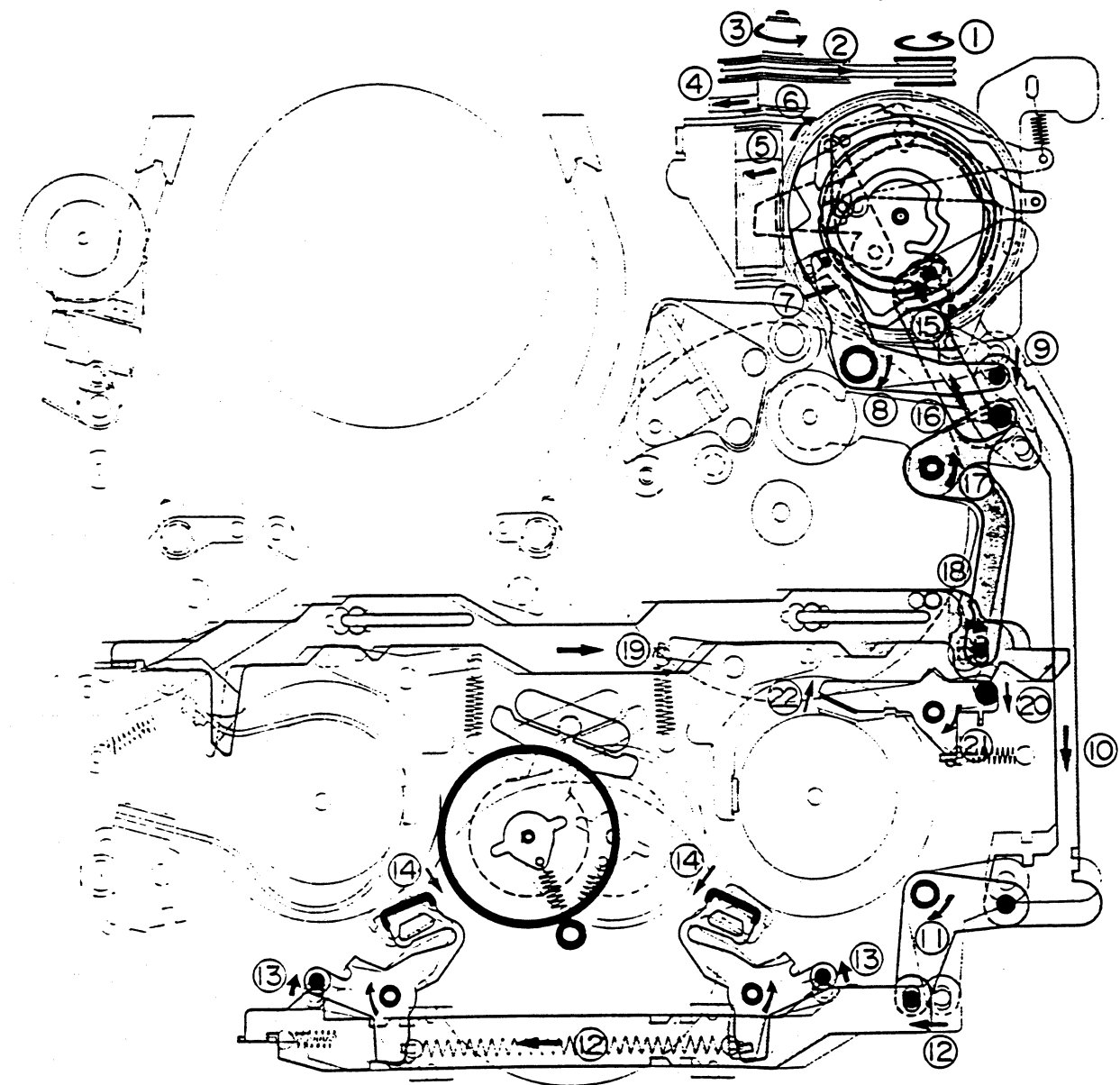


Fig. 3-3-2

Note:

Operation from FF/REW mode to STOP mode

- * When the loading motor rotates in forward direction, the lock lever actuates and the T- and S-main brakes are immediately actuated.

3-4. Playback System Mode

3-4-1. Loading mode

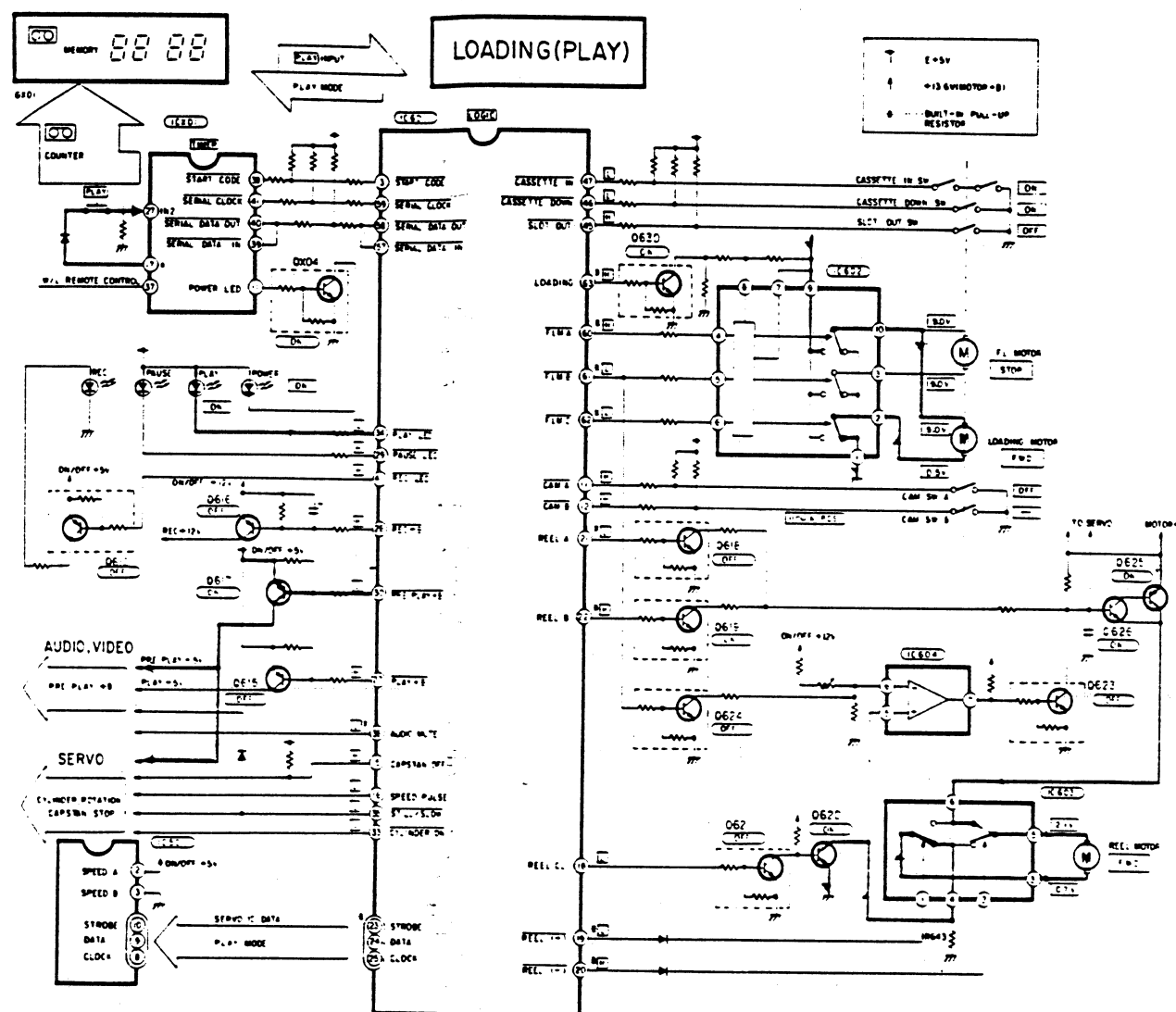


Fig. 3-4-1

1. When the PLAY button is pushed in the stop mode, ICX01 serially transfers the playback input signal to IC601 to set the playback mode.
2. IC601 and IC603 make the reel motor rotate in forward direction and idler moves toward the T-reel table side. After that, the output at pin 22 of IC601 turns to "H" level and this makes Q619 on, keeping the motor terminal voltage at approx. 1.5V so that the T-reel table does not rotate in reverse direction. (Since the reverse brake is actuated, no tape is wound.)
3. Next, the loading motor rotates in forward direction. At the same time the cam gear rotates. (Mode No. 1 to 6). Then the brake slider moves and releases the T- and S-main brakes. (Mode No. 7 to 14).
4. When the loading motor rotates in forward direction, the loading ring and the loading gear make the T- and S-sliders move along the loading guide. (Mode No. 15)
In the loading mode (position II - IV), pin 63 of IC601 goes "H" level, and this sets the motor terminal voltage to 8.5V, thus controlling moving speed of the T- and S-sliders.

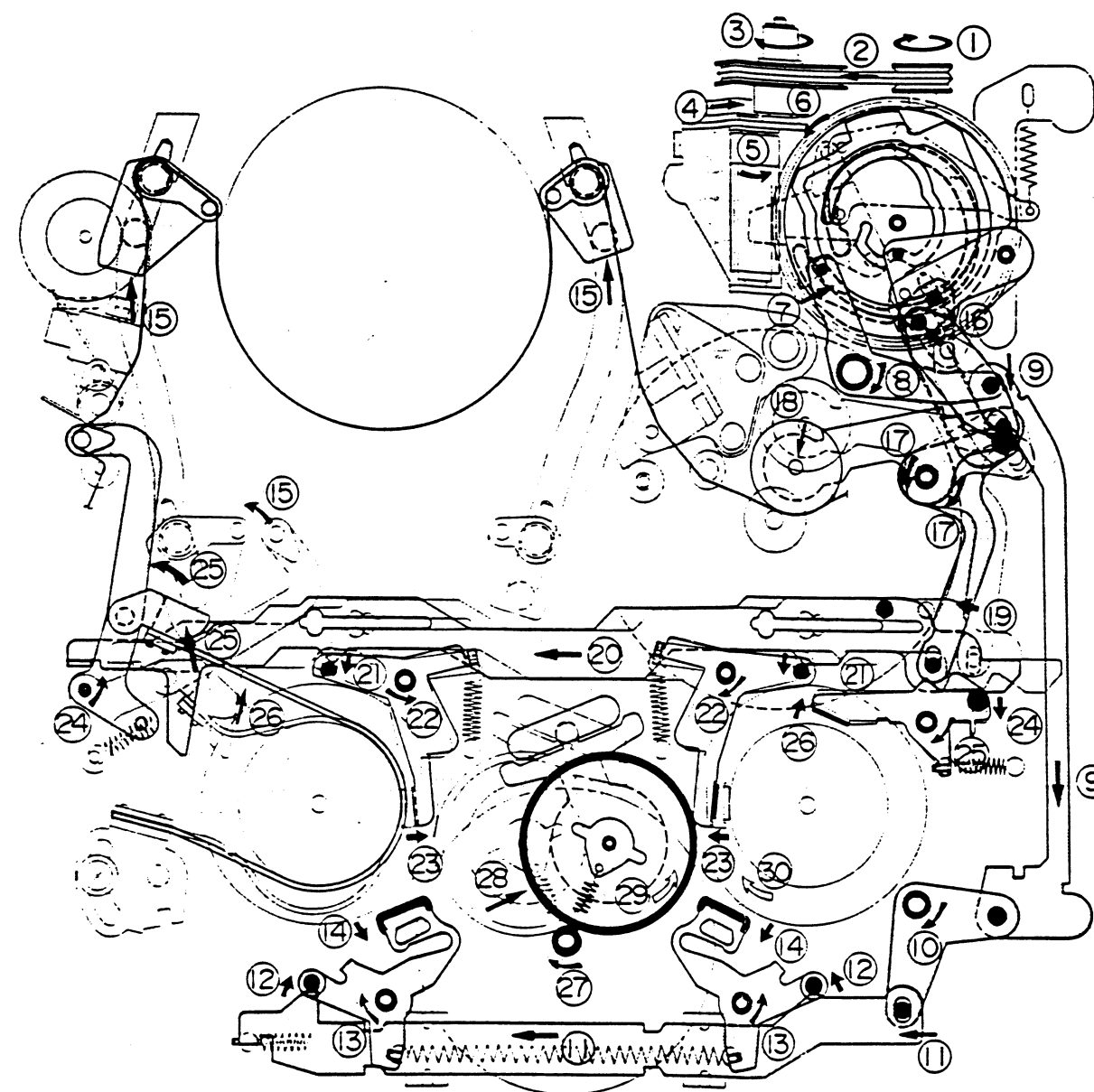


Fig. 3-4-2

5. When the cam gear reaches the position IV, pin 63 of IC601 develops "L" level, and the terminal voltage of the loading motor rises to approx. 11.5V. Then, the T- and S-sliders are fixed to the cylinder base. At the same time, the logic slider moves, the T- and S-soft brakes are released, (Mode No. 19 to 23), and the reverse brake is also released, (Mode No. 24 to 26). The tension lever moves, furthermore, toward the No. 1 guide side, the band brake actuates, and the back tension mechanism functions.
6. The pinch roller engages with the capstan with a specified pressure. (Mode No. 16 to 18)
7. When the cam gear exceeds the playback mode (position V), the loading motor rotates in reverse direction and when the cam returns to the position V the motor stops.

3-4-2. Playback mode

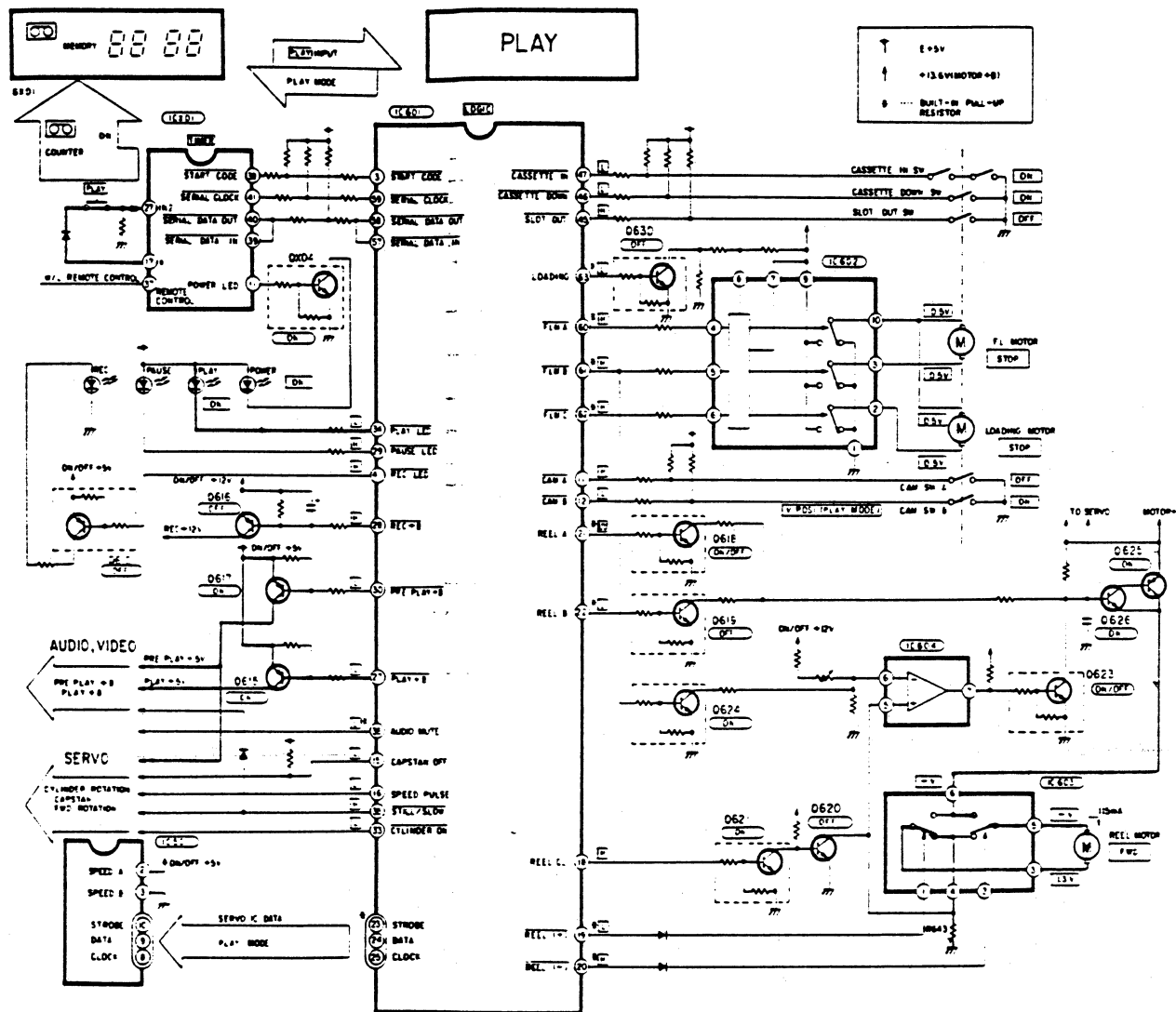


Fig. 3-4-3

1. When the loading operation completes, pin 15 of IC601 develops "L" level output.
2. IC601 controls IC603 and makes the reel motor rotate in forward direction. The idler touches the T-reel table and transfers rotational force wind the tape. (Mode No. 27 and 28)
3. Under this condition, pin 18 of IC601 develops "H" level and Q620 turns off. Feedback voltage across R643 (by reel current) and a reference voltage at pin 6 of IC604 are compared, and if a current higher than the specified flows,
4. Pin 27 of IC601 turns to "L" level and Q615 turns on, connecting the playback +5V to the audio and video circuits to set the playback mode.

Q623 is turned on to lower the base potential of Q626, thus limiting the current to a constant value of approx. 85mA or driving the tape with a constant torque.

3-4-3. Unloading

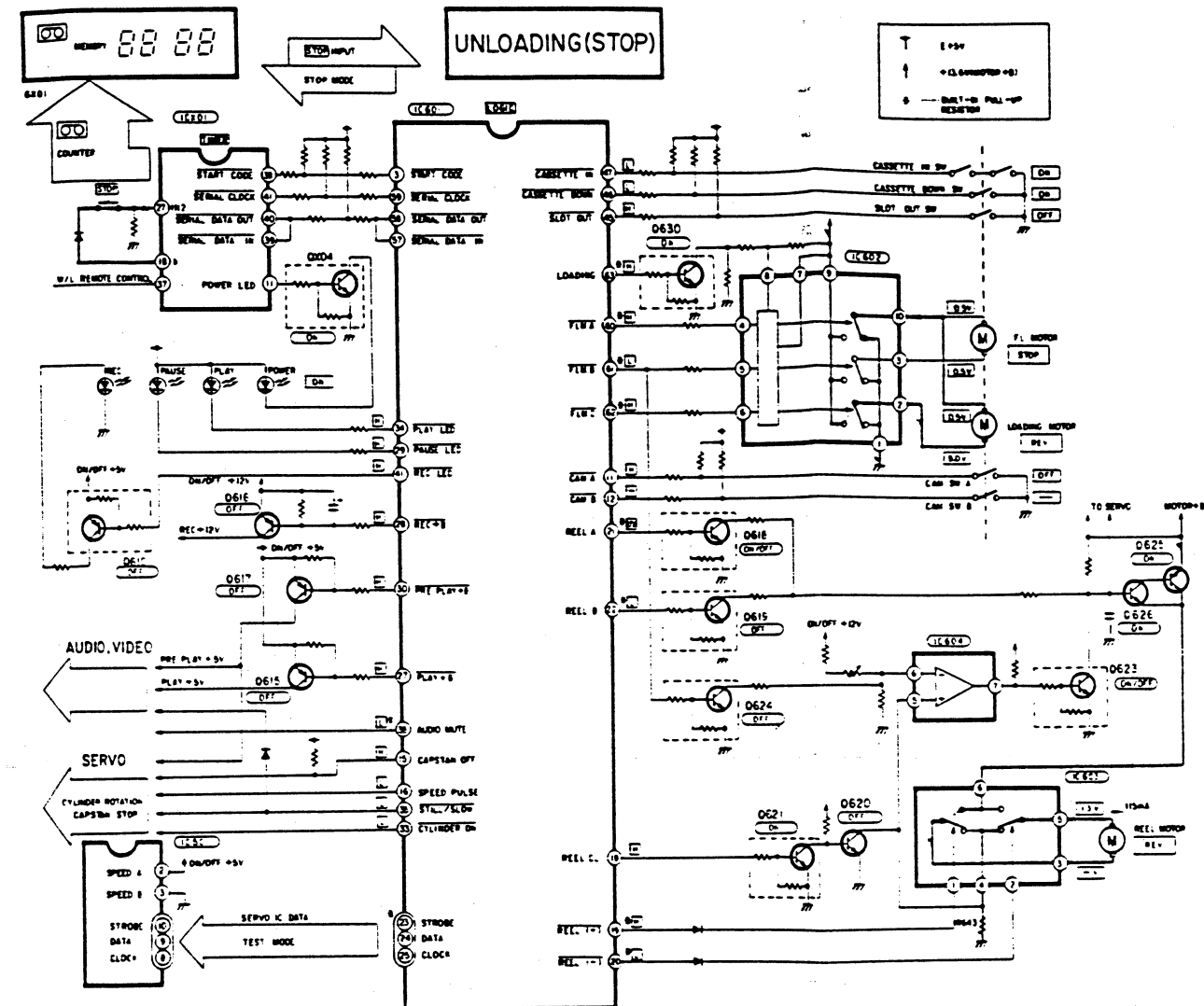


Fig. 3-4-4

1. When the STOP button is pushed in the playback mode, ICX01 sets IC601 to the stop mode.
2. The cam gear is in the playback mode (position V).
3. The cylinder motor rotates and the capstan motor stops. At the same time the reel motor also stops.
4. The loading motor rotates reversely and the cam moves from the position V to the position II. Under this condition, mechanical parts move in reverse order of the loading operation.
5. When the cam gear reaches the position V, pin 63 of IC601 develops "H" level signal and controls the moving speed of the T- and S-sliders. The reel motor rotates in reverse direction and makes the idler move toward the S-reel table. As stated in 3-4-2 step 3, the reel current flowing through R643 is fed back to pin 5 of IC604 to drive the tape with a constant current of approx. 110mA.
6. When the cam gear reaches the position II, the cylinder motor, loading motor and the reel motor stop.

3-4-4. Review mode

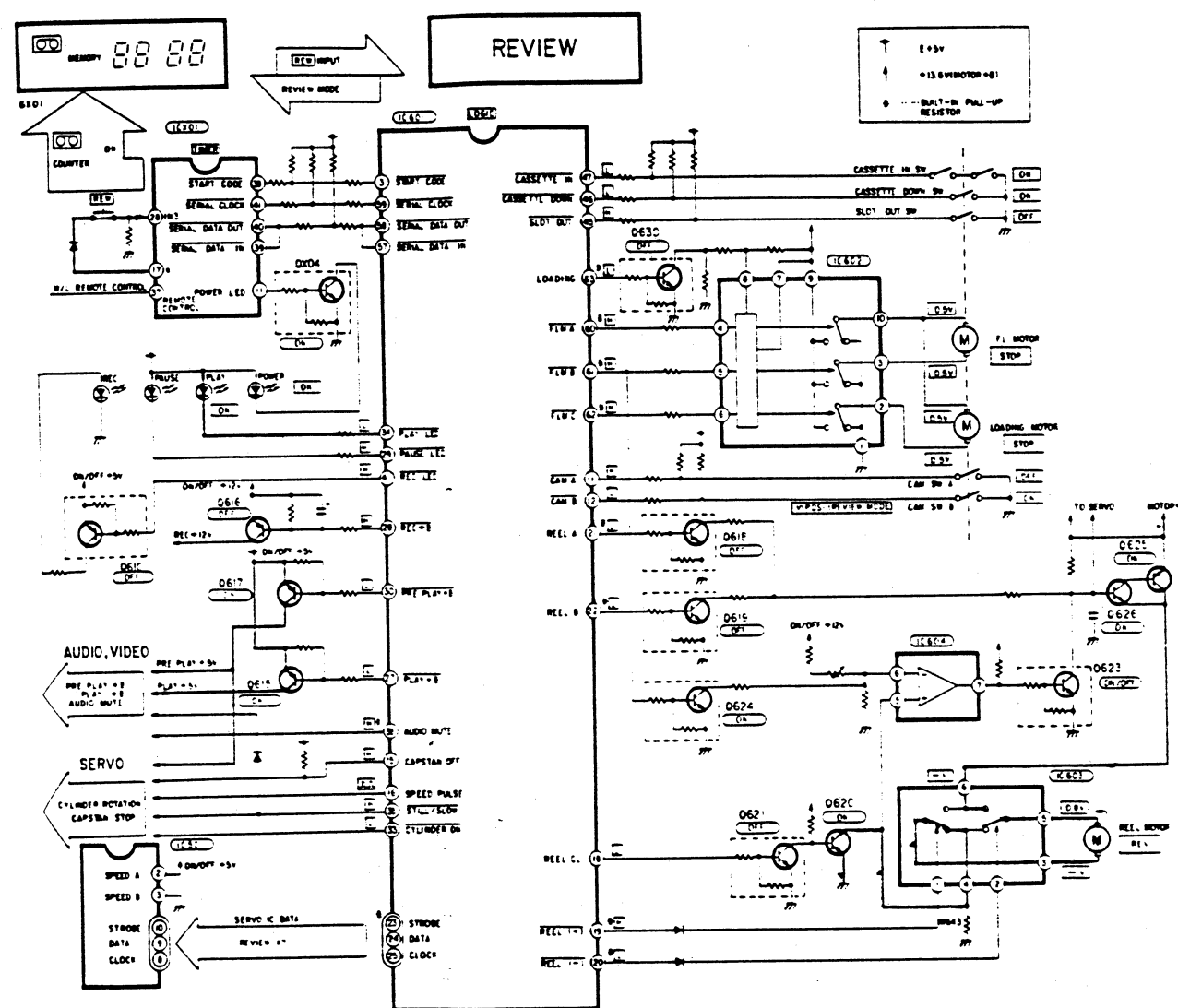


Fig. 3-4-5

1. When the REW button is pushed in the playback mode, IC601 is set to the review mode.
2. Pin 38 of IC601 develops "H" level and mutes audio signals.
In this case, the cylinder motor rotates but the capstan motor stops.
3. The reel motor is driven at a constant voltage in forward direction and the idler transfers rotational force to the T-reel table, thus winding the tape.
4. The loading motor rotates in forward direction (direction mode No. 1) and the cam moves from the position V to the position VII.

In this case, the cam gear rotates forwardly (Mode No. 1 to 6) and the pinch roller moves away from the capstan. (Mode No. 7 to 9)
The logic slider also moves S-soft brake is applied, and the tension lever moves away from No. 1 guide. (Mode No. 10 to 16)
Furthermore, the brake slider moves, and T- and S-main brakes operate.

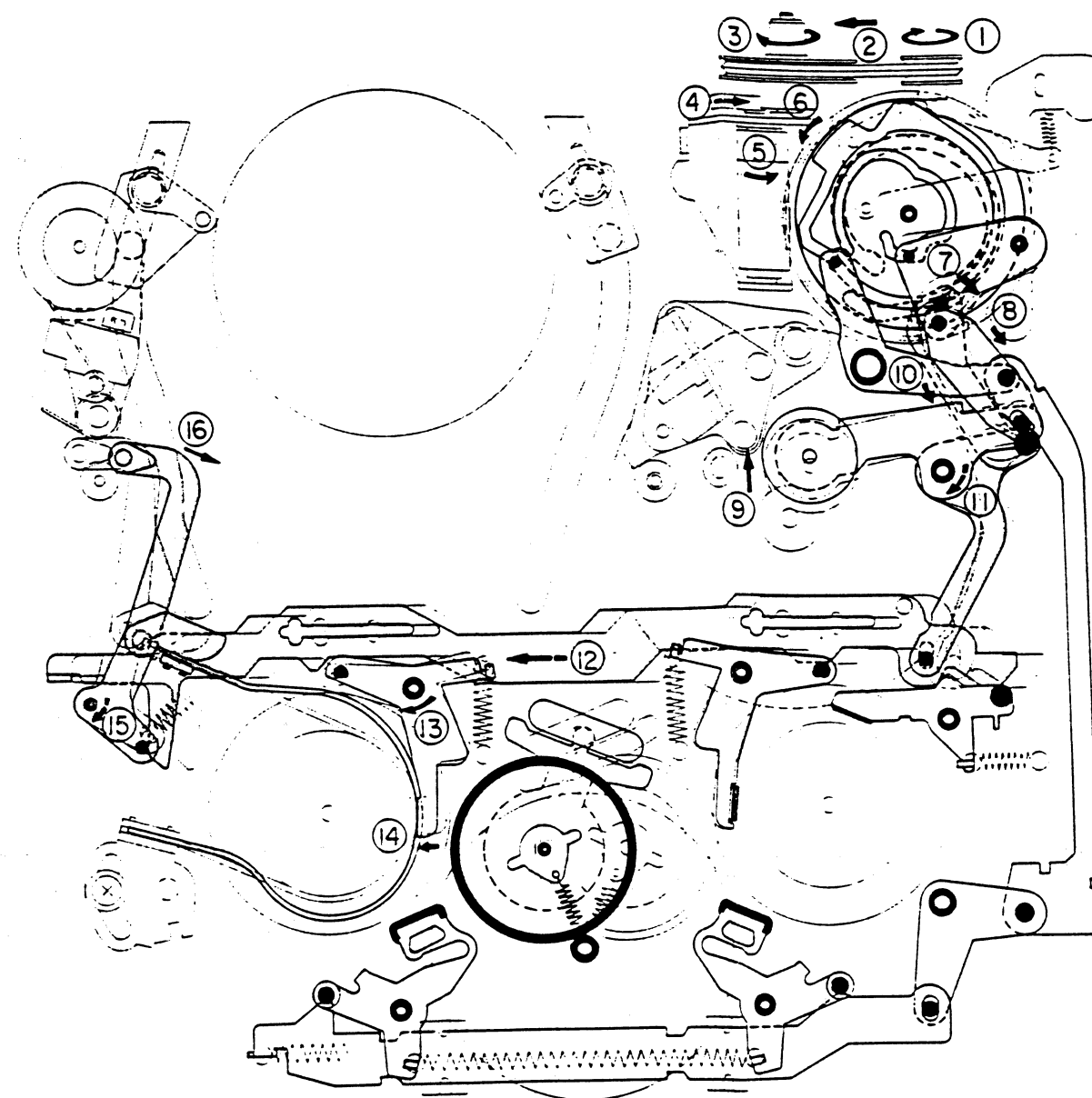


Fig. 3-4-6

5. Then the cam gear reaches the position VII, the loading motor stops and the reel motor rotates reversely.
In this case, the idler moves toward the S-reel table to wind the tape so that the tape does not slip off the cylinder.
6. Next, the loading motor rotates in reverse direction and the cam moves from position VII to VI.
In this case the cam gear rotates, the brake slider moves and the T- and S-main brake is released.
7. When the cam gear reaches the review mode (position VI), the loading motor stops.
8. The reel motor also rotates reversely and the idler transfers the rotational force to the S-reel table and the reel winds the tape.
At the same time, the servo circuit controls the CTL pulse so that the reel motor rotates at the speed 7 times higher than the normal speed.

3-4-5. Still mode

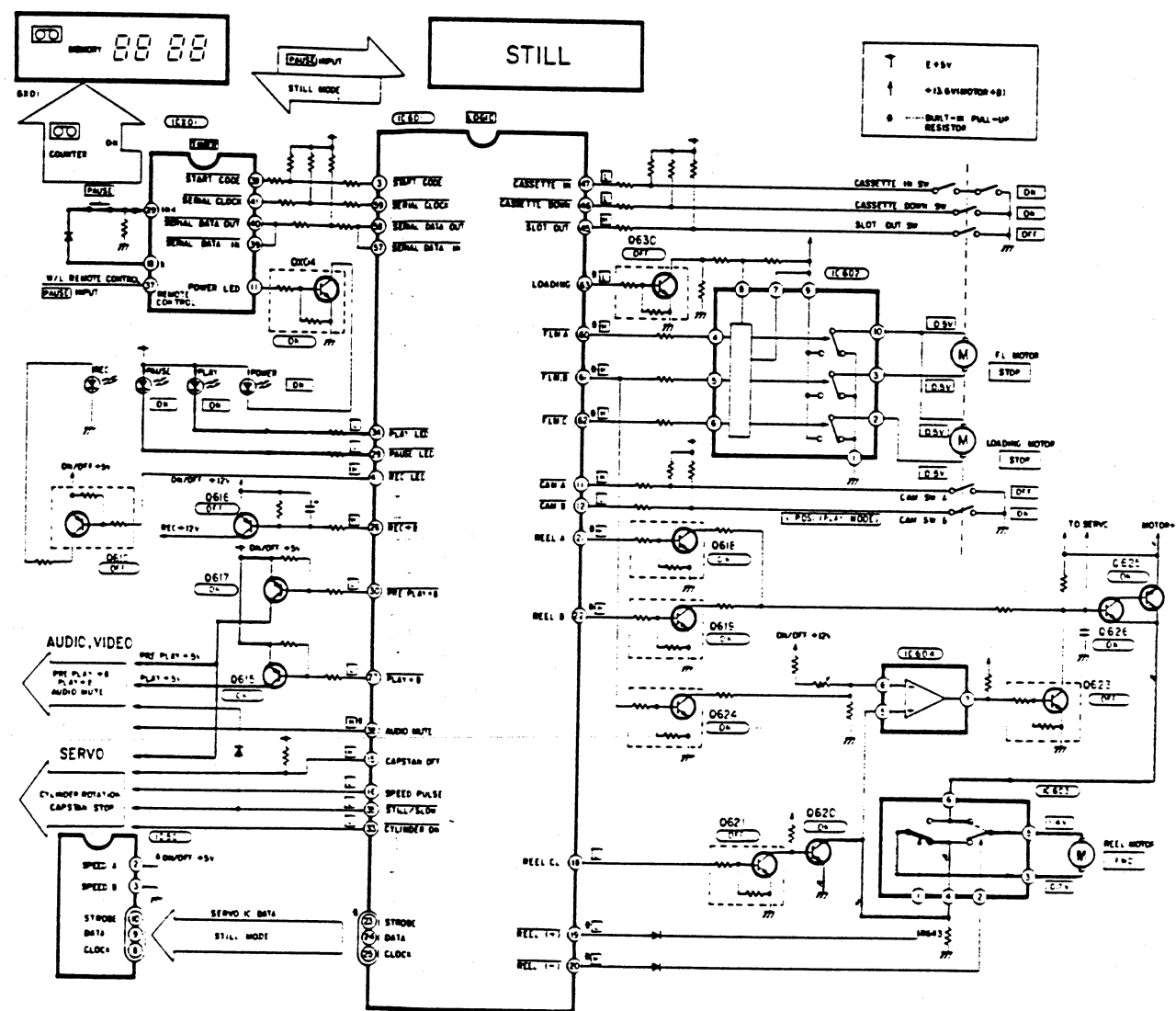


Fig. 3-4-7

1. When the PAUSE button is pushed during the playback mode, IC601 is set to the still mode.
2. The cam gear is in the playback mode (position V) and the cylinder motor is rotating. Under this condition each pin of IC601 develops output voltages as shown in Fig. 3-4-7.
3. Pin 38 of IC601 develops "H" level and mutes audio signals.

4. A mode data (still) is sent to IC501.
5. The capstan motor is stopped.
6. The reel motor is driven at a constant voltage and the idler transfers rotational force to the T-reel table, thus winding the tape. Under this condition a voltage of approx. 0.7V is applied to the motor terminals to prevent tape slack.

3-4-6. Frame feeding mode

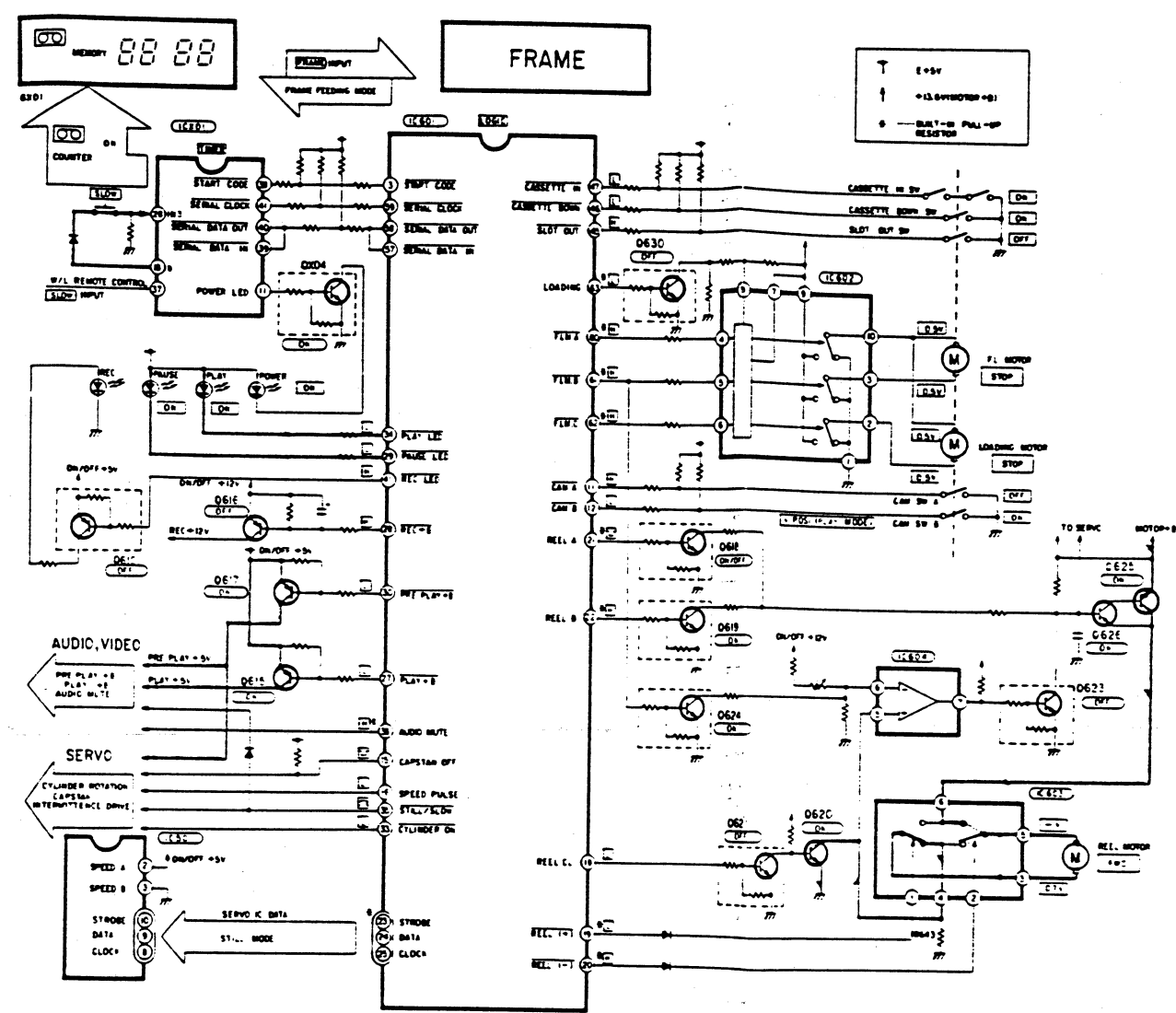


Fig. 3-4-8

When the FRAME button is pushed during the still operation, the capstan motor and the reel motor rotate. When the FRAME button is pushed, the capstan motor and the reel motor are intermittently driven. (Refer to Fig. 3-4-9)

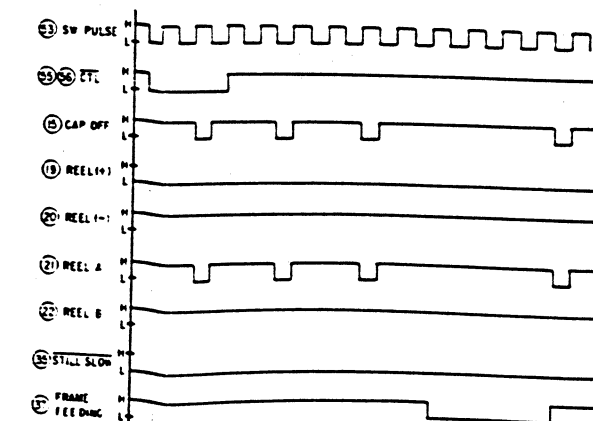
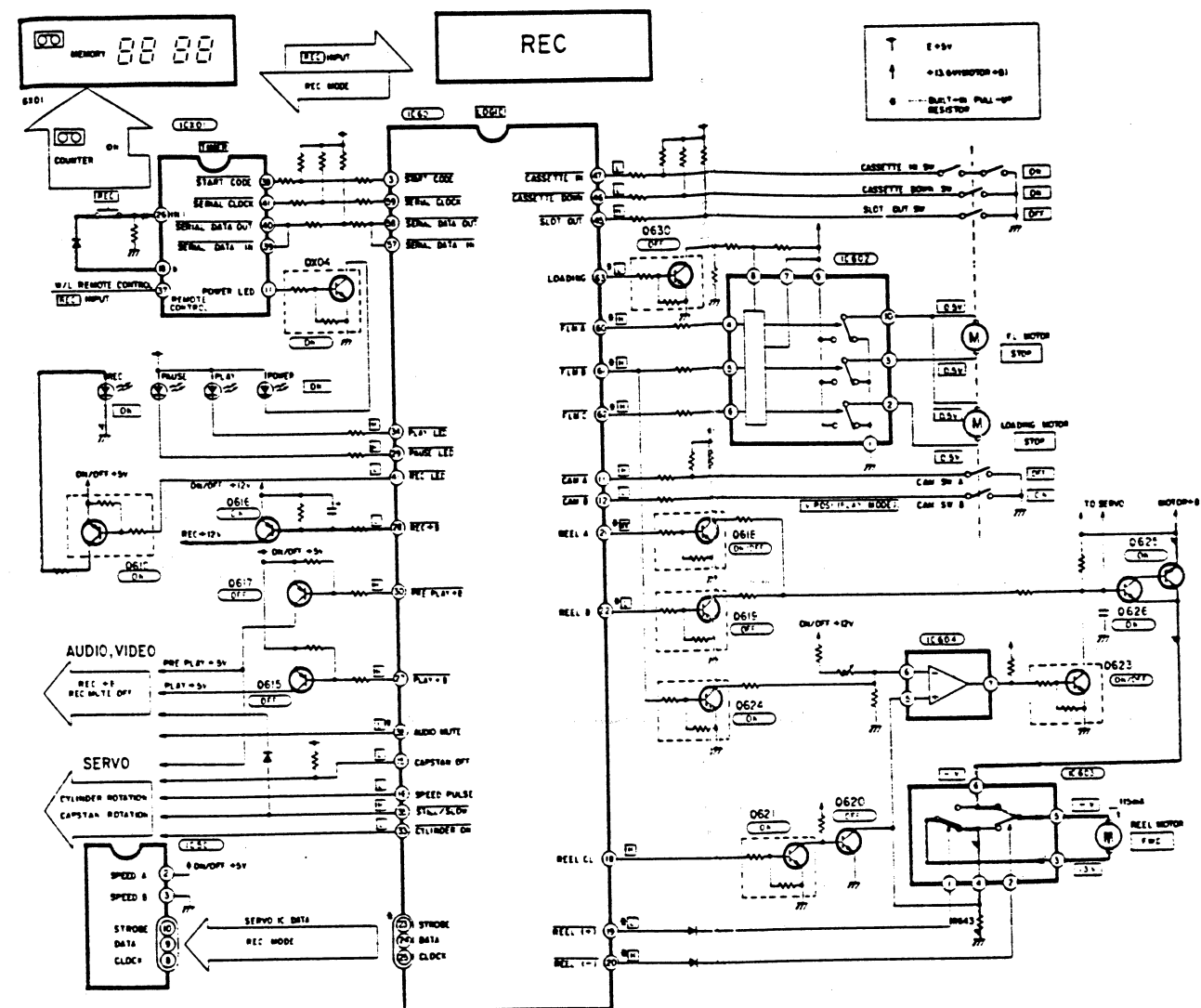


Fig. 3-4-9 Basic timing chart

1. When the FF button is pushed during the playback mode, IC601 is set to the cue (FF playback) mode.
2. The loading motor rotates in forward direction and the cam moves from the position V to the position VI.
3. Pin outputs of IC601 in the cue mode are shown in Fig. 3-4-10.
4. Pin 38 of IC601 develops "H" level and mutes audio signals.
5. A mode data is sent to IC501.
6. The reel motor rotates in forward direction and the idler transfers rotational force to the T-reel table to wind the tape.
At the same time, the servo circuit controls the CTL pulse so that the reel motor rotates at the speed 7 times higher than the normal speed.

3-5-1. Record mode (from stop mode)



1. When the REC button is pushed in the stop mode, ICX01 transfers the record input signal serially to IC601 and sets the record mode.
2. Pin 41 of IC601 develops "L" level and Q610 turns on.
The REC LED is also turned on.
3. The loading mode is set as mentioned in 3-4-1, steps 1 to 7.
4. Next, operations which are the same as those mentioned in the playback mode 3-4-2, steps 1 to 3 are performed and the tape is driven.
5. Pin 28 of IC601 goes "L" level and the REC +12V is supplied to the audio, video, and the servo circuits, and the recording will be made.

3-5-2. Rewinding for synchronous editing

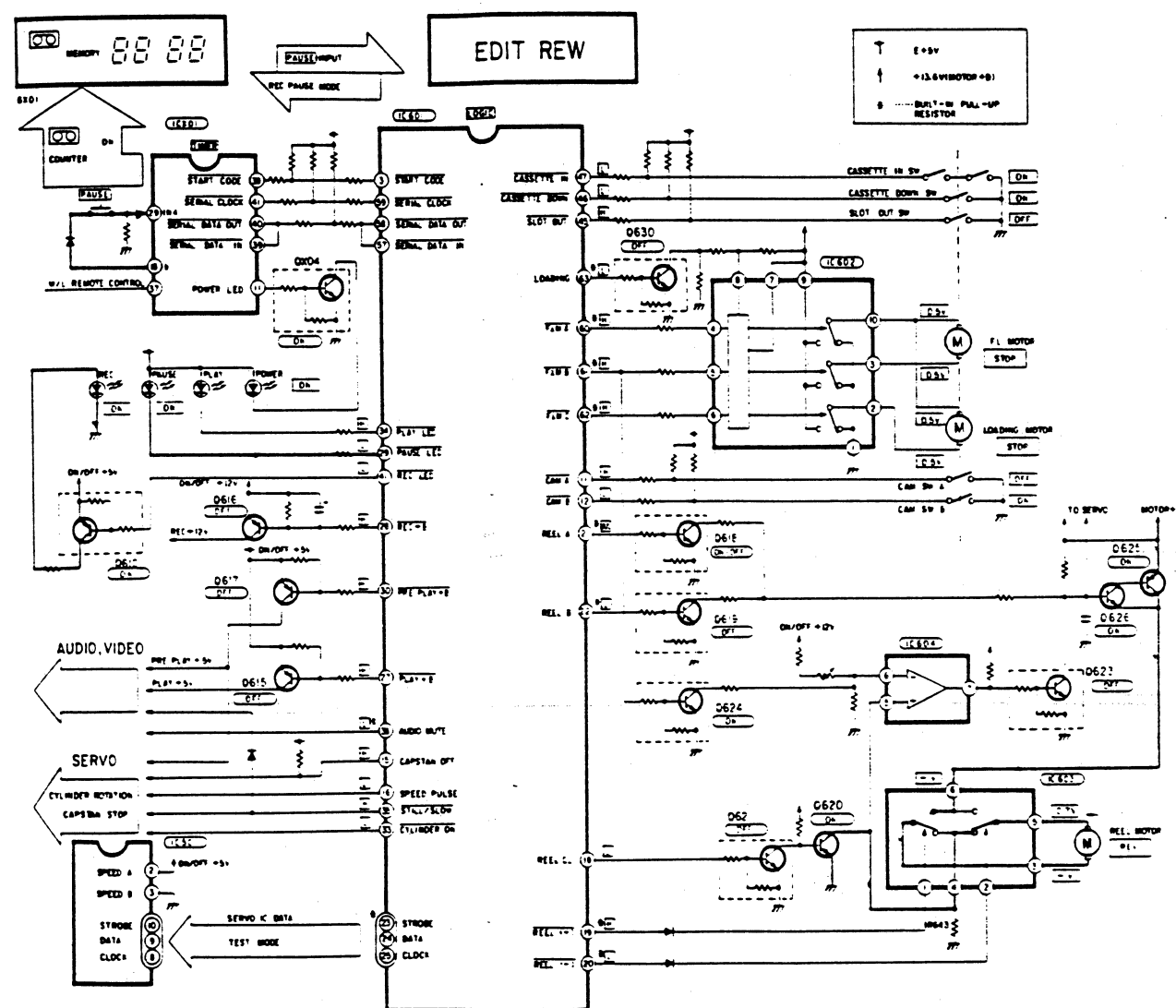


Fig. 3-5-2

1. When the PAUSE or STOP button is pushed during recording, IC601 is set to a record pause mode or the stop mode.
2. The loading motor rotates in forward direction and the cam moves from the position V to the position VI.
3. Each pin of IC601 develops output as shown in Fig. 3-5-2 and the record LED and pause LED light up. Pin 28 develops "H" level output and Q616 turns OFF. Then the audio and video signals are muted.
4. The reel motor is rotated reversely by IC601 and IC603 (Pin 17 and 19). Tape is wound by a specified length equivalent to 100 CTL pulses and then the loading motor rotates in forward direction and the cam moves from the position VI to the position VII (Mode No. 20 to 32).
5. Next, the reel motor rotates in forward direction and winds the tape for a specified length and then the motor stops (Mode No. 31 to 33). At the same time, the loading motor rotates in reverse direction, and the cam moves from the position VII to the position V.

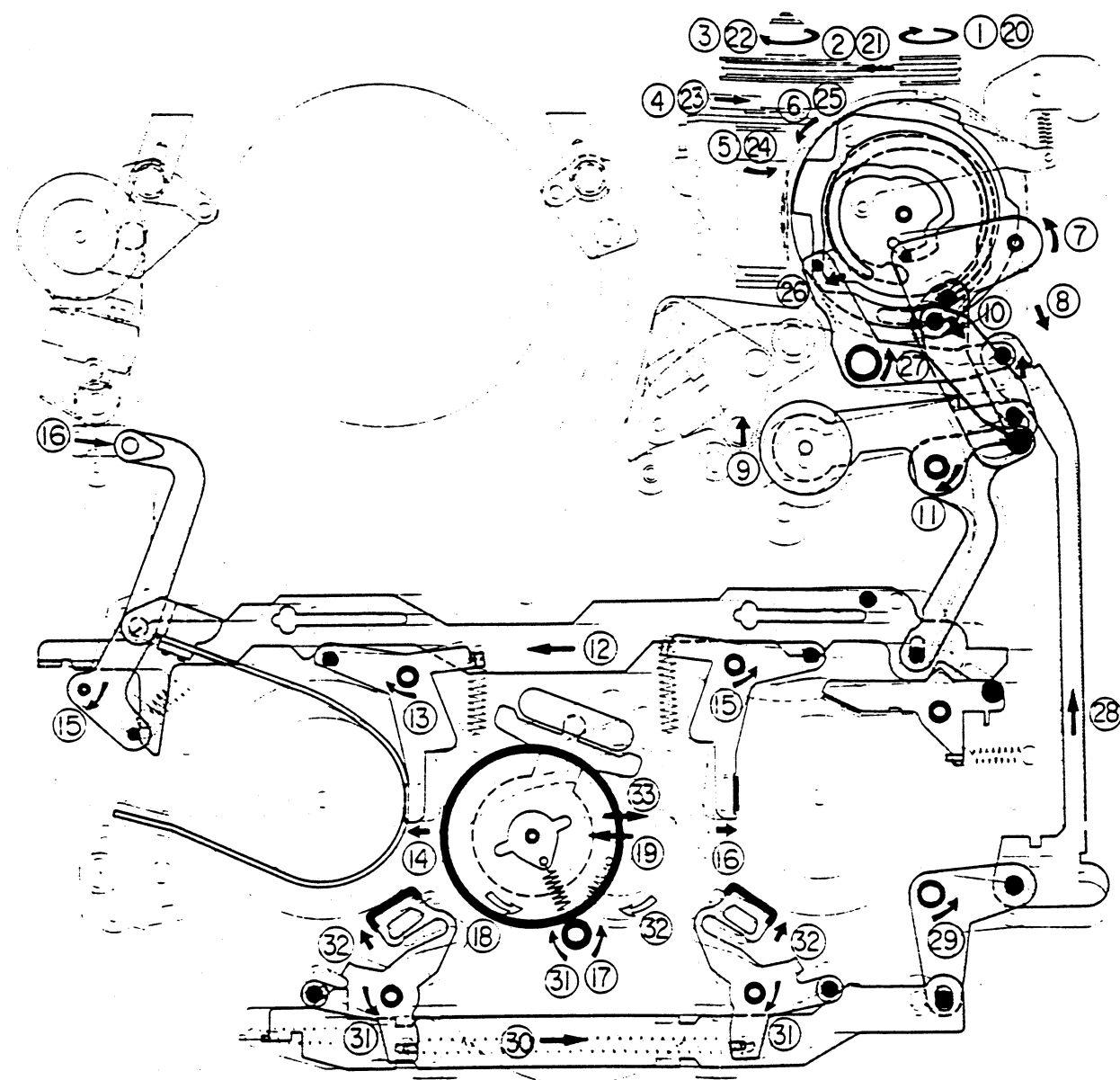


Fig. 3-5-3

6. Furthermore, loading motor rotates in forward direction and the cam moves from the position V to the position VII.
7. At the same time the reel motor rotates in forward direction and then the reel motor stops.

3-5-3. Stop mode (from record to stop)

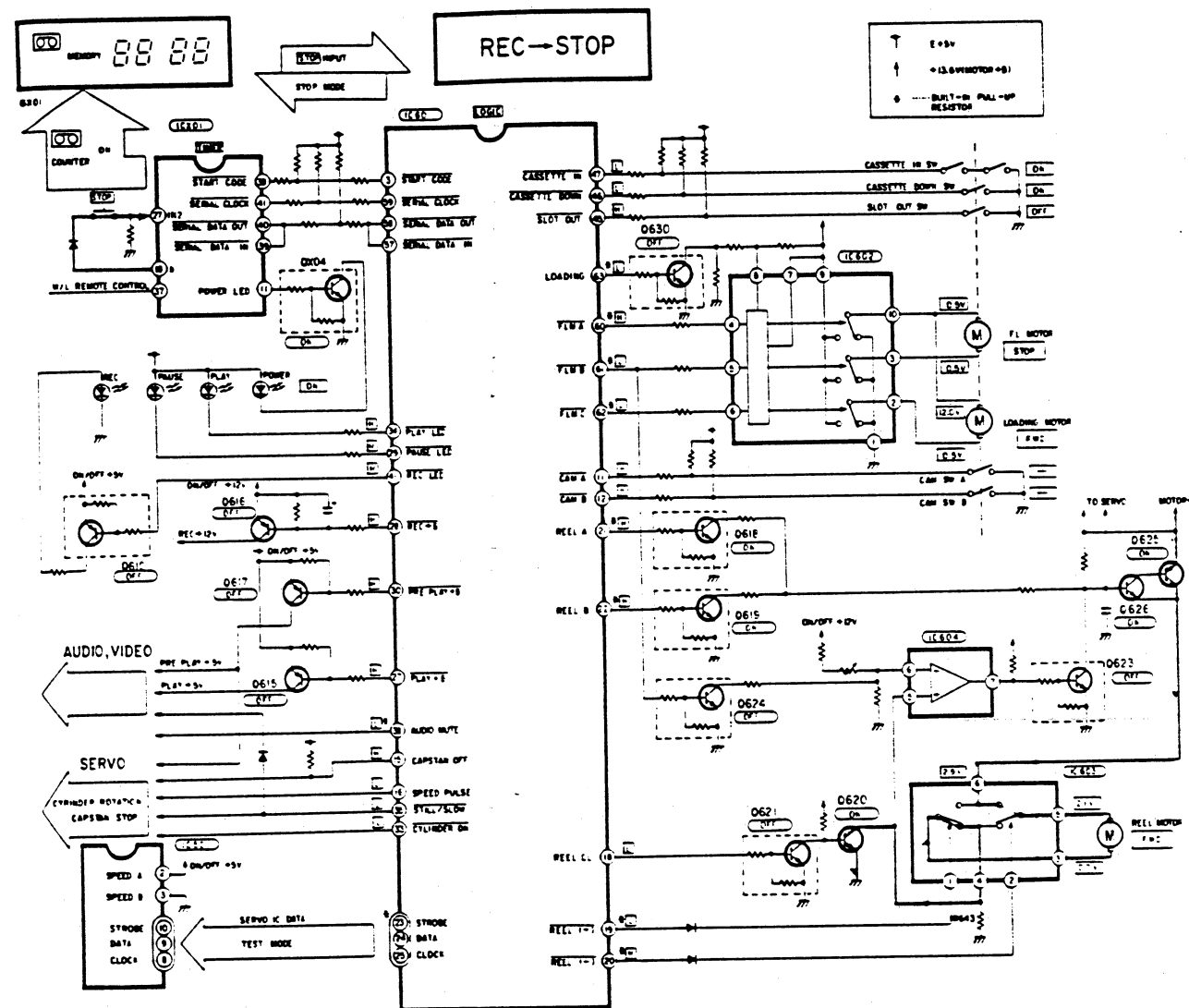


Fig. 3-5-4

1. When the STOP button is pushed during recording, the unit enters the stop mode after completion of temporary rewind operation for synchronous editing. The cam gear is in the REC pause mode (position VII).
2. The cylinder motor, reel motor, and capstan motor stops.
3. When the STOP button is pushed again, unloading operation starts and the cam moves to the position II. (Refer to the unloading operation.)

3-5-4. Record pause (PAUSE)

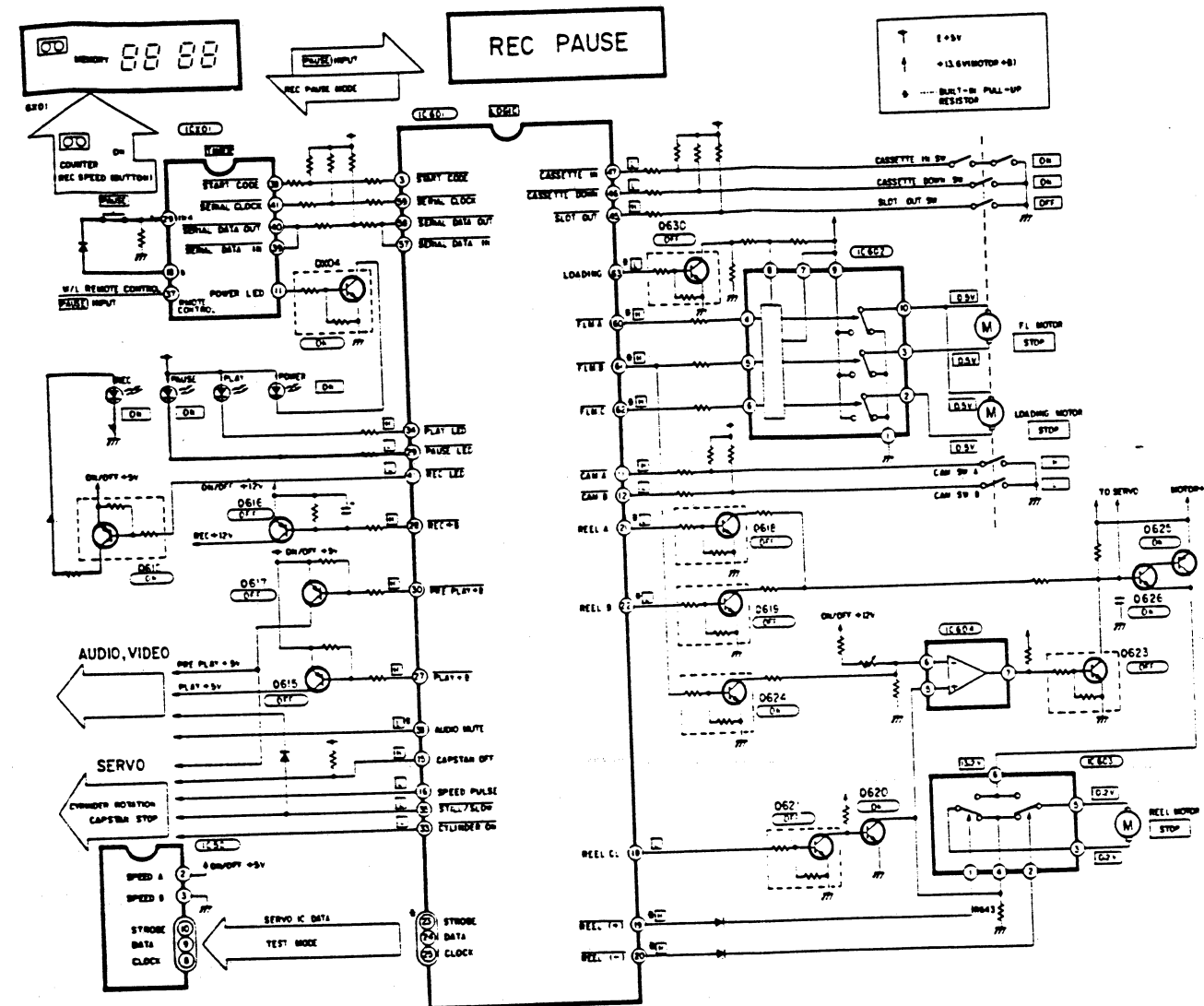


Fig. 3-5-5

1. When the PAUSE button is pushed during a recording, the unit enters the record pause mode after completion of temporary rewinding operation for synchronous editing. In this case, the cam gear is in the REC pause mode (position VII).
2. The cylinder motor rotates, and the capstan motor and the reel motor stop.
3. Each pin of IC601 develops outputs as shown above and the pause LED lights up. Pin 28 develops "H" level output and Q616 turns OFF, and mutes the audio and video signals.

4. CIRCUIT DESCRIPTIONS

4-1. Power Supply Circuit

4-1-1. Outline

The power supply circuit consists of the line filter circuit, power supply transformer, rectification circuits, voltage regulator circuits, heater power supply (3.6V AC) for the FL display tube, etc. The major power supply output is divided into four systems: the first system supplies M + B (13.6V), +12V (ON/OFF 12V), E12V (EVER 12V) and H + B (HEATER + B); the second system +9V (rectification output for 5V); the third system +60V (rectification output for 32V and for bias in the power supply circuit) and; the fourth system -60V (rectification output for -30V) and -28V to the loads.

Furthermore, 3.6V AC is supplied from the power supply transformer as HEATER voltage for the FL tube.

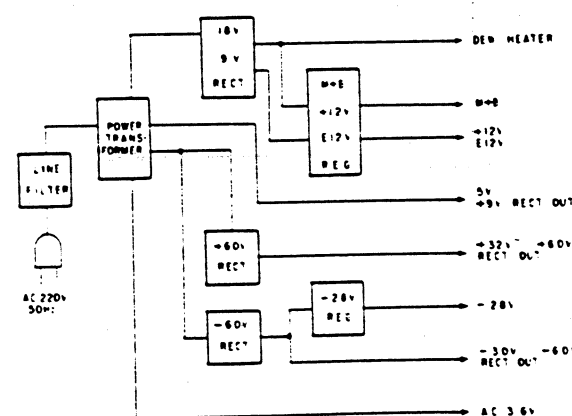


Fig. 4-1-1

4-1-2. Circuit description

1. Rectification circuit

The rectification circuit consists of three systems.

a. The first system

The first rectifier system generates three rectification outputs. AC voltage obtained from the first winding of the secondary windings of the power transformer is rectified and smoothed by the bridge rectifier circuit consisting of D801 - D804 and C805. The DC output of approx. 18V is supplied to the voltage regulator circuits for +12V and E12V. The voltage developed across the same winding is rectified and smoothed by the bridge rectifier circuit consisting of D801, D802, D805 and D806 to obtain DC voltage of approx. 18V.

The DC voltage is supplied to M + B voltage regulator circuit and DEW HEATER. Finally, center tap output of the first winding on the secondary windings is rectified and smoothed by the full-wave rectifier circuit consisting of D801, D802 and C807. The resultant DC output of approx. 9V is supplied to develop 5V.

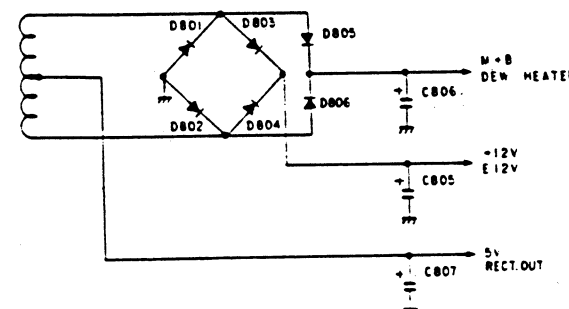


Fig. 4-1-2

b. The second system

In the second system, AC voltage obtained from the second winding on the secondary windings of the power transformer is half-wave rectified and smoothed by D807 and C808 to obtain DC of approx. +60V. The voltage is supplied as a bias for the +32V regulator circuit and power supply circuit.

c. The third system

In the third system, AC voltage obtained from the second winding on the secondary windings of the power supply transformer is half-wave rectified and smoothed by D808 and C809 to obtain DC of approx. -60V. The voltage is supplied to the voltage regulator circuits for -28V and -30V.

2. Voltage regulator circuits

a. +12V voltage regulator circuit

The +12V voltage regulator circuit consists of the output transistor Q804, error amplifier transistor Q805, reference voltage zener diode D815 and error detection resistors R814, R815, and R851 etc.

When a bias is supplied from the power ON/OFF circuit through R825, Q804 turns on, supplying current to the zener diode D815 via R813 to generate reference voltage. Then the error amplifier transistor Q805 and error detection resistors R851, R814 and R815 detect error voltage between the reference

voltage and the output voltage and control the output transistor Q804 so that it always maintains a constant output of 12V.

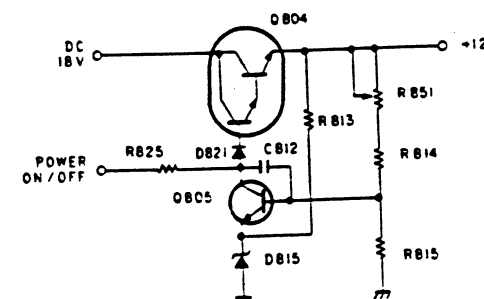


Fig. 4-1-3

b. M + B (13.6V) voltage regulator circuit

The M + B voltage regulator circuit consists of the output transistor Q802, error amplifier transistor Q803 and error detection resistors R811 and R812.

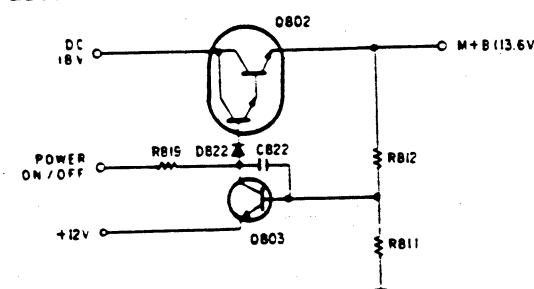


Fig. 4-1-4

When a bias is supplied from the power ON/OFF circuit through R819, Q802 turns on. The error detection resistors R811 and R812 detect fluctuation of the output voltage, and the error amplifier transistor Q803 controls the output transistor Q802 in such a way to maintain the output always at 13.6V.

c. E12V voltage regulator circuit

The E12V voltage regulator circuit consists of the output transistor Q806, zener diode D817 for the reference voltage, etc. 18V DC rectification output is supplied to the collector of the output transistor Q806 via the fuse resistor R816 and also to the zener diode D817 for the reference voltage via R817, obtaining output of 12V.

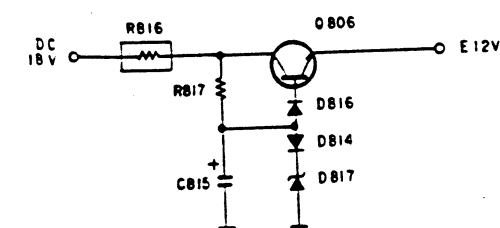


Fig. 4-1-5

d. -28V voltage regulator circuit

In the -28V voltage regulator circuit, -60V rectifier output is stabilized into -28V by zener diodes D809 and D810 via R802.

e. DEW HEATER switch circuits

DEW HEATER is controlled by the switching transistor Q801.

The switching transistor Q801 is controlled by the two control signals (DEW HEATER ON, POWER ON/OFF). +18V rectification output is applied to DEW HEATER and Q801 base (as the bias).

Power OFF:

Q801 base is biased from +18V rectification output and the DEW heater is turned on.

Power ON:

(When the cylinder is in stop.)

Power ON/OFF signal turns on Q807 (on POWER 2 unit) and this cut off the base bias from +18V rectification output to Q801 base.

However, the DEW heater ON signal turns to "H" and this turns on Q801, so the DEW heater is turned on.

(When the cylinder is rotating)

The DEW heater ON signal turns to "L" and Q801 turns off, so the DEW heater is also turned off.

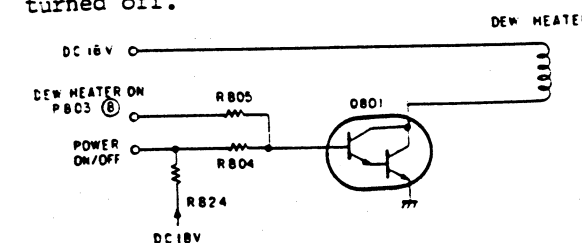


Fig. 4-1-6

f. Protection circuit

The protection circuit consists of the zener diode D819 for output voltage detection and switching transistors Q808 and Q810.

Q808 base is always supplied with bias from 18V DC via R824 when the power is turned off, or from M + B via R820 when the power is turned on, thus maintaining Q808 at ON and Q810 at OFF.

If the output of M + B or +12V is short-circuited to the GND etc. and M + B lowers to a value less than the operating voltage of D819, D819 is cut off and Q808 turns off supplying no bias to the Q801 base.

Accordingly, a bias is supplied to the Q810 base via R818 turning Q810 on and turning off the bias for the M + B and +12V circuits, thus cutting off the M + B and +12V outputs.

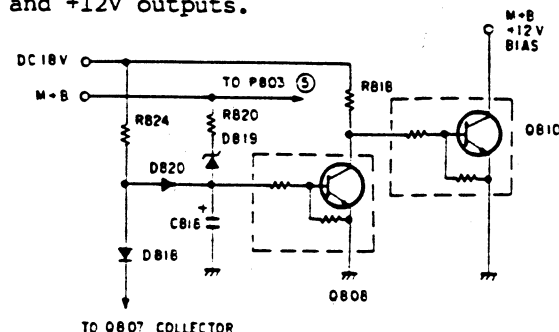


Fig. 4-1-7

4-1-3. TIMER 2 Circuit

1. Back up +B regulator circuit

EVER 12V supplies a current to zener diode DL10 in passing through a current limiting resistor RL16 and a reverse current protection diode DL12, and the DL10 develops 5V reference voltage. At the same time, EVER 12V charges capacitor CL10 through the resistor RL14. If EVER 12V is not applied due to a power failure, etc., the capacitor CL10 supplies the charged electricity as the Back +B through the diode DL13.

2. Timer reset circuit

Timer reset circuit consists of the reset IC ICL10 (PST520C) and resistor RL10. ICL10 detects the Back Up +B and generates a reset signal at the time of rising of the Back Up +B at power failure.

3. -30V voltage regulator circuit

-60V from the power supply enters the zener diode DL11 (05Z30Y) via resistor RL18 for current regulation, generating voltage of -30V.

4. ON/OFF 5V regulator circuit

ON/OFF 5V is generated by turning on or off EVER 5V with the switching transistors QL11 and QL12 controlled by signal (POWER ON) from pin 6 of the connector PL02.

4-2. RF and Receiving Circuit

4-2-1. Outline

1. The receiving circuit consists of an ANT input/output circuit, channel selection circuit, PIF and SIF circuits. The receiving circuit selects a desired broadcast signal from TV signals induced on an antenna and sends stable video signal and audio signal obtained by processing program signals to the video and audio circuits.
2. The output signals from the video and audio circuits are converted to a conventional TV signal for the channel 31 to 39 with an RF modulator so that it can be received by conventional TV receivers.

4-2-2. ANT input & output circuits

1. In this VTR the RF signal splitter, mixer and the RF modulator have been structured as an integrated unit.
2. The RF splitter splits TV input signals from the antenna into two: and send one of them to the tuner's RF input terminal and another to the mixer.
3. The RF splitter output and the RF modulator output are mixed in the mixer circuit, and the resultant output is used as an RF output. To discriminate the RF modulator output from an antenna input signals a test signal generator has been provided in the modulator. The modulator has been designed so that its output channel can be varied with a control VC to prevent the antenna signals from interference.

4-2-3. PIF, SIF Circuits

1. TV signals from the antenna input circuit are fed to the tuner, and the tuner develops the IF signal corresponding to the channel selected by the channel selector circuit.
2. The IF signal passes the IF filter (surface acoustic wave filter) and enters pins 1, 16 of IC002 (TA7607AP).
3. The IC002 amplifies and detects the IF signal, and the resultant video signal is output from pin 12.
4. One part of the output is applied to the video circuit in passing through 5.5 MHz trap circuit, 6.5 MHz trap circuit, SYNC UP circuit, and Q003 buffer. In the SYNC UP circuit, the sync signal is separated with a diode D002 connected to emitter side of Q008 and a capacitor C032, and then the sync section of a video signal suppressed in detection process is expanded properly in IC002, thus the sync level is being corrected.

5. Another part of the output enters pin 2 of IC005 (TA7337P) in passing through SIF converter circuit (ZB01, ZB02, ZB03, ZB04) and 6.5 MHz BPF (ZB04). The IC006 detects the 6.5 MHz FM signal to obtain audio signal. The audio signal is output from pin 9 and sent to the audio circuit.

4-2-4. Channel selection circuit

1. Outline

The channel selection circuit employs a voltage synthesizer (VS). The VS circuit consists of a memory circuit, ICA02 and a VS microcomputer, ICA01. Various information such as band selection & tuning voltage data required for channel selection, data for AFC defeat, and audio muting are transferred serially between the timer microcomputer and the PIF circuit as well as other display data are sent to the timer circuit.

2. Functions

* Channel pre-setting mode

The VS microcomputer sends real channel data relating to a band data and a tuning voltage data obtained from the key matrix to the memories to keep the information. The VS microcomputer also sends the same kind of data to the timer circuit to display the information on the FL display tube.

* Conventional reception mode

- a. In a conventional channel selecting operation, a channel data is read out from a memory with a channel position data sent from the timer circuit and the data is transferred to the timer section circuit. Furthermore, a band voltage and a tuning voltage of the channel are sent to the PIF section.

Table 4-2-1

Band	Microcomputer terminal		
	VB	UB	SW
VL	H	L	L
VH	H	L	H
U	L	H	L

Table 4-2-2

Band	Tuner terminal		
	VB	UB	SW
VL	12V(H)	0V(L)	23V(L)
VH	12V(H)	0V(L)	0V(H)
U	0V(L)	12V(H)	23V(L)

(): Microcomputer

4-3. Timer, Display Circuit

4-3-1. Outline

- These circuit include various functional circuits such as the timer, channel selection, electronic counter, remote control light signal reception and the logic switch circuits etc., and consist of a microcomputer (TMP47C410AN-6775) playing primarily roles in these circuits, FL display tube (FIP8YM7) indicating time counted value, channel, cassette, etc.; operation key matrix and the remote control light signal reception circuit. These circuits are used to perform following functions; time count, timer recording channel selection, key input reading, information reading from a wireless remote control unit etc.

4-3-2. Different features from conventional models

- Conventionally used three microcomputers, each of which is relating to a timer, sublogic and main logic circuits respectively, are replaced by two microcomputers (timer, logic circuit) which also perform operations conducted by the sublogic microcomputer so far.
- As new features, auto power on and auto play functions are added.

4-3-3. Functions

- Clock**
 - 24 hours digital clock
 - 50/60 Hz automatic switching
- Programmable timer**
 - 4 programs in 14 days
 - Every day, every week or every day (Sun. through Sat.)
 - One touch timer recording (Max. 4 hours)
 - Reserved program confirmation using the confirmation key

3. Channel selection

- Real channel display in 16 positions of 0 through 99.
- Two button UP & DOWN system
- Band and channel position indication in preset mode (Time display is switched for this indication)

4. Electronic counter

- 4 digit indication in FL display tube (Time display is switched for this indication)
- (Count operation is performed in the logic microcomputer)

5. Input data reading

- Data reading from key switches on the unit
- Data reading from the wireless remote control

6. Additional functions

- Auto power on
(Inserting a cassette turns the power on automatically.)
- Auto play
(Playback operation automatically starts after completion of tape rewind operation.)

4-3-4. Theory of operation

1. Operation keys

As can be seen in Fig. 4-3-1, 24 push switches and 1 slide switches are used to control the timer, channel selection, logic mode, counter, and the power of the unit. In addition to this, wireless remote control codes are read through pin 37.

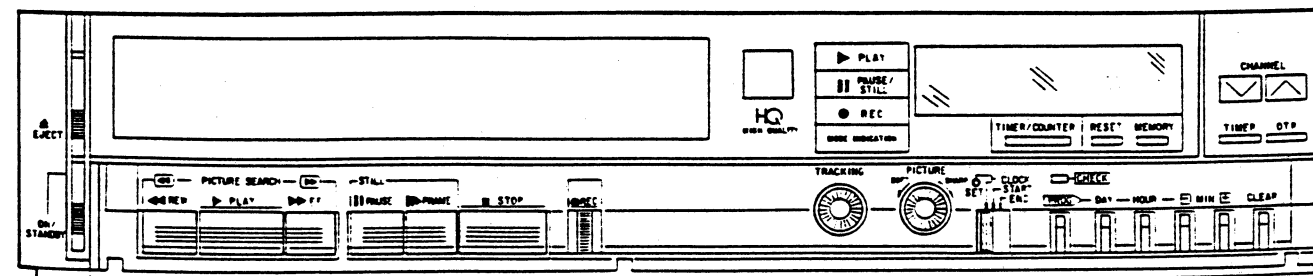


Fig. 4-3-1 Operation keys

2. Clock

- The AC clock signal (utility power frequency) supplied from the power transformer is first wave-shaped by the wave-shape & clamp circuits (DX01) and then applied to pin 35 of ICX01, timer microcomputer through the buffer (QX02).
- The clock operates in synchronization with this clock signal. The microcomputer discriminates 50 Hz and 60 Hz and automatically takes required operations.

3. Channel selection

- Channel selection is performed by the channel UP and DOWN keys on the unit.
- The channel selecting operation is conducted inside the ICA01 (M50430-81SP) on the SELECT P.C. board. The ICA01 controls four bus lines for serial data transmitting. The ICX01 transmits a channel position data relating to the channel selected to ICA01, and the ICA01 transmits a real channel data and a band data to the ICX01, thus allowing the FL display tube to indicate the channel selected (0 - 99).

4. Serial transmission

- Data of 4 bits x 16 words are transmitted serially from or to the main logic circuit. This data transmission is performed eight times for every cycle of 30 msec starting from ICX01, IC601, ICX01, . . . alternately in this sequence.
- When ICX01 develops first output, the start code is set to "L" and after the reception of first transmission from the IC601 the start code is set to "H".
- In this serial transmission, the ICX01 transmits input key codes, power on, auto play, counter memory, counter values, etc. to the IC601, and the IC601 transmits power on off signal, logic mode signal, counter values, etc. to the ICX01.

5. Electronic counter

Operation of the electronic counter is conducted inside IC601. Counted values are transmitted serially and the content is displayed on the display tube.

6. FL display tube

- Time, content of timer reserved programs, or a counter value is switched and displayed.
- Furthermore, cassette, counter memory, and a real channel selected are displayed.
- A dynamic drive system which lights up each digit segment sequentially with grid pulses and segment pulses sent from the microcomputer is employed in the FL display tube.
- The FL display tube is of triode type and lights up when both of the grid voltage E_c and the plate voltage E_b become +27V against the filament center voltage (-22V).
- To turn off the display tube, E_c or E_b must be lowered to 6V below the filament voltage.

7. Power failure compensation

When power failure occurs, content of reserved programs, etc. will be maintained if the failure is resumed within 0.5 sec. The display tube turns off during the power failure but its colon will blink after the failure is resumed.

8. Additional function

- Auto power on**
Loading a cassette turns the power on automatically, if the power is turned off.
- Auto play**
When the PLAY key is pushed with the REW key during rewind operation, the auto PLAY mode is set and the playback LED blinks. And the PLAY mode is automatically set when the rewind operation completes. The auto play mode does not work with the wireless remote control unit.

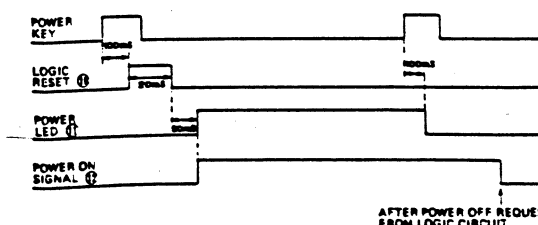


Fig. 4-3-2

4-4. Logic Circuit

4-4-1. Outline

1. The logic circuit consists of two microcomputers TMP4746N5759 (for system control . . . hereafter called logic microcomputer) and TMP47410AN6775 (for button operation, remote control processing, etc. . . hereafter called timer microcomputer), main unit which performs the system control; timer unit which controls each mode operation and the LED indication; and the logic switch unit.
2. Mechanism control for each mode is conducted with a cam system. A slot-in mechanism is employed for tape loading. Controls for these mechanisms are performed by the electronic logic operations using the microcomputers stated above.

4-4-2. Functions

1. Mode operation

Fig. 4-4-2 shows a mode shift diagram. Operation of each button is accepted through the routine shown in Fig. 4-4-1. During the mode shift operation, IC601 performs the system control as follows:

- a. Determines an operation mode by analyzing input signals from the operation button(s) and sensor switches provided to detect abnormal operation, etc.
- b. Performs the mode LED display and the counter control and sends the counted value to ICX01.
- c. Controls servo systems (servo IC, cylinder motor and capstan motor).
- d. Controls audio and video systems (mode +B, and muting signals)
- e. Controls the loading motor to set a desired cam position, thus controlling the mechanism system.
(Output: pins 60, 61, 62, 63 of IC601)
(Input: pins 11, 12 of IC601)
- f. Controls the reel motor.

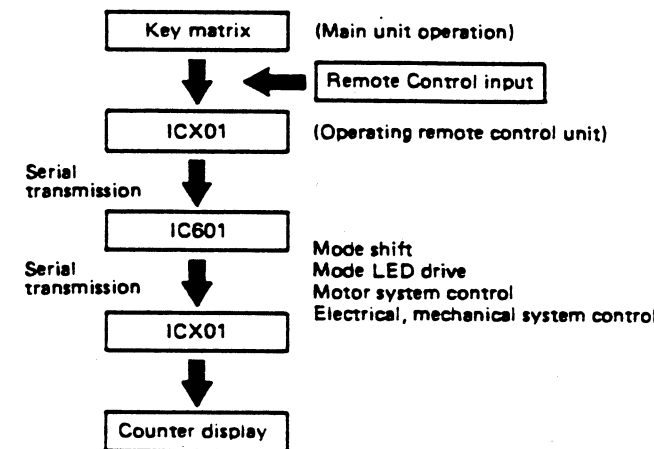


Fig. 4-4-1 Mode shift

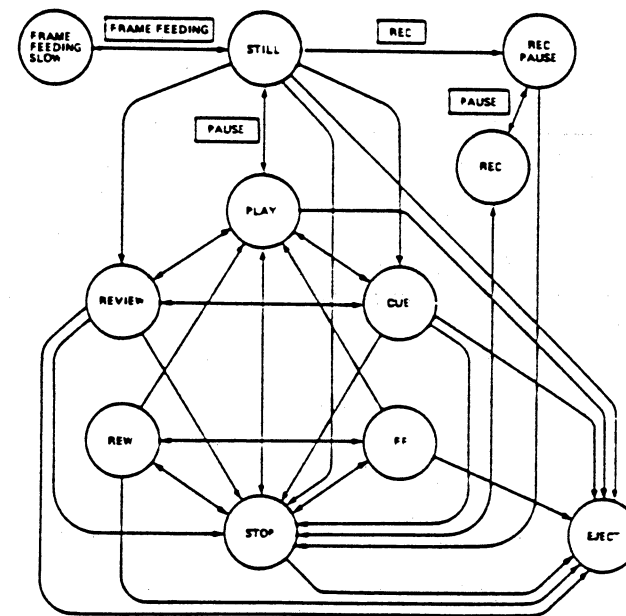


Fig. 4-4-2 Mode shift diagram

2. Slot mechanism control

Input: Pins 45, 46, 47, 13, 14 of IC601
Output: Pins 60, 61, 62 of IC601

- a. During cassette loading or unloading operation, IC601 checks status of three FL-SW (cassette in 47, cassette down 46, and slot out 45) and controls the FL motor.
- b. IC601 also checks status of tape end sensors (tape start sensor 13 and tape end sensor 14) after the packet is moved down and performs the eject operation if no cassette is loaded.

3. Loading mechanism control

Input: Pins 11, 12 of IC601
Output: Pins 60, 61, 62, 63 of IC601

During loading, unloading or cam position transitional period, IC601 checks status of the cam switches (Cam A 11, Cam B 12) and controls the loading motor.

4. Tape end detection (tape start)

Input: Pin 13 of IC601

- a. When tape start position is detected in a rewind mode or review mode, the rewind operation is stopped and a short length of tape is wound in forward direction.
- b. When tape start position is detected in a forward mode, a short length of tape is rewound and then the unit enters that mode.

5. Tape end detection (tape end)

Input: Pin 14 of IC601

When the tape end is detected during forward modes such as playback, recording, etc., the tape is automatically rewound.
(In the timer recording mode, the rewind operation is not performed but the unit enters the stop mode and the power is automatically shut off.)

6. Accidental erase prevention

Input: Pin 48 of IC601

If a cassette with its safety tab removed is loaded, the record mode can not be set, and when the REC button is pushed the cassette is automatically ejected.

7. Timer recording

Input: Serial transferring

The timer recording mode is set with the timer recording input sent from the timer microcomputer ICX01.

8. Synchronous editing

After completion of the following mode change operations (from record to stop or record pause; from still to record pause or timer record), tape is slightly rewound to allow overlap recording for that area.

9. Counter memory

When fast forward or rewind operation is performed with the counter memory mode actuated, the VTR stops automatically when the counter reaches "0000". To increase stop position accuracy of the tape, output from pin 21 of IC601 is controlled in terms of PWM so that the rotating speed of the reel is slow down at a location preceded by 200 count pulses from the zero stop position.

10. Auto play

- a. When the PLAY button is pushed with the REW button during rewind mode, auto play mode is set and the playback LED blinks at a rate of 1 Hz.
- b. If the counter memory mode is set, playback mode is automatically set after the zero stop operation.
- c. The playback operation starts automatically after detection of a tape start position.

11. Auto power on

When a cassette is newly loaded under the power off condition, the power is automatically turned on and the cassette is slotted in and loaded.

12. Audio muting

Output: Pin 38 of IC601

Audio signals are muted during the frame, still, and picture search operations.

13. Automatic mode release

To protect tape from damage the still, slow, or the record pause mode is automatically released after a specified time elapsed as shown in Table 4-4-1 below.

Table 4-4-1 Automatic mode release time

Mode	Release after:	Mode after released
Still/Frame	Approx. 5 min.	Playback
Rec . Pause	Approx. 10 min.	Stop

14. Abnormal reel rotation detection

Input: Pin 54 of IC601

If rotational pulses from the take-up reel do not enter for a specified period determined for each mode as shown in Table 4-4-2, IC601 assumes there may be some troubles in the mechanism, etc. and sets the stop mode.

If abnormality is detected during timer recording, the power is automatically turned off.

15. Abnormal cylinder rotation detection

Input: Pin 53 of IC601

If switching pulse input does not vary for approx. 3 seconds with the cylinder motor rotating, the VTR enters the stop mode. However, when abnormality is found during timer recording, the power is shut off.

16. Motor protection

Provisions for motor protection is provided as shown in Table 4-4-3.

Table 4-4-3 Motor protection function

Mode	Abnormal operation	Abnormality detection time	Operation made shifts to:
Slot in	Cassette in SW Off.	Approx. 0.5 sec.	Slot out
	Cassette does not move down.	Approx. 3 sec.	Slot out
Slot out	Cassette does not move out.	Approx. 3 sec.	Slot in
Slot in after abnormality detection in slot out operation	Cassette does not move down.	Approx. 3 sec.	Power turned off after FL motor was stopped.
Loading	Cam does not move to its correct position.	Approx. 10 sec.	Power turned off after loading motor was stopped.
Unloading	Cam does not move to its correct position.	Approx. 10 sec.	Power turned off after loading motor was stopped.

Table 4-4-2 Reel abnormal rotation detection time

Modes	Detection time
FF	Approx. 2.5 sec.
REW	Approx. 3.5 sec.
CUE	Approx. 2.5 sec.
Review	Approx. 10 sec.
PLAY	Approx. 2.5 sec.
Frame	Approx. 90 sec.
REC	Approx. 2.5 sec.
Unloading	-

4-5. Servo Circuit

4-5-1. Outline

In the servo circuit, a digital servo IC (TD6360P) functions a primary role and controls the cylinder motor and the capstan motor. The servo circuit performs functions as shown below.

- Cylinder servo circuit
Controls rotating speed and phase of video head
- Capstan servo circuit
Controls tape speed at a specified value so that the video heads can precisely trace tape patterns in playback operation
- Reel servo circuit
Drives the tape at speed of seven time the normal speed
- Capstar pulse drive
Noise shifting
- Vertical sync separation circuit, various amplifier circuits.
- Controls synchronous editing.

4-5-2. Servo IC

- The servo IC, TD6360P is a 42 pin shrink type IC which has been newly developed with following functions:
 - Cylinder system processing circuits: phase detection, speed detection, reference signal generation
 - Capstan system processing circuits: phase detection, speed detection, reference signal generation
 - Built-in Schmitt amplifiers for input signals (PG, FG, CTL).
 - Cylinder FH correction circuit.
 - Built-in control record current source.
 - Synchronous editing function
- Pin configuration is almost the same as that of TD6314P, but differs in that the function 4) shown above was added and the mode designation is conducted by serial data inputs to pins 8 - 10.

4-5-3. Cylinder servo circuit

The cylinder servo circuit controls rotational speed and phase of the video heads so that video signals can be recorded on specified video track correctly in the record mode and the heads can precisely trace on the recorded patterns in playback mode.

1. PG and SW pulse generation circuits

- The PG pulse is created by detecting rotation of the PG magnets mounted on the lower part of the cylinder with the fixed PG heads. When the servo is locked, the PG pulse is set approx. 0.9 msec before head switching point. Fig. 4-5-1 shows the timing chart.

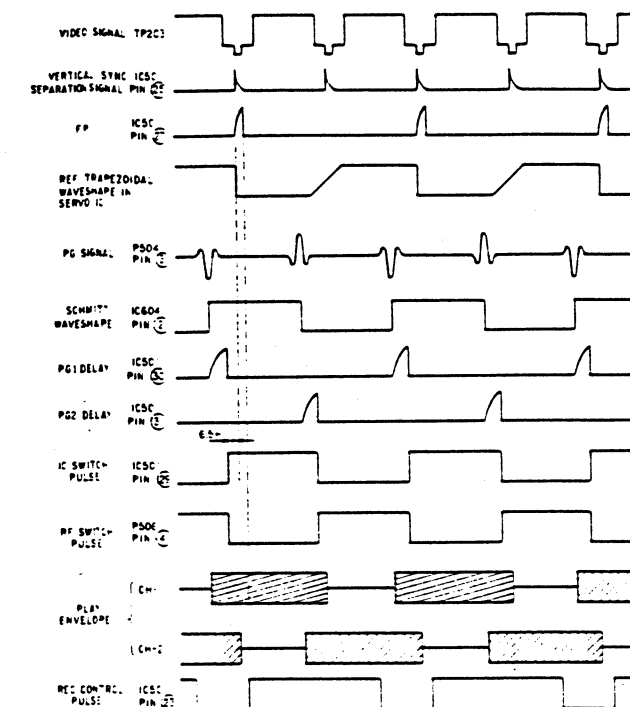


Fig. 4-5-1 Cylinder servo timing chart

- The PG signal induced on the PG heads is waveshaped in the Schmitt circuit of IC503 (pins 5, 6, 7) and then sent to pin 32 of IC501. Each of PG 1 and PG 2 pulse is delayed by time constant circuits consisting of R551 (VR), C503 and R552 (VR), C504, respectively. Each of the delayed output triggers flip-flops inside the IC, and develops at pin 29 as the SW pulse. The SW pulse is sent to the video circuit through the inverter Q514.

2. Phase detection (APC), speed detection (APC)

- The phase detection and the speed detection are conducted inside IC501.
- In the phase detection circuit, a rising edge of the switching pulse created from the PG pulse as previously described is compared with a reference signal (25 Hz) in their time difference (phase). In the record mode, a vertical sync signal (input to pin 25 of IC501) is counted down to half and the resultant signal is used as the reference signal.
- On the other hand, in the playback mode the internal reference signal of 25 Hz, which is created from the clock signal of 4.43 MHz (applied to pin 41 of IC501), is used as the reference signal. This is the only difference observed between the record and playback modes in the cylinder servo operation.

- d. These reference signals are synchronized with rising edge of the delayed waveform at pin 27 (FP) of IC501.
- e. In the speed detection circuit rising and falling time of the switching pulse (speed or time difference) is compared. Results of the phase and speed detections are output from pins 13 and 12 of IC501 as 69 kHz rectangular pulse signals modulated in pulse width (PWM).
- f. When the servo is locked under the stabilized condition, the PWM output shows about 50% duty, but when excessive speed and/or phase variations are caused the duty may vary considerably and in the worst case the duty becomes high or low.
- g. However, if the rotating speed of the cylinder deviates considerably (in this case the AFC output becomes high or low) the duty of the APC output (pin 13 of IC501) is maintained at 50%, so care must be needed.

3. Phase compensation and output amplifier circuits

- a. The output from pin 13 of IC501 passes through a filter (R524, C510, R567, R521, C511, C531) provided to stabilize the servo response and to filter the 69 kHz PWM carrier component and enters pin 12 of IC502, op-amplifier.
- b. The double throw diode D513 connected in parallel to R567 is provided to enhance quick charging or discharging of C511 and C531 in transient time period.
- c. The AFC output from pin 12 of IC501 enters pin 13 of IC502, op-amplifier. The AFC output is fed back from the emitter of drive transistor Q533 with the carrier component removed by the feedback capacitor C519.
- d. R540 and C520 determine the gain of the op-amplifier, at the same time, they constitute a filter for APC and AFC.
- e. The op-amplifier output enters the base of drive transistor Q533 and drives the cylinder motor. To stop the cylinder motor approx. 3.5V is applied to the inverted input terminal of the op-amplifier through D511 to decrease the op-amplifier output to a low level.

4. fH correction

- a. In the cue/review mode, it is necessary to decrease or increase the rotating speed of the cylinder in response to the tape speed to keep relative tape speed between the cylinder and the tape at the specified value or to obtain constant horizontal sync frequency of 15.625 kHz.

- b. Conventionally, this rotating speed control of the cylinder has been made by an external circuit, but in this model, the cylinder speed is automatically increased or decreased according to the speed control signal sent from the microcomputer to pins 8 - 10 of TD6360P, thereby performing the fH correction.

4-5-4. Capstan servo circuit

In the capstan system, tape is driven by rotating the capstan flywheel coupled to the Capstan motor through a belt. Fig. 4-5-2 shows the timing chart in record mode and Fig. 4-5-3 shows the timing chart in playback mode.

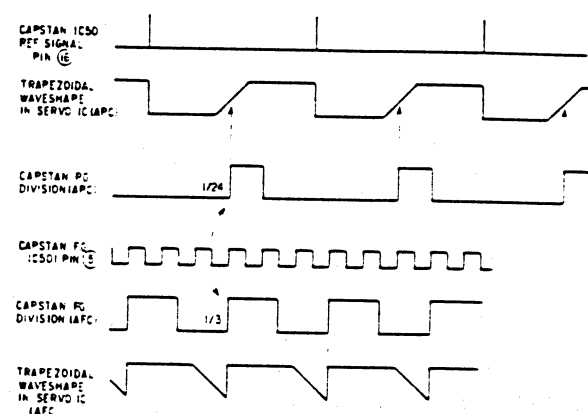


Fig. 4-5-2 Timing chart (Record mode)

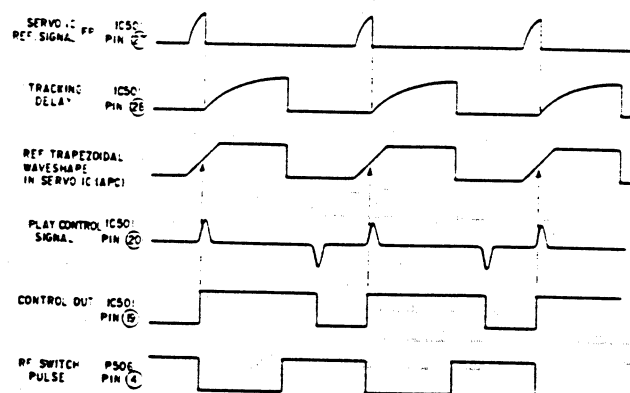


Fig. 4-5-3 Timing chart (Playback mode)

1. FG signal generator

- a. The FG signal is a signal obtained from the capstan flywheel as a speed feedback signal of the capstan.
- b. A pulse generator consisting of a coil, magnet, and gears is provided inside the flywheel and is generating 240 pulses per one revolution of the capstan.
- c. Generally, the FG frequency is 504 Hz when the servo is locked in the record or playback mode of operation.
- d. These pulses are amplified by IC502 and then clamped by D510. The clamped output of approx. 1.4V square wave is fed to pin 5 of IC501.

2. Speed detection (inside servo IC)

- a. The FG signal entered pin 5 of servo IC501 is compared in its speed in the speed detector circuit and pin 15 develops a rectangular signal modulated with pulse width (PWM) of approx. 69 kHz. Since the capstan system is subject to more disturbance than the cylinder system, generally the AFC output has considerable duty variations under locked condition of the servo system.

3. Phase detection (inside servo IC) (RECORD mode):

- a. The FG pulse signal entered pin 5 of IC501 is counted down to 1/24 to create 21 Hz pulse, and compared with the reference signal in their time difference (phase detection) in the phase comparator. The compared output is developed from pin 14 as a 69 kHz PWM signal.
- b. The reference signal is the 21 Hz signal developed inside the IC for exclusive use of the capstan control and applied to pin 16 as a positive pulse signal.

(PLAY mode):

- a. The reference signal delayed by a time equivalent to the time constant of R556 (main tracking), R553, C505 (subtracking) from the falling edge of the reference signal (pin 27 of IC501, delayed wave of FP) used as a reference for cylinder phase detection inside the IC and the CTL signal are compared in time (phase detection), and output from pin 14 as a PWM output.
- b. With servo unlocked, the duty is also forced to 50% in both record and playback modes as in the cylinder servo system.

4. Phase compensation & output amplifier circuits

- a. The APC output developed at pin 14 of IC501 passes through the phase compensation filter (R525, C535, R571, R522, R528, R527, C512) and a smoothing circuit, and enters pin 10 of IC502.
- b. A double throw diode D514 connected across R571 functions to speed up circuit response by rapidly charging or discharging C512 in a transient period.
- c. The AFC output developed at pin 15 of IC501 is applied to pin 9 of IC502, equalized in a filter of C517, R530, smoothed with carrier components removed through C516, and then led to the transistor Q534 which drives the capstan motor. The capstan is stopped by turning Q505 on.

5. Control (CTL) signal recording

- a. In recording, 25 Hz control signal (CTL pulse) is created from the V sync signal (pin 25 of IC501). A current is alternately supplied from pins 22 and 23 of IC501 to the control head, and the current is recorded in saturation level on the control track. The current is limited to approx. 3mA by R514.
- b. D508 connected to the op-amplifier input functions to clamp the control signal.
- c. Duty of the record CTL pulse is determined by the tracking delay time at pin 26 of IC501 and has been set to approx. 75% by R513, R566 and C505.

6. Playback CTL pulse amplifier circuit

- a. In playback mode, pin 22 of IC501 is open and a bias voltage of approx. 2.2V is developed at pin 23 of IC501 to bias one end of the CTL head.
- b. A fine level signal appears on the control head as the tape travels, and enters pin 6 of IC502 and amplified by approx. 60 dB.
- c. The amplified output enters pin 20 of IC501 and furthermore amplified, wave-shaped by the Schmitt amplifier inside the IC. Thus amplified output is used for phase detection.
- d. On the other hand, the wave-shape pulse develops at pin 19 and enters pin 2 of P506.
- e. D505 and R562 operate to clamp 12Vp-p (voltage induced on the CTL head is amplified by the op-amplifier) to approx. 4V for protecting the input circuit of the IC.

7. Still noise shifting

- A simple pulse drive type still & slow functions capable of freezing a picture at a given position are provided, but no noise shifting circuit which moves undesirable noise bars to a less susceptible position on a screen is provided.
- With the still or slow mode set, the logic circuit sends a still/slow signal (LOW) and a voltage at pin 9 of IC502 is turned to LOW by D520, D521 connected in parallel with the feedback capacitor (C517) of a filter in the capstan system, and the op-amplifier's output (pin 8 of IC502) becomes HIGH.
- In the still mode Q505 turns on and in the slow mode Q506 turns on. As a result, the op-amplifier output is divided by R542, R543, and R544, and as Q505 is turned on or off repetitively the capstan motor is driven repetitively.
- The slow speed is set to 1/10 through 1/20 times the normal speed.
- The still & slow signal is also developed for transitional period from the picture search/stop to the playback mode. D509 and R539 function to provide almost the same bias voltage as in the play mode across C517 to assure rapid mode transition.

8. Cue/Review

- In the cue/review mode, tape is driven by a reel motor and the tape speed is controlled by detecting the control (CTL) pulses and by controlling its frequency.
- In the cue/review mode, the CTL pulse enters pin 20 of IC501 and outputs from pin 19 as a square wave signal. This signal is inverted (CTL) and applied to pins 55, 56 of IC601 logic microcomputer. Then, pin 16 develops a rectangular signal in synchronization with falling edge of the CTL pulse. A part of HIGH in the signal developed at pin 16 is a time depending upon the ROM of the logic microcomputer and set so that the playback CTL frequency becomes approx. 179 Hz in the cue mode and approx. 170 Hz in the review mode.
- Since the normal playback CTL frequency is 25 Hz, the cue/review operation is conducted at a speed of approx. 7 times the normal speed.

- The playback CTL signal frequency is different in the cue and review modes. The reason is as follows: To make fH correction the rotating speed of the cylinder is increased in the cue mode and is decreased in the review mode, as a result if the CTL frequency does not match to 7 times the cylinders' rotating speed, motion of noise bars increases, thus disturbing screen image. To prevent this the different CTL frequency is used for each mode.
- The output developed at pin 16 of IC601 is smoothed by a LPF consisting of R535, R536, R537, R554 (VR), and C518, and its integrated value is compared with a reference voltage determined by resistor division ratio of R522 and R528. The resultant error voltage is output from pin 8 of IC502 and is sent to the drive transistor Q625 in passing through Q507 which is turned on.
- In this way the AFC servo functions with the CTL pulse recorded on the tape.

9. Synchronous editing

- Purpose of the synchronous editing is to not disturb continuity of the CTL pulse. To realize this, a slight amount of tape is rewound by driving the reel motor with pulse voltage immediately after the operation mode is changed from record to the record pause mode, and then the unit enters the standby mode.
- At the same time, the servo IC is also set to the edit mode but in this mode the CTL pulse is set to the playback mode and the IC itself is also in the playback condition.
- When the pause mode is released, the tape is reproduced for 1.7 sec to match phase of the CTL pulse and then the unit enters the record mode.

4-6. Video Circuit

4-6-1. Outline

The video circuit consists of 8 ICs in total. This unit features good cost performance and various user controls including picture sharpness control to provide easy-to-use full functions. Operations and functions for each IC used are shown in Table 4-6-1.

Table 4-6-1

Part No.	IC	Operation	Function
IC101	TA7772P (16 pin DIP)	Record amplifier Playback RF process	Record amplifier circuit, Low noise high gain head amplifier circuit, REC/PLAY switching, CH-1/CH-2 switching
IC121	TA8607P (16 pin DIP)	Playback RF process	AGC, Drop-out compensate circuit, Phase equalizing circuit
IC122	TA7302P (7 pin SIP)	Limiter	Limiter circuit
IC201	TA8605N (30 pin small package)	Y signal process FM MO/DEM	Sync AGC, Peak AGC, Sync clamp, Feedback clamp, FM modulation, Sync separation circuit, REC/PLAY switching, Main emphasis, White/dark clip, Double limiter circuit, Playback Y/C mixing, False V inserting
IC202	TA8606N (24 pin small package)	Y signal process Sub-emphasis	Non-linear sub-emphasis, 1/2 fH shift, Sharpness control circuit, Noise canceller
IC401	BA7267S (22 pin small package)	Color signal process	REC/PLAY switching, Burst ACC, Frequency CONV I, 4.43 MHz X'tal OSC (XO), Voltage control X'tal OSC (VXO), ACK, 321fH/320fH VCO, APC detect circuit, Frequency CONV II
IC402	BU2763S (18 pin small package)	Digital color signal process	Color rotary circuit, Side lock detection circuit, DPLL circuit, AFC detect circuit, Digital phase locked loop, Burst gate pulse generation circuit, 1/320 . 1/321 divider circuit, REC/PLAY switching circuit
IC481	BA7025L (18 pin SIP)	PAL/SECAM defector	PAL/SECAM defector

4-6-2. Record Circuit

1. Y-signal record circuit

- a. A composite video signal selected from either one of the line input or the tuner input circuit by the Phono jack switch P210 (line input has priority over the tuner input) is applied to pin 4 of IC201 as well as to the color process circuit.
- b. The composite video signal entered pin 4 of IC201 is subject to gain control and fed back clamp operations in the sync AGC and the peak AGC circuits, and then outputs from pin 10 of IC201 as an EE output signal and from pin 1 as a record Y signal.
- c. The EE signal at pin 10 is led to the line output terminal (P211). At the same time the EE signal is subject to an attenuation and the signal is applied to the RF modulator through Q206 buffer.
- d. While the signal output from pin 1 enters the LPF (Z202). The LPF removes color components from the input signal and the signal (Y signal) with color components removed passes the buffer amplifier Q206 and enters pin 3 of IC202 and the AGC detector circuit through pin 29 of IC201.
- e. The Y signal entered pin 3 of IC202 is subject to a sync tip clamp. At the same time the Y signal outputs from pin 24 of IC202 as a sync separation signal. The signal enters pin 27 of IC201 through a LPF and becomes as a composite sync signal with the sync signal separated. The composite sync signal outputs from pin 25 and enters pin 14 of IC402 and used to create fH reference for color process and burst gate pulse.
- f. The composite sync signal is also applied to the vertical sync separation circuit in the servo circuit and processed to develop the V-sync signal. The V-sync signal is used as a reference signal in the servo circuit during record operation.
- g. Moreover, the composite sync signal is used for sync clamp operation in the AGC detector inside the IC201 or for sync clamp operation of playback Y signal in the playback mode, and applied to sync AGC detector as keyed pulse after it is delayed and waveshaped.
- h. The Y signal, which is entered pin 3 of IC202 and subject to the sync tip clamp, outputs from pin 15 after it is subject to the non-linear pre-emphasis (sub-emphasis) and 1/2fH shift. The non-linear emphasis is the emphasis where the emphasis level is increased as the signal amplitude decreases to prevent lowering of S/N.
- i. 1/2fH shift means to increase FM carrier frequency for CH-1 by 1/2fH to convert vertical stripes into diagonally crossed stripes to make the stripes less perceptible on the screen. In practice, video signal's DC level is shifted by the amount equivalent to 1/2fH in the FM carrier frequency.
- j. The non-linear emphasis operation is performed as follows: High frequency components are extracted from the Y signal developed at pin 19 with a filter consisting of R234, L204, and then applied to the original signal after the extracted signals are compressed so that the higher the amplitude of the signals, the more the signals are compressed inside the IC.
- k. The 1/2 shift operation is conducted inside the IC and is controlled by the state of pin 16. ("H" for CH-1 mode, and "L" for CH-2).
- l. The Y signal output from pin 15 of IC202 directly enters pin 12 of IC201 and is subject to the pre-emphasis (main-emphasis) by R222, R223 and C225. The signal is then subject to the white clip and dark clip to prevent overmodulation. Thus processed signal outputs from pin 16 and enters the FM modulator (pin 18) in passing through the deviation adjustment control (R252). FM carrier frequency adjustment control (R251) is also connected to pin 18.
- m. The FM modulator modulates the sync tip level to 3.6 MHz and 100% white level to 4.6 MHz. Thus, created Y-FM signal outputs from pin 21 of IC201 and enters the record Y-FM equalizer (Q123) where the signal is processed to have an emphasis characteristic over a lower frequency band and to have a high-pass characteristic for the down converted color signal to be superimposed. The signal is then sent to the Y/C MIX AMP consisting of Q124, and Q125.
- n. Q129 functions as a record muting circuit.
- o. The signal superimposed with the down converted color signal in the Y/C MIX AMP passes Q126 buffer and pin 5 of P202, and enters pins 11 and 15 of IC101 record amplifier on the PRE AMP unit, and amplified.
- p. The amplified record current developed from pins 3 and 5 enters the video heads through the rotary transformer.

2. Color signal record circuit

- a. A video signal passed through the built-in switch of jack P210, and is selected by REC/PLAY switches (Q403 and Q404). The selected output enters the ACC amplifier through a BPF and pin 22 of IC401. The ACC amplifier is fed to the burst ACC circuit which keeps the burst level at a constant value in the record mode. That is, the ACC amplifier operates to increase the ACC output level as a color signal decreases, thus increasing a relative color recording current or S/N even if the color signal level is low.
- b. The color signal with its amplitude stabilized in this way by the ACC amplifier outputs from pin 21, and enters pin 20. Then the signal is applied to the main BM (Balanced Modulator).
- c. The 4.43 MHz color signal applied to the BM is mixed with 5.06 MHz carrier (the phase of which is fixed at the CH-1 and shifted at the CH-2) being applied to the BM, thus frequency conversion of 5.06 \pm 4.43 MHz will be performed. The converted outputs developed pin 14 are led to two LPFs to extract only a lower component of 627 kHz (= 5.06 MHz - 4.43 MHz = (40 \pm 1/8)fH) color signal. Thus created color recording signal is adjusted in its current level and passes through the group delay circuit (Q405, Q406) and then fed to the Y/C mixer circuit (Q124, Q125) and sent to the record amplifier IC101.
- d. The composite sync signal entered pin 14 of IC402 becomes a HD pulse with its equalizing pulses removed. AFC detection is performed with this HD pulse and the fH signal created by counting down the 321fH VCO output (pin 2 of IC402) to 1/321 to control the VCO or to lock the VCO to 321fH (= 5.015 MHz) precisely.
- e. The VCO output counted down to 1/8 or (40 \pm 1/8)fH (= 627 kHz) carrier is phase-shifted using the fH pulse stabilized in the DPLL (Digital Phase Locked Loop) as a trigger pulse. The rotational direction of the Phase Shifter (PS) depends upon the head switching pulse applied to pin 6 of IC402. When the switching pulse is in the "H" level, the phase is fixed and in the "L" level, the phase delays by 90 degrees every 1H. Thus created 40 1/8fH PSCC (Phase Shifted Sub-Carrier) develops at pin 16 of IC402, and enters a LPF to remove harmonics included. Then the signal enters the sub BM from pin 9 of IC401.
- f. Since 4.43 MHz carrier, which is locked to the color burst frequency by the record APC signal, is being applied to the sub-BM, the PSCC signal is converted to 4.43 MHz \pm 627 kHz and outputs from pin 7 of IC401. This output enters the BPF and the BPF extracts 5.06 MHz (= 4.43 MHz + 627 kHz) component. Thus converted 5.06 MHz signal is used as the carrier signal to down-convert the color signal.

4-6-3. Playback circuit

1. Y signal playback circuit

- a. Signals reproduced by video heads are applied to pin 6 (CH-2) and pin 2 (CH-1) of IC101, pre-amplifiers. The pre-amplifiers amplify these signals by approx. 60 dB. These signals are switched by switching pulses and output from pin 10.
- b. The playback signal developed at pin 10 passes a buffer amplifier Q102 and pin 3 of W102, and returns to the main unit. Then the signal enters pin 9 of IC121, amplified by approx. 13 dB, and outputs from pin 11.
- c. The playback RF signal output from pin 11 enters the equalizer circuit and the color signal playback circuit. At the same time the RF signal output also enters the servo unit as a playback envelope output (TP101).
- d. The equalizer circuit functions to make the video frequency response flat with the PRE-SET control R259 for sharpness adjustment, thus preventing possible overmodulation due to parameter spread of the video heads.
- e. Thus processed signal passes the LPF and the high frequency noises are removed. Then, the signal enters pin 12 of IC121 in passing through a trap and the down converted color signal component is removed. The signal then passes through pins 3 and 5 of the FM phase compensation circuit and enters the AGC circuit through pin 2. Thus processed playback RF signal with its amplitude adjusted to a specified level outputs from pin 16 and enters the double limiter.
- f. The FM phase compensation circuit functions to reduce phase distortion observed at around the Y-FM carrier signal which has been subject to frequency compensation.

- g. On the other hand, the playback Y-FM signal enters the dropout detection circuit inside IC121. The detection circuit develops a dropout detection pulse at pin 15 when an envelope output reduces. The dropout detection pulse is used to switch in the signal at pin 14 which is delayed by 1H glass delay line, thus performing the dropout compensation.
- h. The AGC output at pin 16 of IC121 passes the LPF consisting of R146, R147, C144, R148, and C145, and enters pin 19 of IC201. At the same time the same signal also passes the HPF consisting of C147, R149, C148, and R160 and enters pin 1 of IC122, limiter. The limited output develops from pin 6 of IC122 and enters pin 17 of IC201 where the signal is sent to the FM demodulator through a double limiter. The limiter inside IC122 is used to compensate insufficient gain of the limiter in IC201 to improve over-modulation characteristic.
- i. The FM demodulator consists of a non-stable multivibrator and a multiplier, and the demodulated output is led to pin 1 through a LPF (Z202).
- j. Thus demodulated Y signal is then subject to edge expander and white clip circuit consisting of Q218 to Q221. This circuit improves edge waveform of Y signal. R256 adjusts the playback Y signal level to a constant level. Q207 functions to raise higher frequency (approx. 2.8 MHz) level. The signal is subject to main de-emphasis operation in the de-emphasis circuit consisting of R227, R229, C229 and C248. The signal is then applied to pin 21 of IC202.
- k. The signal amplified by approx. 20 dB inside IC202 is subject to non-linear de-emphasis and to 1/2 fH shift restoration and then signal outputs from pin 14. The non-linear de-emphasis is performed as in the record mode. That is, high frequency components of the signal are applied to pin 18, compressed, and then subtraction is conducted in reverse as in the record mode.
- l. The Y signal restored to the original recorded signal enters pin 13 and is led to the sharpness adjustment circuit inside IC202. A DC voltage applied to pin 7 controls the picture sharpness and the controlled signal outputs from pins 6 and 8 and the both are mixed then enters pin 5 again, then applied to the noise canceller circuit.

- m. The noise canceller circuit extracts only high frequency components from the signal at pin 24 with the HPF consisting of C229, C228, L207, and R231, and supplies them to pin 23 to take out only the noise components with the limiter. Thus developed noise signals are subtracted from the original signal (same signal at pin 24) to cancel the noises each other. The signal at pin 24 is also used as a signal for sync separation as in the record mode and is led to pin 27 of IC201.
 - n. The Y signal with its high frequency noises removed in this way outputs from pin 1 and enters pin 6 of IC201. The Y signal is subject to a sync clamp operation in this stage and then mixed with a playback color signal being applied to pin 8 of IC201, resulting in a video signal of 2Vp-p. The video signal outputs from pin 10. Operations in following stages are the same as those in the record mode, so description will be omitted.
- 2. Color signal playback circuit (PAL/SECAM)**
- a. A playback RF signal developed at pin 11 of IC121 passes through amplifier Q128 and LPF and the down converted 627 kHz color signal contained in the RF signal is separated.
 - b. Then the color signal enters the ACC amplifier from pin 1 of IC401 to stabilize the level.
 - c. Thus stabilized 627 kHz down converted color signal outputs from pin 21 of IC401 and enters the main BM through pin 20 of IC401. In the main BM, the 627 kHz color signal is mixed with 5.06 MHz carrier signal (with the phase shifted) being applied to the BM and frequency conversion of 5.06 MHz \pm 627 kHz is performed.
 - d. In this case, as the phase of 5.06 MHz signal is preset by the APC loop so that horizontal jitter components caused by the rotational system of the mechanism are cancelled each other, the converted color signal has almost no jitter components.
 - e. The color signal with the jitter component removed in this way outputs from pin 16. The color signal enters 2H comb filter (X401) to remove its crosstalk components from adjacent tracks at PAL mode and enters an attenuator at SECAM mode. The color signal, then, pass through the REC/PLAY switch of Q404, and is amplified. The amplified output enters pin 22 of Q401 in passing through a BPF (4.43 MHz) and outputs from the pin 14.

- f. The output at pin 14 is generally biased by approx. 2V DC, but the DC component becomes zero when the color killer circuit functions. The playback color signal at pin 14 passes through Q407 buffer and is adjusted in its color level, and then enters the Y/C MIX circuit from pin 8 of IC201 and mixed with the playback Y signal. The mixed output is obtained at pin 10.
- g. In the playback mode, the color sync circuit system operates as follows:
- h. A composite sync signal separated from a playback Y signal develops at pin 25 of IC201 and enters pin 14 of IC402. A burst gate pulse is created from the composite sync signal (output from pin 16 of IC402), and applied to pin 6 of IC401.
- i. A burst section of the playback color signal is sampled with this burst gate pulse and compared with the 4.43 MHz reference signal. The resultant error signal controls the 321fH VCO so that its phase is locked. In this case, a stable point of the APC exists every period of fH because of the burst gate synchronization performed every 1H, so it may be possible for the VCO to be locked at a frequency other than 321fH.
- j. To prevent this, a HD pulse created from the composite sync signal at pin 14 of IC402 and the VCO output fed through pin 2 are compared in their frequencies to develop a side lock detection pulse that functions to correct the frequency deviation to 321fH when the VCO is locked at a frequency other than 321fH.
- k. The VCO output of 321fH is counted down to 1/8 or to $(40 + 1/8)fH$ as in the record mode and then subject to the phase-shift. The $(40 + 1/8)fH$ signal and the 4.43 MHz reference signal are mixed in the sub-BM circuit and a 5.06 MHz carrier signal is generated.
- l. The 5.06 MHz carrier and the 627 kHz color signal are applied to the main BM and demodulated to a 4.43 MHz color signal. In this case, amount of phase shift and rotational direction of phases of 627 kHz color signal and 5.06 MHz carrier signal become the same. That is, the color signal is demodulated correctly with the phase relation returned to that of the original signal.
- m. On the other hand, crosstalk components from adjacent tracks are demodulated with their phases rotated in 90 degrees shift direction. As a result, phase rotation

of 4.43 MHz crosstalk component becomes 90 degrees \times 2 = 180 degrees every 2H or the phase is inverted. Thus, they can be removed by the 2H comb filter.

4-6-4. PAL/SECAM identification circuit

- 1. In the REC/EE mode, the color signal from pin 21 of IC401 is applied to pin 4 of IC481. At the same time, a burst gate pulse from pin 18 of IC402 is entered pin 5 of IC481.
- 2. The color signal applied to pin 4 of IC481 is gated only for the burst period and output from pin 7 with the amplitude limited by the limiter amplifier.
- 3. The output from pin 7 will be processed in different ways depending upon the PAL or SECAM system as explained below:
- 4. (SECAM signal)
For the SECAM signal, one of signals with different frequencies of (DR = 4.40 MHz) and (DB = 4.25 MHz) is alternately applied every 1H to the bandpass filter. Since the filter has been designed to pass 4.25 MHz component and to attenuate 4.40 MHz, the 4.40 MHz signal has a lower amplitude than that of 4.25 MHz signal.
- 5. Accordingly, the frequency difference between DR and DB is expressed in the amplitude difference. That is, a signal alternately showing a large and a small amplitude is developed every 1H. The signal is applied to pin 9 and detected in amplitude, and then led to the resonant circuit consisting of L451 and C485 between pins 11 to 13.
- 6. Since the resonant frequency is set to fH/2 and the signal alternately showing a different amplitude every 1H has a period of 2H (= fH/2 frequency), a resonant waveform will be obtained at pin 11. The waveform output is converted into a DC voltage in the comparators 1 & 2, and output as a high level signal identifying the SECAM signal. The output voltage is called SECAM + B.
- 7. (PAL signal)
Since the gated PAL signal includes only 4.43 MHz component, the Band Pass Filter develops the output having a constant amplitude. Accordingly, if the output is applied to the resonant circuit, no resonant waveform output will be obtained. Thus the comparators 1 & 2 do not develop any DC output. That is, the PAL signal is not identified as the SECAM signal and pin 16 develops 0V output.
- 8. During playback mode, the color signal from pin 22 of IC401 is applied to pin 1 of IC481 and the PAL/SECAM identification is performed in the same way.

4-7. Audio Circuit

4-7-1. Outline

1. The audio circuit is mounted on the main P.C. board and employs a monaural system.
2. Major blocks in the audio circuit are the audio 1 chip IC (containing ALC, line-amplifier, record amplifiers, equalizer amplifier, muting circuit, etc.) erase oscillator circuit, etc.

4-7-2. EE mode circuit description

1. Input signal switching (P710)

- a. Input signal switching is performed by the built-in switch of the audio line input jack (P710).
- b. A line input is selected when a line input plug is inserted to the jack, and the tuner input is selected when no plug is connected.
- c. The nominal line input level is -10 dBs (245mVrms).

2. Record & play back switching circuit and muting circuit (IC701)

- a. The record & play back switching circuit and the muting circuit are provided inside IC701.
- b. The record & play back switching circuit becomes a play back mode when PB + B (HIGH) is applied to pin 21 of IC701 and becomes EE or record mode when LOW level voltage is applied.
- c. The muting circuit mutes a playback signal when HIGH level signal is applied to pin 20 of IC701. (The muting circuit only works in track playback modes.)

3. Output amplifier (IC701)

- a. The signal entered pin 11 of IC701 is amplified by approx. 35 dB and outputs from pin 13. The output is applied to the line output terminals as well as to the RF modulator.
- b. The nominal output level is -7 dBs (350mVrms).

4. ALC circuit (IC701)

- a. The ALC circuit is also contained inside the IC701.
- b. The signal entered pin 11 of IC701 is amplified by approx. 35 dB and outputs from pin 13.
- c. When the output at pin 13 exceeds -4.5 dBs, a detector circuit inside the IC automatically functions and adjusts the line amplifier input level to an optimum level.
As a result, the output level is automatically adjusted so that the audio head does not cause any distortion if a signal higher than the reference input level is applied.
- d. The ALC operates only in record mode and the EE mode.

4-7-3. Record circuit

1. Record amplifier circuit (IC701)

- a. The signal developed at pin 13 of IC701 enters pin 15 in passing through the record equalizer consisting of R710, R711, R724, C722. The record equalizer attenuates signals lower than 1 kHz by approx. 1 dB and prevents frequency peak over mid to high frequency range.
- b. The signal applied to pin 15 is amplified by approx. 11 dB (400 Hz) in the record amplifier, outputs from pin 18, and enters the audio head through the constant current resistor (R713).
- c. Pin 17 is a feedback terminal for the record amplifier and constitutes a high frequency peaking circuit.
- d. L701 and C713 function as a peaking circuit and rises signal level by approx. 6 dB at 12 kHz.

2. Erase oscillator circuit (Q705, T701)

The oscillator circuit consisting of Q705 and T701 works during record mode, and oscillates frequency of approx. 68 kHz. The oscillator signal is used as the erasing current for the full width erase head and the audio erase head as well as a record bias for recording of audio signals.

3. Audio head switching circuit (IC702)

- a. IC702 grounds its pins 3 and 1 when a voltage is applied to pins 5 and 7, respectively. In the EE and record modes pin 3 grounds the playback terminal of the audio head through a fine resistance and opens only in the playback mode, thus allowing the playback signal to enter pin 4 of IC701.
- b. Pin 1 opens only in the record mode thus allowing record signals and bias signal to flow to the audio head.
- c. In the playback mode, the record signal terminal of the audio head is grounded.

4-7-4. Playback circuit

1. Playback amplifier (IC701)

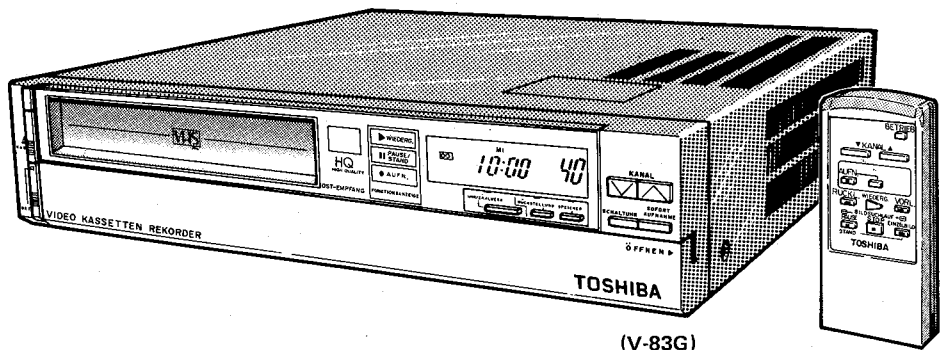
- a. A playback signal induced on the audio head is first adjusted in its frequency response in the peaking circuit consisting of the head coil and C704 and then applied to pin 4 of IC701. The IC704 amplifies the signal by approx. 45 dB at 400 Hz and feeds the output to pin 6.
- b. Pin 7 of IC701 functions as a negative feedback terminal and adjusts the frequency response with the impedance connected between pin 7 and pin 6. That is, an equalizing response showing a descending response from a low end (approx. 50 Hz) to mid range approx. 1.3 kHz) and a flat response over a higher frequency range is provided.
- c. The signal processed in this way enters pin 10 in passing through the playback level adjusting control (R751), selected by the switch, amplified, and then applied to the output terminals as described in 4-7-2, steps 2 and 3.

AK33

TOSHIBA

COLOR VIDEO CASSETTE RECORDER

V-81/83G, 81/83W



(V-83G)

SPECIFICATIONS

GENERAL

Video recording system: Head configuration 2-head rotary
Video signal: CCIR standard, PAL color
Storage temperature: -20° to $+60^{\circ}\text{C}$ (-4° to $+140^{\circ}\text{F}$)
Operating temperature: 5° to 40°C (41° to 104°F)
Antenna: 75-ohms external aerial terminal for VHF and UHF

Channel coverage:

	STD	CATV
V.L: Lower VHF band	E2 - E4	S21 - S23, S1 (V-81/83G Only) X - S1 (V-81/83W Only)
V.H: Higher VHF band	E5 - E12	S2 - S20
UHF band	21 - 69	

a total of up to 16 preselected channels

AERIAL output signal: UHF channel E31 to E39 (selectable)
Power requirements: AC 220V, 50 Hz
Power consumption: 30W
Weight: 7.7 kg (V-81W), 7.8 kg (V-83W),
7.9 kg (V-81/83G)
Dimensions: 430 x 95 x 375mm (W/H/D)

VIDEO

Input: VIDEO LINE IN:
Phono jack, 1.0V (p-p), 75-ohms,
unbalanced, sync, negative
Output: VIDEO LINE OUT:
Phono jack, 1.0V (p-p), 75-ohms,
unbalanced, sync, negative
Signal-to-noise ratio: Better than 43 dB

AUDIO

Input: AUDIO LINE IN:
Phono jack, 50 k-ohms, -10 dBs
Output: AUDIO LINE OUT:
Phono jack, less than 10 k-ohms,
 -7 dBs, unbalanced
Frequency response: 80 to 8 kHz
Signal-to-noise ratio: Better than 40 dB

TAPE TRANSPORT

Tape speed: 23.39 mm/sec.
Maximum recording time: 4 hours (with E-240)
Fast forward time: Within 5 min. (E-180)
Rewind time: Within 5 min. (E-180)

TIMER

Fluorescent digital display
Count down from AC-line frequency.

Caution: Copyright Act 1956 Users of video recording equipment should note that it may be unlawful to record television broadcasts, cinematograph films or video recording without the permission of the relevant copyright owner.

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1. OVERVIEW

1-1 VHS Format

The VHS format has been specified to assure correct operations of VHS type VTRs (Video Tape Recorder) and to maintain interchangeability between VHS type cassette tapes. The format has specifications as described below.

(1) Magnetic tape pattern

The tape pattern in the VHS format features:

- Guard bandless recording
- Azimuth angle of ± 6 degrees, and
- "H-alignment"

1. Since a guard bandless recording system is employed a signal on an adjacent track will be reproduced in addition to the signal on a desired track if a tracking deviation is caused by any reason in the playback mode, thus causing undesirable crosstalk signals. Of the crosstalk signals, higher frequency components of a luminance FM signal can be removed by making use of azimuth loss effect of the heads. However, lower frequency components of the luminance FM signal can not be removed sufficiently because of poor azimuth loss effect to the lower frequencies.

2. To compensate the poor azimuth loss effect in the lower frequency range, a line correlation between tape patterns is introduced to remove the lower frequency components of the crosstalks. That is, each horizontal sync pulse is recorded so that it is always aligned with other sync pulses on the adjacent tracks. This is called "H-alignment".
3. Under this condition, crosstalks have frequencies close to a playback FM frequency of the main signal and develop considerably lower interference signal when they are demodulated.
4. Moreover, with the "H-alignment" established, skew distortion, which is caused when a video head traces on two or more tracks in a mode such as Cue or Review, will cause almost no problem because of horizontal sync signals reproduced in the specific period.

Fig. 1-1-1 shows magnetic tape patterns in the VHS format. Table 1-1-1 shows specifications for the patterns shown in Fig. 1-1-1.

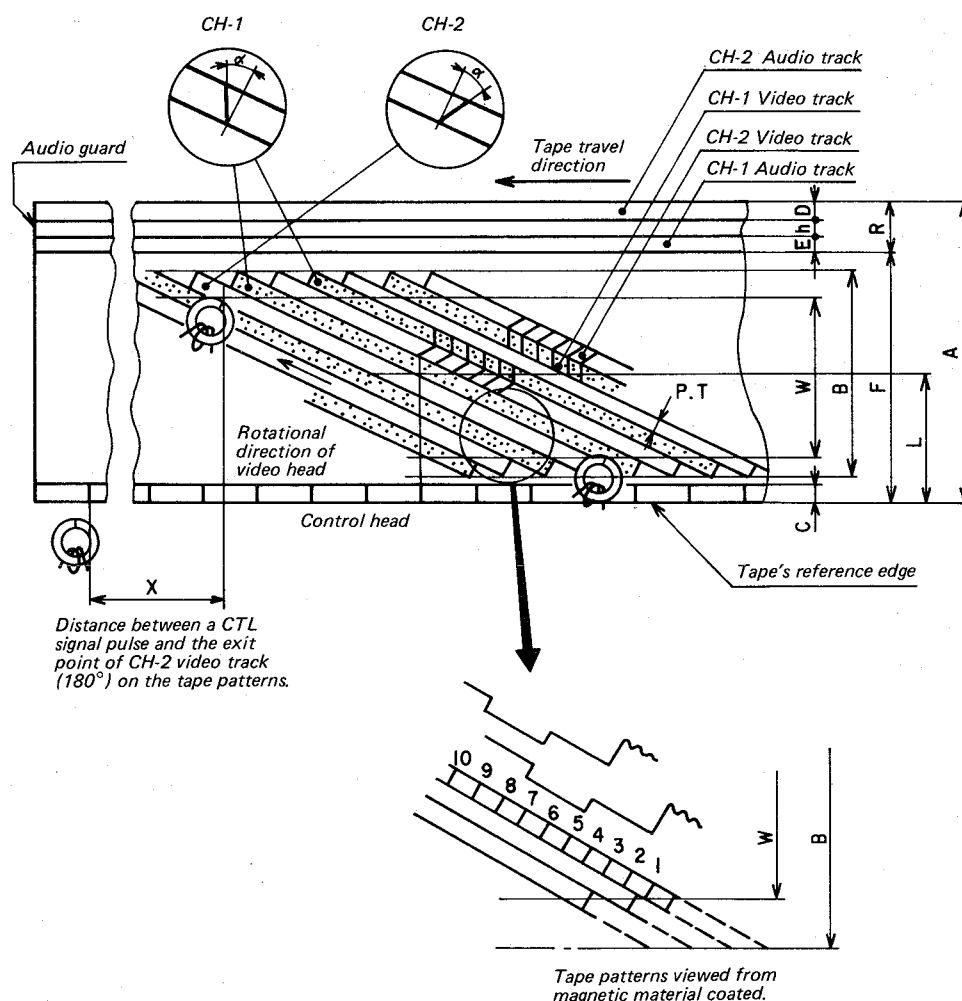


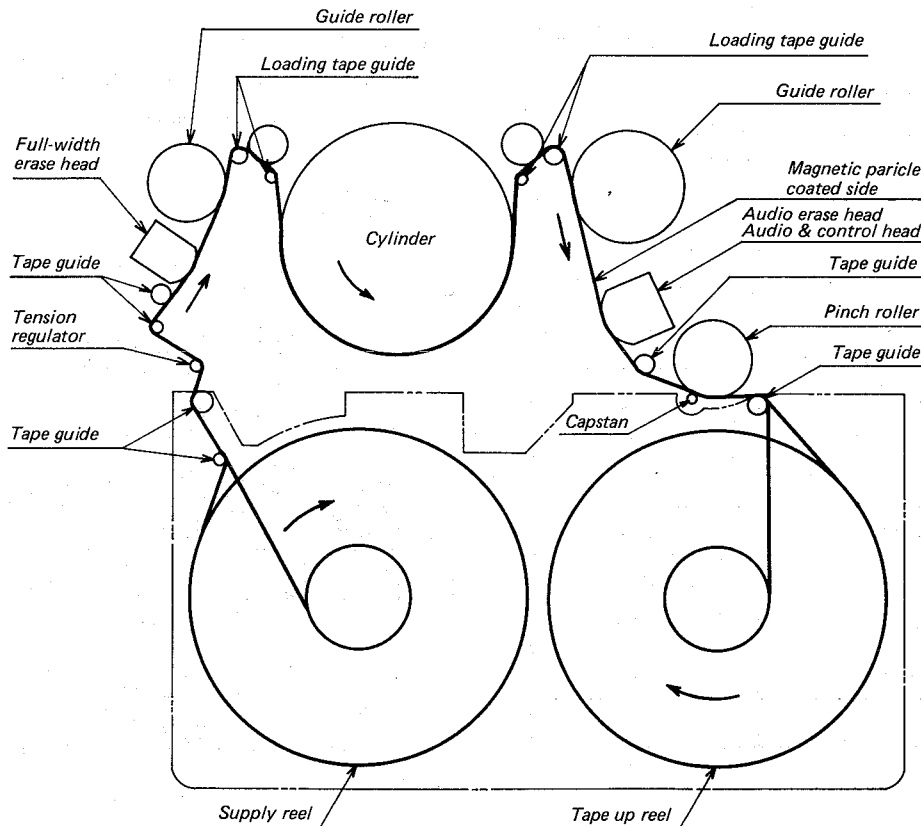
Fig. 1-1-1 Magnetic tape patterns

Table 1-1-1 VHS specifications

Items			Specifications	Note
1.	(A) Tape width	mm	12.65 ± 0.01	Upper cylinder
2.	(Vt) Tape travel speed	mm/sec	$23.39 \pm 0.5\%$	
3.	(ϕ) Cylinder diameter	mm	62 ± 0.01	
4.	(Vh) Relative speed	m/sec	4.85	
5.	(P) Video track pitch	mm	0.049	
6.	(B) Video fullwidth	mm	10.60	From reference edge of tape
7.	(W) Video width	mm	10.07	
8.	(L) Video track center	mm	6.2	
9.	(T) Video track width	mm	0.049	
10.	(C) Control track width	mm	0.75	
11.	(R) Audio track width	mm	1.0	Single track
12.	(D) Audio track width	mm	0.35	CH-2 (R)
13.	(E) Audio track width	mm	0.35	CH-1 (L)
14.	(F) Audio track reference edge	mm	11.65	From reference edge of tape
15.	(h) Audio track guard width	mm	0.3	
16.	(θ) Video track angle		$5^\circ 56' 7.4''$	During tape stopped
17.	(θ) Video track angle		$5^\circ 57' 50.3''$	During tape running
18.	(α) Video head azimuth angle		$6^\circ \pm 10'$	
19.	(X) Position of audio and control heads	mm	79.244	
20.	Position of V-sync front porch		5 – 8H	Inside from lower end of W
21.	Back tension of tape		30 – 45 g	Beginning of tape wound cylinder entrance

Tape Path

(This is not standardized, but shows a general arrangement in the VHS mechanism.)



(2) Video cassette

VHS type video cassettes have specifications as follows:

a. Video tape

Length: Determined by a length calculated by the following equation, depending upon nominal recording or playback time.

$$L = (1.42t + 2) \begin{matrix} +3 \\ -0 \end{matrix}$$

Where L: Tape length (m)

t: Recording or playback time

L should be integer with all decimal points rounded-up

Width: 12.65 ± 0.01 mm

Allowance of width: Less than $6\mu\text{m}$

Thickness: $19 + 1, -2\mu\text{m}$

Coercive force: Optimum recording current for 600 oersted (nominal) class should not differ from that of the reference tape.

b. Leader tape and trailer tape

Length: When recording or playback time exceeds 90 min: 170 ± 20 mm

not exceeds 90 min: 150 ± 20 mm

Width: 12.65 ± 0.03 mm

Thickness: $40 + 5, -25\mu\text{m}$

Material: Polyester film

Light transmissivity: Higher than 50%

Splicing length: 12 – 19 mm

Splicing clearance: 0 – $70\mu\text{m}$

Splicing strength: Higher than 3 kg

c. Reel

Outside diameter: 89 ± 0.2 mm

Hub diameter: When recording or playback time exceeds 90 min.: 26 ± 0.15 mm

not exceeds 90 min.: 62 ± 0.2 mm

is less than 30 min.: 70 ± 0.2 mm allowable

Margin of wrapping: More than 1.5 mm

d. Types and indication

Types of blank cassette

Type	Record or playback time	Length of video tape
E-240	240 min.	$343 \begin{matrix} +3 \\ -0 \end{matrix}$ m
E-180	180 min.	$258 \begin{matrix} +3 \\ -0 \end{matrix}$ m
E-150	150 min.	$215 \begin{matrix} +3 \\ -0 \end{matrix}$ m
E-120	120 min.	$173 \begin{matrix} +3 \\ -0 \end{matrix}$ m
E-90	90 min.	$130 \begin{matrix} +3 \\ -0 \end{matrix}$ m
E-60	60 min.	$88 \begin{matrix} +3 \\ -0 \end{matrix}$ m
E-30	30 min.	$45 \begin{matrix} +3 \\ -0 \end{matrix}$ m

e. Shape and dimensions of cassette

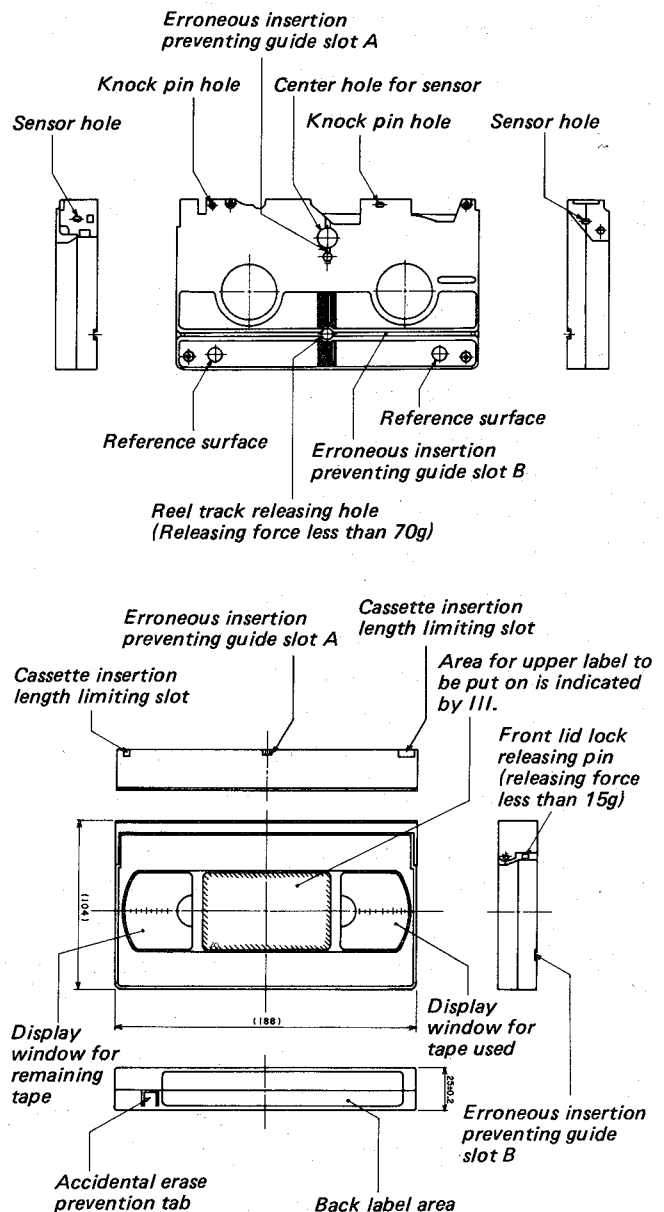


Fig. 1-1-2

f. Tape threading

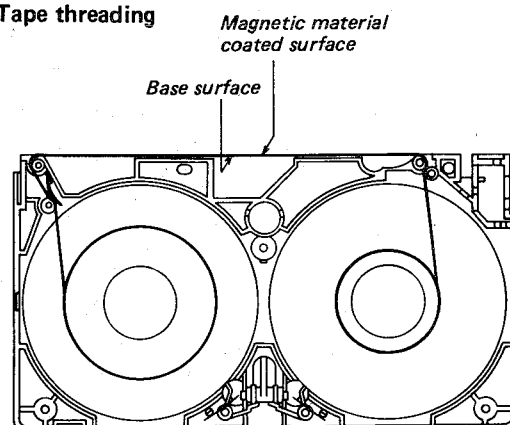


Fig. 1-1-3

(3) Recording system

a. Video signal recording system

Recording signal: CCIR B/W and PAL, SECAM color TV signals.

Luminance signals for black & white and color signals: FM recording

Carrier color signal: PAL: Down converted phase shifted direct recording.

b. Luminance signal record system

Pre-emphasis characteristic: $T = 1.3 \pm 0.05 \mu\text{sec}$

$$X = 4 \pm 0.3$$

FM carrier frequency: WHITE PEAK $4.8 \pm 0.1 \text{ MHz}$

SYNC TIP $3.8 \text{ MHz} \pm 0.1 \text{ MHz}$

FM carrier frequency deviation: $1 \pm 0.1 \text{ MHz}$

White clip level: $160 \pm 10\%$ (from sync tip)

Dark clip level: $40 \pm 10\%$ (from sync tip)

(100% is assured from sync tip to white peak.)

Recording current characteristics

FM signal record amplifier characteristic: For frequencies more than 3.8 MHz. . . saturated optimum record current.

For currents at 2 MHz and 1 MHz. . . 3 dB ± 1 dB and 6 dB ± 1.5 dB referred to 0 dB current of 3.8 MHz, and flat response at frequencies less than 1 MHz.

Bandwidth of converted carrier color signal: Constant current response

Head current of FM signal: $\pm 1.5 \text{ dB}$ within optimum record current at 4 MHz

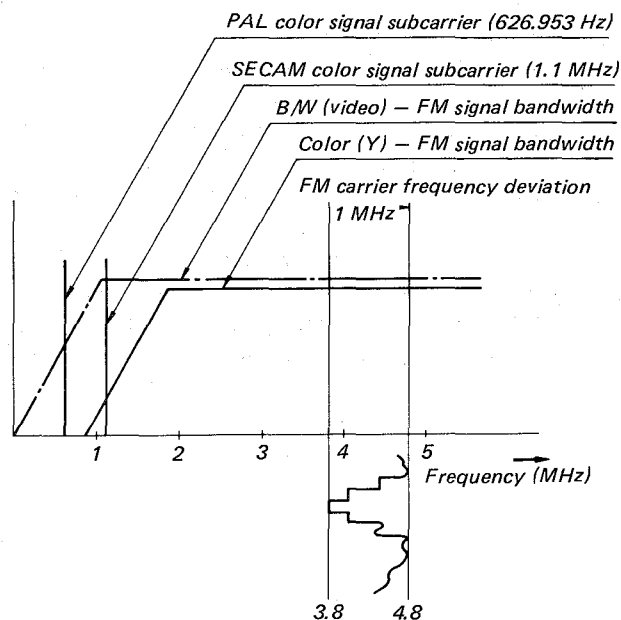
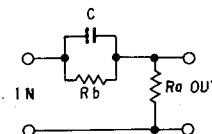
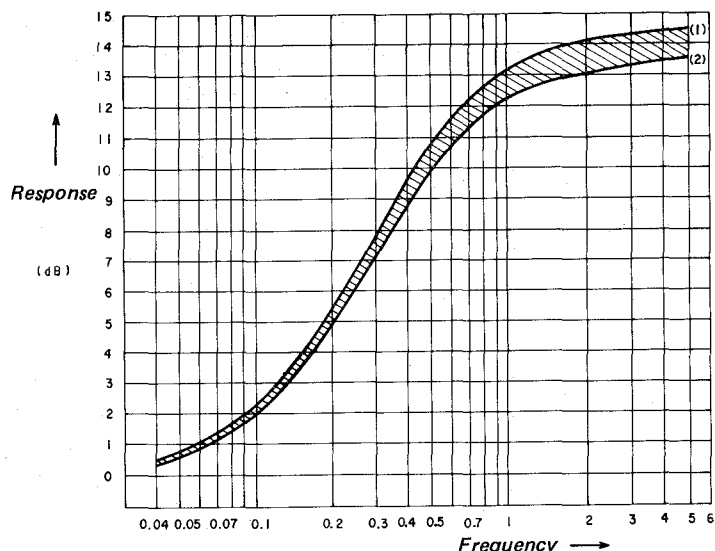


Fig. 1-1-5 Recording signal spectrum



$$T = C \cdot Rb = 1.3 \mu\text{sec} \pm 0.05 \mu\text{sec}$$

$$X = \frac{Rb}{Ra} = 4 \pm 0.3$$

$$T = 1.35 \mu\text{sec} \quad \dots (1)$$

$$X = 4.3$$

$$T = 1.25 \mu\text{sec} \quad \dots (2)$$

$$X = 3.7$$

Fig. 1-1-6 Pre-emphasis characteristic

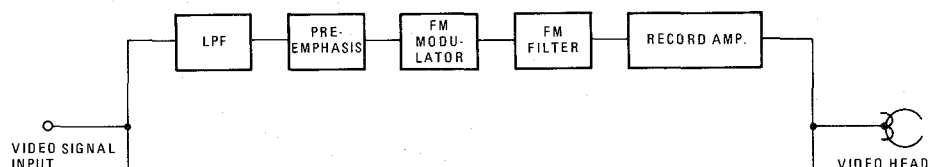


Fig. 1-1-7 Basic block diagram of recording system

c. Color signal recording system

Fig. 1-1-8 shows a block diagram of a color recording system in the VHS system.

Converted carrier color signal frequency: $f_c = 40 \times f_H + 1.953 \text{ Hz}$ (626,953 Hz)

(Where f_H stands for the horizontal sync frequency of an input video signal)

Record conversion carrier color signal phase:

CH-1: Constant (6° rightward in head azimuth).

CH-2: phase is retarded by 90° every one horizontal period. (6° leftward in head azimuth).

Phase switching per line of the record carrier color signal is performed at a position equivalent to horizontal sync signal period or the front porch, and the burst phase should be free from any deterioration.

Recording level of converted carrier color signal:

$-7 - -10 \text{ dB}$ (in playback output level) from the saturation level.

Video head polarity: Shall coincide between the channels.

Time difference between luminance signal and converted color signal: Shall be less than $0.1 \mu\text{sec}$ on video tape.

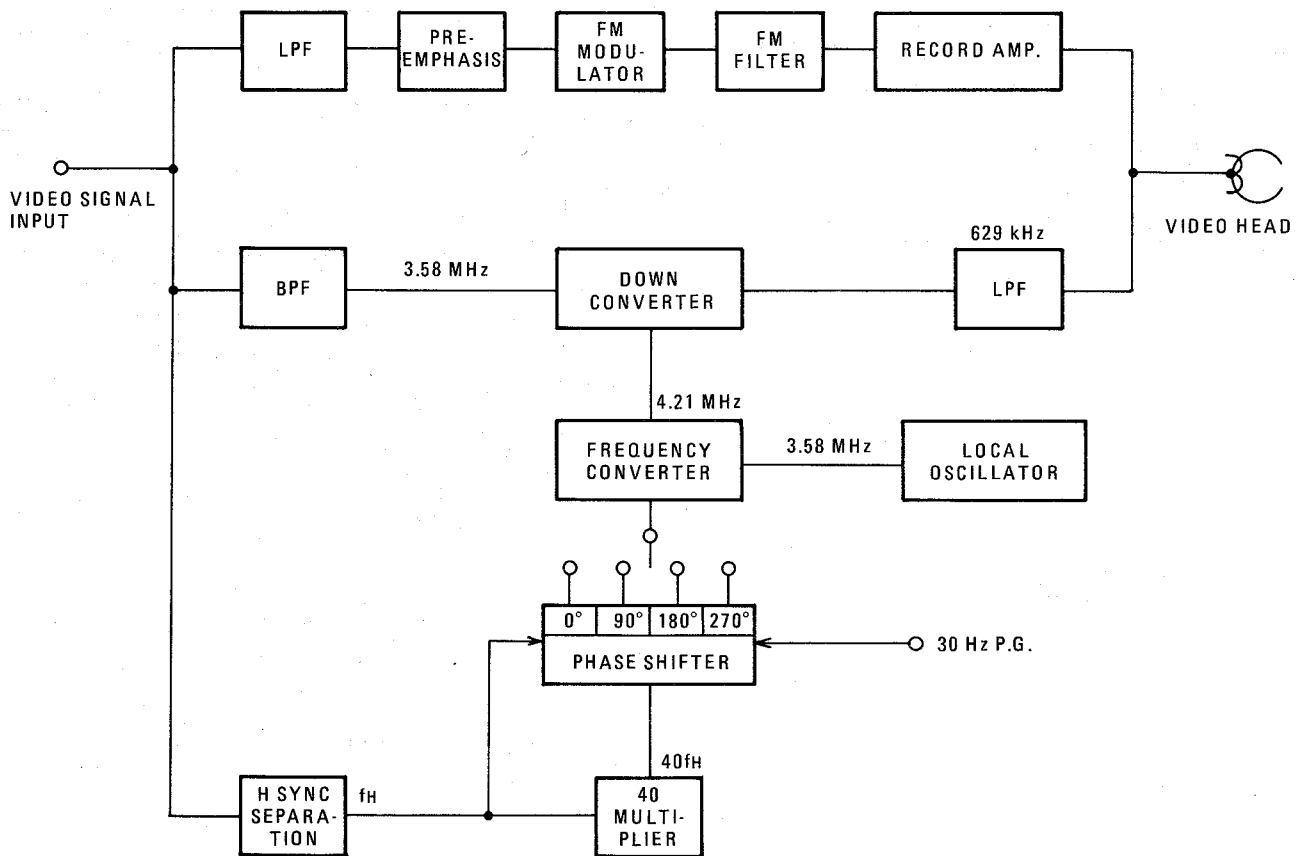


Fig. 1-1-8 Block diagram of PAL signal recording system

(4) Recording format of control signal

Recording level: The control signal should be recorded with a level higher than a saturation recording level on the control track.

Correlations among waveform, polarities of control signal and video heads should be as follows:

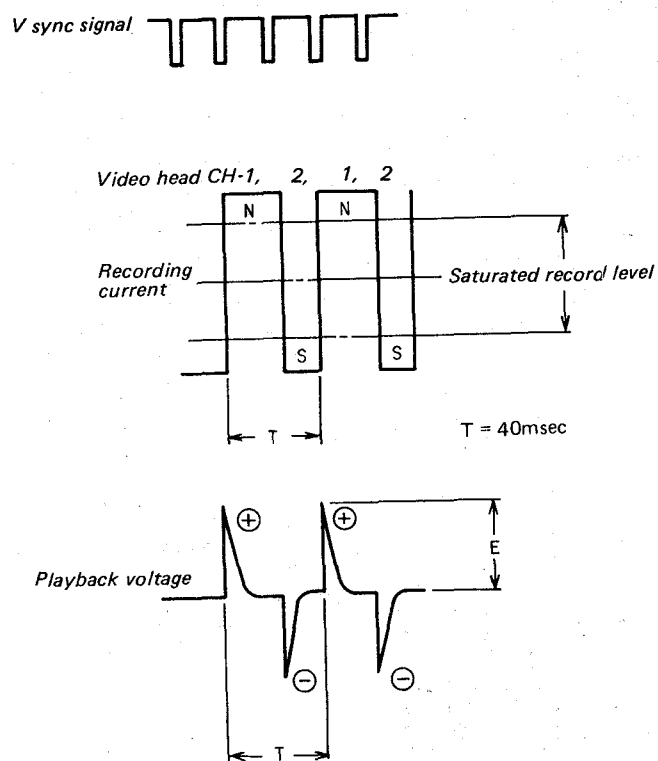


Fig. 1-1-9

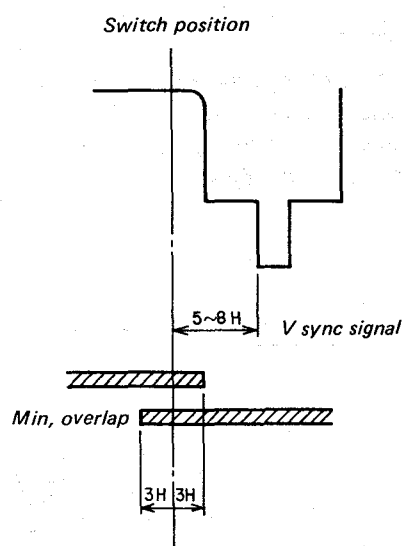


Fig. 1-1-10

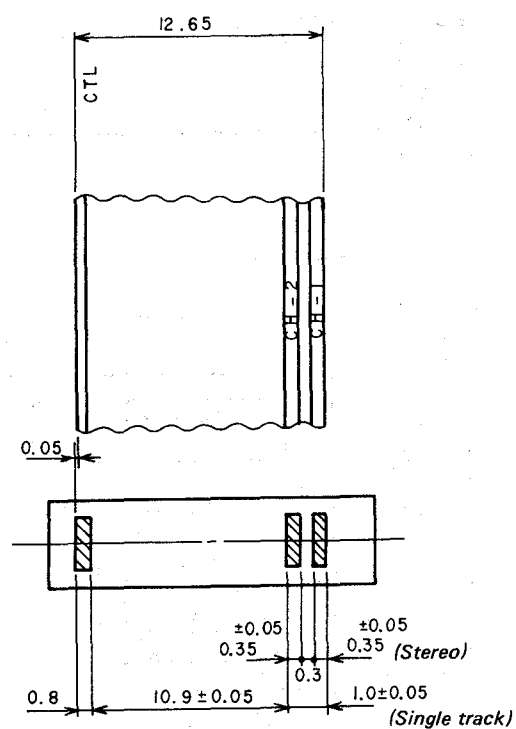


Fig. 1-1-11 Audio and control head

Note: Gaps for a control head and an audio head should be aligned in line.

2. OPERATION THEORY, MECHANISM

2-1. Outline

2-1-1 Mechanism system configuration

Fig. 2-1-1 shows a diagram of mechanical system configuration consisting of functional blocks. In addition to this a tape transport adjusting mechanism is included.

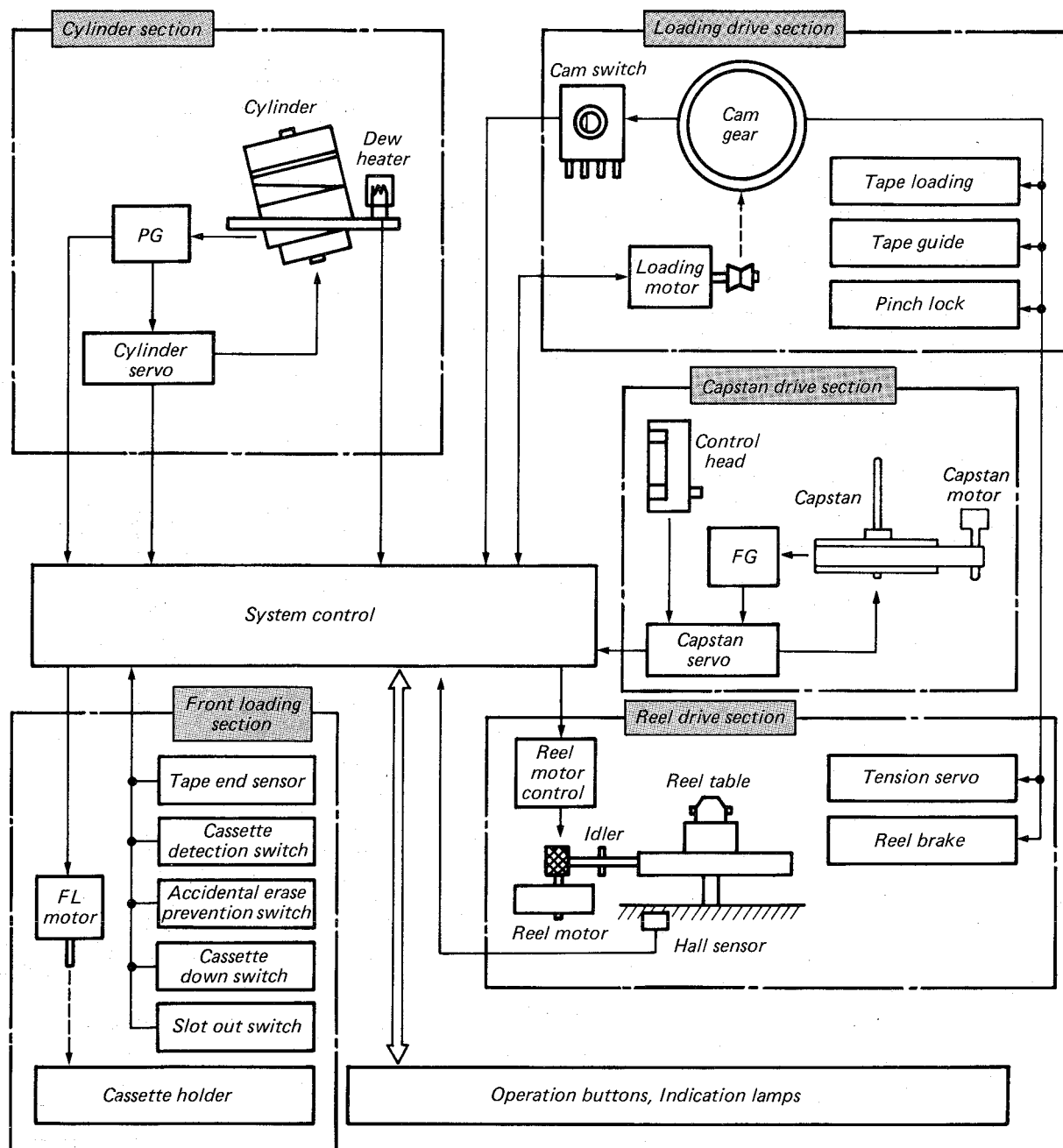


Fig. 2-1-1 Mechanical system diagram

2-1-2 Description on each functional block

(1) Front loading

The front loading mechanism consists of the following main parts.

Mechanical Parts	<ul style="list-style-type: none"> • Cassette holder • Guide bracket • Slot mechanism • Door control mechanism • Cassette dual insertion protection mechanism • Cassette lid opening mechanism
Electrical Parts	<ul style="list-style-type: none"> • FL motor • Cassette insertion detection switches (L, R) • Cassette down detection switch • Accidental erase prevention • Slot out detection switch • Tape end detection switch

(2) Loading drive

Loading drive operations are performed in the following orders.

- 1 The loading motor rotates the cam gear.
- 2 The rotating cam gear moves the pinch lock lever, logic slider and the brake slider, thus setting each part of mechanisms to a specified mode.
- 3 The loading motor also rotates the loading ring and moves the S, T sliders, thereby wrapping a tape around the cylinder or unwrapping the tape from the cylinder.

(3) Reel drive

- 1 The reel motor rotates the T-reel table or the S-reel table through an idler.
It is determined by swing direction of the idler (depending upon rotating direction of the reel motor) that which one of the reel tables is driven.
- 2 In the playback mode, the reel motor is driven by a constant current source to develop a constant torque.
The band brake which is wrapped around the S-reel table applies a specified tension to the tape.
- 3 Detection of rotating reel tables is performed by magnets mounted under the T-reel table and hall sensor.

(4) Capstan

1) A out drive system is employed in the capstan drive system.

Speed control in the playback mode is conducted by a FG servo system and a phase control circuit using control pulses.

(5) Cylinder

The cylinder is driven by a built-in direct drive type motor.

Rotating speed control of the cylinder is conducted by detecting rotating speed of the rotor with a PG head.

To prevent dew condensation on the cylinder surface, a dew heater is provided. The heater operates when the main power is turned off and the cylinder is in stop.

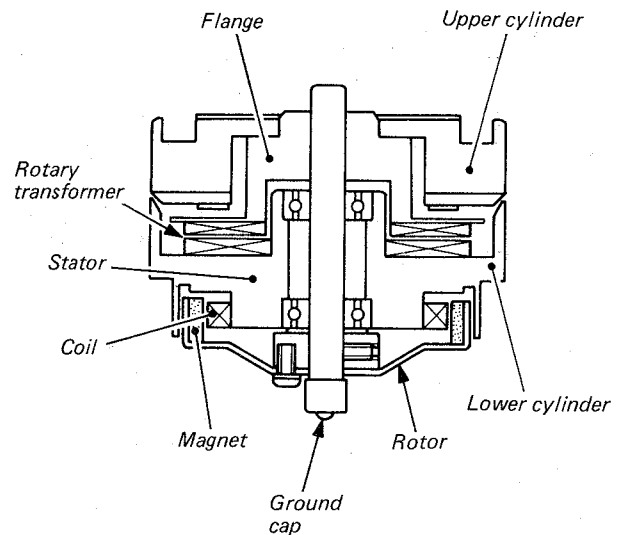


Fig. 2-1-2 Structure of cylinder

(6) Tape transport adjustment mechanism

This adjustment mechanism consists of following parts:

1. Nos. 3 and 8 guide posts
2. S- and T- guide rollers
3. FE and ACE heads

The purpose of the transport adjustment is as follows:

- To obtain a playback RF signal envelope with fine linearity.
- To adjust azimuth control position to assure good interchangeability of cassette tapes.

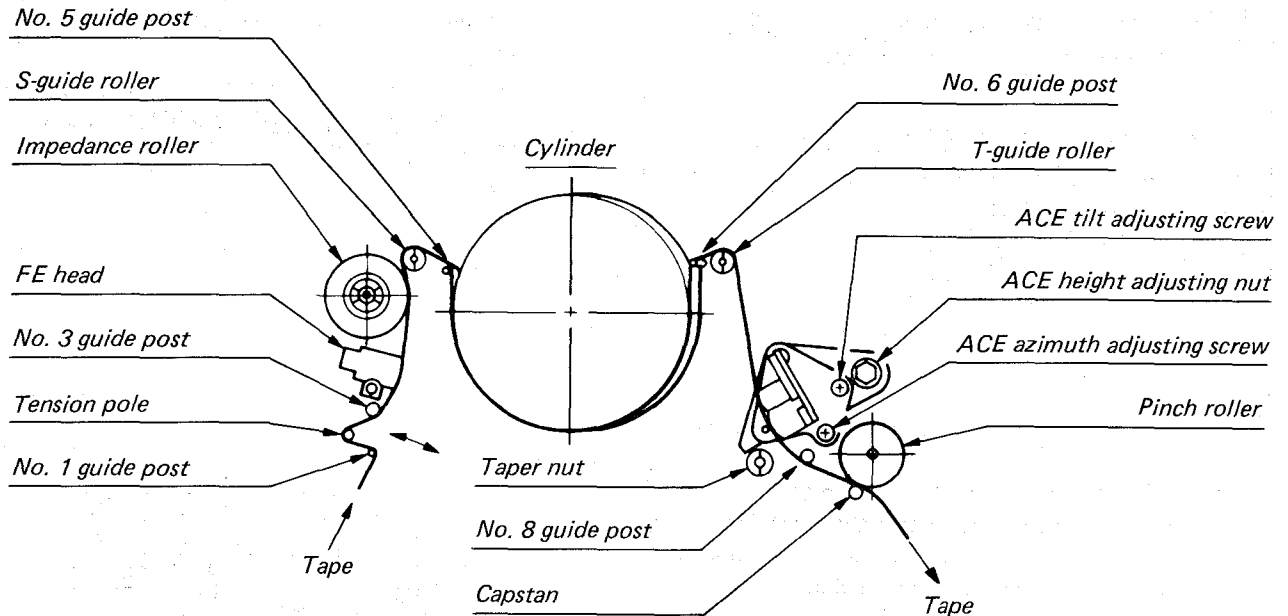


Fig. 2-1-3 Tape transport adjustment location

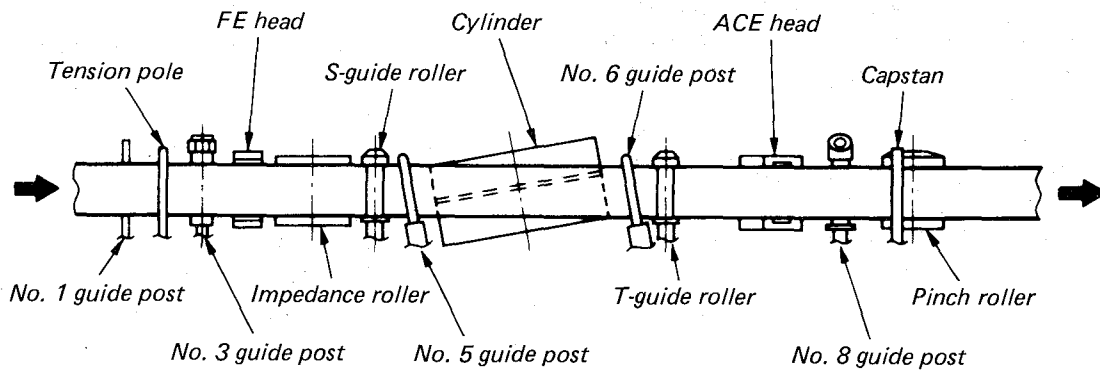


Fig. 2-1-4 Tape path diagram

2-2. Cam Gear Operation

2-2-1 Cam gear and operation of each mechanism

- (1) Four cams A — D are provided on one disc. (Fig. 2-2-3)
- (2) These cams control the main brakes, soft brakes, pinch roller, band brakes, etc. through the logic slider, brake slider, and the pinch lock lever. (Fig. 2-2-1)
- (3) The cam gear rotates the loading ring which in turn moves the S, T sliders. (Fig. 2-2-3)
- (4) Fig. 2-2-3 shows shapes of the cams and position for each mode of operation.

Table 2-2-1 also shows operation modes and their timings.

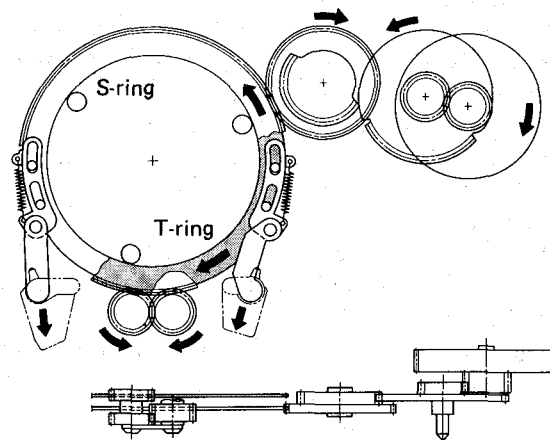


Fig. 2-2-1

Cam A, B, C

Table 2-2-1
Timing table for cam gear and each mode

Mode	Operation guide	Slider position	Cam position	Cam SW position
FF/REW	FF, FF Short Rewind	A	①	I
Stop	Stop, Cassette eject, Rewind short	A	②	II
Play	Play, Still, Rec, Frame	B	③	V
Cue/Review	Cue/Review, EDIT REW	B	④	VI
Pause	Timer operation standby REC → Stop, Pause	B	⑤	VII

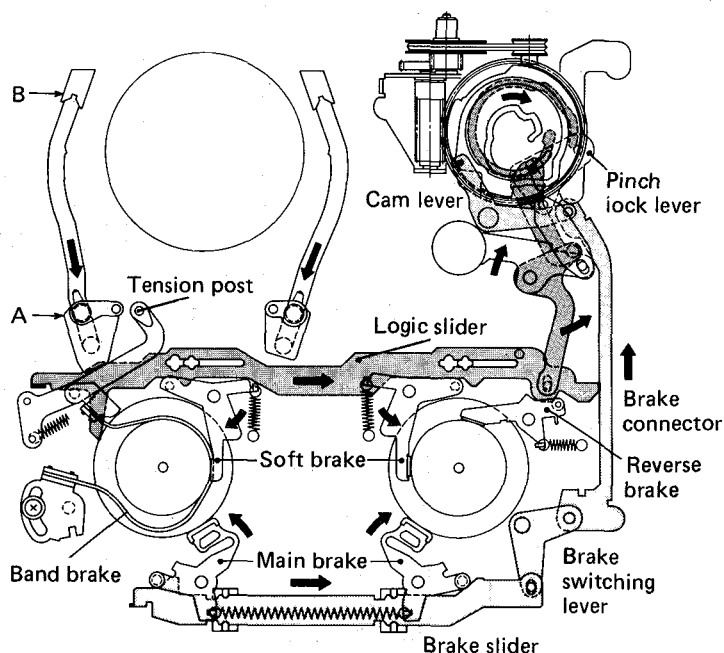
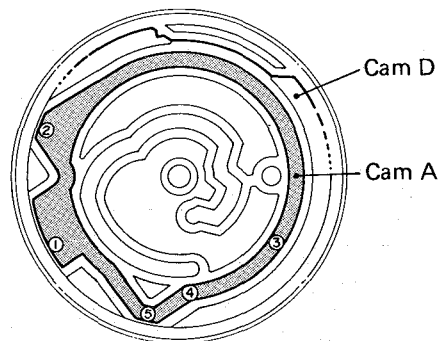
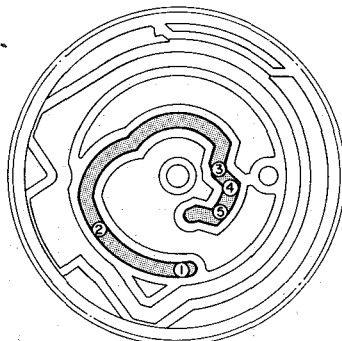


Fig. 2-2-2

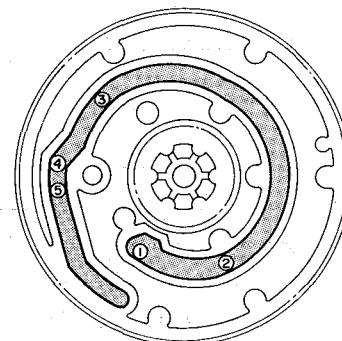
Cam A, D



Cam B



Cam C (rear side)



Cam A and cam D control the main brakes through cam lever, brake connector, brake switching lever and brake slider.

Cam B controls pinch roller through pinch lock lever.

Cam C controls soft brakes, band brakes and reverse brakes through logic slider.

Fig. 2-2-3

2-2-2 Cam switch drive

- (1) Cam switches function to convert each mode of the mechanisms into electrical signals and transfer them to the microcomputer.
- (2) The cam switches are rotated in synchronization with the cam gear by the loading motor and each mode signal is created in relation to the angle of the cam rotated.
- (3) IC601 controls IC602 to drive the loading motor in forward or reverse direction for setting the cam to a desired mode position.

Fig. 2-2-4 shows forward rotation modes of the cam.

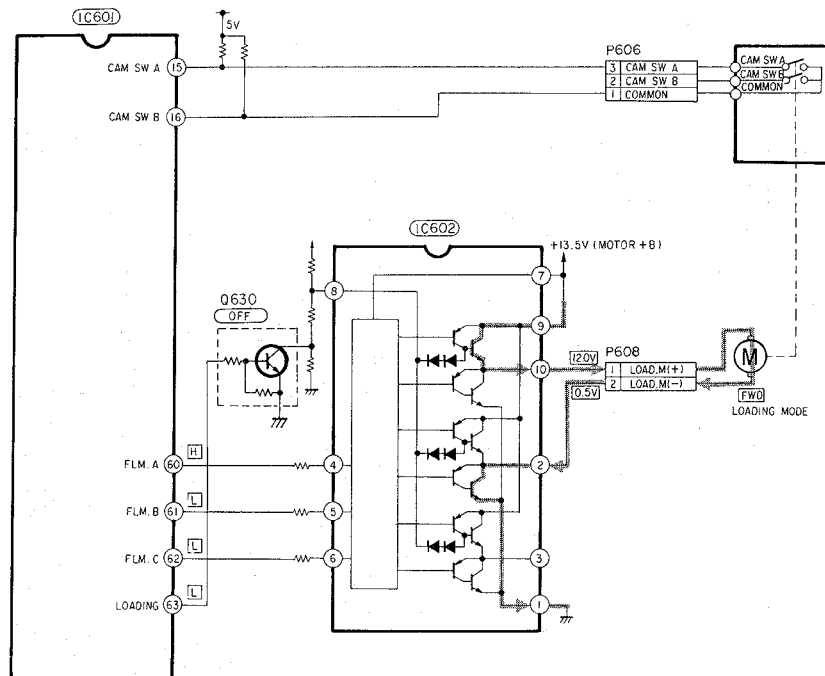


Fig. 2-2-4 Loading motor drive (FF rotation)

Mode	IC601				Loading motor
	⑥0	⑥1	⑥2	⑥3	
Stop	H	H	H	L	Stop
Cam rotates forwardly (Loading)	H	L	L	L	FORWARD rotation (11.5V)
				H	FORWARD rotation (8.5V)
Cam rotate reversely (Unloading)	H	L	H	L	REVERSE rotation (11.5V)
				H	REVERSE rotation (8.5V)

2-2-3 Cam control

- (1) The loading motor rotates and moves the cam gear, thus setting a mechanical mode.
- (2) Cam gear positions corresponding to various modes, cam switches, and mechanical system operations are given in the cam control chart.

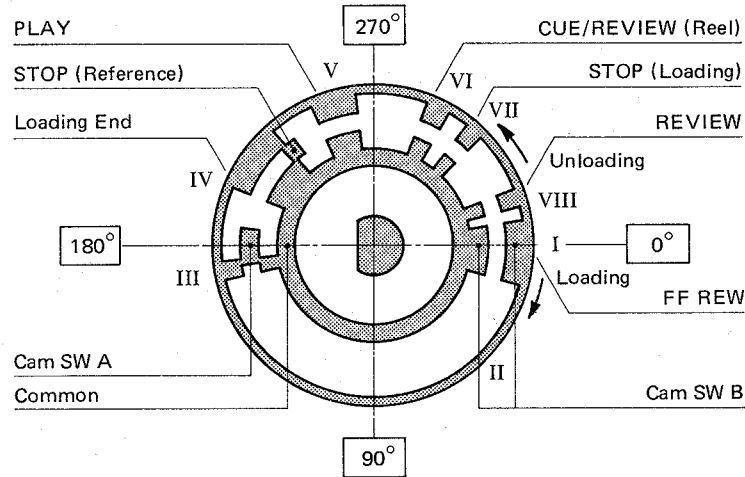


Fig. 2-2-5 Shape of cam switch

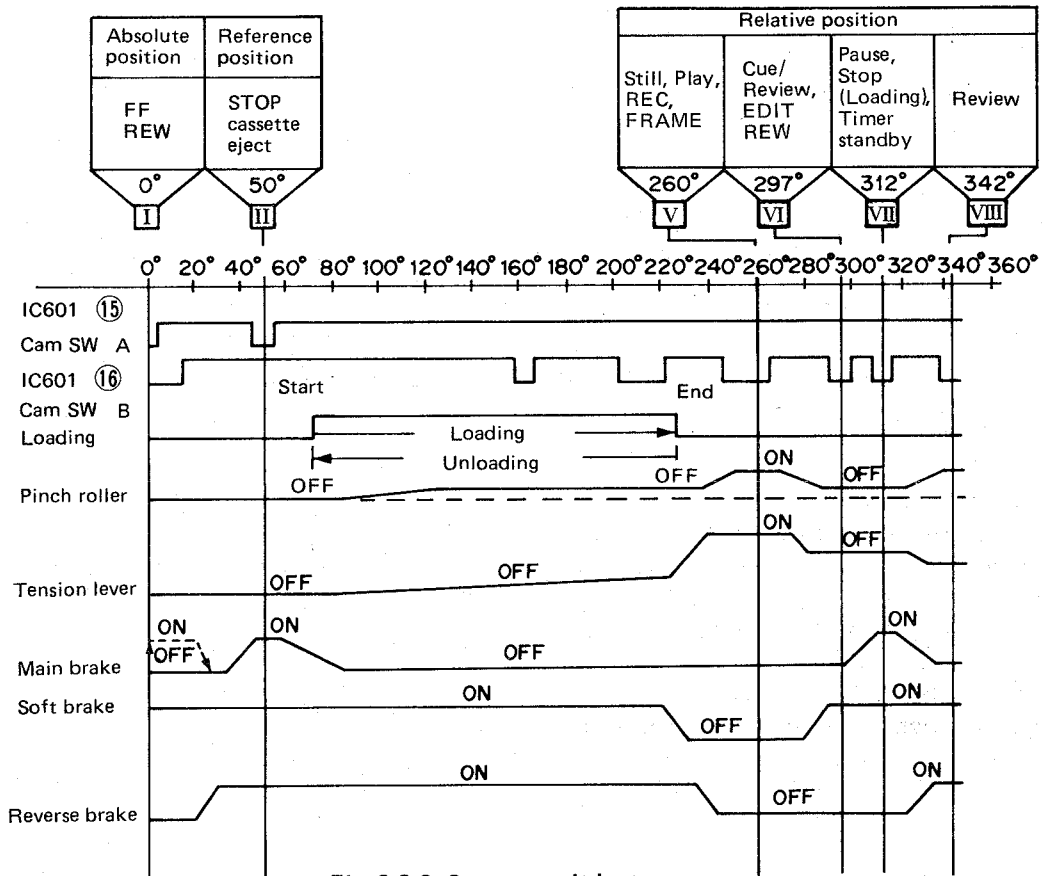


Fig. 2-2-6 Cam control chart

3. DESCRIPTION ON EACH MODE OPERATION

3-1. Front Loading

3-1-1 Slot-in operation

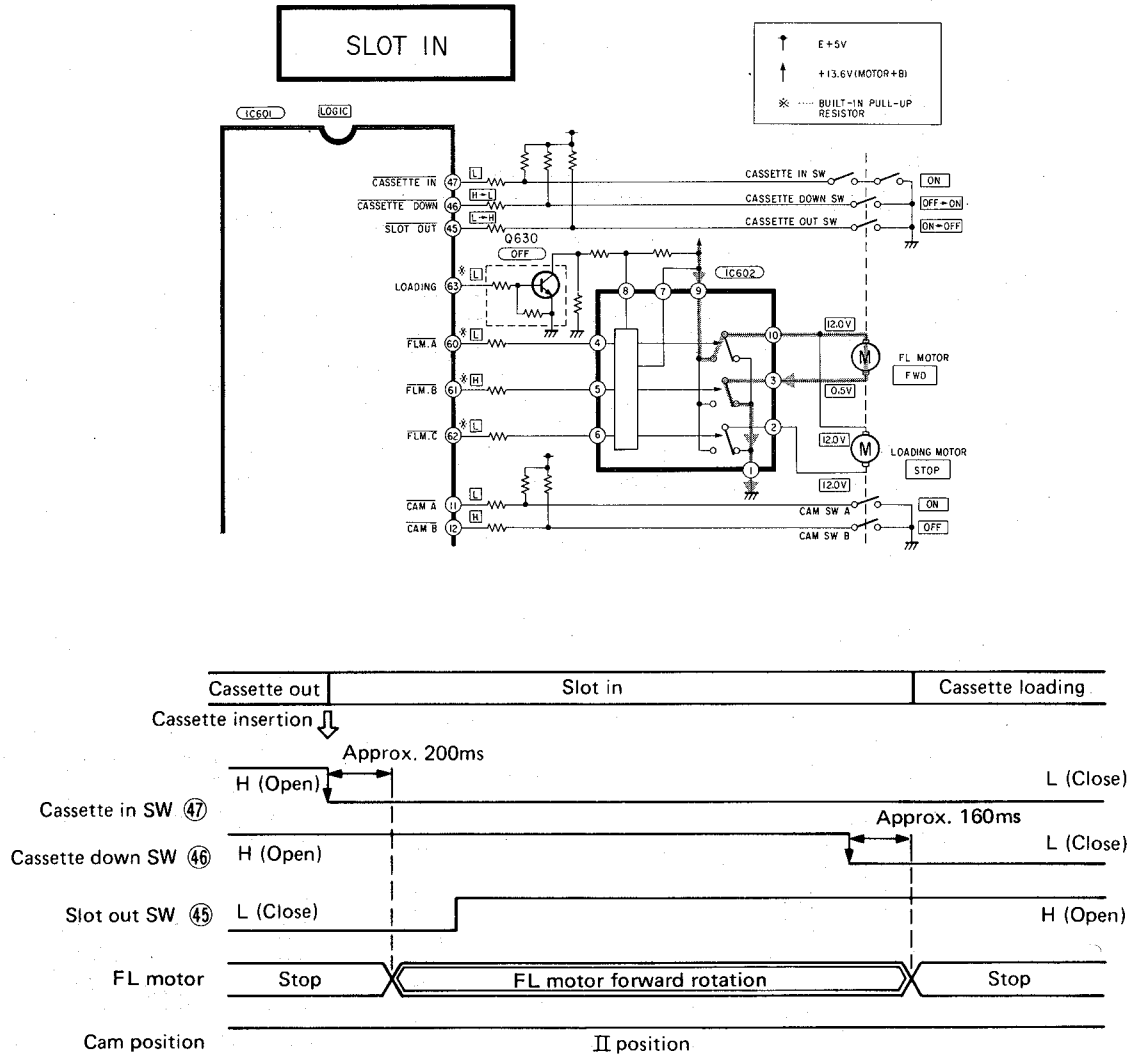


Fig. 3-1-1 Slot in operation

- (1) When a cassette is loaded into the cassette holder, two cassette detection switches mounted under the cassette holder are pressed by the bottom case of the cassette and closed. (IC601 controls IC602 to rotate the FL motor in forward direction.) (Fig. 3-1-2)
- (2) The motor rotates in direction shown by the arrow (clockwise direction viewed from front side) with the two left and right cassette detection switches in operation.

The rotational force of the motor is transferred to the arm gear L through the coupling, worm gear, worm wheel, arm gear R and the left and right drive gears, and the arm gear L moves the cassette holder horizontally. (Refer to Fig. 3-1-3)

Pressed by lower
end of cassette
and turned on.

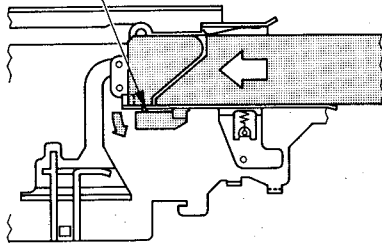


Fig. 3-1-2

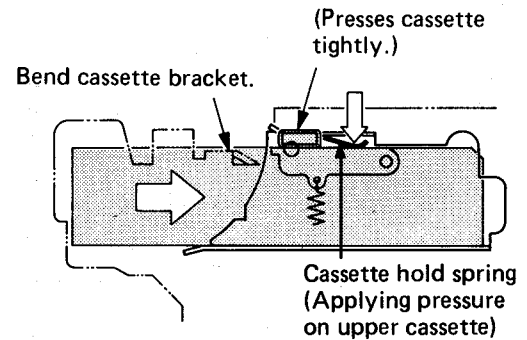


Fig. 3-1-4

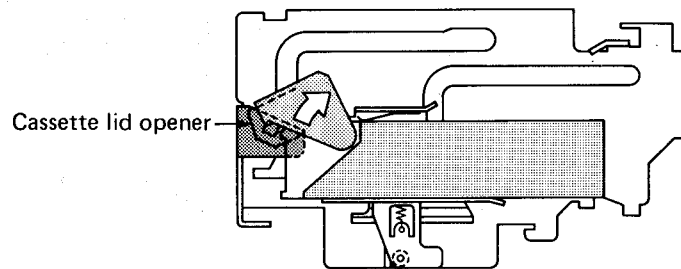


Fig. 3-1-5

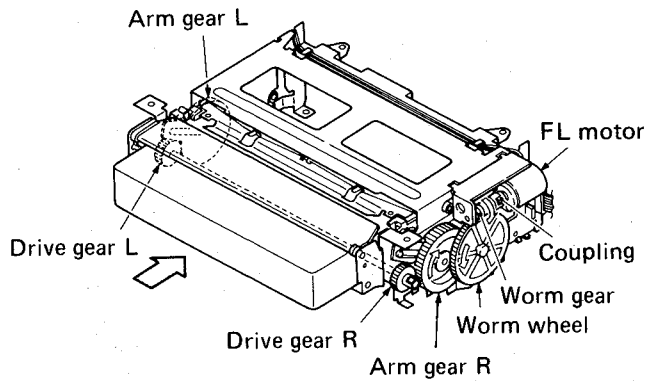


Fig. 3-1-3

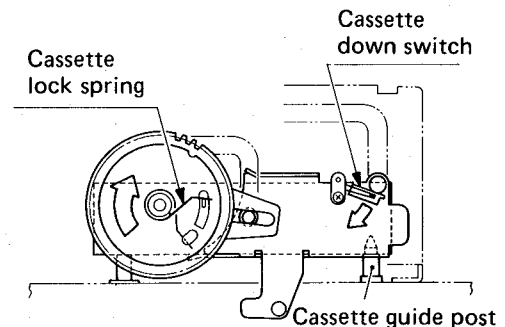


Fig. 3-1-6

(3) The cassette loaded in the cassette holder is, first, held in a place by two cassette hold springs (strip) provided on left and right sides of the holder reinforcement plates, thus preventing the cassette from its positional deviation at the starting period. Motion of the cassette holder unlatches both left and right cassette levers from their hooks provided on the guide bracket and allows the cassette to rotate in the direction being pressed, thus holding the cassette more tightly and preventing positional deviation of the cassette due to the cassette lid opener. (Fig. 3-1-4)

(4) In the last stage of the cassette holder's horizontal motion, the cassette lid is engaged with the cassette opener and opened widely as the cassette holder moves down.

(5) When the cassette is mounted on the cassette guide posts, the cassette down switch turns on. The slot motor continues to rotate for approx. 160 msec after the above operation and the cassette is pressed by the left and right cassette lock springs and stopped. (Fig. 3-1-6)

3-1-2 Slot-out operation

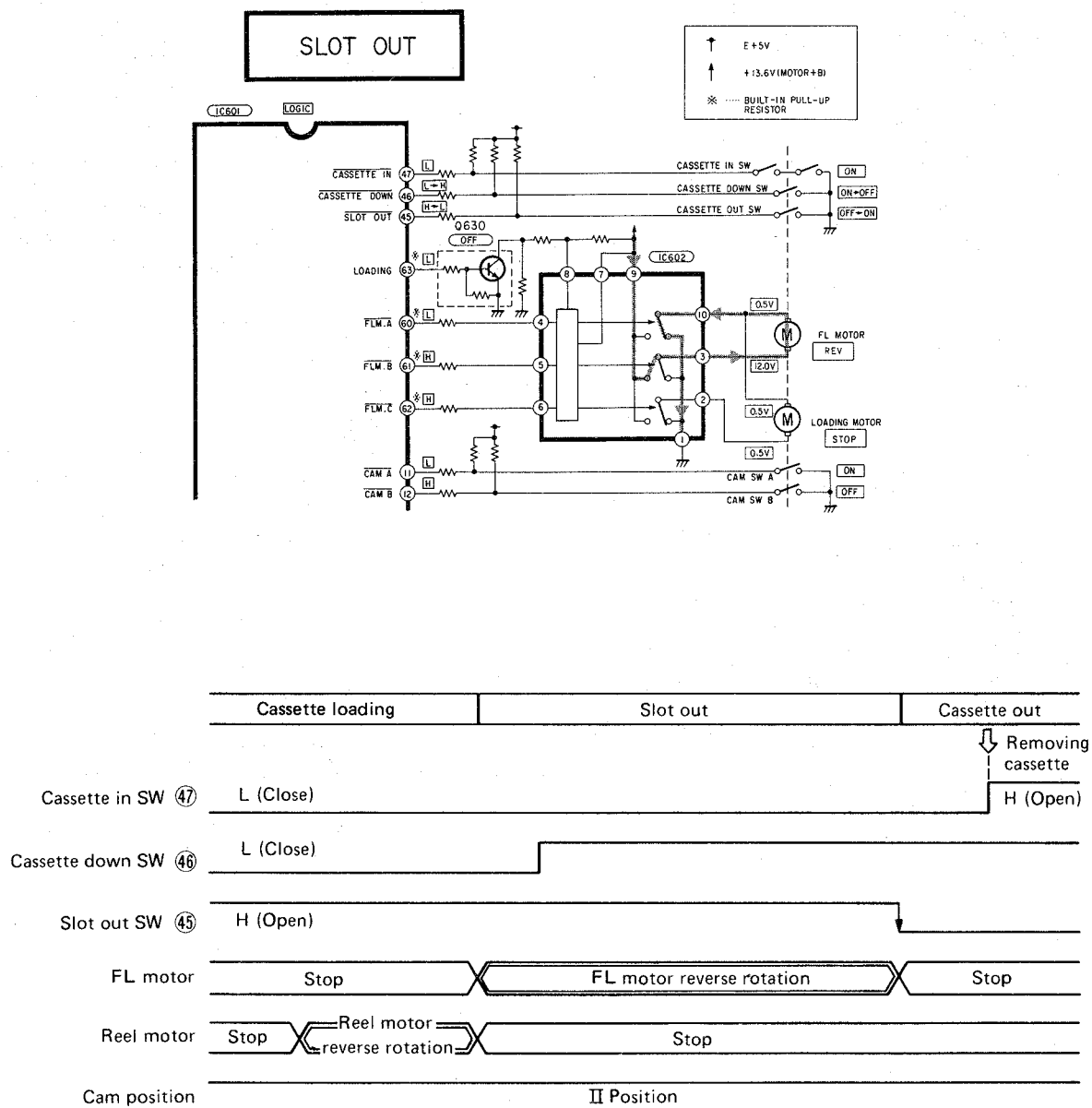


Fig. 3-1-7 Slot out operation

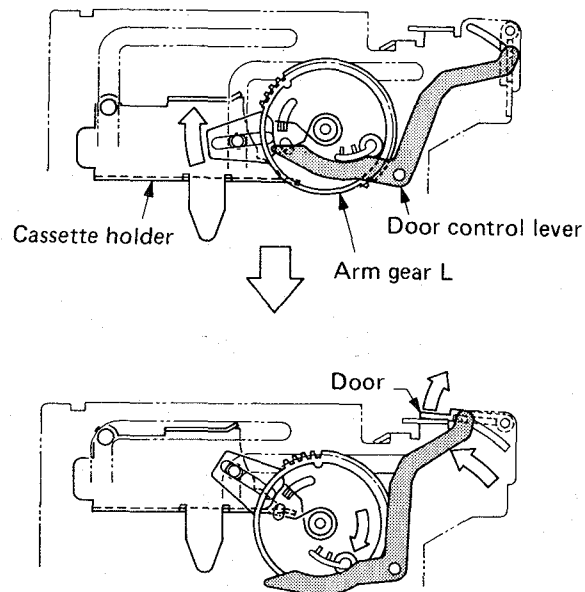


Fig. 3-1-8

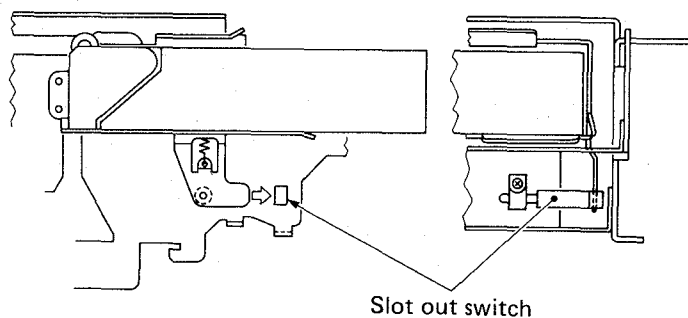


Fig. 3-1-9

- (1) The loading motor rotates and sets the cam gear to the stop mode (position II) and actuates the main brakes for the reel tables.
- (2) IC601 controls IC603 so that the reel motor rotates in opposite direction for approx. 1 sec to remove tape slack. Then, IC601 also controls IC603 and rotates the FL motor in reverse direction.
- (3) While the cassette holder is moving upward, the door control lever rotatively moves along the cam surface of the arm gear and the door opens. (Fig. 3-1-8)
- (4) The cassette holder horizontally moves and reaches close to the stop position, the slot-out switch is turned on by the lower end of the cassette holder. (Fig. 3-1-9)

3-2. Stop Mode

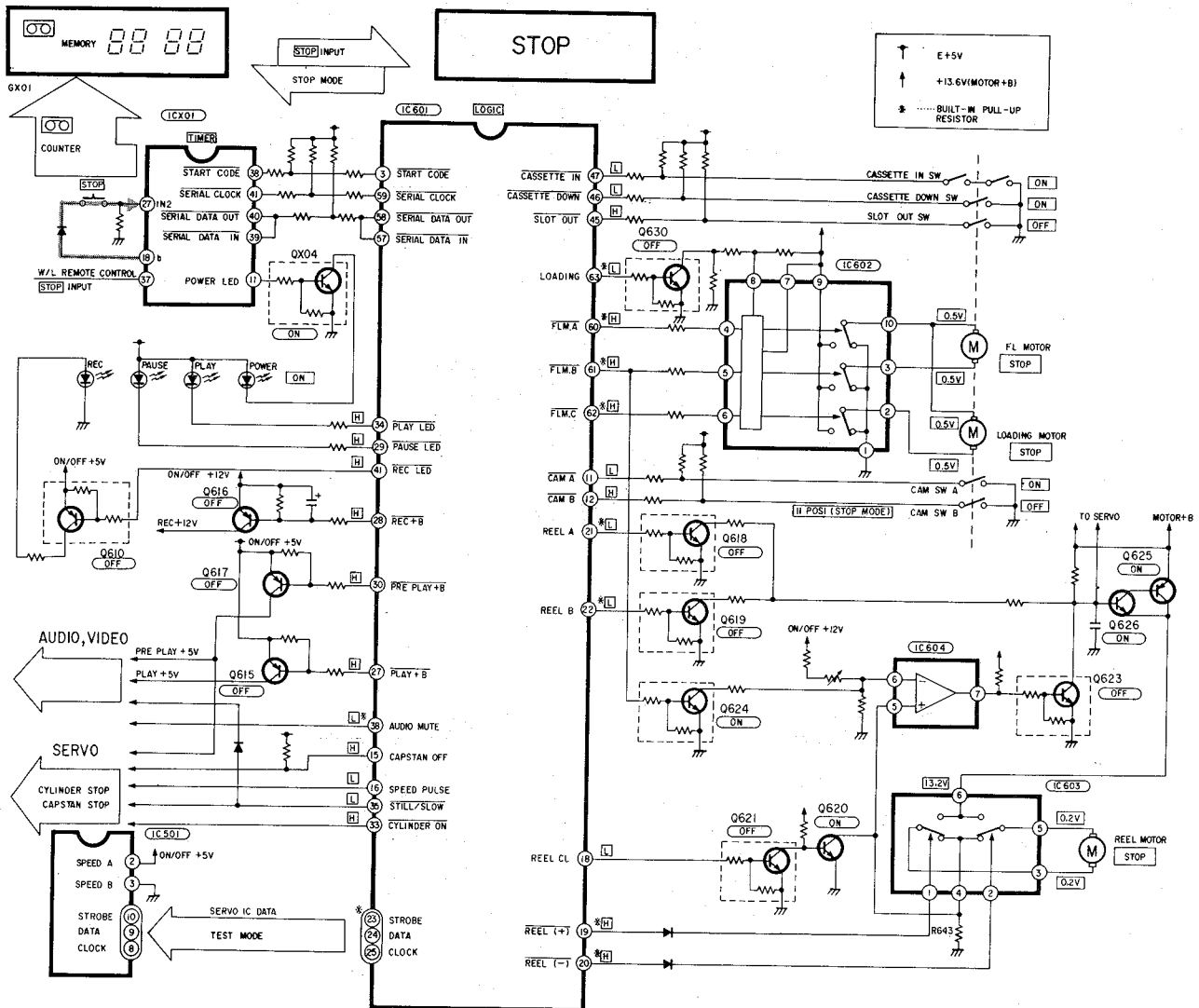


Fig. 3-2-1

- (1) The cam gear is in the stop mode (position II).
Under this condition, the cylinder motor, capstan motor, and the reel motor are also stopped.
- (2) Each part of the mechanism is set as follows:
 - 1 The T- and S- sliders are set in unloading condition.
 - 2 The pinch roller is away from the capstan.
 - 3 The tension lever is stored on the reel table side.
That is, the band brake is released and the back tension is released.
 - 4 The T- and S-main brakes, T- and S-soft brakes and the reverse brakes are being actuated.

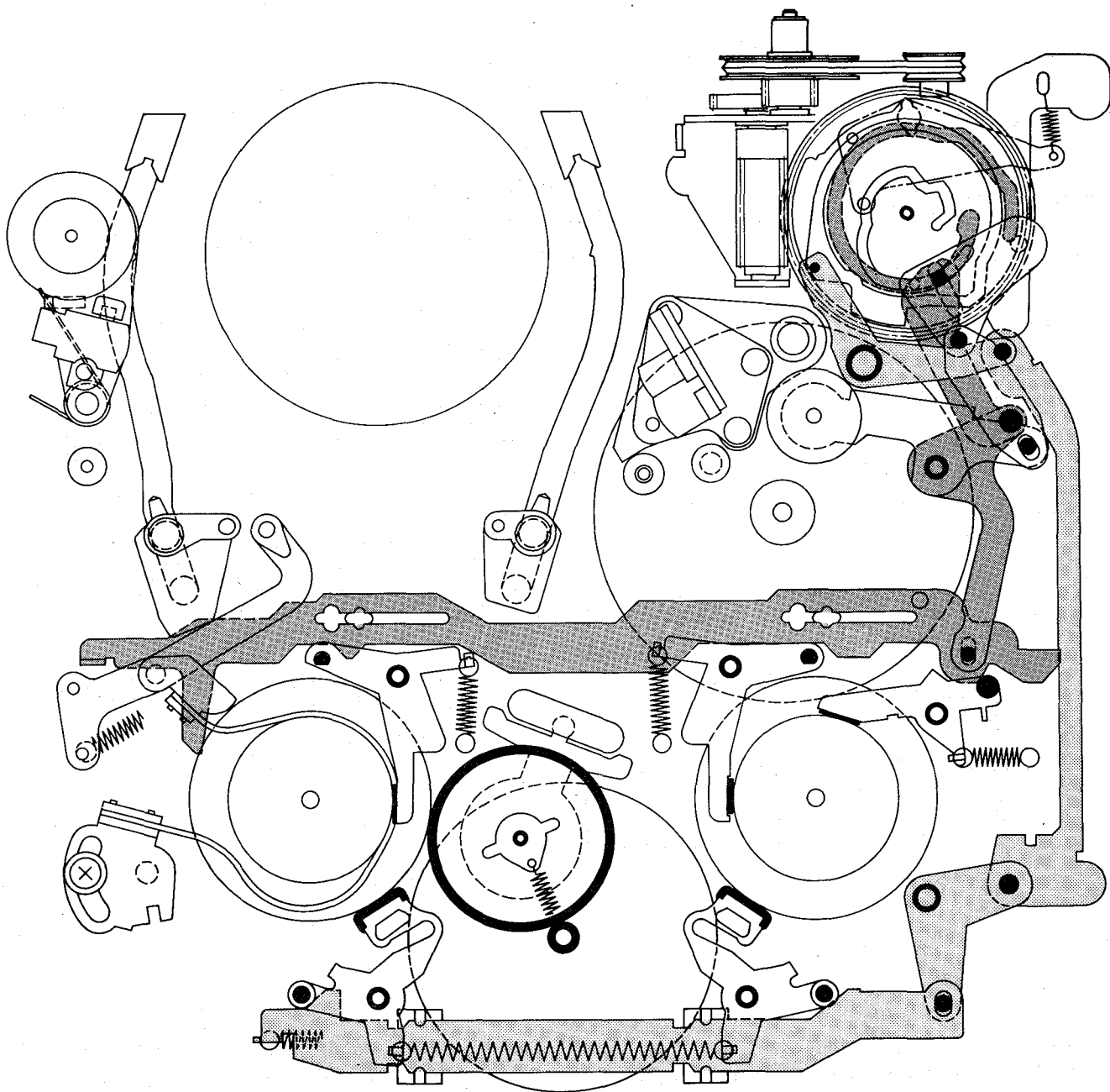


Fig. 3-2-2

3-3. FF/REW Mode (From Stop Mode)

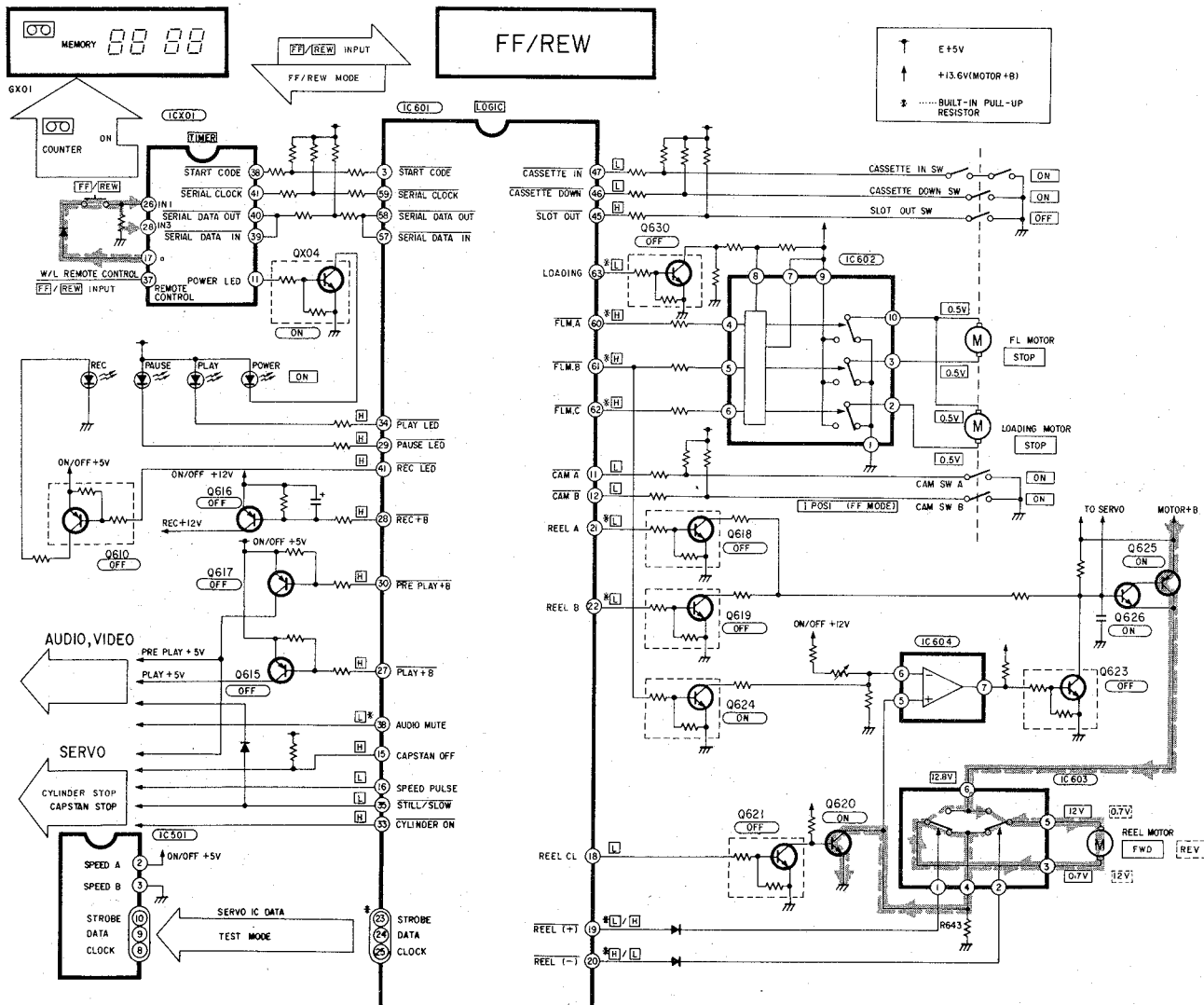


Fig. 3-3-1

- (1) When the FF button is pushed in the stop mode, ICX01 transfers the FF input signal serially to IC601 to set the FF mode.
- (2) IC601 controls IC602 and rotates the loading motor in reverse direction. (direction ①)
- (3) The cam gear rotates (②—⑥), the brake slider starts to move and releases the T- and S-main brakes (⑦—⑭).
The logic slider also moves and releases the reverse brakes. (⑮—⑳)
- (4) When the cam gear is set to the FF mode (position I), the loading motor stops.
IC601 controls IC603 which in turn drives the reel motor with a constant voltage. Then the idler contacts the T-reel table and transfers rotational force, thus winding the tape.
- (5) In the REW mode, the reel motor rotates in reverse direction, and the idler contacts the S-reel table, thus rewinding the tape.

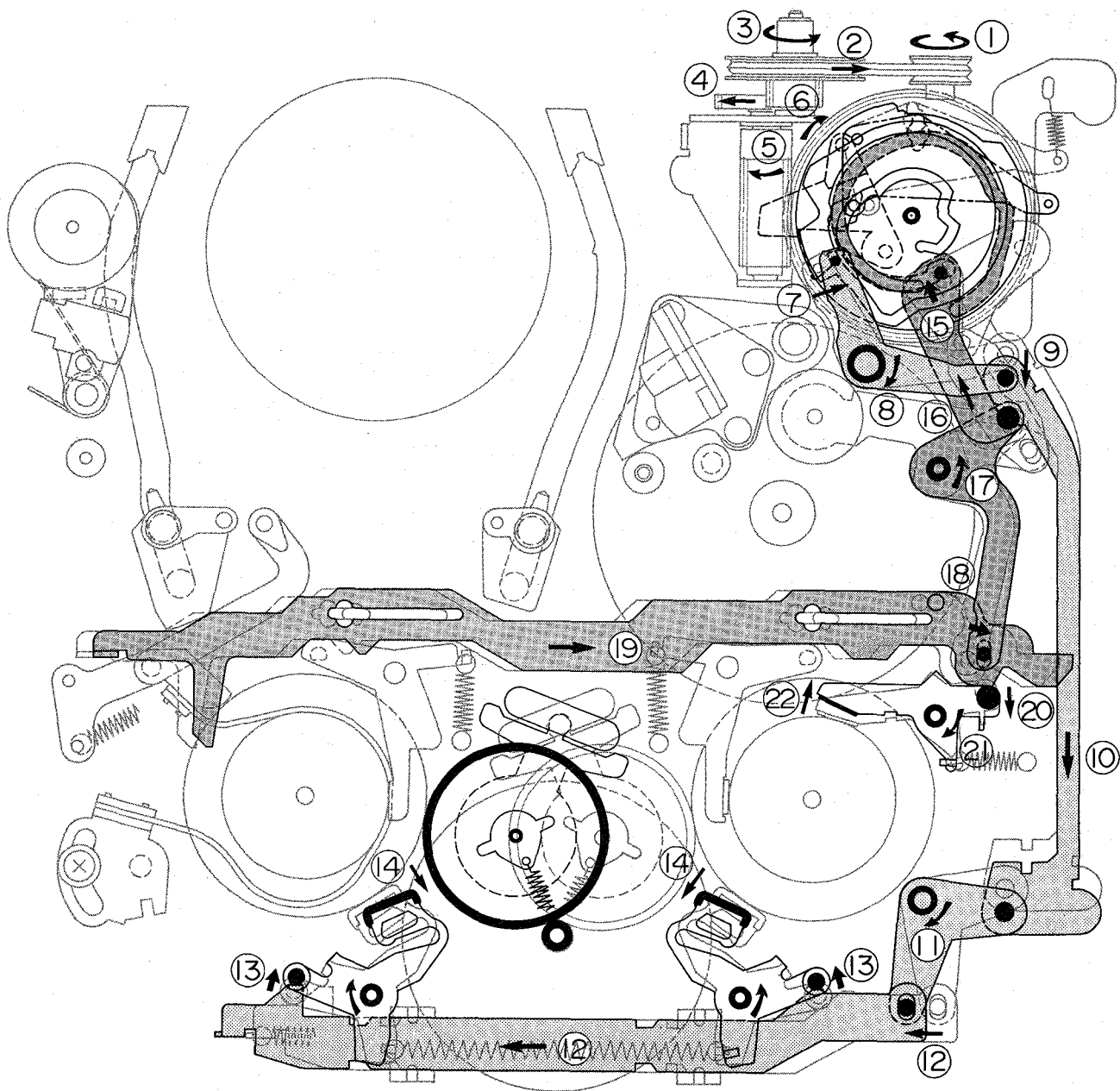


Fig. 3-3-2

(6) The cylinder motor and the capstan motor are in stop condition.

Note: Operation from FF/REW mode to STOP mode

- When the loading motor rotates in forward direction, the lock lever actuates and the T- and S-main brakes are immediately actuated.

3-4. Playback System Mode

3-4-1 Loading mode

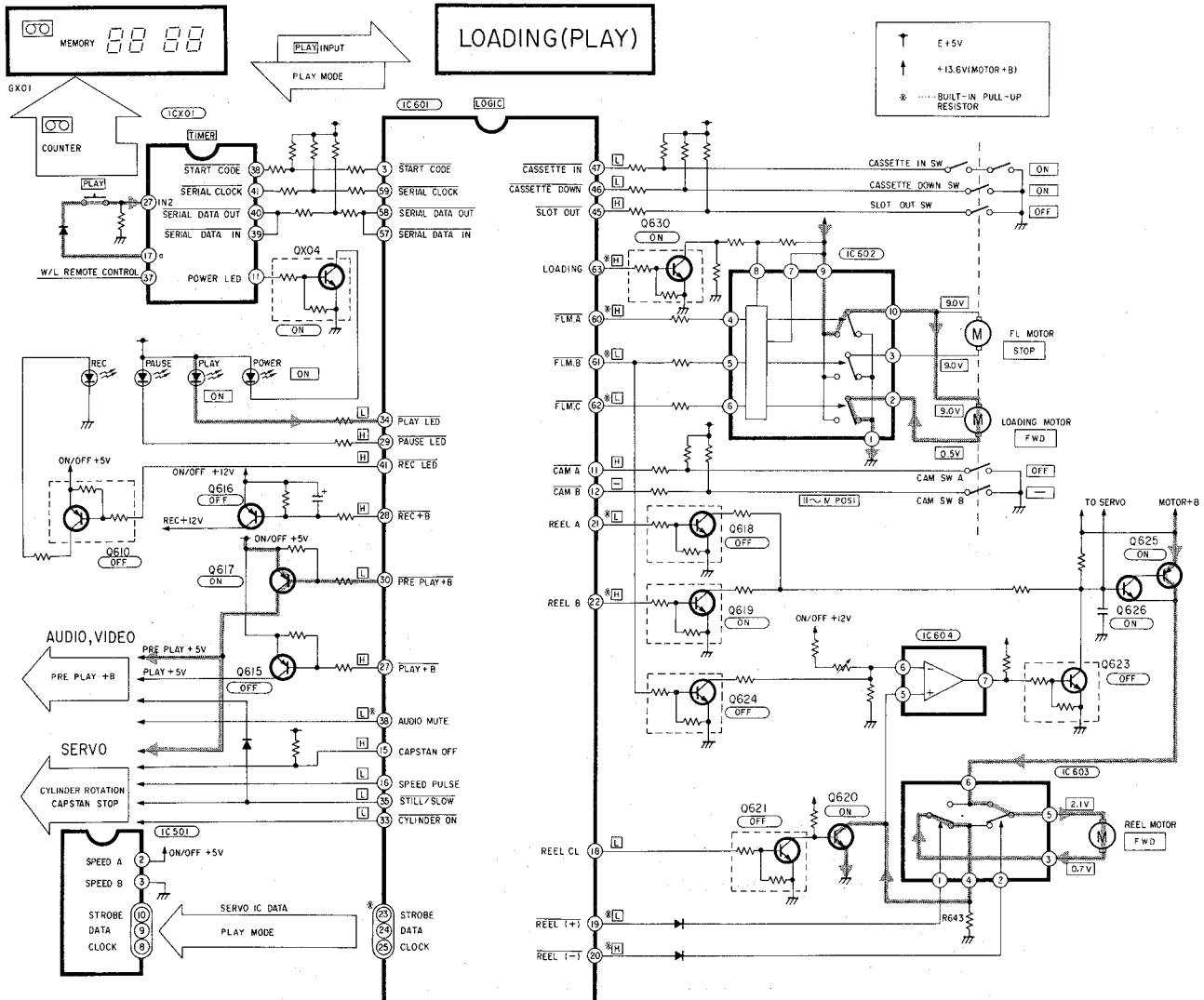


Fig. 3-4-1

- (1) When the PLAY button is pushed in the stop mode, ICX01 serially transfers the playback input signal to IC601 to set the playback mode.
- (2) IC601 and IC603 make the reel motor rotate in forward direction and the idler moves toward the T-reel table side. After that, the output at pin ②② turns to "H" level and this makes Q619 on, keeping the motor terminal voltage at approx. 1.5V so that the T-reel table does not rotate in reverse direction. (Since the reverse brake is actuated, no tape is wound.)
- (3) Next, the loading motor rotates in forward direction. At the same time the cam gear rotates. (① - ⑥). Then the brake slider moves and releases the T- and S-main brakes. (⑦ - ⑭)

- (4) When the loading motor rotates in forward direction, the loading ring and the loading gear make the T- and S-sliders move along the loading guide. (⑮)
In the loading mode (position II - IV), pin ⑥③ of IC601 goes "H" level, and this sets the motor terminal voltage to 8.5V, thus controlling moving speed of the T- and S-sliders.
When the cam gear exceeds the position II, the cylinder motor starts to run.
At the same time, the tension lever also moves toward the No. 1 guide.
Furthermore, the pinch lock lever moves and the pinch roller moves toward the capstan side. (⑯ - ⑰)

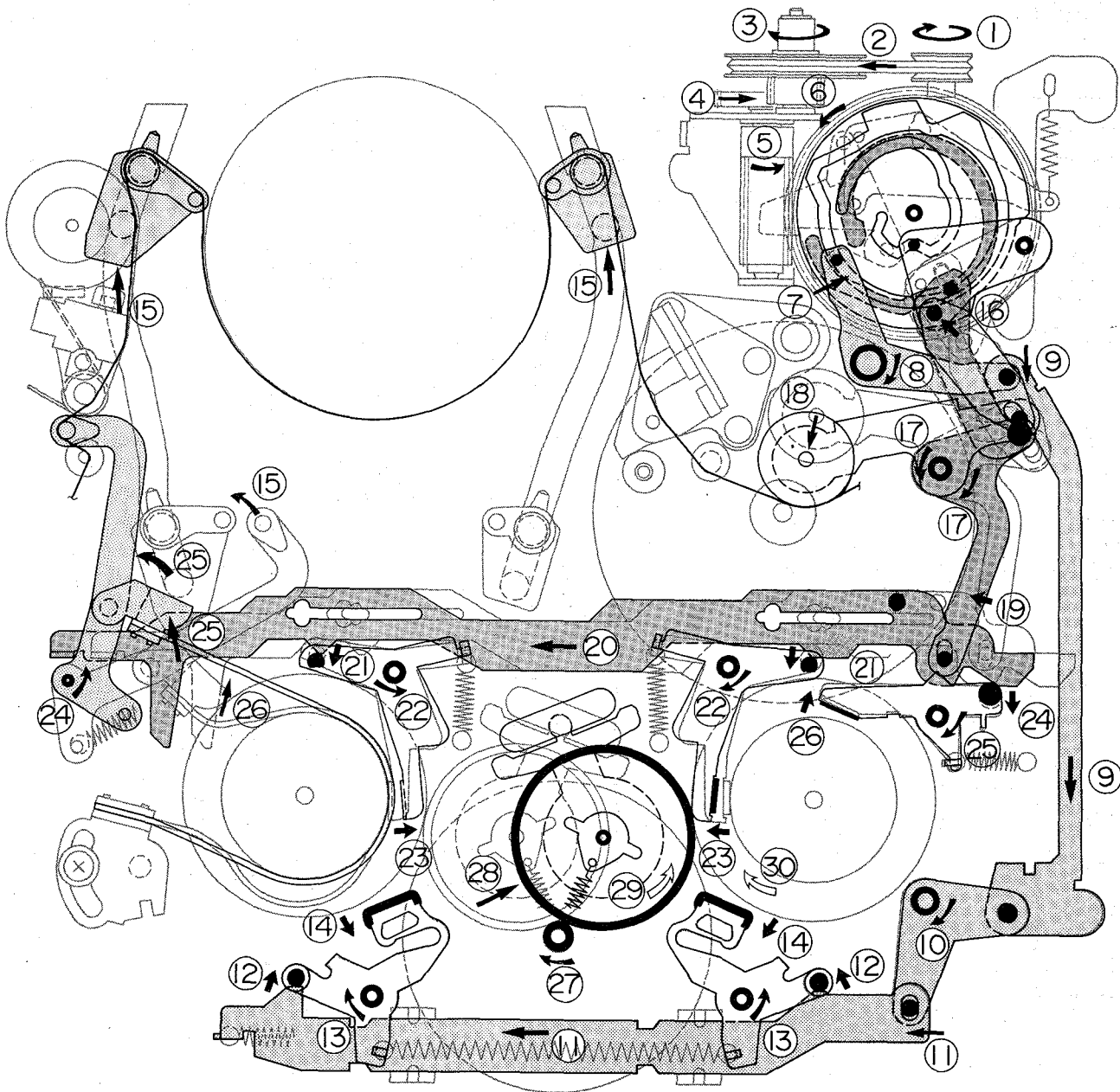


Fig. 3-4-2

(5) When the cam gear reaches the position IV, pin (63) of IC601 develops "L" level, and the terminal voltage of the loading motor rises to approx. 11.5V. Then, the T- and S-sliders are fixed to the cylinder base. At the same time, the logic slider moves, the T- and S-soft brakes are released, (19 - 23), and the reverse brake is also released, (24 - 26). The tension lever moves, furthermore, toward the No. 1 guide side, the band brake actuates, and the back tension mechanism functions.

(6) The pinch roller engages with the capstan with a specified pressure. (16 - 18)

(7) When the cam gear exceeds the playback mode (position V), the loading motor rotates in reverse direction and when the cam returns to the position V the motor stops.

3-4-2 Playback mode

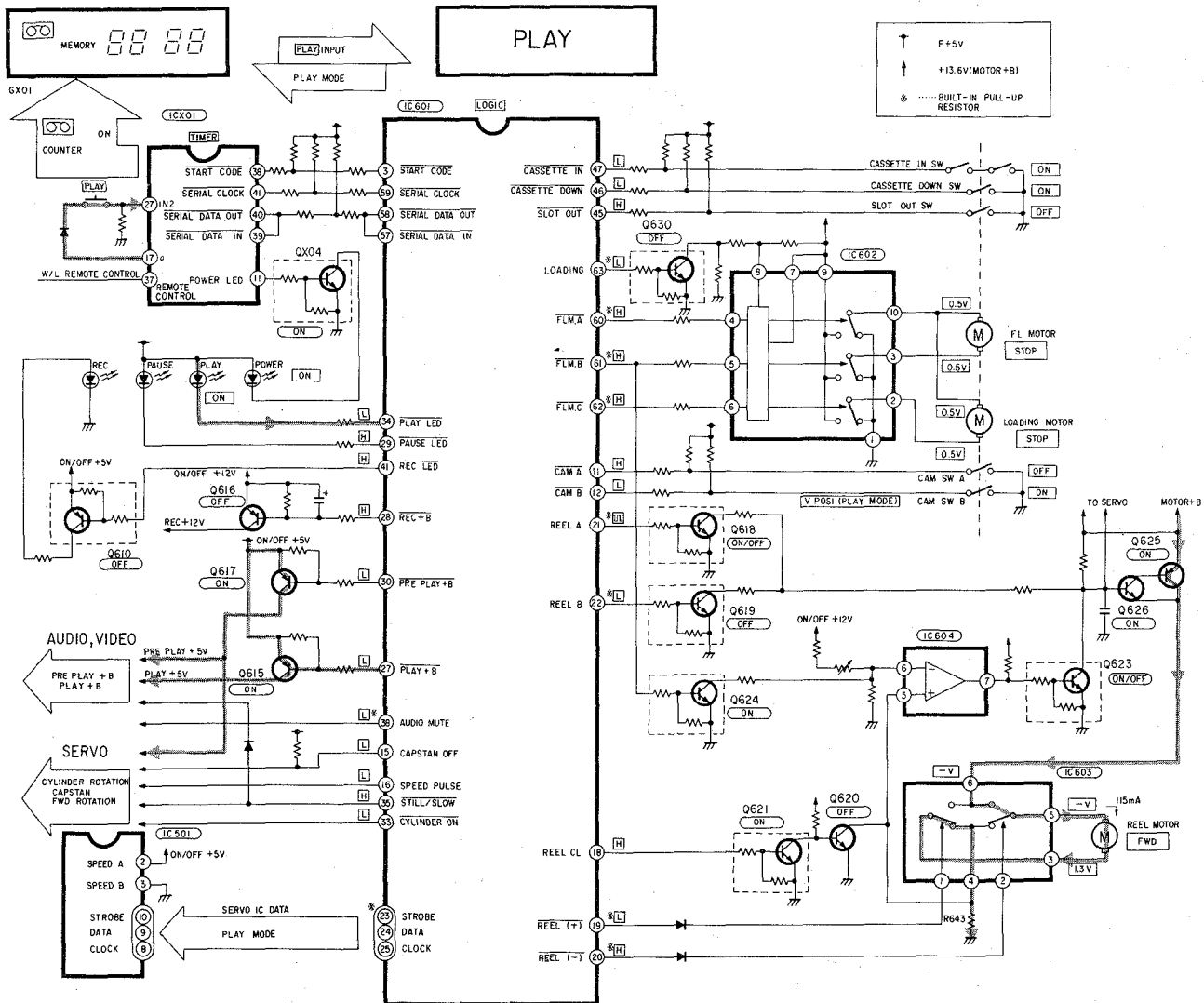


Fig. 3-4-3

- (1) When the loading operation completes, pin ⑮ of IC601 develops "L" level output.
- (2) IC601 controls IC603 and makes the reel motor rotate in forward direction. The idler touches the T-reel table and transfers rotational force to wind the tape. (⑳ - ㉔)
- (3) Under this condition, pin ⑱ of IC601 develops "H" level and Q620 turns off.

- Feedback voltage across R643 (by reel current) and a reference voltage at pin ⑥ of IC604 are compared, and if a current higher than the specified flows, Q623 is turned on to lower the base potential of Q626, thus limiting the current to a constant value of approx. 85 mA or driving the tape with a constant torque.
- Pin ⑳ of IC601 turns to "L" level and Q615 turns on, connecting the playback +5V to the audio and video circuits to set the playback mode.

3-4-3 Unloading

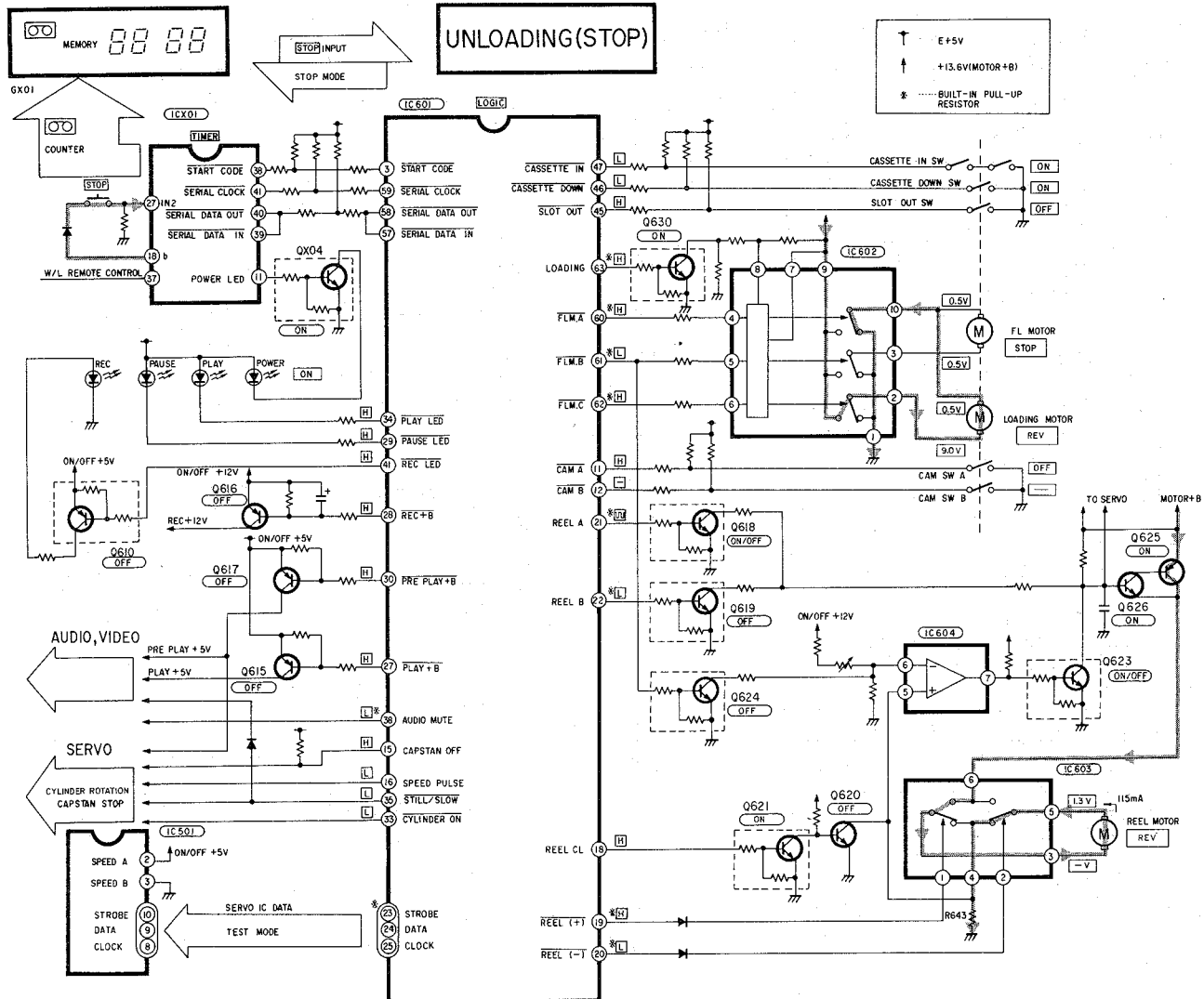


Fig. 3-4-4

- (1) When the STOP button is pushed in the playback mode, ICX01 sets IC601 to the stop mode.
 - (2) The cam gear is in the playback mode (position V).
 - (3) The cylinder motor rotates and the capstan motor stops. At the same time the reel motor also stops.
 - (4) The loading motor rotates reversely and the cam moves from the position V to the position II.
- Under this condition, mechanical parts move in reverse order of the loading operation.

- (5) When the cam gear reaches the position V, pin (63) of IC601 develops "H" level signal and controls the moving speed of the T- and S-sliders. The reel motor rotates in reverse direction and makes the idler move toward the S-reel table. As stated in 3-4-2 (3), the reel current flowing through R643 is fed back to pin (5) of IC604 to drive the tape with a constant current of approx. 110 mA.
- (6) When the cam gear reaches the position II, the cylinder motor, loading motor and the reel motor stop.

3-4-4 Review mode

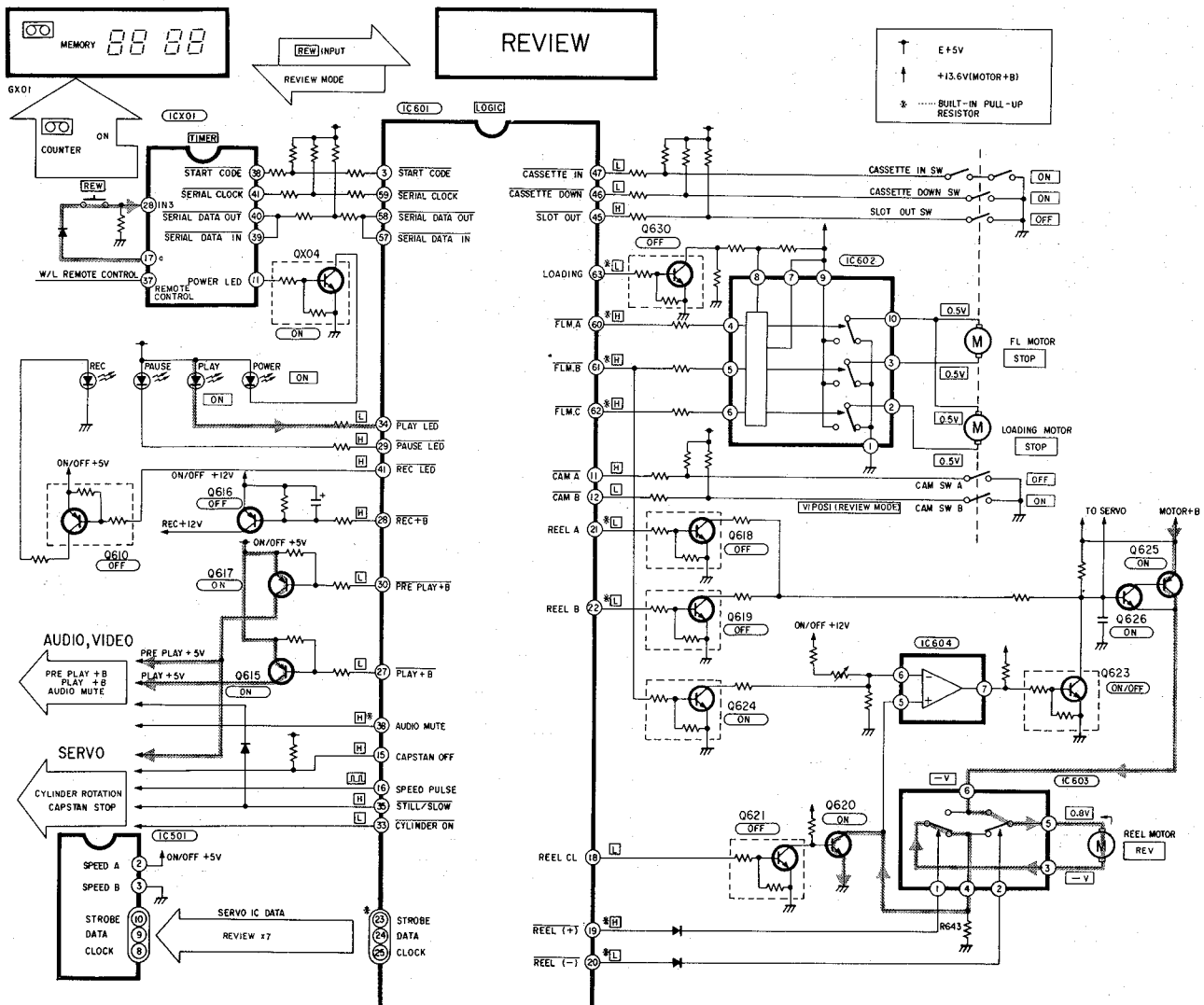


Fig. 3-4-5

- (1) When the REW button is pushed in the playback mode, IC601 is set to the review mode.
- (2) Pin 38 of IC601 develops "H" level and mutes audio signals.
In this case, the cylinder motor rotates but the capstan motor stops.
- (3) The reel motor is driven at a constant voltage in forward direction and the idler transfers rotational force to the T-reel table, thus winding the tape.
- (4) The loading motor rotates in forward direction (direction ①) and the cam moves from the position V to the position VII. In this case, the cam gear rotates forwardly (① - ⑥) and the pinch roller moves away from the capstan. (⑦ - ⑨)

- (5) The logic slider also moves S-soft brake is applied, and the tension lever moves away from No. 1 guide. (⑩ - ⑬)
Furthermore, the brake slider moves, and T- and S-main brakes operate.
- (5) Then the cam gear reaches the position VII, the loading motor stops and the reel motor rotates reversely.
In this case, the idler moves toward the S-reel table to wind the tape so that the tape does not slip off the cylinder.

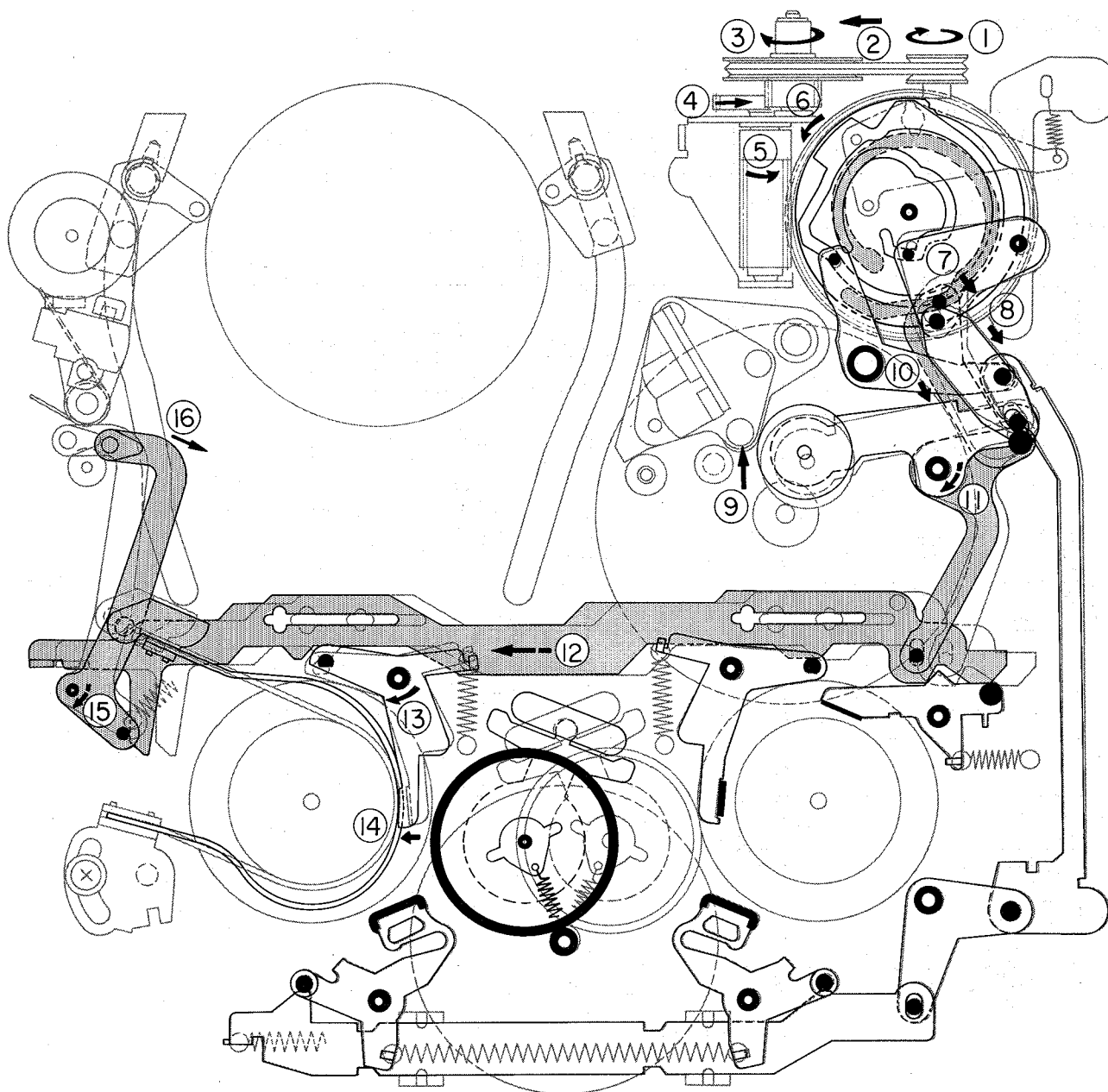


Fig. 3-4-6

- (6) Next, the loading motor rotates in reverse direction and the cam moves from position VII to VI. In this case the cam gear rotates, the brake slider moves and the T- and S-main brake is released.
- (7) When the cam gear reaches the review mode (position VI), the loading motor stops.

- (8) The reel motor also rotates reversely and the idler transfers the rotational force to the S-reel table and the reel winds the tape. At the same time, the servo circuit controls the CTL pulse so that the reel motor rotates at the speed 7 times higher than the normal speed.

3-4-5 Still mode

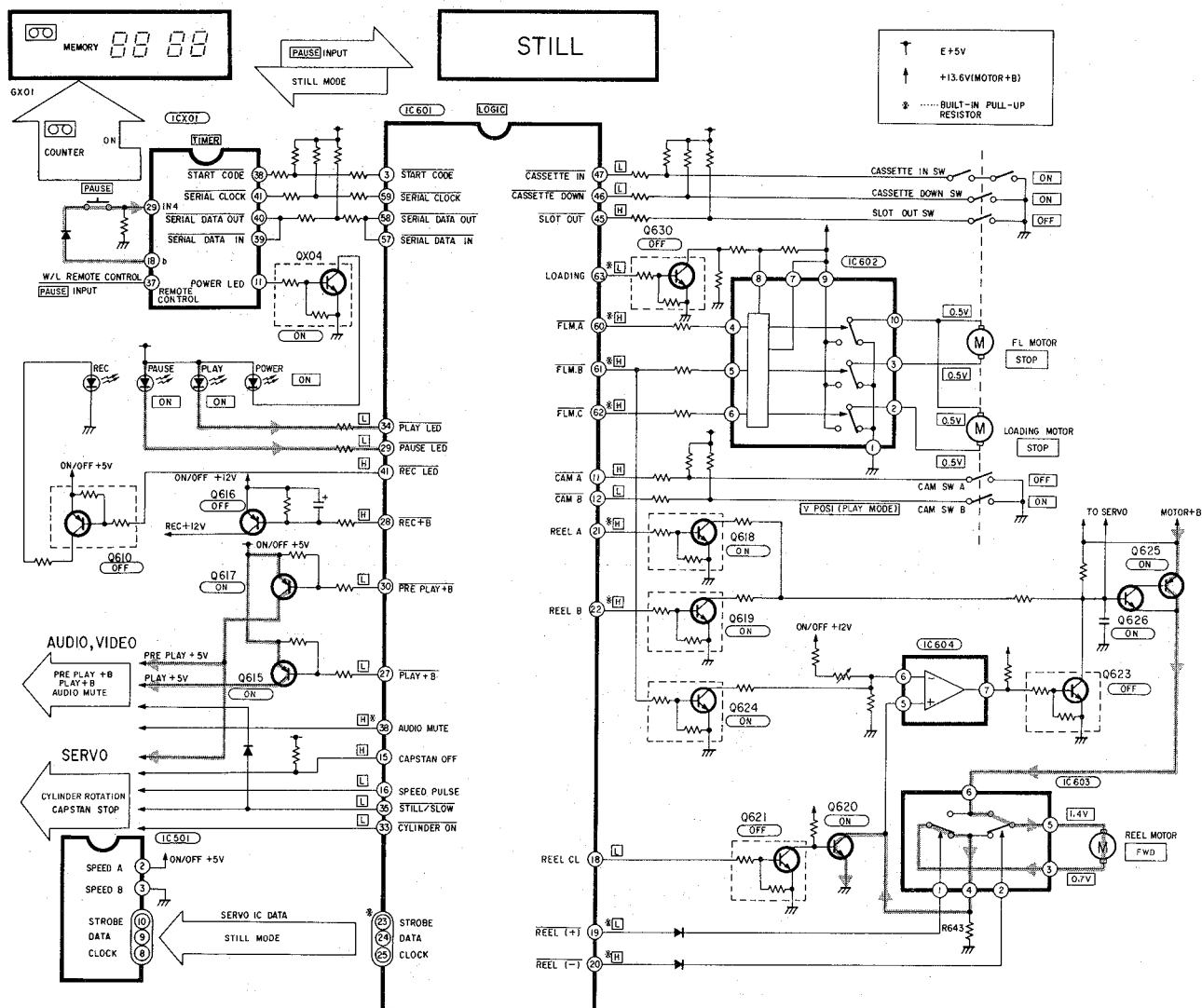


Fig. 3-4-7

- (1) When the PAUSE button is pushed during the playback mode, IC601 is set to the still mode.
- (2) The cam gear is in the playback mode (position V) and the cylinder motor is rotating. Under this condition each pin of IC601 develops output voltages as shown in Fig. 3-4-7.
- (3) Pin (38) of IC601 develops "H" level and mutes audio signals.

- (4) A mode data (still) is sent to IC501.
- (5) The capstan motor is stopped.
- (6) The reel motor is driven at a constant voltage and the idler transfers rotational force to the T-reel table, thus winding the tape. Under this condition a voltage of approx. 0.7V is applied to the motor terminals to prevent tape slack.

3-4-6 Frame feeding mode

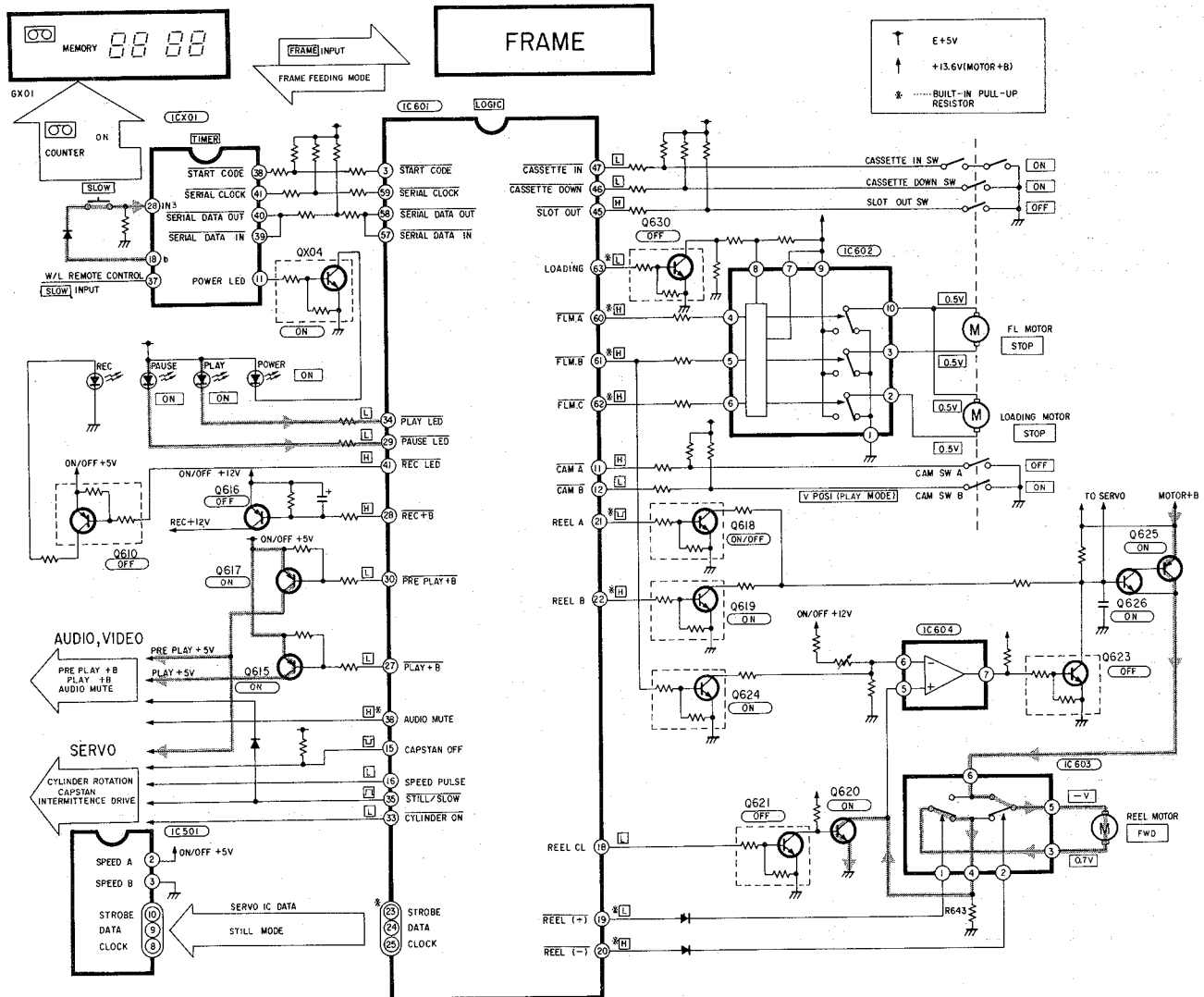


Fig. 3-4-8

- (1) When the FRAME button is pushed during the still operation, the capstan motor and the reel motor rotate. When the FRAME button is pushed, the capstan motor and the reel motor are intermittently driven. (Refer to Fig. 3-4-9)

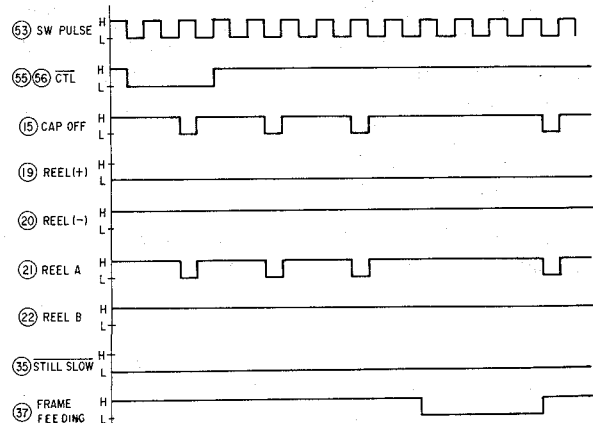


Fig. 3-4-9 Basic timing chart

3-4-7 Cue mode

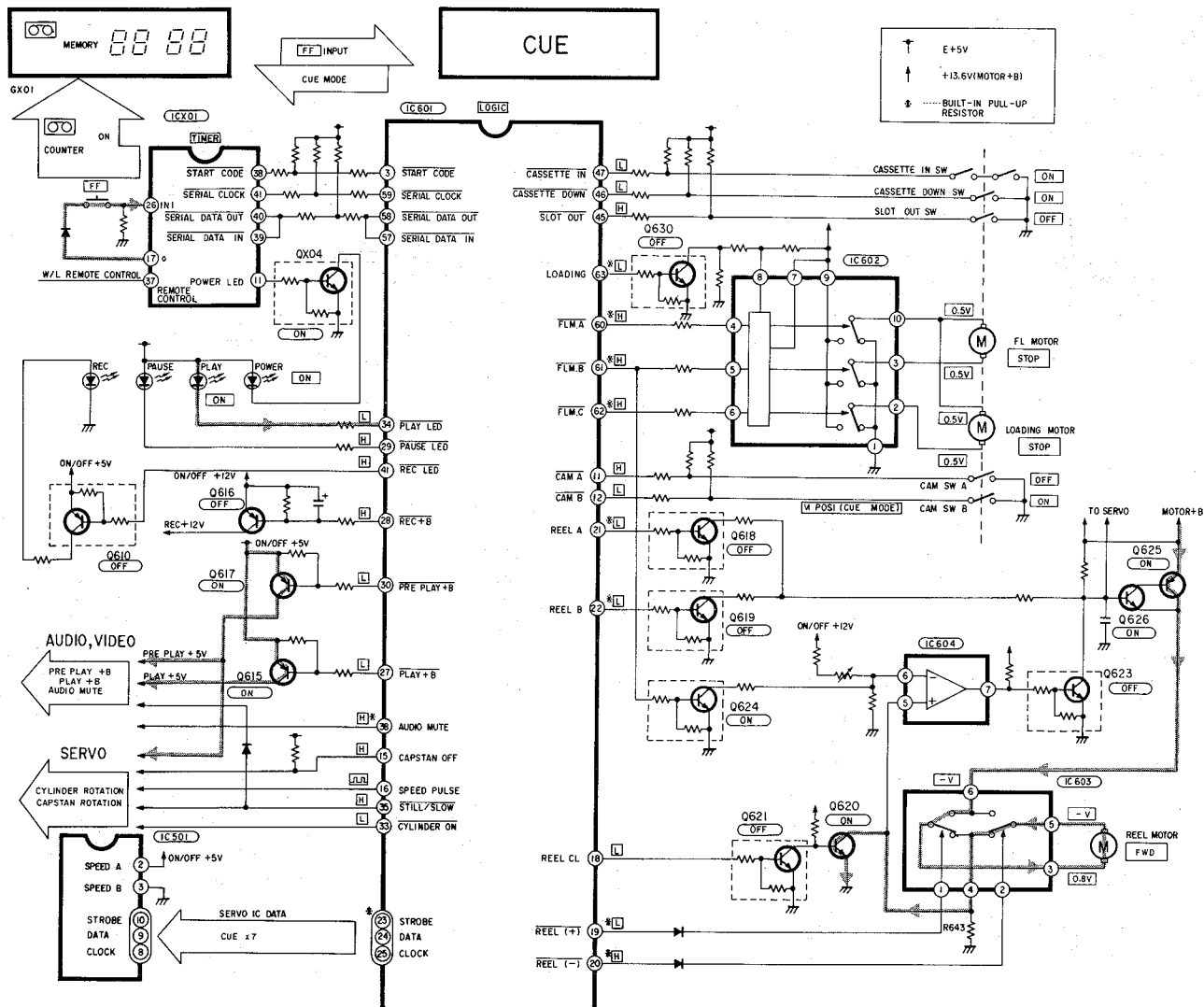


Fig. 3-4-10

- (1) When the FF button is pushed during the playback mode, IC601 is set to the cue (FF playback) mode.
- (2) The loading motor rotates in forward direction and the cam moves from the position V to the position VI.
- (3) Pin outputs of IC601 in the cue mode are shown in Fig. 3-4-10.
- (4) Pin 39 of IC601 develops "H" level and mutes audio signals.
- (5) A mode data is sent to IC501.
- (6) The reel motor rotates in forward direction and the idler transfers rotational force to the T-reel table to wind the tape.
At the same time, the servo circuit controls the CTL pulse so that the reel motor rotates at the speed 7 times higher than the normal speed.

3-5. Record System Mode

3-5-1 Record mode (from stop mode)

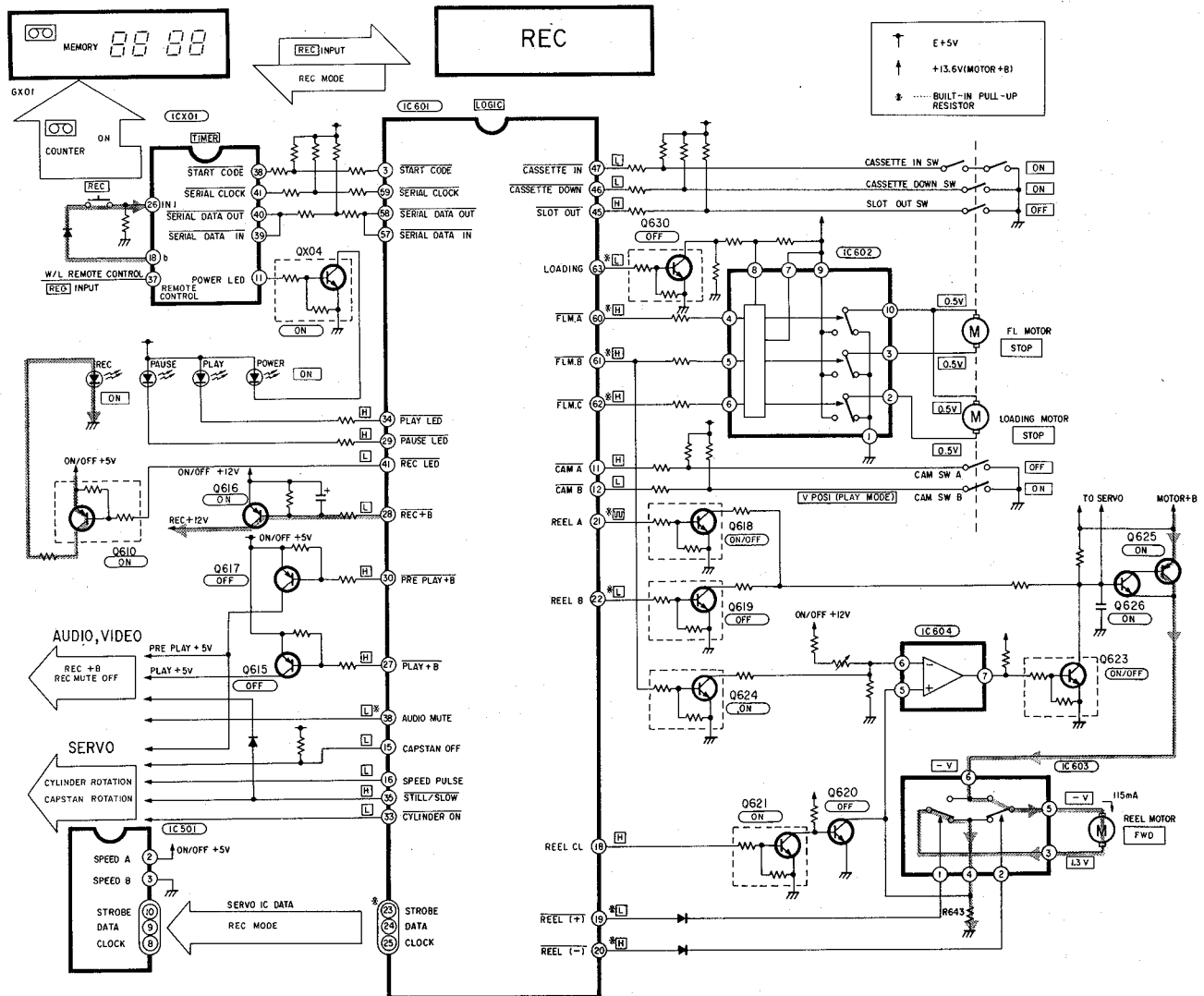


Fig. 3-5-1

- (1) When the REC button is pushed in the stop mode, ICX01 transfers the record input signal serially to IC601 and sets the record mode.
- (2) Pin (41) of IC601 develops "L" level and Q610 turns on.
The REC LED is also turned on.
- (3) The loading mode is set as mentioned in 3-4-1 (1) – (7).
- (4) Next, operations which are the same as those mentioned in the playback mode 3-4-2 (1) – (3) are performed and the tape is driven.
- (5) Pin (28) of IC601 goes "L" level and the REC + 12V is supplied to the audio, video, and the servo circuits, and the recording will be made.

3-5-2 Rewinding for synchronous editing

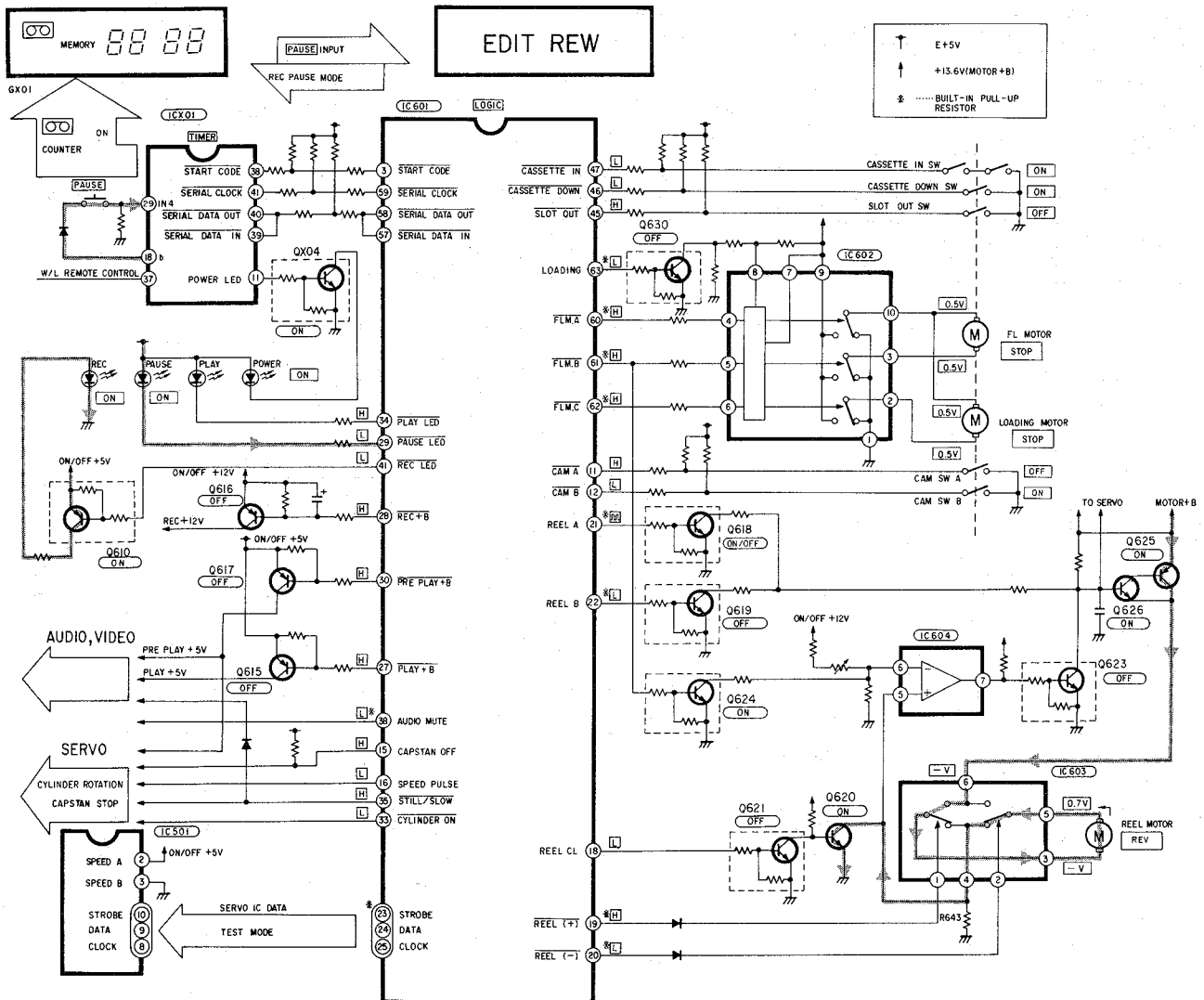


Fig. 3-5-2

- (1) When the PAUSE or STOP button is pushed during recording, IC601 is set to a record pause mode or the stop mode.
- (2) The loading motor rotates in forward direction and the cam moves from the position V to the position VI.
- (3) Each pin of IC601 develops output as shown in Fig. 3-5-2 and the record LED and pause LED light up. Pin ②⑧ develops "H" level output and Q616 turns OFF. Then the audio and video signals are muted.
- (4) The reel motor is rotated reversely by IC601 and IC603 (①⑦ - ①⑨). Tape is wound by a specified length equivalent to 100 CTL pulses and then the

- loading motor rotates in forward direction and the cam moves from the position VI to the position VII (②⑩ - ③②).
- (5) Next, the reel motor rotates in forward direction and winds the tape for a specified length and then the motor stops (③① - ③③). At the same time, the loading motor rotates in reverse direction, and the cam moves from the position VII to the position V.
- (6) Furthermore, loading motor rotates in forward direction and the cam moves from the position V to the position VII.
- (7) At the same time the reel motor rotates in forward direction and then the reel motor stops.

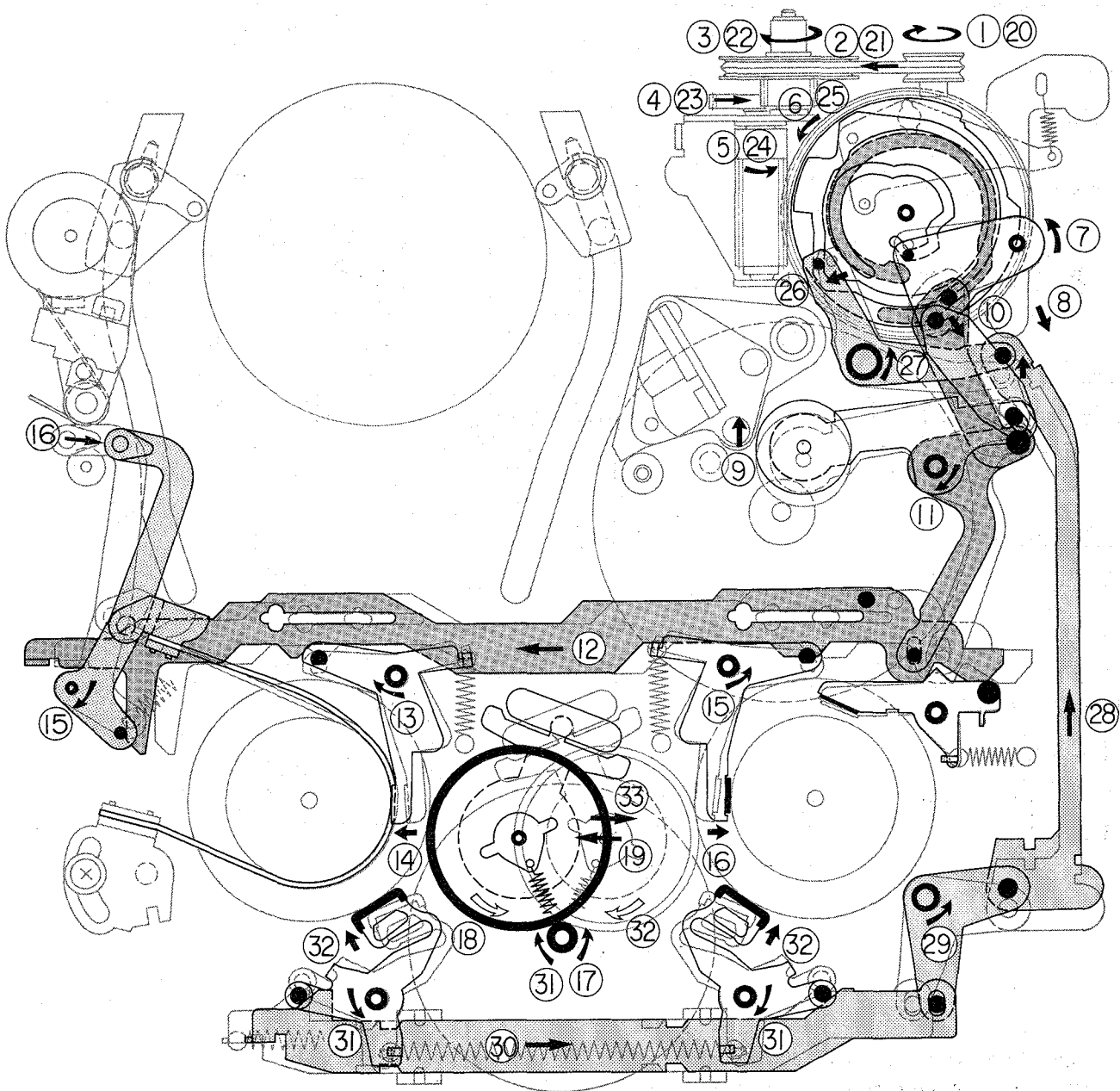


Fig. 3-5-3

3-5-3 Stop mode (from record to stop)

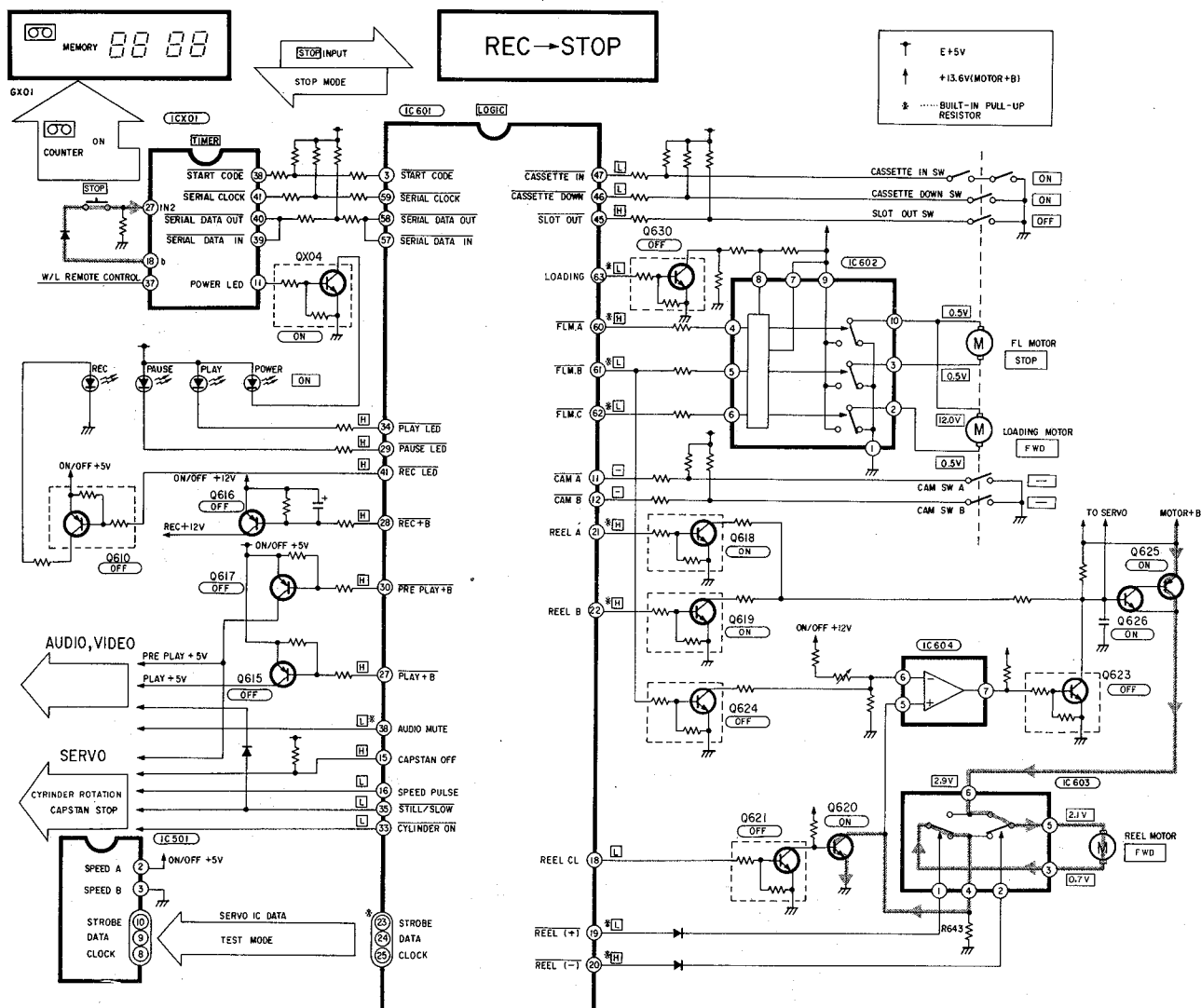


Fig. 3-5-4

- (1) When the STOP button is pushed during recording, the unit enters the stop mode after completion of temporary rewind operation for synchronous editing. The cam gear is in the REC pause mode (position VII).
- (2) The cylinder motor, reel motor, and capstan motor stops.
- (3) When the STOP button is pushed again, unloading operation starts and the cam moves to the position II. (Refer to the unloading operation.)

3-5-4 Record pause (PAUSE)

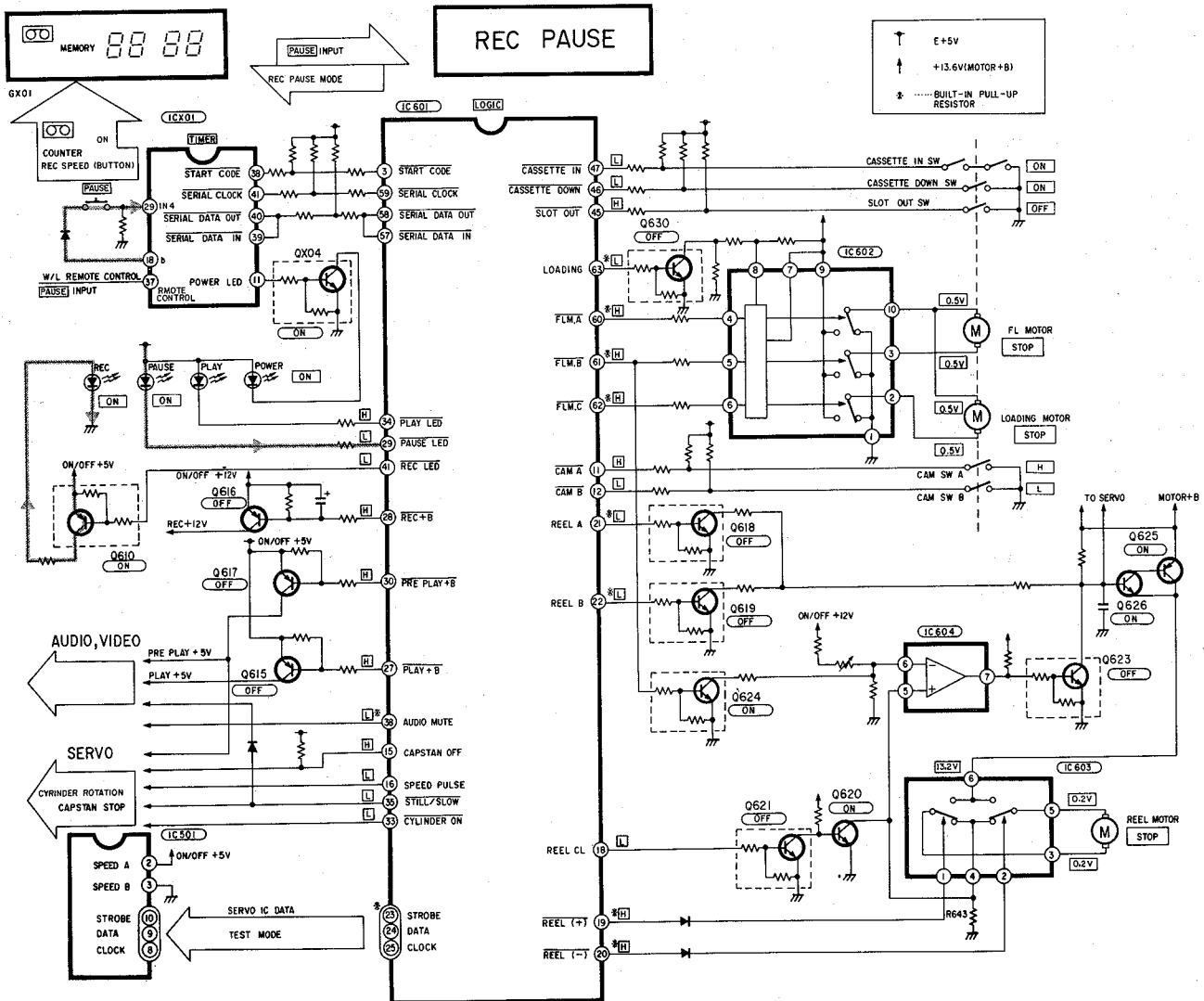


Fig. 3-5-5

- (1) When the PAUSE button is pushed during a recording, the unit enters the record pause mode after completion of temporary rewinding operation for synchronous editing.
In this case the cam gear is in the REC pause mode (position VII).
- (2) The cylinder motor rotates, and the capstan motor and the reel motor stop.
- (3) Each pin of IC601 develops outputs as shown above and the pause LED lights up.
Pin 28 develops "H" level output and Q616 turns OFF, and mutes the audio and video signals.

4. ELECTRIC CIRCUITS

4-1. Power Supply Circuit

4-1-1 Outline

The power supply circuit consists of the line filter circuit, power supply transformer, rectification circuits, voltage regulator circuits, heater power supply (3.6V AC) for the FL display tube, etc.

The major power supply output is divided into four systems: the first system supplies M + B (13.6V), + 12V (ON/OFF 12V), E 12V (EVER 12V) and H + B (HEATER + B); the second system + 9V (rectification output for 5V); the third system + 60V (rectification output for 32V and for bias in the power supply circuit) and; the fourth system -60V (rectification output for -30V) and -28V to the loads.

Furthermore, 3.6V AC is supplied from the power supply transformer as HEATER voltage for the FL tube.

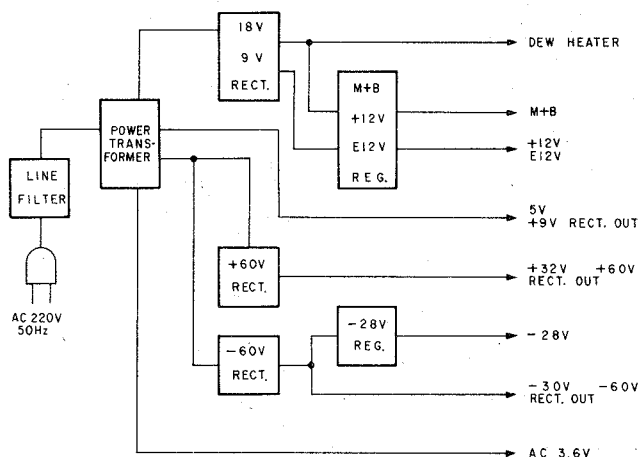


Fig. 4-1-1

4-1-2 Circuit description

1. Rectification circuit

The rectification circuit consists of three systems.

(1) The first system

The first rectifier system generates three rectification outputs.

AC voltage obtained from the first winding of the secondary windings of the power transformer is rectified and smoothed by the bridge rectifier circuit consisting of D801 - D804 and C805. The DC output of approx. 18V is supplied to the voltage regulator circuits for + 12V and E12V. The voltage developed across the same winding is rectified and smoothed by the bridge rectifier circuit consisting of D801, D802, D805 and D806 to obtain DC voltage of approx. 18V. The DC voltage is supplied to M + B voltage regulator circuit and DEW HEATER.

Finally, center tap output of the first winding on the secondary windings is rectified and smoothed by the full-wave rectifier circuit consisting of D801, D802 and C807. The resultant DC output of approx. 9V is supplied to develop 5V.

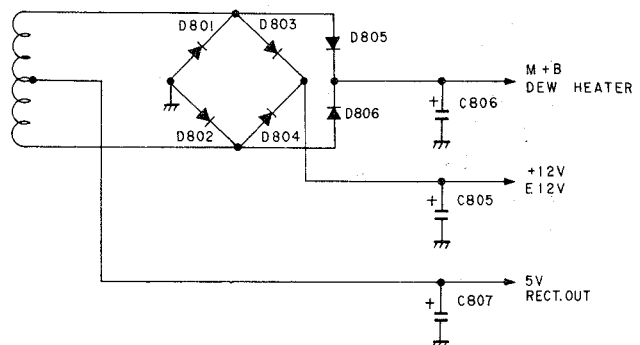


Fig. 4-1-2

(2) The second system

In the second system, AC voltage obtained from the second winding on the secondary windings of the power transformer is half-wave rectified and smoothed by D807 and C808 to obtain DC of approx. + 60V. The voltage is supplied as a bias for the + 32V regulator circuit and power supply circuit.

(3) The third system

In the third system, AC voltage obtained from the second winding on the secondary windings of the power supply transformer is half-wave rectified and smoothed by D808 and C809 to obtain DC of approx. -60V. The voltage is supplied to the voltage regulator circuits for -28V and -30V.

2. Voltage regulator circuits

(1) +12V voltage regulator circuit

The +12V voltage regulator circuit consists of the output transistor Q804, error amplifier transistor Q805, reference voltage zener diode D815 and error detection resistors R814, R815, and R851 etc.

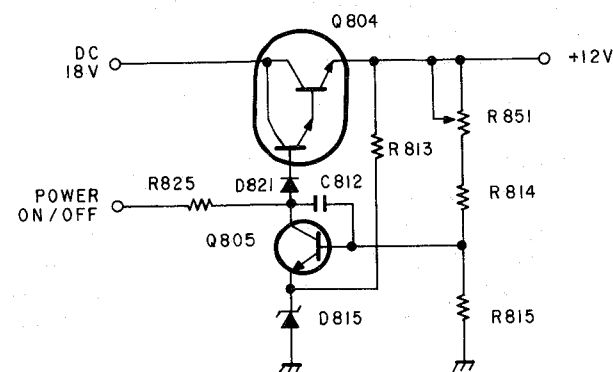


Fig. 4-1-3

When a bias is supplied from the power ON/OFF circuit through R825, Q804 turns on, supplying current to the zener diode D815 via R813 to generate reference voltage. Then the error amplifier transistor Q805 and error detection resistors R851, R814 and R815 detect error voltage between the reference voltage and the output voltage and control the output transistor Q804 so that it always maintains a constant output of 12V.

(2) M+B (13.6V) voltage regulator circuit

The M+B voltage regulator circuit consists of the output transistor Q802, error amplifier transistor Q803 and error detection resistors R811 and R812.

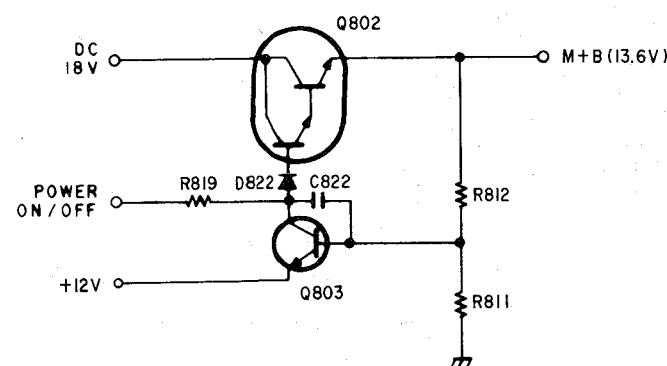


Fig. 4-1-4

When a bias is supplied from the power ON/OFF circuit through R819, Q802 turns on. The error detection resistors R811 and R812 detect fluctuation of the output voltage, and the error amplifier transistor Q803 controls the output transistor Q802 in such a way to maintain the output always at 13.6V.

(3) E12V voltage regulator circuit

The E12V voltage regulator circuit consists of the output transistor Q806, zener diode D817 for the reference voltage, etc.

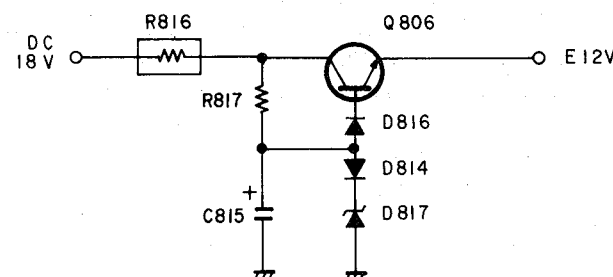


Fig. 4-1-6

18V DC rectification output is supplied to the collector of the output transistor Q806 via the fuse resistor R816 and also to the zener diode D817 for the reference voltage via R817, obtaining output of 12V.

(4) -28V voltage regulator circuit

In the -28V voltage regulator circuit, -60V rectifier output is stabilized into -28V by zener diodes D809 and D810 via R802.

(5) DEW HEATER switch circuits

DEW HEATER is controlled by the switching transistor Q801.

The switching transistor Q801 is controlled by the two control signals (DEW HEATER ON, POWER ON/OFF). +18V rectification output is applied to DEW HEATER and Q801 base (as the bias).

Power OFF:

Q801 base is biased from +18V rectification output and the DEW heater is turned on.

Power ON:

(When the cylinder is in stop.)

Power ON/OFF signal turns on Q807 (on POWER 2 unit) and this cut off the base bias from +18V rectification output to Q801 base.

However, the DEW heater ON signal turns to "H" and this turns on Q801, so the DEW heater is turned on.

(When the cylinder is rotating)

The DEW heater ON signal turns to "L" and Q801 turns off, so the DEW heater is also turned off.

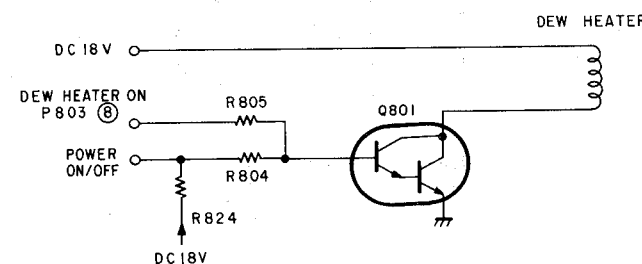


Fig. 4-1-5

(6) Protection circuit

The protection circuit consists of the zener diode D819 for output voltage detection and switching transistors Q808 and Q810.

Q808 base is always supplied with bias from 18V DC via R824 when the power is turned off, or from M+B via R820 when the power is turned on, thus maintaining Q808 at ON and Q810 at OFF.

If the output of M+B or +12V is short-circuited to the GND etc. and M+B lowers to a value less than the operating voltage of D819, D819 is cut off and Q808 turns off supplying no bias to the Q801 base.

Accordingly, a bias is supplied to the Q810 base via R818 turning Q810 on and turning off the bias for the M+B and +12V circuits, thus cutting off the M+B and +12V outputs.

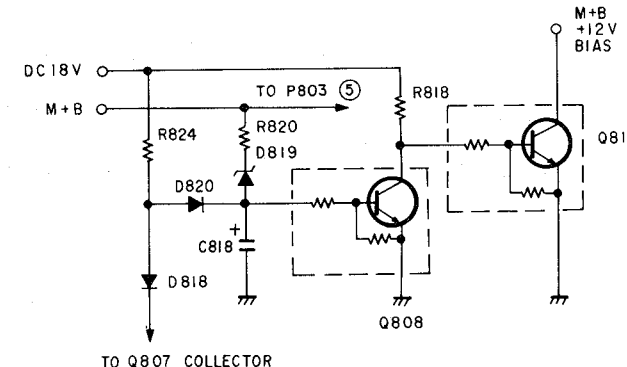


Fig. 4-1-7

4-1-3 TIMER 2 Circuit

(1) Back up +B regulator circuit

EVER 12V supplies a current to zener diode DL10 in passing through a current limiting resistor RL16 and a reverse current protection diode DL12, and the DL10 develops 5V reference voltage.

At the same time, EVER 12V charges capacitor CL10 through the resistor RL14.

If EVER 12V is not applied due to a power failure, etc., the capacitor CL10 supplies the charged electricity as the Back +B through the diode DL13.

(2) Timer reset circuit

Timer reset circuit consists of the reset IC ICL10 (PST520C) and resistor RL10.

ICL10 detects the Back Up +B and generates a reset signal at the time of rising of the Back Up +B at power failure.

(3) -30V voltage regulator circuit

-60V from the power supply enters the zener diode DL11 (05Z30Y) via resistor RL18 for current regulation, generating voltage of -30V.

(4) ON/OFF 5V regulator circuit

ON/OFF 5V is generated by turning on or off EVER 5V with the switching transistors QL11 and QL12 controlled by signal (POWER ON) from pin ⑥ of the connector PL02.

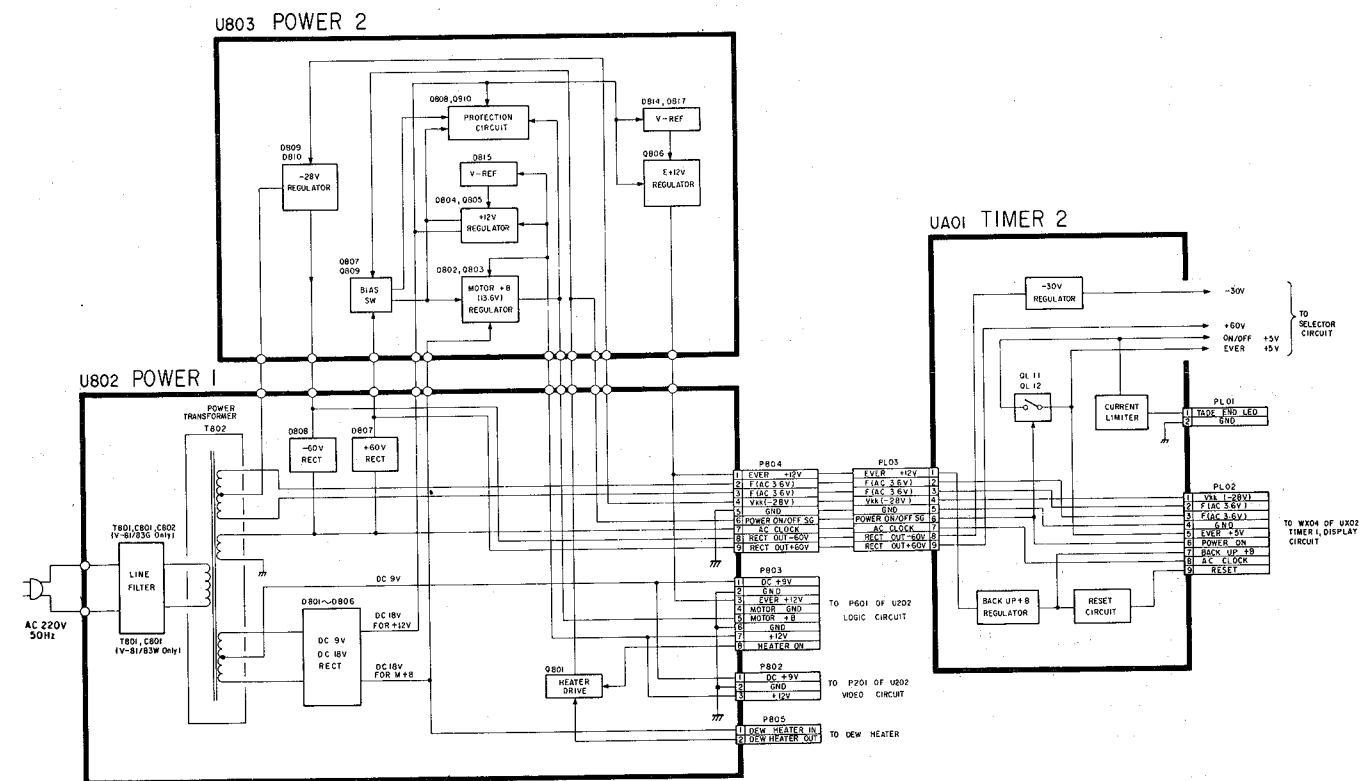


Fig. 4-1-8 Power supply block diagram

4-2. RF and Receiving Circuit

4-2-1 Outline

- 1) The receiving circuit consists of an ANT input/output circuit, channel selection circuit, PIF and SIF circuits. The receiving circuit selects a desired broadcast signal from TV signals induced on an antenna and sends stable video signal and audio signal obtained by processing program signals to the video and audio circuits.
- 2) The output signals from the video and audio circuits are converted to a conventional TV signal for the channel 31 to 39 with an RF modulator so that it can be received by conventional TV receivers.

4-2-2 ANT input & output circuits

- 1) In this VTR the RF signal splitter, mixer and the RF modulator have been structured as an integrated unit.
- 2) The RF splitter splits TV input signals from the antenna into two: and send one of them to the tuner's RF input terminal and another to the mixer.
- 3) The RF splitter output and the RF modulator output are mixed in the mixer circuit, and the resultant output is used as an RF output. To discriminate the RF modulator output from an antenna input signals a test signal generator has been provided in the modulator. The modulator has been designed so that its output channel can be varied with a control VC to prevent the antenna signals from interference.

4-2-3 PIF, SIF Circuits

- 1) TV signals from the antenna input circuit are fed to the tuner, and the tuner develops the IF signal corresponding to the channel selected by the channel selector circuit.
- 2) The IF signal passes the IF filter (surface acoustic wave filter) and enters pins ①, ⑩ of IC002 (TA7607AP).
- 3) The IC002 amplifies and detects the IF signal, and the resultant video signal is output from pin ⑫.

V-81/83G Only

- 4) One part of the output passes through 5.5 MHz trap circuit and the buffer of Q004, then applied to the video circuit.
- 5) Another part of the output enters pin ② of IC006 (TA7337P) in passing through 5.5 MHz BPF. The IC006 detects the 5.5 MHz FM signal to obtain audio signal. The audio signal is output from pin ⑨ and sent to the audio circuit.

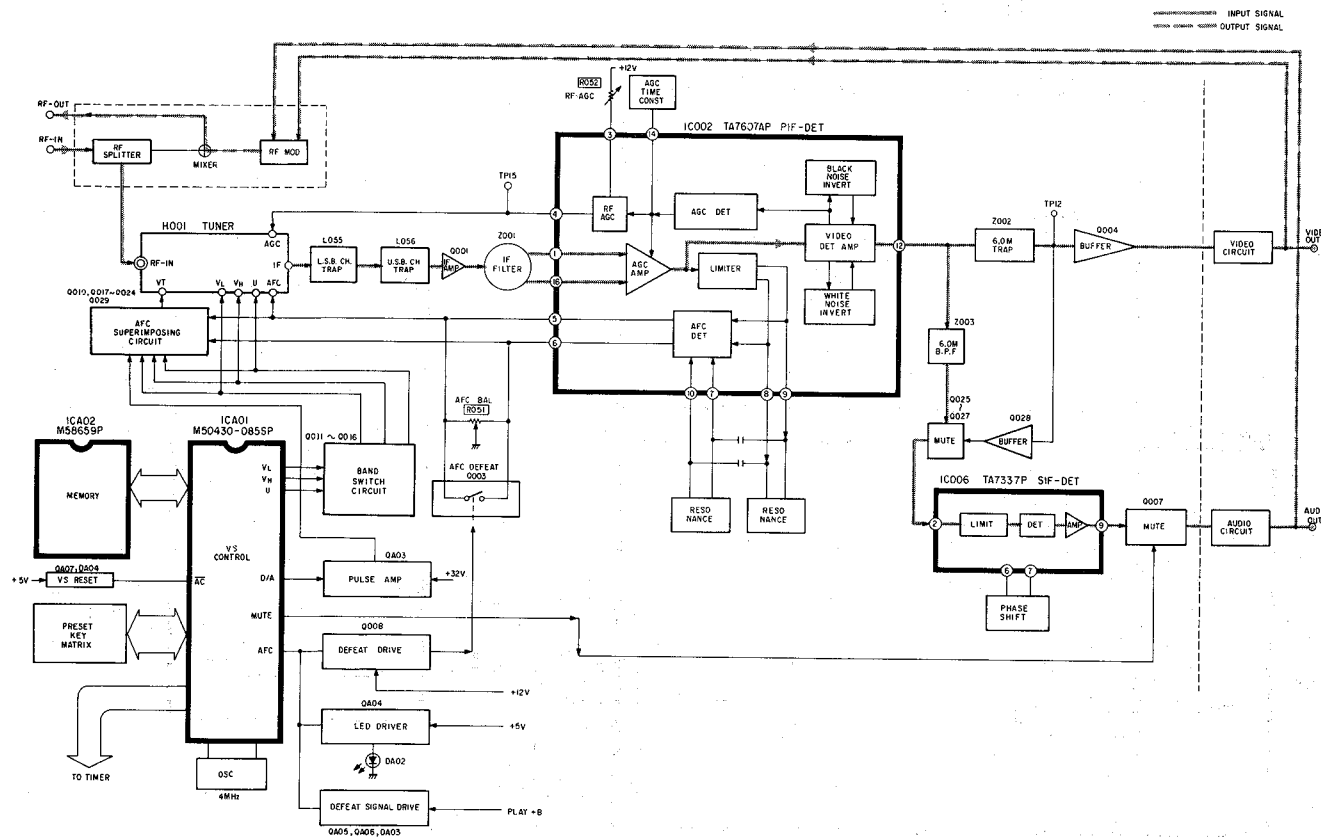


Fig. 4-2-1 PIF, selector block diagram (81/83G model)

V-81/83W Only

- 4) One part of the output is applied to the video circuit in passing through 5.5 MHz trap circuit, SYNC UP circuit, and Q003 buffer. In the SYNC UP circuit, the sync signal is separated with a diode D002 connected to emitter side of Q008 and a capacitor C032, and then the sync section of a video signal suppressed in detection process is expanded properly in IC002, thus the sync level is being corrected.
- 5) Another part of the output enters pin ② of IC005 (TA7337P) in passing through 5.5 MHz BPF. The IC005 detects the 5.5 MHz FM signal to obtain audio signal. The audio signal is output from pin ⑨ and sent to the audio circuit.

4-2-4 Channel selection circuit

(1) Outline

The channel selection circuit employs a voltage synthesizer (VS). The VS circuit consists of a memory circuit, ICA02 and a VS microcomputer, ICA01. Various information such as band selection & tuning voltage data required for channel selection, data for AFC defeat, and audio muting are transferred serially between the timer microcomputer and the PIF circuit as well as other display data are sent to the timer circuit.

(2) Functions

1) Channel pre-setting mode

The VS microcomputer sends real channel data relating to a band data and a tuning voltage data obtained from the key matrix to the memories to keep the information. The VS microcomputer also sends the same kind of data to the timer circuit to display the information on the FL display tube.

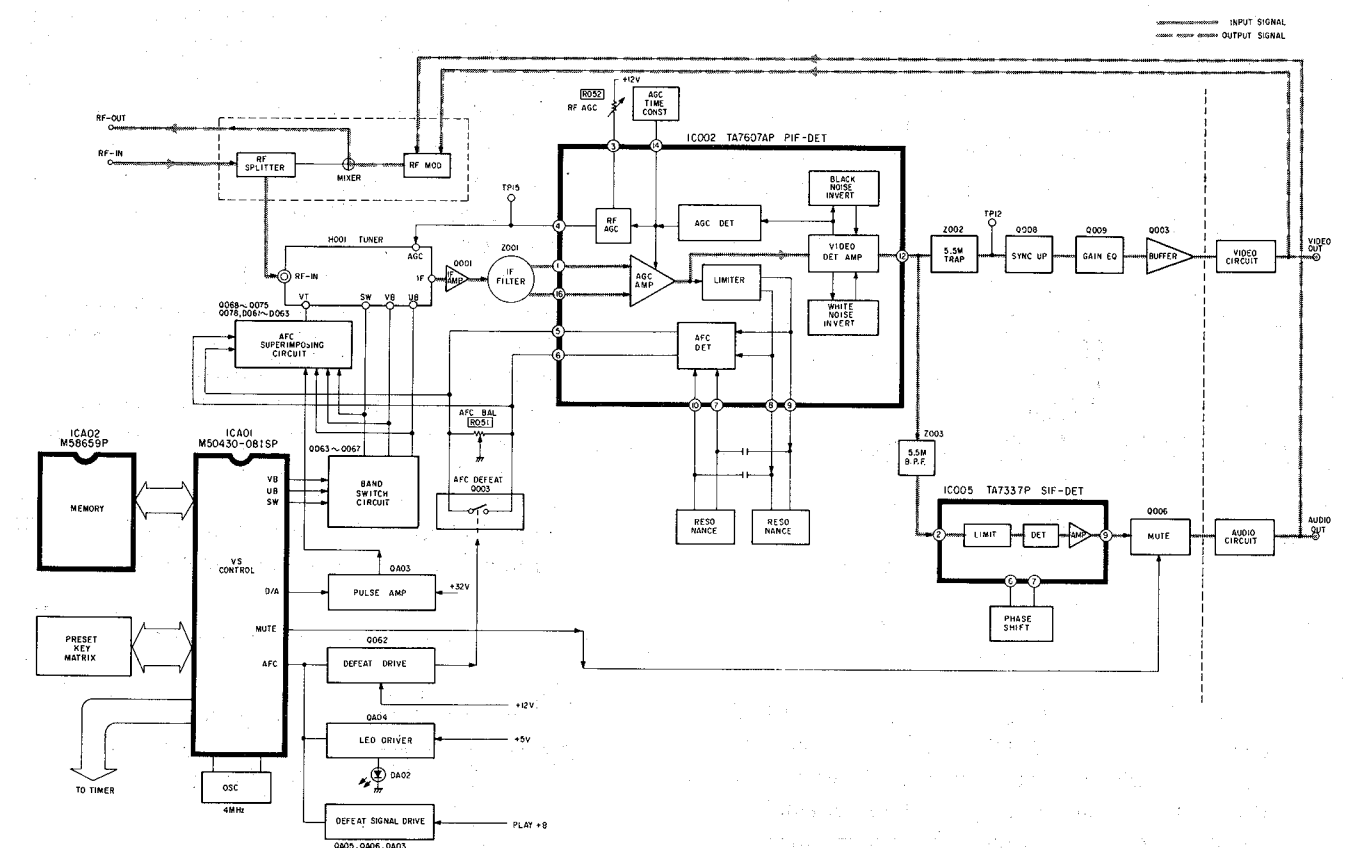


Fig. 4-2-2 PIF, selector block diagram (81/83W model)

(V-81/83G model)

Table 4-2-1

Band	Microcomputer terminal		
	LB	HB	UB
VL	H	L	L
VH	L	H	L
U	L	L	H

Table 4-2-2

Band	Tuner terminal		
	LB	HB	UB
VL	12V(H)	0V(L)	0V(L)
VH	0V(L)	12V(H)	0V(L)
U	0V(L)	0V(L)	12V(H)

(): Microcomputer

(V-81/83W model)

Table 4-2-3

Band	Microcomputer terminal		
	VB	UB	SW
VL	H	L	L
VH	H	L	H
U	L	H	L

Table 4-2-4

Band	Tuner terminal		
	VB	UB	SW
VL	12V(H)	0V(L)	23V(L)
VH	12V(H)	0V(L)	0V(H)
U	0V(L)	12V(H)	23V(L)

(): Microcomputer

2) Conventional reception mode

- In a conventional channel selecting operation, a channel data is read out from a memory with a channel position data sent from the timer circuit and the data is transferred to the timer section circuit. Furthermore, a band voltage and a tuning voltage of the channel are sent to the PIF section.
- The band data is output through pins ⑳, ㉑, ㉒. They are indicated in Tables 4-2-1 and 4-2-2.
- The tuning voltage is a pulse signal modulated in 14 bit format and developed at pin ⑱. The tuning voltage is amplified by QA03 and then converted into a DC voltage in passing through a filtering network consisting of RA04, RA05, RA06, CA03, CA04, and CA05. Thus developed DC voltage is applied to VT terminal of the tuner.
- Since noises occur at the time of channel switching, an audio muting pulse from pin ㉑ is applied to the switching circuit of Q007 (V-81/83G) or Q006 (V-81/83W) to eliminate the noises.

Pin ㉑ develops an AFC defeat pulse at the time of channel switching, and the pulse triggers the switching circuits of Q008 and Q003 (V-81/83G) or Q062 and Q061 (V-81/83W) which turn off the AFC at the moment of channel switching, thus preventing erroneous operation of the AFC.

(3) Channel setting with AFC off

When a channel setting is required with the AFC off, push the tuning buttons (+) and (−) in the conventional receive mode, and that position can be memorized with the AFC turned off. In this case, QA04 turns on and LED DA02 lights up.

When releasing, set the CH setting mode and resume the normal receive mode. (V-81/83G)

When releasing, set the CH setting mode and resume the normal receive mode after pushing the tuning buttons (+) and (−). (V-81/83W)

4-3. Timer, Display Circuit

4-3-1 Outline

- 1) These circuit include various functional circuits such as the timer, channel selection, electronic counter, remote control light signal reception and the logic switch circuits etc., and consist of a microcomputer (TMP47C410AN-6775) playing primarily roles in these circuits, FL display tube (FIP8BLM7 for V-81/83G or FIP8YM7 for V-81/83W) indicating time counted value, channel, cassette, etc.; operation key matrix and the remote control light signal reception circuit. These circuits are used to perform following functions; time count, timer recording channel selection, key input reading, information reading from a wireless remote control unit etc.

4-3-2 Different features from conventional models

- 1) Conventionally used three microcomputers, each of which is relating to a timer, sublogic and main logic circuits respectively, are replaced by two microcomputers (timer, logic circuit) which also perform operations conducted by the sublogic microcomputer so far.
- 2) As new features, auto power on and auto play functions are added.

4-3-3 Functions

- (1) **Clock**
 - 1 24 hours digital clock
 - 2 50/60 Hz automatic switching
- (2) **Programmable timer**
 1. 4 programs in 14 days
 2. Every day, every week or every day (Sun. through Sat.)
 3. One touch timer recording (Max. 4 hours)
 4. Reserved program confirmation using the confirmation key
- (3) **Channel selection**
 1. Real channel display in 16 positions of 0 through 99.
 2. Two button UP & DOWN system
 3. Band and channel position indication in preset mode (Time display is switched for this indication)
- (4) **Electronic counter**
 1. 4 digit indication in FL display tube (Time display is switched for this indication)
 2. (Count operation is performed in the logic micro-computer)
- (5) **Input data reading**
 1. Data reading from key switches on the unit
 2. Data reading from the wireless remote control
- (6) **Additional functions**
 1. Auto power on (Inserting a cassette turns the power on automatically.)
 2. Auto play (Playback operation automatically starts after completion of tape rewind operation.)

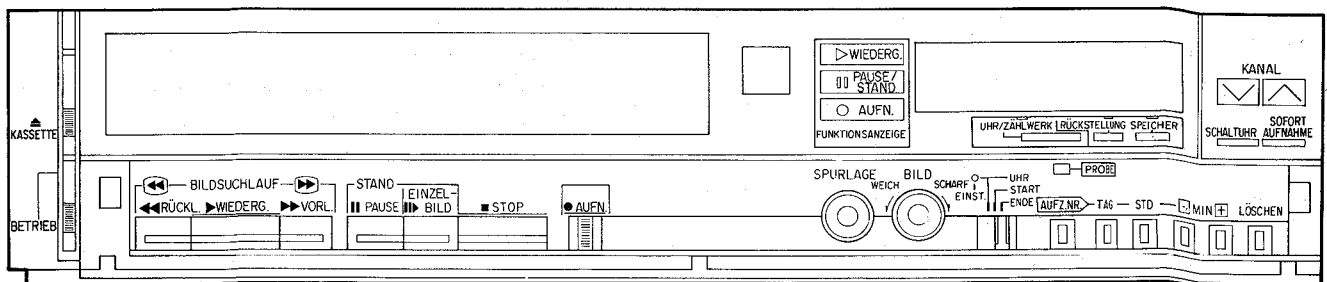


Fig. 4-3-1 Operation keys

4-3-4 Theory of operation

(1) Operation keys

As can be seen in Fig. 4-3-1, 24 push switches and 1 slide switches are used to control the timer, channel selection, logic mode, counter, and the power of the unit. In addition to this, wireless remote control codes are read through pin ③⑦.

(2) Clock

- 1) The AC clock signal (utility power frequency) supplied from the power transformer is first wave-shaped by the wave-shape & clamp circuits (DX01) and then applied to pin ③⑤ of ICX01, timer microcomputer through the buffer (QX02).
- 2) The clock operates in synchronization with this clock signal.
The microcomputer discriminates 50 Hz and 60 Hz and automatically takes required operations.

(3) Channel selection

- 1) Channel selection is performed by the channel UP and DOWN keys on the unit.
- 2) The channel selecting operation is conducted inside the ICA01 (M5043-85SP for V-81/83G or M50430-81SP for V-81/83W) on the SELECT P.C.

board. The ICA01 controls four bus lines for serial data transmitting. The ICX01 transmits a channel position data relating to the channel selected to ICA01, and the ICA01 transmits a real channel data and a band data to the ICX01, thus allowing the FL display tube to indicate the channel selected (0 - 99).

(4) Serial transmission

- 1) Data of 4 bits x 16 words are transmitted serially from or to the main logic circuit. This data transmission is performed eight times for every cycle of 30 msec starting from ICX01, IC601, ICX01, ... alternately in this sequence.
- 2) When ICX01 develops first output, the start code is set to "L" and after the reception of first transmission from the IC601 the start-code is set to "H".
- 3) In this serial transmission, the ICX01 transmits input key codes, power on, auto play, counter memory, counter values, etc. to the IC601, and the IC601 transmits power on off signal, logic mode signal, counter values, etc. to the ICX01.

(5) Electronic counter

- 1) Operation of the electronic counter is conducted inside IC601.
Counted values are transmitted serially and the content is displayed on the display tube.

(6) FL display tube

- Time, content of timer reserved programs, or a counter value is switched and displayed.
- Furthermore, cassette, counter memory, and a real channel selected are displayed.
- A dynamic drive system which lights up each digit segment sequentially with grid pulses and segment pulses sent from the microcomputer is employed in the FL display tube.
- The FL display tube is of triode type and lights up when both of the grid voltage E_c and the plate voltage E_b become +27V against the filament center voltage (-22V).
- To turn off the display tube, E_c or E_b must be lowered to 6V below the filament voltage.

(7) Power failure compensation

- 1) When power failure occurs, content of reserved programs, etc. will be maintained if the failure is resumed within 0.5 sec.
The display tube turns off during the power failure but its colon will blink after the failure is resumed.

(8) Additional function

- 1) **Auto power on**
Loading a cassette turns the power on automatically, if the power is turned off.
- 2) **Auto play**
When the PLAY key is pushed with the REW key during rewind operation, the auto PLAY mode is set and the playback LED blinks. And the PLAY mode is automatically set when the rewind operation completes.
The auto play mode does not work with the wireless remote control unit.

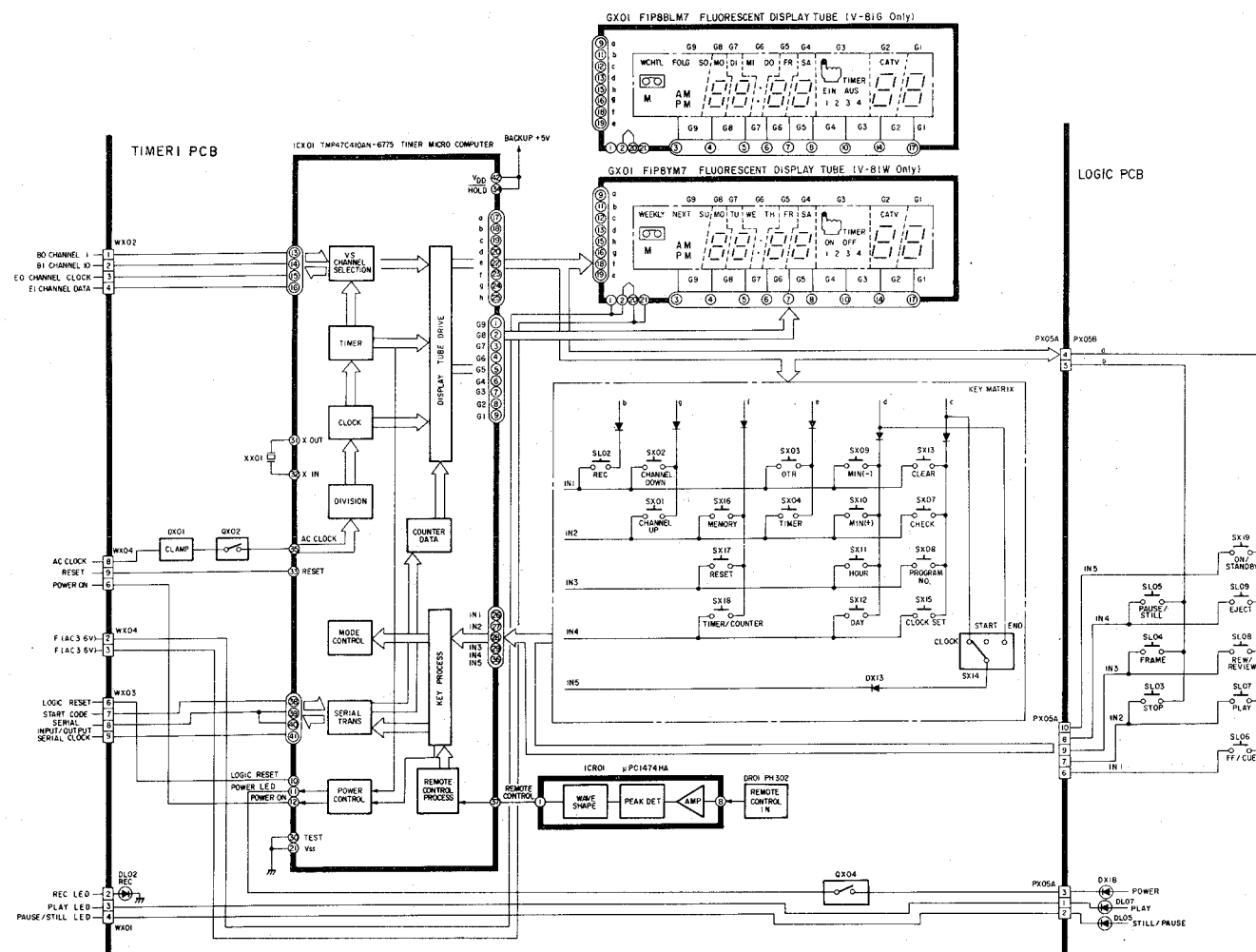


Fig. 4-3-2 Timer, display block diagram (81G/W model)

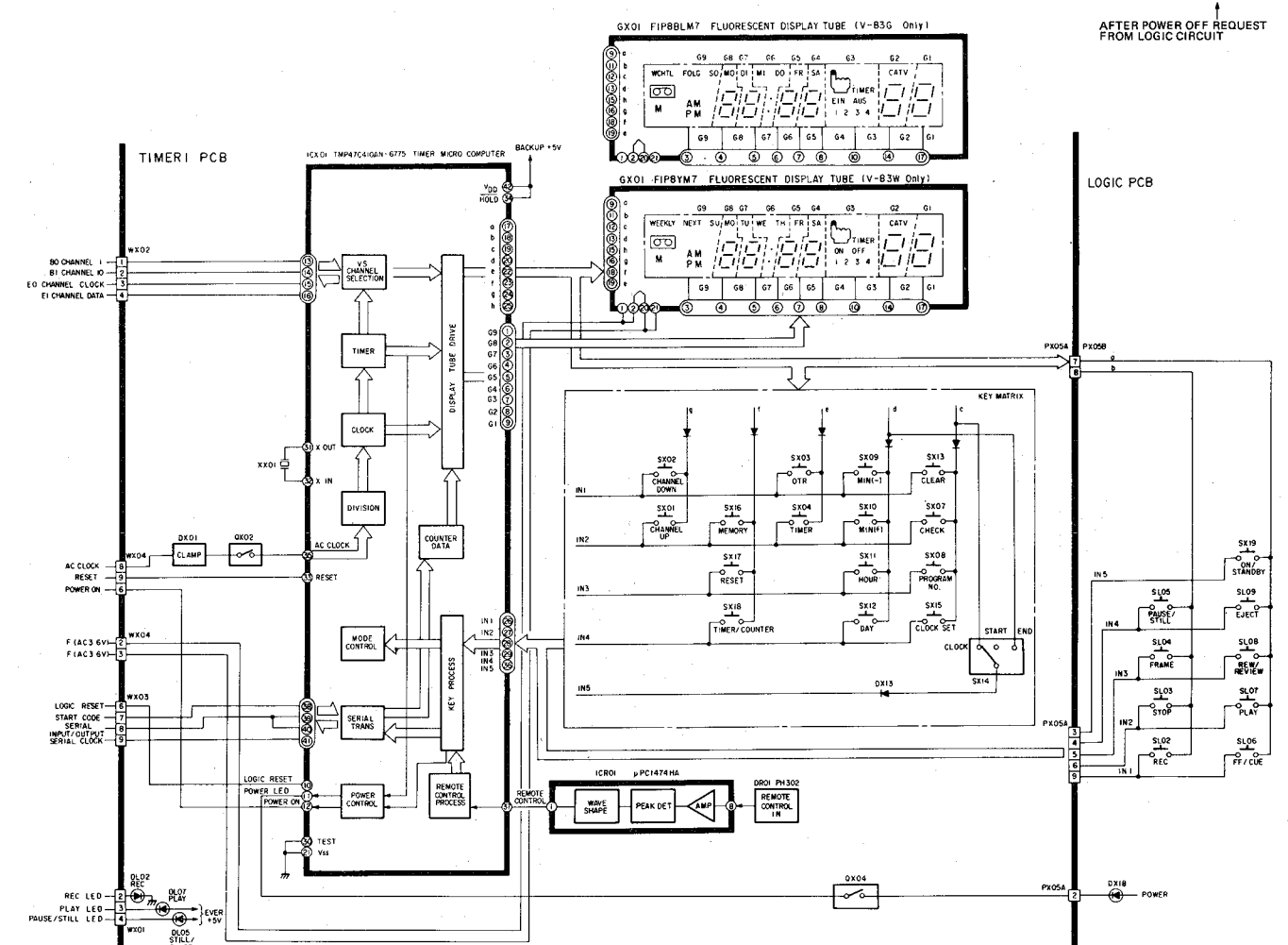


Fig. 4-3-3 Timer, display block diagram (83G/W model)

4-4. Logic Circuit

4-4-1 Outline

1) The logic circuit consists of two microcomputers TMP4746N5759 (for system control . . . hereafter called logic microcomputer) and TMP47410AN6775 (for button operation, remote control processing, etc. . . hereafter called timer microcomputer); main unit which performs the system control; timer unit which controls each mode operation and the LED indication; and the logic switch unit.

2) Mechanism control for each mode is conducted with a cam system. A slot-in mechanism is employed for tape loading. Controls for these mechanisms are performed by the electronic logic operations using the microcomputers stated above.

3) Fig. 4-4-1 shows the system block diagram of the logic circuit.

4-4-2 Functions

1) Mode operation

Fig. 4-4-3 shows a mode shift diagram. Operation of each button is accepted through the routine shown in Fig. 4-4-2. During the mode shift operation, IC601 performs the system control as follows:

1) Determines an operation mode by analyzing input signals from the operation button(s) and sensor switches provided to detect abnormal operation, etc.

2) Performs the mode LED display and the counter control and sends the counted value to ICX01.

3) Controls servo systems (servo IC, cylinder motor and capstan motor).

4) Controls audio and video systems (mode +B, and muting signals)

5) Controls the loading motor to set a desired cam position, thus controlling the mechanism system. (Output: pins 60, 61, 62, 63 of IC601) (Input: pins 11, 12 of IC601)

6) Controls the reel motor.

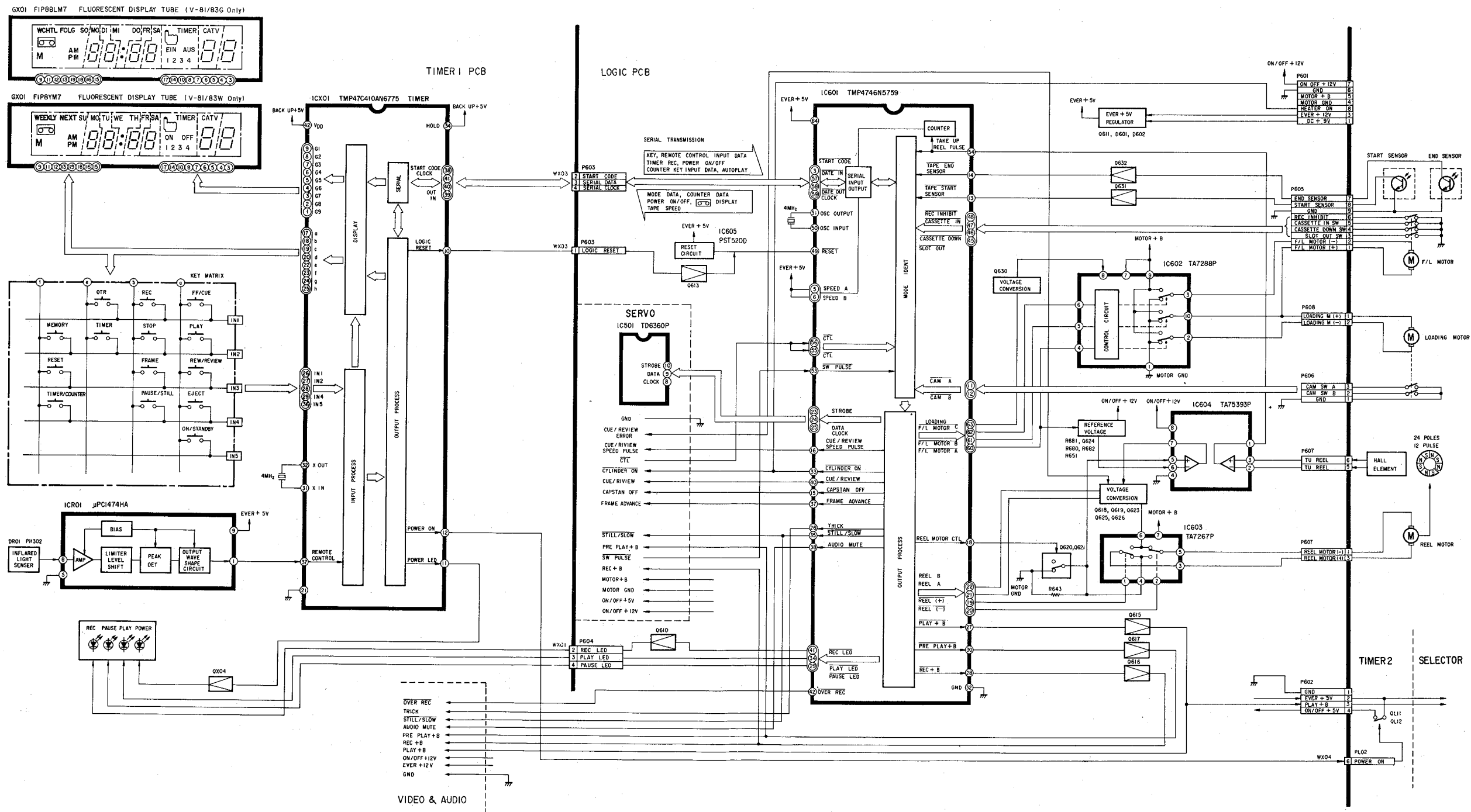


Fig. 4-4-1 Logic circuit system block diagram

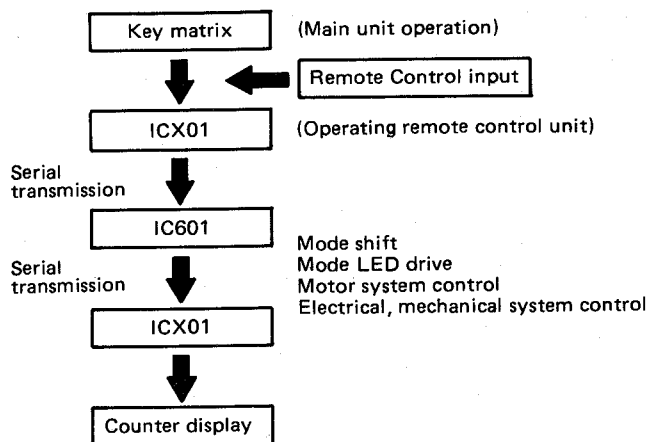


Fig. 4-4-2 Mode shift

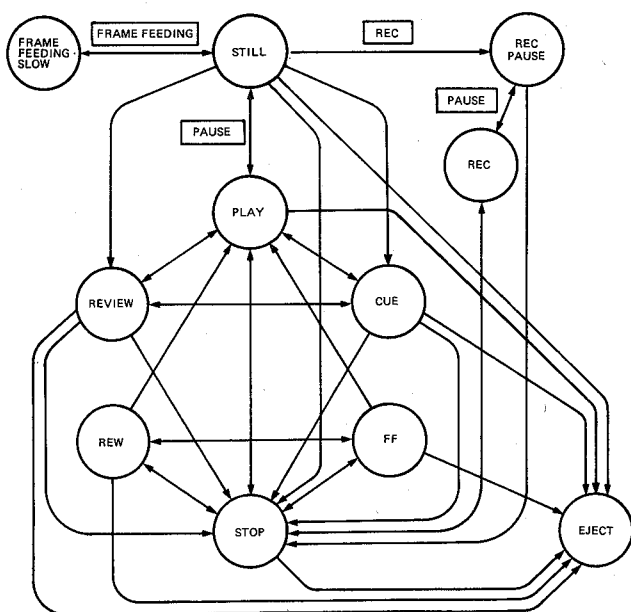


Fig. 4-4-3 Mode shift diagram

(2) Slot mechanism control

Input : Pins ④⑤, ④⑥, ④⑦, ①③, ①④ of IC601

Output: Pins ⑥①, ⑥② of IC601

- 1) During cassette loading or unloading operation, IC601 checks status of three FL-SW (cassette in ④⑦, cassette down ④⑥, and slot out ④⑤) and controls the FL motor.
- 2) IC601 also checks status of tape end sensors (tape start sensor ①③ and tape end sensor ①④) after the packet is moved down and performs the eject operation if no cassette is loaded.

(3) Loading mechanism control

Input : Pins ①①, ①② of IC601

Output: Pins ⑥①, ⑥②, ⑥③ of IC601

- During loading, unloading or cam position transitional period, IC601 checks status of the cam switches (Cam A ①①, Cam B ①②) and controls the loading motor.

(4) Tape end detection (tape start)

Input : Pin ①③ of IC601

- 1) When tape start position is detected in a rewind mode or review mode, the rewind operation is stopped and a short length of tape is wound in forward direction.
- 2) When tape start position is detected in a forward mode, a short length of tape is rewound and then the unit enters that mode.

(5) Tape end detection (tape end)

Input : Pin ①④ of IC601

- When the tape end is detected during forward modes such as playback, recording, etc., the tape is automatically rewound.
- (In the timer recording mode, the rewind operation is not performed but the unit enters the stop mode and the power is automatically shut off.)

(6) Accidental erase prevention

Input: Pin ④⑧ of IC601

- If a cassette with its safety tab removed is loaded, the record mode can not be set, and when the REC button is pushed the cassette is automatically ejected.

(7) Timer recording

Input: Serial transferring

- The timer recording mode is set with the timer recording input sent from the timer microcomputer, ICX01.

(8) Synchronous editing

- After completion of the following mode change operations (from record to stop or record pause; from still to record pause or timer record), tape is slightly rewound to allow overlap recording for that area.

(9) Counter memory

- When fast forward or rewind operation is performed with the counter memory mode actuated, the VTR stops automatically when the counter reaches "0000". To increase stop position accuracy of the tape, output from pin ②① of IC601 is controlled in terms of PWM so that the rotating speed of the reel is slow down at a location preceded by 200 count pulses from the zero stop position.

(10) Auto play

- 1) When the PLAY button is pushed with the REW button during rewind mode, auto play mode is set and the playback LED blinks at a rate of 1 Hz.
- 2) If the counter memory mode is set, playback mode is automatically set after the zero stop operation.
- 3) The playback operation starts automatically after detection of a tape start position.

(11) Auto power on

- When a cassette is newly loaded under the power off condition, the power is automatically turned on and the cassette is slotted in and loaded.

(12) Audio muting

Output: Pin ③⑧ of IC601

- Audio signals are muted during the frame, still, and picture search operations.

(13) Automatic mode release

- To protect tape from damage the still, slow, or the record pause mode is automatically released after a specified time elapsed as shown in Table 4-4-1 below.

Table 4-4-1 Automatic mode release time

Mode	Released after:	Mode after released
Still/Frame	Approx. 5 min.	Playback
Rec · Pause	Approx. 10 min.	Stop

(14) Abnormal reel rotation detection

Input: Pins ⑤④ of IC601

- If rotational pulses from the take-up reel do not enter for a specified period determined for each mode as shown in Table 4-4-2, IC601 assumes there may be some troubles in the mechanism, etc. and sets the stop mode.

If abnormality is detected during timer recording, the power is automatically turned off.

Table 4-4-2 Reel abnormal rotation detection time

Modes	Detection time
FF	Approx. 2.5 sec.
REW	Approx. 3.5 sec.
CUE	Approx. 2.5 sec.
Review	Approx. 10 sec.
PLAY	Approx. 2.5 sec.
Frame	Approx. 90 sec.
REC	Approx. 2.5 sec.
Unloading	—

(15) Abnormal cylinder rotation detection

Input: Pin ⑤③ of IC601

- If switching pulse input does not vary for approx. 3 seconds with the cylinder motor rotating, the VTR enters the stop mode. However, when abnormality is found during timer recording, the power is shut off.

(16) Motor protection

Provisions for motor protection is provided as shown in Table 4-4-3.

Table 4-4-3 Motor protection function

Mode	Abnormal operation	Abnormality detection time	Operation made shifts to:
Slot in	Cassette in SW Off.	Approx. 0.5 sec.	Slot out
	Cassette does not move down.	Approx. 3 sec.	Slot out
Slot out	Cassette does not move out.	Approx. 3 sec.	Slot in
Slot in after abnormality detection in slot out operation.	Cassette does not move down.	Approx. 3 sec.	Power turned off after FL motor was stopped.
Loading	Cam does not move to its correct position.	Approx. 10 sec.	Power turned off after loading motor was stopped.
Unloading	Cam does not move to its correct position.	Approx. 10 sec.	Power turned off after loading motor was stopped.

4-5. Servo Circuit

4-5-1 Outline

- (1) In the servo circuit, a digital servo IC (TD6360P) functions a primary role and controls the cylinder motor and the capstan motor. The servo circuit performs functions as shown below.
 - 1) Controls rotating speed and phase of video head Cylinder servo circuit
 - 2) Controls tape speed at a specified value so that the video heads can precisely trace tape patterns in playback operation. Capstan servo circuit
 - 3) Drives the tape at speed of seven time the normal speed Reel servo circuit
 - 4) Noise shifting Capstan pulse drive
 - 5) Vertical sync separation circuit, various amplifier circuits.
 - 6) Controls synchronous editing.

4-5-2 Servo IC

- (1) The servo IC, TD6360P is a 42 pin shrink type IC which has been newly developed with following functions:
 - 1) Cylinder system processing circuits: phase detection, speed detection, reference signal generation
 - 2) Capstan system processing circuits: phase detection, speed detection, reference signal generation
 - 3) Built-in Schmitt amplifiers for input signals (PG, FG, CTL).
 - 4) Cylinder fh correction circuit.
 - 5) Built-in control record current source.
 - 6) Synchronous editing function
- (2) Pin configuration is almost the same as that of TD6314P, but differs in that the function 4) shown above was added and the mode designation is conducted by serial data inputs to pins ⑧ - ⑩.

4-5-3 Cylinder servo circuit

The cylinder servo circuit controls rotational speed and phase of the video heads so that video signals can be recorded on specified video track correctly in the record mode and the heads can precisely trace on the recorded patterns in playback mode.

(1) PG and SW pulse generation circuits

- 1) The PG pulse is created by detecting rotation of the PG magnets mounted on the lower part of the cylinder with the fixed PG heads. When the servo is locked, the PG pulse is set approx. 0.9 msec before head switching point. Fig. 4-5-2 shows the block diagram and Fig. 4-5-1 shows the timing chart.

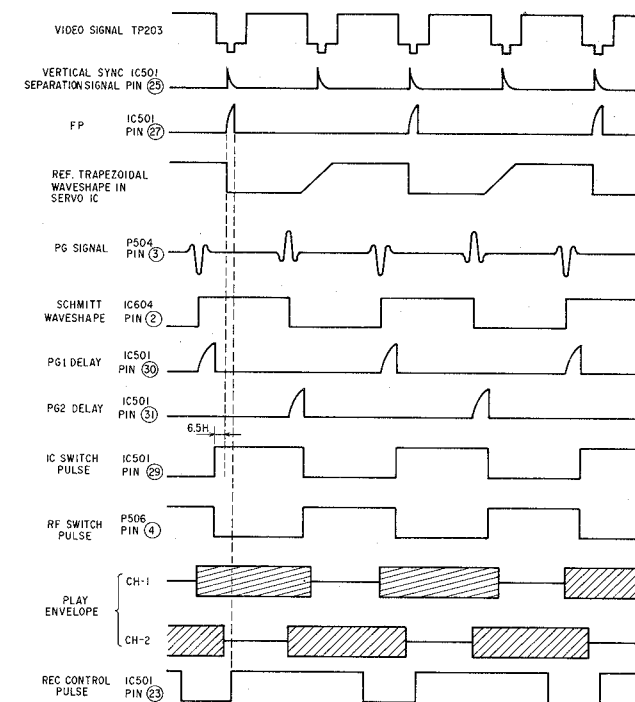


Fig. 4-5-1 Cylinder servo timing chart

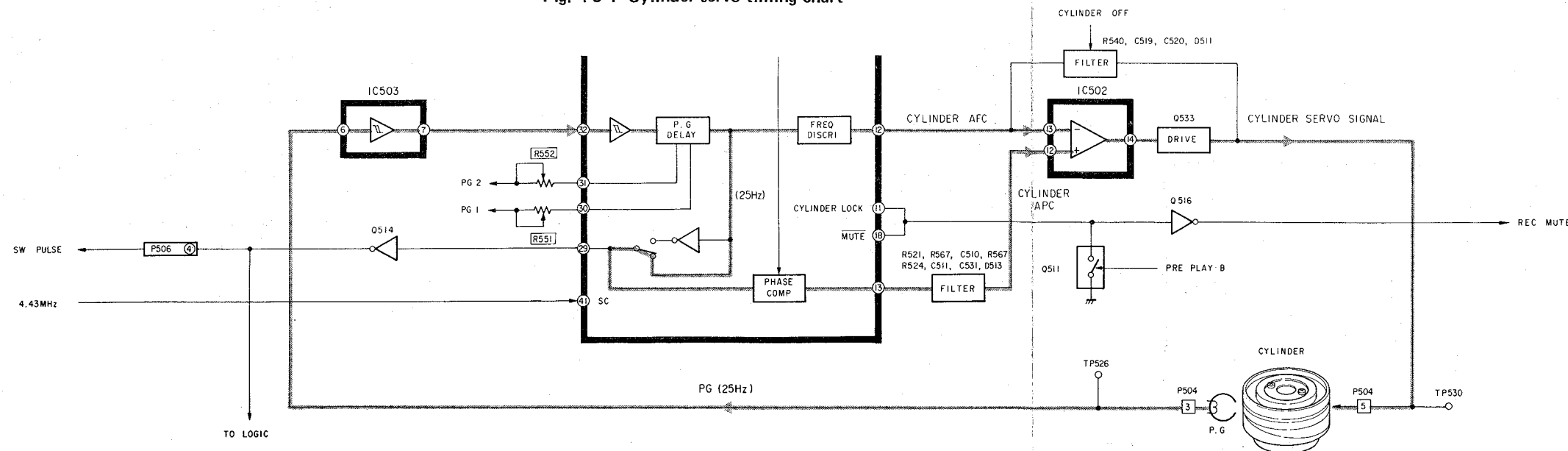


Fig. 4-5-2 Cylinder servo block diagram

- 2) The PG signal induced on the PG heads is wave-shaped in the Schmitt circuit of IC503 (pins ⑤, ⑥, ⑦) and then sent to pin ⑩ of IC501. Each of PG 1 and PG 2 pulse is delayed by time constant circuits consisting of R551(VR), C503 and R552 (VR), C504, respectively. Each of the delayed output triggers flip-flops inside the IC, and develops at pin ⑨ as the SW pulse. The SW pulse is sent to the video circuit through the inverter Q514.

(2) Phase detection (APC), speed detection (AFC)

- 1) The phase detection and the speed detection are conducted inside IC501.
- 2) In the phase detection circuit, a rising edge of the switching pulse created from the PG pulse as previously described is compared with a reference signal (25 Hz) in their time difference (phase). In the record mode, a vertical sync signal (input to pin ⑤ of IC501) is counted down to half and the resultant signal is used as the reference signal.
- 3) On the other hand, in the playback mode the internal reference signal of 25Hz, which is created from the clock signal of 4.43 MHz (applied to pin ④ of IC501), is used as the reference signal. This is the only difference observed between the record and playback modes in the cylinder servo operation.
- 4) These reference signals are synchronized with rising edge of the delayed waveform at pin ⑦ (FP) of IC501.
- 5) In the speed detection circuit rising and falling time of the switching pulse (speed or time difference) is compared. Results of the phase and speed detections are output from pins ⑬ and ⑫ of IC501 as 69 kHz rectangular pulse signals modulated in pulse width (PWM).

- 6) When the servo is locked under the stabilized condition, the PWM output shows about 50% duty, but when excessive speed and/or phase variations are caused the duty may vary considerably and in the worst case the duty becomes high or low.
- 7) However, if the rotating speed of the cylinder deviates considerably (in this case the AFC output becomes high or low) the duty of the APC output (Pin ⑬ of IC501) is maintained at 50%, so care must be needed.

(3) Phase compensation and output amplifier circuits

- 1) The output from pin ⑬ of IC501 passes through a filter (R524, C510, R567, R521, C511, C531) provided to stabilize the servo response and to filter the 69 kHz PWM carrier component and enters pin ⑫ of IC502, op-amplifier.
- 2) The double through diode D513 connected in parallel to R567 is provided to enhance quick charging or discharging of C511 and C531 in transient time period.
- 3) The AFC output from pin ⑫ of IC501 enters pin ⑬ of IC502, op-amplifier. The AFC output is fed back from the emitter of drive transistor Q533 with the carrier component removed by the feedback capacitor C519.
- 4) R540 and C520 determine the gain of the op-amplifier, at the same time, they constitute a filter for APC and AFC.
- 5) The op-amplifier output enters the base of drive transistor Q533 and drives the cylinder motor. To stop the cylinder motor approx. 3.5V is applied to the inverted input terminal of the op-amplifier through D511 to decrease the op-amplifier output to a low level.

(4) fh correction

- 1) In the cue/review mode, it is necessary to decrease or increase the rotating speed of the cylinder in response to the tape speed to keep relative tape speed between the cylinder and the tape at the specified value or to obtain constant horizontal sync frequency of 15.625 kHz.
- 2) Conventionally, this rotating speed control of the cylinder has been made by an external circuit, but in this model, the cylinder speed is automatically increased or decreased according to the speed control signal sent from the microcomputer to pins ⑧ - ⑩ of TD6360P, thereby performing the fh correction.

4-5-4 Capstan servo circuit

In the capstan system, tape is driven by rotating the capstan flywheel coupled to the Capstan motor through a belt. Fig. 4-5-3 shows the timing chart in record mode and Fig. 4-5-4 shows the timing chart in playback mode.

(1) FG signal generator

- 1) The FG signal is a signal obtained from the capstan flywheel as a speed feedback signal of the capstan.
- 2) A pulse generator consisting of a coil, magnet, and gears is provided inside the flywheel and is generating 240 pulses per one revolution of the capstan.
- 3) Generally, the FG frequency is 504 Hz when the servo is locked in the record or playback mode of operation.
- 4) These pulses are amplified by IC502 and then clamped by D510. The clamped output of approx. 1.4V square wave is fed to pin ⑤ of IC501.

(2) Speed detection (inside servo IC)

- 1) The FG signal entered pin ⑤ of servo IC501 is compared in its speed in the speed detector circuit and pin ⑮ develops a rectangular signal modulated with pulse width (PWM) of approx. 69 kHz. Since the capstan system is subject to more disturbance than the cylinder system, generally the AFC output has considerable duty variations under locked condition of the servo system.

(3) Phase detection (inside servo IC)

(RECORD mode):

- 1) The FG pulse signal entered pin ⑤ of IC501 is counted down to 1/24 to create 21 Hz pulse, and compared with the reference signal in their time difference (phase detection) in the phase comparator. The compared output is developed from pin ⑭ as a 69 kHz PWM signal.
- 2) The reference signal is the 21 Hz signal developed inside the IC for exclusive use of the capstan control and applied to pin ⑯ as a positive pulse signal.

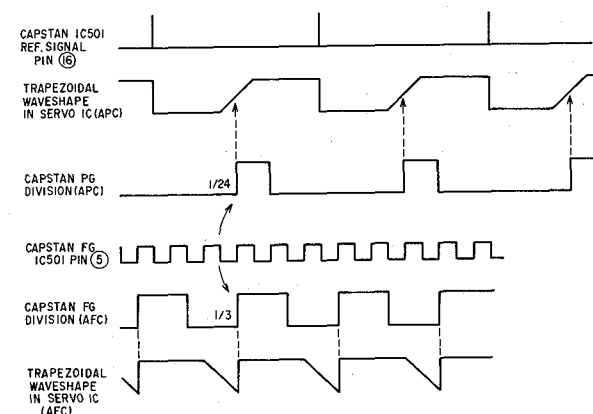


Fig. 4-5-3 Timing chart (Record mode)

(PLAY mode):

- 1) The reference signal delayed by a time equivalent to the time constant of R556 (main tracking), R553, C505 (subtracking) from the falling edge of the reference signal (pin ⑳ of IC501, delayed wave of FP) used as a reference for cylinder phase detection inside the IC and the CTL signal are compared in time (phase detection), and output from pin ⑭ as a PWM output.
- 2) With servo unlocked, the duty is also forced to 50% in both record and playback modes as in the cylinder servo system.

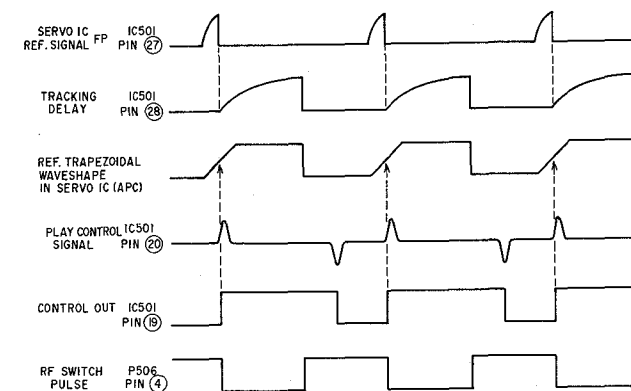


Fig. 4-5-4 Timing chart (Playback mode)

(4) Phase compensation & output amplifier circuits

- 1) The APC output developed at pin ⑭ of IC501 passes through the phase compensation filter (R525, C535, R571, R522, R528, R527, C512) and a smoothing circuit, and enters pin ⑩ of IC502.
- 2) A double throw diode D514 connected across R571 functions to speed up circuit response by rapidly charging or discharging C512 in a transient period.
- 3) The AFC output developed at pin ⑮ of IC501 is applied to pin ⑨ of IC502, equalized in a filter of C517, R530, smoothed with carrier components removed through C516, and then led to the transistor Q534 which drives the capstan motor. The capstan is stopped by turning Q505 on.

(5) Control (CTL) signal recording

- 1) In recording, 25 Hz control signal (CTL pulse) is created from the V sync signal (pin ⑳ of IC501). A current is alternately supplied from pins ⑳ and ㉑ of IC501 to the control head, and the current is recorded in saturation level on the control track. The current is limited to approx. 3mA by R514.
- 2) D508 connected to the op-amplifier input functions to clamp the control signal.
- 3) Duty of the record CTL pulse is determined by the tracking delay time at pin ⑳ of IC501 and has been set to approx. 75% by R513, R566 and C505.

(6) Playback CTL pulse amplifier circuit

- 1) In playback mode, pin ㉑ of IC501 is open and a bias voltage of approx. 2.2V is developed at pin ㉒ of IC501 to bias one end of the CTL head.
- 2) A fine level signal appears on the control head as the tape travels, and enters pin ⑥ of IC502 and amplified by approx. 60dB.
- 3) The amplified output enters pin ㉑ of IC501 and furthermore amplified, wave-shaped by the Schmitt amplifier inside the IC. Thus amplified output is used for phase detection.
- 4) On the other hand, the wave-shape pulse develops at pin ⑩ and enters pin ② of P506.
- 5) D505 and R562 operate to clamp 12Vp-p (voltage induced on the CTL head is amplified by the op-amplifier) to approx. 4V for protecting the input circuit of the IC.

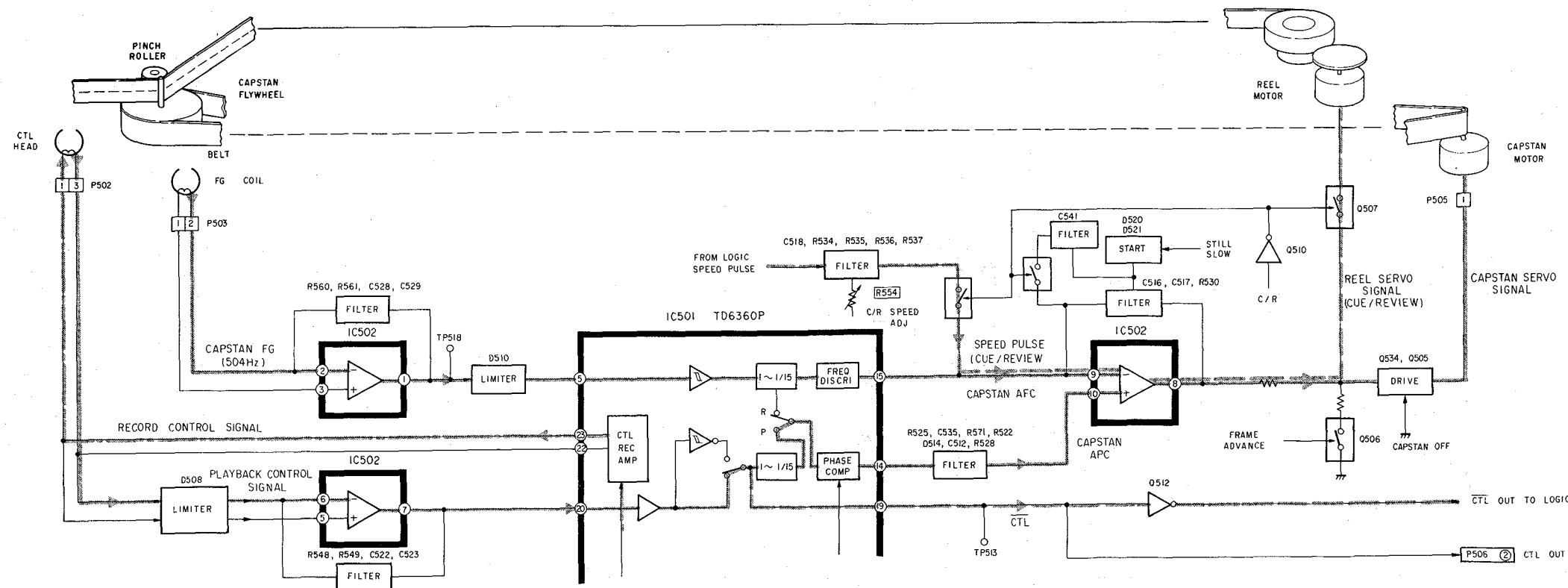


Fig. 4-5-5 Capstan servo block diagram

(7) Still noise shifting

- 1) A simple pulse drive type still & slow functions capable of freezing a picture at a given position are provided, but no noise shifting circuit which moves undesirable noise bars to a less susceptible position on a screen is provided.
- 2) With the still or slow mode set, the logic circuit sends a still/slow signal (LOW) and a voltage at pin ⑨ of IC502 is turned to LOW by D520, D521 connected in parallel with the feedback capacitor (C517) of a filter in the capstan system, and the op-amplifier's output (pin ⑧ of IC502) becomes HIGH.
- 3) In the still mode Q505 turns on and in the slow mode Q506 turns on. As a result, the op-amplifier output is divided by R542, R543, and R544, and as Q505 is turned on or off repetitively the capstan motor is driven repetitively.
- 4) The slow speed is set to 1/10 through 1/20 times the normal speed.
- 5) The still & slow signal is also developed for transitional period from the picture search/stop to the playback mode. D509 and R539 function to provide almost the same bias voltage as in the play mode across C517 to assure rapid mode transition.

(8) Cue/Review

- 1) In the cue/review mode, tape is driven by a reel motor and the tape speed is controlled by detecting the control (CTL) pulses and by controlling its frequency.
- 2) In the cue/review mode, the CTL pulse enters pin ②① of IC501 and outputs from pin ①⑨ as a square wave signal. This signal is inverted ($\overline{\text{CTL}}$) and applied to pins ⑤⑤, ⑤⑥ of IC601 logic microcomputer. Then, pin ①⑥ develops a rectangular signal in synchronization with falling edge of the $\overline{\text{CTL}}$ pulse. A part of HIGH in the signal developed at pin ①⑥ is a time depending upon the ROM of the logic microcomputer and set so that the playback CTL frequency becomes approx. 179 Hz in the cue mode and approx. 170 Hz in the review mode.
- 3) Since the normal playback CTL frequency is 25 Hz, the cue/review operation is conducted at a speed of approx. 7 times the normal speed.

- 4) The playback CTL signal frequency is different in the cue and review modes. The reason is as follows: To make FH correction the rotating speed of the cylinder is increased in the cue mode and is decreased in the review mode, as a result if the CTL frequency does not match to 7 times the cylinders' rotating speed, motion of noise bars increases, thus disturbing screen image. To prevent this the different CTL frequency is used for each mode.
- 5) The output developed at pin ①⑥ of IC601 is smoothed by a LPF consisting of R535, R536, R537, R554 (VR), and C518, and its integrated value is compared with a reference voltage determined by resistor division ratio of R522 and R528. The resultant error voltage is output from pin ⑧ of IC502 and is sent to the drive transistor Q625 in passing through Q507 which is turned on.
- 6) In this way the AFC servo functions with the CTL pulse recorded on the tape.

(9) Synchronous editing

- 1) Purpose of the synchronous editing is to not disturb continuity of the CTL pulse. To realize this, a slight amount of tape is rewound by driving the reel motor with pulse voltage immediately after the operation mode is changed from record to the record pause mode, and then the unit enters the standby mode.
- 2) At the same time, the servo IC is also set to the edit mode but in this mode the CTL pulse is set to the playback mode and the IC itself is also in the playback condition.
- 3) When the pause mode is released, the tape is reproduced for 1.7 sec to match phase of the CTL pulse and then the unit enters the record mode.

4-6. Video Circuit

4-6-1 Outline

The video circuit consists of 8 ICs in total. This unit features good cost performance and various user controls including picture sharpness control to provide easy-to-use full functions.

Operations and functions for each IC used are shown in Table 4-6-1.

Table 4-6-1

Part No.	IC	Operation	Function
IC101	TA7772P (16 pin DIP)	Record amplifier Playback RF process	Record amplifier circuit, Low noise high gain head amplifier circuit, REC/PLAY switching, CH-1/CH-2 switching
IC121	TA8607P (16 pin DIP)	Playback RF process	AGC, Drop-out compensate circuit, Phase equalizing circuit
IC122	TA7302P (7 pin SIP)	Limiter	Limiter circuit
IC201	TA8605N (30 pin small package)	Y signal process FM MO/DEM	Sync AGC, Peak AGC, Sync clamp, Feedback clamp, FM modulation, Sync separation circuit, REC/PLAY switching, Main emphasis, White/dark clip, Double limiter circuit, Playback Y/C mixing, False V inserting
IC202	TA8606N (24 pin small package)	Y signal process Sub-emphasis	Non-linear sub-emphasis, 1/2 fH shift, Sharpness control circuit, Noise canceller
IC401	BA7267S (22 pin small package)	Color signal process	REC/PLAY switching, Burst ACC, Frequency CONV I, 4.43 MHz X'tal OSC (XO), Voltage control X'tal OSC (VXO), ACK, 321fH/320fH VCO, APC detect circuit, Frequency CONV II
IC402	BU2763S (18 pin small package)	Digital color signal process	Color rotary circuit, Side lock detection circuit, DPLL circuit AFC detect circuit, Digital phase locked loop, Burst gate pulse generation circuit, 1/320 · 1/321 divider circuit, REC/PLAY switching circuit
IC481	BA7025L (18 pin SIP)	PAL/SECAM defector	PAL/SECAM defector

4-6-2 Record Circuit

(1) Y-signal record circuit

- 1) A composite video signal selected from either one of the line input or the tuner input circuit by the Phono jack switch P210 (line input has priority over the tuner input) is applied to pin ④ of IC201 as well as to the color process circuit.
- 2) The composite video signal entered pin ④ of IC201 is subject to gain control and fed back clamp operations in the sync AGC and the peak AGC circuits, and then outputs from pin ⑩ of IC201 as an EE output signal and from pin ① as a record Y signal.
- 3) The EE signal at pin ⑩ is led to the line output terminal (P211). At the same time the EE signal is subject to an attenuation and the signal is applied to the RF modulator through Q206 buffer.
- 4) While the signal output from pin ① enters the LPF (Z202). The LPF removes color components from the input signal and the signal (Y signal) with color components removed passes the buffer amplifier Q208 and enters pin ③ of IC202 and the AGC detector circuit through pin ② of IC201.
- 5) The Y signal entered pin ③ of IC202 is subject to a sync tip clamp. At the same time the Y signal outputs from pin ④ of IC202 as a sync separation signal. The signal enters pin ⑦ of IC201 through a LPF and becomes as a composite sync signal with the sync signal separated. The composite sync signal outputs from pin ⑤ and enters pin ⑭ of IC402 and used to create fH reference for color process and burst gate pulse.
- 6) The composite sync signal is also applied to the vertical sync separation circuit in the servo circuit and processed to develop the V-sync signal. The V-sync signal is used as a reference signal in the servo circuit during record operation.
- 7) Moreover, the composite sync signal is used for sync clamp operation in the AGC detector inside the IC201 or for sync clamp operation of playback Y signal in the playback mode, and applied to sync AGC detector as keyed pulse after it is delayed and waveshaped.
- 8) The Y signal, which is entered pin ③ of IC202 and subject to the sync tip clamp, outputs from pin ⑮ after it is subject to the non-linear pre-emphasis (sub-emphasis) and 1/2fH shift. The non-linear emphasis is the emphasis where the emphasis level is increased as the signal amplitude decreases to prevent lowering of S/N.
- 9) 1/2 fH shift means to increase FM carrier frequency for CH-1 by 1/2 fH to convert vertical stripes into diagonally crossed stripes to make the stripes less perceptible on the screen. In practice, video signal's DC level is shifted by the amount equivalent to 1/2 fH in the FM carrier frequency.
- 10) The non-linear emphasis operation is performed as follows:

High frequency components are extracted from the Y signal developed at pin ⑮ with a filter consisting of R234, L204, and then applied to the original signal after the extracted signals are compressed so that the higher the amplitude of the signals, the more the signals are compressed inside the IC.
- 11) The 1/2 shift operation is conducted inside the IC and is controlled by the state of pin ⑯. ("H" for CH-1 mode, and "L" for CH-2)
- 12) The Y signal output from pin ⑮ of IC202 directly enters pin ⑫ of IC201 and is subject to the pre-emphasis (main-emphasis) by R222, R223 and C225. The signal is then subject to the white clip and dark clip to prevent overmodulation. Thus processed signal outputs from pin ⑯ and enters the FM modulator (pin ⑰) in passing through the deviation adjustment control (R252). FM carrier frequency adjustment control (R251) is also connected to pin ⑰.
- 13) The FM modulator modulates the sync tip level to 3.8 MHz and 100% white level to 4.8 MHz. Thus, created Y-FM signal outputs from pin ⑱ of IC201 and enters the record Y-FM equalizer (Q123) where the signal is processed to have an emphasis characteristic over a lower frequency band and to have a high-pass characteristic for the down converted color signal to be superimposed. The signal is then sent to the Y/C MIX AMP consisting of Q124, and Q125.
- 14) Q129 functions as a record muting circuit.
- 15) The signal superimposed with the down converted color signal in the Y/C MIX AMP passes Q126 buffer and pin ⑤ of P202, and enters pins ① and ⑮ of IC101 record amplifier on the PRE AMP unit, and amplified.
- 16) The amplified record current developed from pins ③ and ⑤ enters the video heads through the rotary transformer.

(2) Color signal record circuit

- 1) A video signal passed through the built-in switch of jack P210, and is selected by REC/PLAY switches (Q403 and Q404). The selected output enters the ACC amplifier through a BPF and pin ② of IC401. The ACC amplifier is fed to the burst ACC circuit which keeps the burst level at a constant value in the record mode. That is, the ACC amplifier operates to increase the ACC output level as a color signal decreases, thus increasing a relative color recording current or S/N even if the color signal level is low.
- 2) The color signal with its amplitude stabilized in this way by the ACC amplifier outputs from pin ②, and enters pin ③. Then the signal is applied to the main BM (Balanced Modulator).
- 3) The 4.43 MHz color signal applied to the BM is mixed with 5.06 MHz carrier (the phase of which is fixed at the CH-1 and shifted at the CH-2) being applied to the BM, thus frequency conversion of 5.06 ± 4.43 MHz will be performed. The converted outputs developed pin ④ are led to two LPFs to extract only a lower component of 627 kHz ($= 5.06 \text{ MHz} - 4.43 \text{ MHz} = (40 + 1/8)f_H$) color signal. Thus created color recording signal is adjusted in its current level and passes through the group delay circuit (Q405, Q406) and then fed to the Y/C mixer circuit (Q124, Q125) and sent to the record amplifier IC101.
- 4) The composite sync signal entered pin ④ of IC402 becomes a HD pulse with its equalizing pulses removed. AFC detection is performed with this HD pulse and the f_H signal created by counting down the 321 f_H VCO output (pin ② of IC402) to 1/321 to control the VCO or to lock the VCO to 321 f_H ($= 5.015 \text{ MHz}$) precisely.
- 5) The VCO output counted down to 1/8 or $(40 + 1/8)f_H$ ($= 627 \text{ kHz}$) carrier is phase-shifted using the f_H pulse stabilized in the DPLL (Digital Phase Locked Loop) as a trigger pulse. The rotational direction of the Phase Shifter (PS) depends upon the head switching pulse applied to pin ⑥ of IC402. When the switching pulse is in the "H" level, the phase is fixed and in the "L" level, the phase delays by 90° every 1H. Thus created 40 1/8 f_H PSCC (Phase Shifted Sub-Carrier) develops at pin ⑥ of IC402, and enters a LPF to remove harmonics included. Then the signal enters the sub BM from pin ⑨ of IC401.
- 6) Since 4.43 MHz carrier, which is locked to the color burst frequency by the record APC signal, is being applied to the sub-BM, the PSCC signal is converted to 4.43 MHz $\pm 627 \text{ kHz}$ and outputs from pin ⑦ of IC401. This output enters the BPF and the BPF extracts 5.06 MHz ($= 4.43 \text{ MHz} + 627 \text{ kHz}$) component. Thus converted 5.06 MHz signal is used as the carrier signal to down-convert the color signal.

4-6-3 Playback circuit

(1) Y signal playback circuit

- 1) Signals reproduced by video heads are applied to pin ⑥ (CH-2) and pin ② (CH-1) of IC101, pre-amplifiers. The preamplifiers amplify these signals by approx. 60 dB. These signals are switched by switching pulses and output from pin ⑩.
- 2) The playback signal developed at pin ⑩ passes a buffer amplifier Q102 and pin ③ of W102, and returns to the main unit. Then the signal enters pin ⑨ of IC121, amplified by approx. 13 dB, and outputs from pin ⑪.
- 3) The playback RF signal output from pin ⑪ enters the equalizer circuit and the color signal playback circuit. At the same time the RF signal output also enters the servo unit as a playback envelope output (TP101).
- 4) The equalizer circuit functions to make the video frequency response flat with the PRE-SET control R259 for sharpness adjustment, thus preventing possible overmodulation due to parameter spread of the video heads.
- 5) Thus processed signal passes the LPF and the high frequency noises are removed. Then, the signal enters pin ⑫ of IC121 in passing through a trap and the down converted color signal component is removed. The signal then passes through pins ③ and ⑤ of the FM phase compensation circuit and enters the AGC circuit through pin ②. Thus processed playback RF signal with its amplitude adjusted to a specified level outputs from pin ⑬ and enters the double limiter.
- 6) The FM phase compensation circuit functions to reduce phase distortion observed at around the Y-FM carrier signal which has been subject to frequency compensation.
- 7) On the other hand, the playback Y-FM signal enters the dropout detection circuit inside IC121. The detection circuit develops a dropout detection pulse at pin ⑮ when an envelope output reduces. The dropout detection pulse is used to switch in the signal at pin ⑭ which is delayed by 1H glass delay line, thus performing the dropout compensation.
- 8) The AGC output at pin ⑬ of IC121 passes the LPF consisting of R146, R147, C144, R148, and C145, and enters pin ⑰ of IC201. At the same time the same signal also passes the HPF consisting of C147, R149, C148, and R160 and enters pin ① of IC122, limiter. The limited output develops from pin ⑥ of IC122 and enters pin ⑰ of IC201 where the signal is sent to the FM demodulator through a double limiter. The limiter inside IC122 is used to compensate insufficient gain of the limiter in IC201 to improve over-modulation characteristic.

- 9) The FM demodulator consists of a non-stable multivibrator and a multiplier, and the demodulated output is led to pin ① through a LPF (Z202).
- 10) Thus demodulated Y signal is then subject to edge expander and white clip circuit consisting of Q218 to Q221. This circuit improves edge waveform of Y signal. R256 adjusts the playback Y signal level to a constant level. Q207 functions to raise higher frequency (approx. 2.8 MHz) level. The signal is subject to main de-emphasis operation in the de-emphasis circuit consisting of R227, R229, C229 and C248. The signal is then applied to pin ② of IC202.
- 11) The signal amplified by approx. 20 dB inside IC202 is subject to non-linear de-emphasis and to 1/2 fh shift restoration and then signal outputs from pin ④. The non-linear de-emphasis is performed as in the record mode. That is, high frequency components of the signal are applied to pin ⑧, compressed, and then subtraction is conducted in reverse as in the record mode.
- 12) The Y signal restored to the original recorded signal enters pin ⑬ and is led to the sharpness adjustment circuit inside IC202. A DC voltage applied to pin ⑦ controls the picture sharpness and the controlled signal outputs from pins ⑥ and ⑧ and the both are mixed then enters pin ⑤ again, then applied to the noise canceller circuit.
- 13) The noise canceller circuit extracts only high frequency components from the signal at pin ④ with the HPF consisting of C229, C228, L207, and R231, and supplies them to pin ③ to take out only the noise components with the limiter. Thus developed noise signals are subtracted from the original signal (same signal at pin ④) to cancel the noises each other. The signal at pin ④ is also used as a signal for sync separation as in the record mode and is led to pin ② of IC201.
- 14) The Y signal with its high frequency noises removed in this way outputs from pin ① and enters pin ⑥ of IC201. The Y signal is subject to a sync clamp operation in this stage and then mixed with a playback color signal being applied to pin ⑧ of IC201, resulting in a video signal of 2Vp-p. The video signal outputs from pin ⑩. Operations in following stages are the same as those in the record mode, so description will be omitted.

(2) Color signal playback circuit (PAL/SECAM)

- 1) A playback RF signal developed at pin ⑪ of IC121 passes through amplifier Q128 and LPF and the down converted 627 kHz color signal contained in the RF signal is separated.
- 2) Then the color signal enters the ACC amplifier from pin ① of IC401 to stabilize the level.
- 3) Thus stabilized 627 kHz down converted color signal outputs from pin ② of IC401 and enters the main BM through pin ② of IC401. In the main BM, the 627 kHz color signal is mixed with 5.06 MHz carrier signal (with the phase shifted) being applied to the BM and frequency conversion of 5.06 MHz \pm 627 kHz is performed.
- 4) In this case, as the phase of 5.06 MHz signal is preset by the APC loop so that horizontal jitter components caused by the rotational system of the mechanism are cancelled each other, the converted color signal has almost no jitter components.
- 5) The color signal with the jitter component removed in this way outputs from pin ⑬. The color signal enters 2H comb filter (X401) to remove its crosstalk components from adjacent tracks at PAL mode and enters an attenuator at SECAM mode. The color signal, then, pass through the REC/PLAY switch of Q404, and is amplified. The amplified output enters pin ② of Q401 in passing through a BPF (4.43 MHz) and outputs from the pin ④.
- 6) The output at pin ④ is generally biased by approx. 2V DC, but the DC component becomes zero when the color killer circuit functions. The playback color signal at pin ④ passes through Q407 buffer and is adjusted in its color level, and then enters the Y/C MIX circuit from pin ⑧ of IC201 and mixed with the playback Y signal. The mixed output is obtained at pin ⑩.
- 7) In the playback mode, the color sync circuit system operates as follows:
- 8) A composite sync signal separated from a playback Y signal develops at pin ⑤ of IC201 and enters pin ④ of IC402. A burst gate pulse is created from the composite sync signal (output from pin ⑧ of IC402), and applied to pin ⑥ of IC401.

- 9) A burst section of the playback color signal is sampled with this burst gate pulse and compared with the 4.43 MHz reference signal. The resultant error signal controls the 321fH VCO so that its phase is locked. In this case, a stable point of the APC exists every period of fH because of the burst gate synchronization performed every 1H, so it may be possible for the VCO to be locked at a frequency other than 321fH.
- 10) To prevent this, a HD pulse created from the composite sync signal at pin ⑭ of IC402 and the VCO output fed through pin ② are compared in their frequencies to develop a side lock detection pulse that functions to correct the frequency deviation to 321fH when the VCO is locked at a frequency other than 321fH.
- 11) The VCO output of 321fH is counted down to 1/8 or to $(40 + 1/8)fH$ as in the record mode and then subject to the phase-shift.
The $(40 + 1/8)fH$ signal and the 4.43 MHz reference signal are mixed in the sub-BM circuit and a 5.06 MHz carrier signal is generated.
- 12) The 5.06 MHz carrier and the 627 kHz color signal are applied to the main BM and demodulated to a 4.43 MHz color signal. In this case, amount of phase shift and rotational direction of phases of 627 kHz color signal and 5.06 MHz carrier signal become the same. That is, the color signal is demodulated correctly with the phase relation returned to that of the original signal.
- 13) On the other hand, crosstalk components from adjacent tracks are demodulated with their phases rotated in 90° shift direction. As a result, phase rotation of 4.43 MHz crosstalk component becomes $90^\circ \times 2 = 180^\circ$ every 2H or the phase is inverted. Thus, they can be removed by the 2H comb filter.

4-6-4 PAL/SECAM identification circuit

- 1) In the REC/EE mode, the color signal from pin ②① of IC401 is applied to pin ④ of IC481. At the same time, a burst gate pulse from pin ⑱ of IC402 is entered pin ⑤ of IC481.
- 2) The color signal applied to pin ④ of IC481 is gated only for the burst period and output from pin ⑦ with the amplitude limited by the limiter amplifier.
- 3) The output from pin ⑦ will be processed in different ways depending upon the PAL or SECAM system as explained below:
- 4) (SECAM signal)
For the SECAM signal, one of signals with different frequencies of ($D_R = 4.40\text{MHz}$) and ($D_B = 4.25\text{MHz}$) is alternately applied every 1H to the bandpass filter. Since the filter has been designed to pass 4.25MHz component and to attenuate 4.40MHz, the 4.40MHz signal has a lower amplitude than that of 4.25MHz signal.
- 5) Accordingly, the frequency difference between D_R and D_B is expressed in the amplitude difference. That is, a signal alternately showing a large and a small amplitude is developed every 1H. The signal is applied to pin ⑨ and detected in amplitude, and then led to the resonant circuit consisting of L451 and C485 between pins ⑪ to ⑬.
- 6) Since the resonant frequency is set to $f_H/2$ and the signal alternately showing a different amplitude every 1H has a period of 2H ($= f_H/2$ frequency), a resonant waveform will be obtained at pin ⑪. The waveform output is converted into a DC voltage in the comparators 1 & 2, and output as a high level signal identifying the SECAM signal. The output voltage is called SECAM + B.
- 7) (PAL signal)
Since the gated PAL signal includes only 4.43MHz component, the Band Pass Filter develops the output having a constant amplitude. Accordingly, if the output is applied to the resonant circuit, no resonant waveform output will be obtained. Thus the comparators 1 & 2 do not develop any DC output. That is, the PAL signal is not identified as the SECAM signal and pin ⑬ develops 0V output.
- 8) During playback mode, the color signal from pin ②② of IC401 is applied to pin ① of IC481 and the PAL/SECAM identification is performed in the same way.

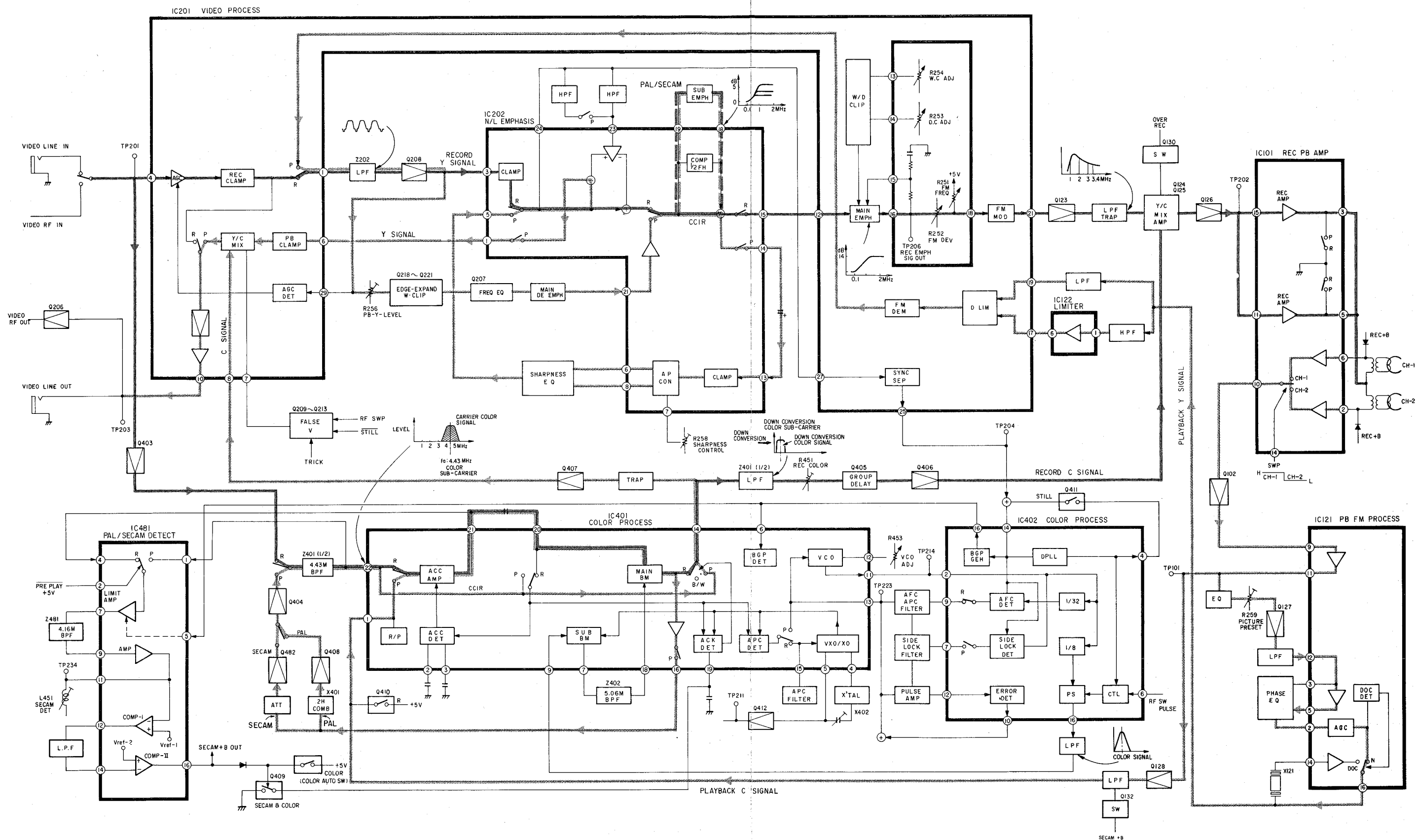


Fig. 4-6-1 Video block diagram

4-7. Audio Circuit

4-7-1 Outline

- 1) The audio circuit is mounted on the main P.C. board and employs a monaural system.
- 2) Major blocks in the audio circuit are the audio 1 chip IC (containing ALC, line-amplifier, record amplifiers, equalizer amplifier, muting circuit, etc.) erase oscillator circuit, etc.

4-7-2 EE mode circuit description

(1) Input signal switching (P710)

- 1) Input signal switching is performed by the built-in switch of the audio line input jack (P710).
- 2) A line input is selected when a line input plug is inserted to the jack, and the tuner input is selected when no plug is connected.
- 3) The nominal line input level is -10 dBs (245mV-rms).

(2) Record & play back switching circuit and muting circuit (IC701)

- 1) The record & play back switching circuit and the muting circuit are provided inside IC701.
- 2) The record & play back switching circuit becomes a play back mode when PB+B (HIGH) is applied to pin ⑪ of IC701 and becomes EE or record mode when LOW level voltage is applied.
- 3) The muting circuit mutes a playback signal when HIGH level signal is applied to pin ⑫ of IC701. (The muting circuit only works in trick playback modes.)

(3) Output amplifier (IC701)

- 1) The signal entered pin ⑪ of IC701 is amplified by approx. 35 dB and outputs from pin ⑬. The output is applied to the line output terminals as well as to the RF modulator.
- 2) The nominal output level is -7 dBs (350 mVrms).

(4) ALC circuit (IC701)

- 1) The ALC circuit is also contained inside the IC701.
- 2) The signal entered pin ⑪ of IC701 is amplified by approx. 35 dB and outputs from pin ⑬.
- 3) When the output at pin ⑬ exceeds -4.5 dBs, a detector circuit inside the IC automatically functions and adjusts the line amplifier input level to an optimum level.
As a result, the output level is automatically adjusted so that the audio head does not cause any distortion if a signal higher than the reference input level is applied.
- 4) The ALC operates only in record mode and the EE mode.

4-7-3 Record circuit

(1) Record amplifier circuit (IC701)

- 1) The signal developed at pin ⑬ of IC701 enters pin ⑮ in passing through the record equalizer consisting of R710, R711, R724, C722. The record equalizer attenuates signals lower than 1 kHz by approx. 1 dB and prevents frequency peak over mid to high frequency range.
- 2) The signal applied to pin ⑮ is amplified by approx. 11 dB (400 Hz) in the record amplifier, outputs from pin ⑯, and enters the audio head through the constant current resistor (R713).
- 3) Pin ⑰ is a feedback terminal for the record amplifier and constitutes a high frequency peaking circuit.
- 4) L701 and C713 function as a peaking circuit and rises signal level by approx. 8 dB at 12 kHz.

(2) Erase oscillator circuit (Q705, T701)

- 1) The oscillator circuit consisting of Q705 and T701 works during record mode, and oscillates frequency of approx. 68 kHz.
The oscillator signal is used as the erasing current for the full width erase head and the audio erase head as well as a record bias for recording of audio signals.

(3) Audio head switching circuit (IC702)

- 1) IC702 grounds its pins ③ and ① when a voltage is applied to pins ⑤ and ⑦, respectively. In the EE and record modes pin ③ grounds the playback terminal of the audio head through a fine resistance and opens only in the playback mode, thus allowing the playback signal to enter pin ④ of IC701.
- 2) Pin ① opens only in the record mode thus allowing record signals and bias signal to flow to the audio head.
- 3) In the playback mode, the record signal terminal of the audio head is grounded.

4-7-4 Playback circuit

(1) Playback amplifier (IC701)

- 1) A playback signal induced on the audio head is first adjusted in its frequency response in the peaking circuit consisting of the head coil and C704 and then applied to pin ④ of IC701. The IC704 amplifies the signal by approx. 45 dB at 400 Hz and feeds the output to pin ⑧.
- 2) Pin ⑦ of IC701 functions as a negative feedback terminal and adjusts the frequency response with the impedance connected between pin ⑦ and pin ⑧. That is, an equalizing response showing a descending response from a low end (approx. 50 Hz) to mid range (approx. 1.3 kHz) and a flat response over a higher frequency range is provided.
- 3) The signal processed in this way enters pin ⑩ in passing through the playback level adjusting control (R751), selected by the switch, amplified, and then applied to the output terminals as described in 4-7-2 (2), (3).

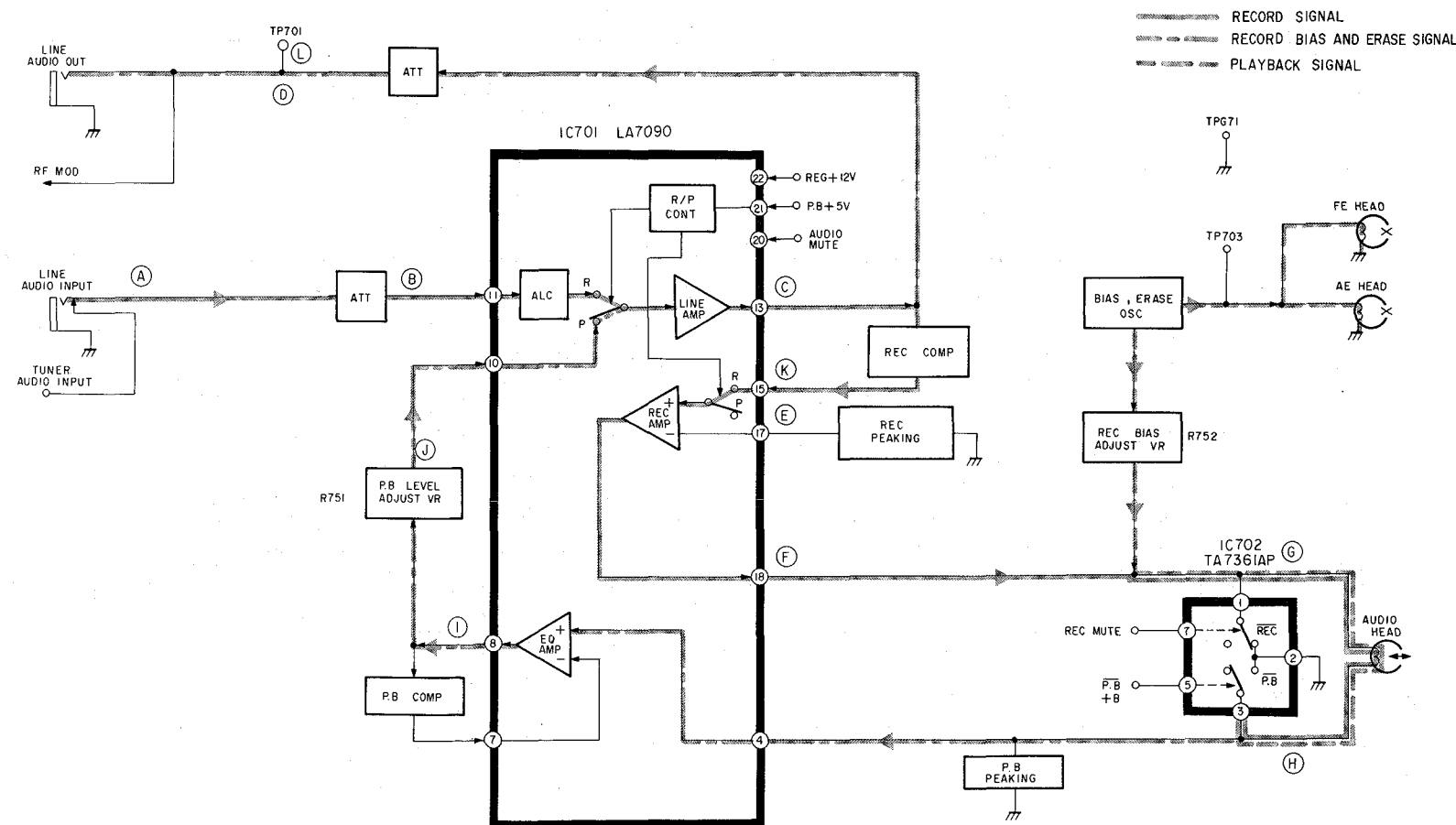


Fig. 4-7-1 Audio block diagram

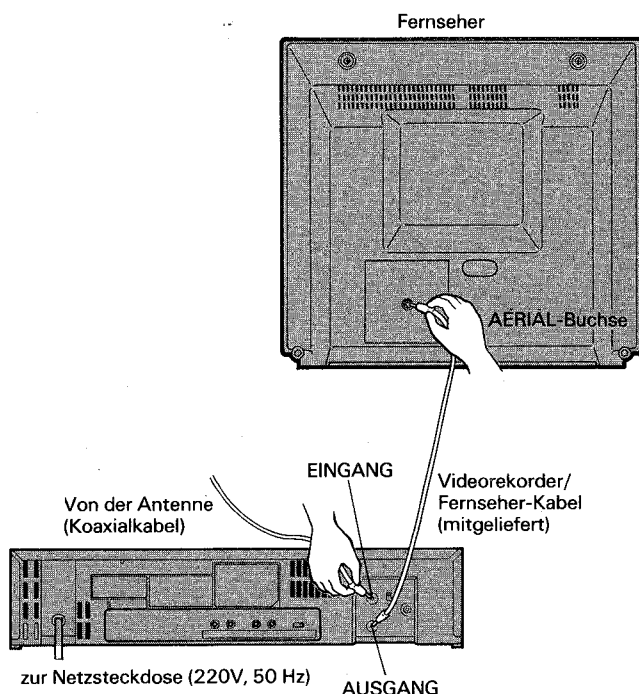
ANSCHLÜSSE

ANSCHLUß DER FERNSEHANTENNE

Die Antennenleitung vom Fernseher abtrennen und an der Antennen-Eingangsbuchse (EINGANG) ⑦ an der Rückseite des Rekorders anschließen.

ANSCHLUß DES VIDEOREKORDERS AN DEN FERNSEHER

Ein Ende des mitgelieferten Kabels an die Antennenbuchse des Fernsehers und das andere Ende an die Antennen-Ausgangsbuchse (AUSGANG) ④ an der Rückseite des Rekorders anschließen. Dieses Kabel hat verschiedene Stecker, nur einer paßt in die Antennenbuchse des Fernsehers.

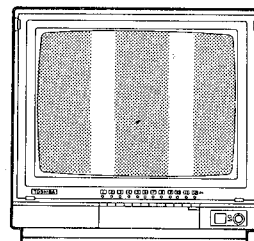


NORMALES FERNSEHEN

Den Fernseher einschalten und den Fernseher auf den gewünschten Kanal einstellen. (Für normales Fernsehen braucht der Videorekorder nicht eingeschaltet zu werden.)

EINSTELLUNG DES FERNSEHERS AUF DEN VIDEOREKORDER-AUSGANGSKANAL

1. Den Fernseher einschalten.
2. Die Betriebstaste (BETRIEB) ① des Videorekorders einschalten.
3. Den Testsignalschalter (TEST SIGNAL) ④ auf „EIN“ stellen.
(Jetzt liefert der Videorekorder ein Testsignal zum Fernseher. Das Testsignal ist auf einem Kanal zwischen 31 und 39.)
4. Den Fernseher auf den Videorekorderkanal einstellen. Den Kanal abstimmen, bis das unten gezeigte Schwarzweiß-Testmuster klar wiedergegeben wird. Für die Wiedergabe einer Videokassette muß der Fernseher jetzt immer auf diesen Videorekorderkanal eingestellt werden.



Hinweis: Das Tonsignal (1-kHz-Rechteckwelle) wird mit dem Bild ausgegeben.

5. Gelegentlich treten Interferenzstörungen von benachbarten Fernsehkanälen auf. Diese Störungen können beseitigt werden, indem der Ausgangskanal des Videorekorders mit dem UHF-Kanalregler (KANAL) ⑥ an der Rückplatte anders eingestellt wird. Anschließend muß der Fernseher auf den neuen Videorekorderkanal eingestellt werden.
6. Den Testsignalschalter (TEST SIGNAL) ④ auf „AUS“ stellen.

KANALWAHL

Bei der Wahl eines UHF/VHF-Senders oder beim Umstellen auf eine andere Reihenfolge das Verfahren in der Reihenfolge wie unten beschrieben durchführen.

Beispiel: Einstellung des UHF-Senders in Stellung 2

- ① Den Fernseher einschalten und den Videorekorder Kanal einstellen.
- ② Die Betriebstaste (BETRIEB) auf Ein schalten (Das Licht leuchtet auf).
- ③ Die Abdeckung des Sendereinstellbereichs des Tuners öffnen.
- ④ Die Vorwahltaste (VORWAHL) drücken. Das Leuchtdisplay wechselt. (Abb. 1)
- ⑤ Die Kanaleinstelltaste auf der Frontplatte drücken, so daß "2" in der Stellungen-Sektion erscheint. (Abb. 2)
- ⑥ Die Wellenbereichstaste (BAND) zur Wahl des Wellenbereichs "U" drücken. (Abb. 2)

Wellenbereichs-anzeige	Wellenbereich	Kanal
L	VL	E2 - E4, S21 - S23, S1
H	VH	E5 - E12, S2 - S20
U	U	21 - 69

- ⑦ Die Taste ABSTIMMUNG "+" oder "-" drücken, um einen Kanal zu empfangen und einzustellen. (Abb. 3)
- ⑧ Die Kanaleinstelltaste (KANALWAHL) drücken (Abb. 2)
- 10er-Taste..... Drücken bis 4 angezeigt wird.
- 1er-Taste..... Drücken bis 8 angezeigt wird.

Hinweis: 1. Die Kanäle Nr. 0 bis 99 können mit diesem Gerät voreingestellt werden.
Beispiel: L: S21 → 85 Kanal
2. Den Kanal mit der Kanaleinstelltaste wählen, wenn die Voreinstellung vorgenommen wurde.
Der eingestellte Kanal wird auf dem Fluoreszenzdisplay angezeigt.

- ⑨ Die Schritte 5 bis 8 wiederholen. (Bis zu 16 Stellungen.)
- ⑩ Die Vorwahltaste (VORWAHL) drücken. Die Zeitanzeige und die Kanalnummer erscheinen. (Abb. 4)
- ⑪ Die Abdeckung schließen.

Abb. 1

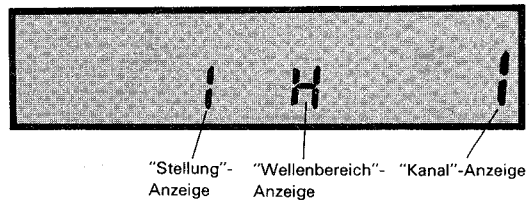


Abb. 2

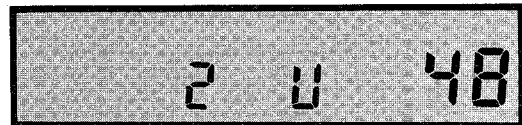


Abb. 3

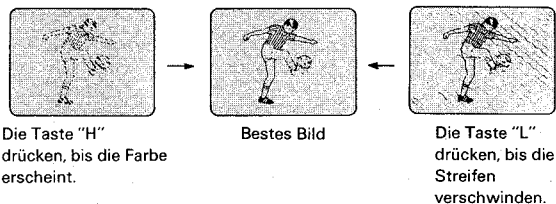
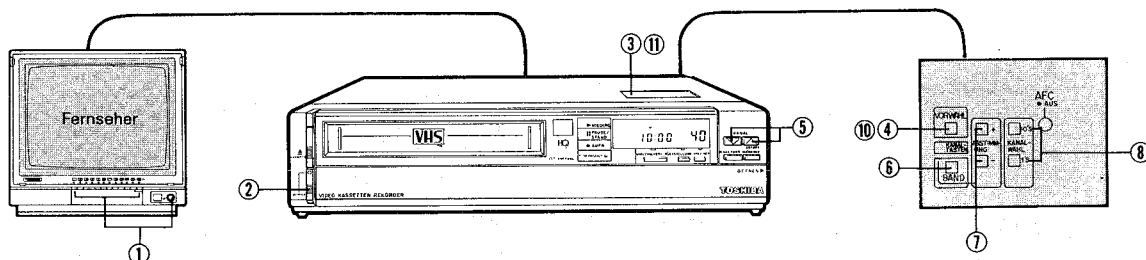
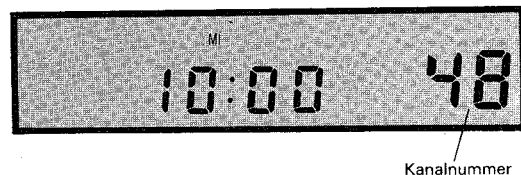


Abb. 4



Einstellung der automatischen Frequenzregelung (AFC)

Wenn die Empfangsfrequenz schwach ist und der Ton Störgeräusche aufweist, die AFC des Empfangskanals ausschalten.

Lampe leuchtet..... AFC ausgeschaltet
Lampe leuchtet nicht..... AFC eingeschaltet

AFC-Ausschaltung

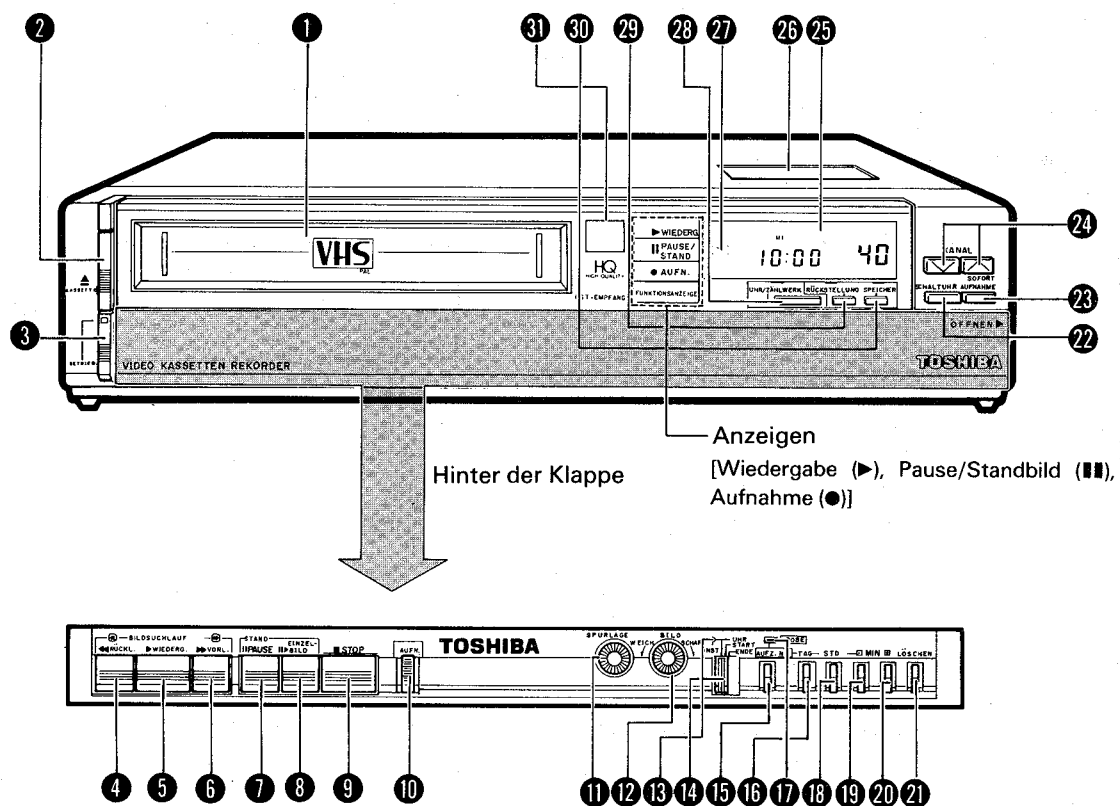
1. Mit der UP/DOWN-Taste den Kanal wählen, dessen AFC ausgeschaltet werden soll.
2. Die Abstimm Taste H oder L drücken.

AFC-Einschaltung

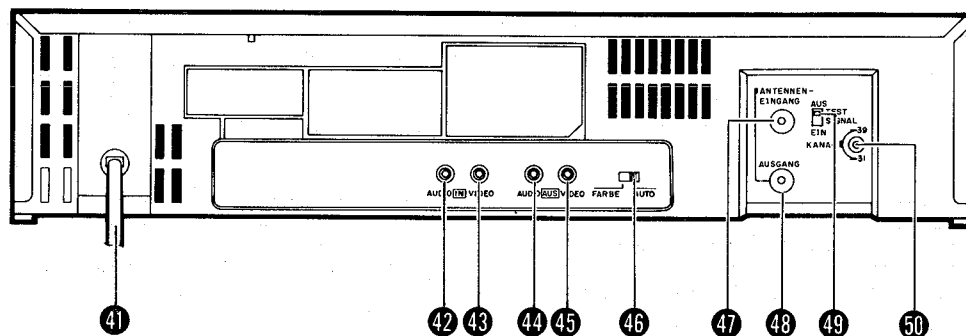
1. Die PRESET-Taste drücken. (AFC wird ausgeschaltet)
2. Dann die PRESET-Taste erneut drücken.

BEZEICHNUNGEN DER BEDIENELEMENTE

VORDERANSICHT



RÜCKANSICHT



BEZEICHNUNGEN DER BEDIENELEMENTE

VORDERANSICHT

- ❶ Kassettenfach
- ❷ Kassettenfach-Öffnungstaste (KASSETTE)
- ❸ Betriebstaste (BETRIEB)
- ❹ Rücklauftaste (RÜCKL.)
- ❺ Wiedergabetaste (WIEDERG.)
- ❻ Vorlauftaste (VORL.)
- ❼ Pause/Standbild-Taste (PAUSE/STAND)
- ❽ Bild-Taste (EINZELBILD)
- ❾ Stoptaste (STOP)
- ❿ Aufnahmetaste (AUFN.)
- ⓫ Spurlagenregler (SPURLAGE)
- ⓬ Bildregler (BILD)
- ⓭ Einstelltaste (EINST)
- ⓮ Betriebsarten-Wahlschalter (UHR/START/ENDE)
- ⓯ Aufzeichnungstaste (AUFZ. NR)
- ⓰ Tag-Taste (TAG)
- ⓱ Prüf-Taste (PROBE)
- ⓲ Stunden-Taste (STD)
- ⓳ Minuten-Minus-Taste (MIN (-))
- ⓴ Minuten-Plus-Taste (MIN (+))
- ⓵ Löschtaste (LÖSCHEN)
- ⓶ Schaltuhr-Taste (SCHALTUHR)
- ⓷ Eintasten-Schaltuhraufnahme-Taste (SOFORT AUFNAHME)
- ⓸ Kanalwahltasten (KANAL)
- ⓹ Leuchtdisplay
- ⓺ Kanalvoreinstellteil
- ⓻ Kassettenanzeige
- ⓼ Schaltuhr/Bandzählwerk-Taste (UHR/ZÄHLWERK)
- ⓽ Rückstelltaste (RÜCKSTELLUNG)
- ⓿ Speichertaste (SPEICHER)
- ⓿ Fernbedienung-Infrarotstrahl-Empfangsfenster

RÜCKANSICHT

- ❶ Netzkabel
- ❷ Audio-Eingangsbuchse (AUDIO IN)
- ❸ Video-Eingangsbuchse (VIDEO IN)
- ❹ Audio-Ausgangsbuchse (AUDIO AUS)
- ❺ Video-Ausgangsbuchse (VIDEO AUS)
- ❻ Farbschalter (FARBE/AUTO)
Dieser Schalter sollte normalerweise auf „AUTO“ eingestellt sein. In Gebieten mit schwachen Signalen diesen Schalter auf FARBE stellen. Bei Wiedergabe diesen Schalter auf die gleiche Position wie bei der Aufnahme einstellen.
- ❼ Antennen-Eingangsbuchse (EINGANG)
- ❽ Antennen-Ausgangsbuchse (AUSGANG)
- ❾ Testsignalschalter (TEST SIGNAL)
Liefert ein Testsignal zur Unterstützung bei der Abstimmung des Fernsehers auf den Ausgang des Videorekorders, siehe die Beschreibung unter „EINSTELLUNG DES FERNSEHERS AUF DEN VIDEOREKORDERAUSGANGSKANAL“. (siehe Seite 2)
- ❿ UHF-Kanalregler (KANAL)
Der Ausgang vom Videorekorder zum Fernseher kann auf jeden Kanal zwischen 31 und 39 mit einem Schraubenzieher eingestellt werden, siehe „EINSTELLUNG DES FERNSEHERS AUF DEN VIDEOREKORDERAUSGANGSKANAL“. (siehe Seite 2)

EINSTELLUNG DER UHRZEIT

Wenn das Netzkabel zum ersten Mal in eine Netzsteckdose eingesteckt wird oder nach einer längeren Unterbrechung der Netzstromversorgung blinkt die Anzeige SO ... SA 0:00 auf.

Beispiel: Einstellung auf „Freitag, 19:25“

1. Den Betriebsarten-Wahlschalter (14) auf UHR stellen.
2. Die Einstelltaste (EINST) (13) drücken, um das Gerät auf die Uhrzeiteinstellung-Betriebsart einzustellen.
3. Mit der Tag-Taste (TAG) (16) den Wochentag einstellen.. „FR“
4. Mit der Stunden-Taste (STD) (18) die Stundenziffern einstellen ... „19“
5. Mit der MIN (+)-Taste (20) die Minutenziffern einstellen ... „25“

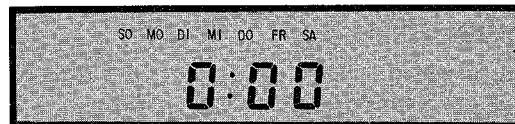
Hinweise:

1. Durch kurzes Drücken der Taste erhöht sich die Anzeige um Eins. Durch Gedrückthalten der Taste erhöht sich die Anzeige fortlaufend.
 2. Wenn versehentlich zu weit vorgegangen wird, mit der Taste MIN (-) (19) zur gewünschten Minutenziffer zurückgehen.
6. Die Einstelltaste (EINST) (13) drücken, um die Uhrzeit anzuzeigen. Wenn die Taste gedrückt wird, beginnt die Uhr von 0 Sekunden zu laufen. Die Uhrzeit kann genau eingestellt werden, indem die Einstelltaste (EINST) (13) beim Zeitzeichen vom Radio oder Fernsehen gedrückt wird.

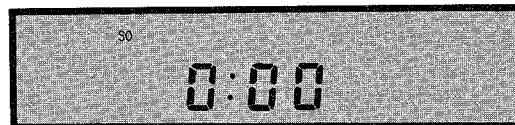
Hinweise:

1. Vor „EINSTELLUNG DER PROGRAMMIERBAREN SCHALTUHR“ muß die Uhrzeit eingestellt werden.
2. Nach einer kurzen Stromzuführungsunterbrechung blinkt das Doppelpunktsymbol (:). Zum Rückstellen des blinkenden Doppelpunktsymbols die Einstelltaste (EINST) (13) zwei Mal drücken.

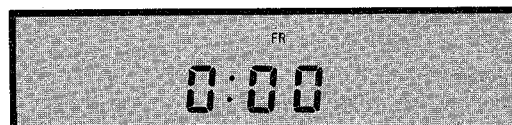
(1)



(2)



(3)



(4)



(5)



(6)



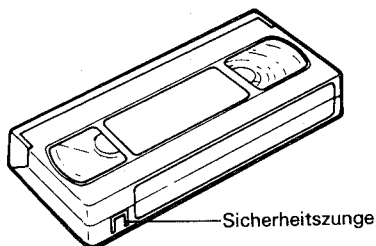
AUFNAHME

VIDEOKASSETTEN

- Dieser Rekorder arbeitet nur mit VHS-Videokassetten. E-240 für 4 Stunden, E-180 für 3 Stunden, E-120 für 2 Stunden, E-60 für 1 Stunde und E-30 für 30 Minuten Aufnahmezeit.

Kassettentyp	Aufnahme/Wiedergabezeit
E-30	30 Minuten
E-60	60 Minuten
E-120	120 Minuten
E-180	180 Minuten
E-240	240 Minuten

- Videokassetten sind mit einer Sicherheitszunge zum Schutz vor unbeabsichtigtem Löschen ausgestattet. Wenn die Zunge entfernt ist, kann die Kassette nicht bespielt werden. Zur Aufnahme auf einer Kassette, deren Zunge entfernt wurde, die Öffnung mit Klebeband verschließen.

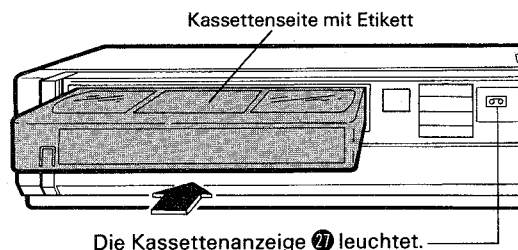


- Die Kassetten nicht direktem Sonnenlicht aussetzen und von der Heizung fernhalten.
- Extreme Feuchtigkeit, starke Vibrationen und Erschütterungen, starke magnetische Felder (in der Nähe eines Motors, Transformators oder Magneten) und staubige Plätze vermeiden.
- Die Kassetten in ihren Behältern aufbewahren und senkrecht aufstellen.

AUFNAHME VON FERNSEHPROGRAMMEN

Dieser Videorekorder ist mit einer automatischen Einschaltfunktion ausgestattet, die bewirkt, daß das Gerät durch Einschieben einer Kassette automatisch eingeschaltet wird.

1. Den Fernseher einschalten und eine Kassette in das Kassettenfach einlegen. Der Videorekorder wird automatisch eingeschaltet (**EINSCHALT-AUTOMATIK**).



2. Den Fernseher auf den Videorekorderkanal einstellen.
3. Den gewünschten Kanal für die Aufnahme mit Hilfe der Kanalwahltasten (24) wählen.
4. Die Aufnahmetaste (AUFN.) (10) drücken.
5. Zum Beenden der Aufnahme die Stoptaste (STOP) (9) drücken.
6. Zum Rückspulen des Bandes die Rücklaufaste (RÜCKL.) (1) drücken.
7. Zum Herausnehmen der Kassette die Kassettenfach-Öffnungstaste (KASSETTE) (2) drücken.

Hinweise:

1. Bei Aufnahme, Wiedergabe und Schnellvorlauf wird das Band bei Erreichen des Bandendes automatisch zurückgespult. Wenn die Speichertaste (SPEICHER) (30) auf EIN steht, stoppt das Gerät an der Zählwerkanzeige „0000“.
2. Zum Wechseln des Aufnahmekanals während der Aufnahme, die Pause/Standbild-Taste (PAUSE/STAND) (7) drücken, mit den Kanalwahltasten (KANAL) (24) den gewünschten Kanal wählen und dann die Pause/Standbild-Taste (PAUSE/STAND) (7) erneut zum Fortsetzen der Aufnahme drücken.
3. Die Pause/Standbild-Taste (PAUSE/STAND) (7) drücken, um unnötiges Material auszulassen. Wenn die Pausenfunktion etwa 10 Minuten lang kontinuierlich eingesetzt wird, kehrt der Videorekorder in Stopp-Betriebsart zurück, um das Band und die internen Bauelemente zu schonen.
4. Geräte, die an den Audio und Video-Eingangsbuchsen an der Rückseite angeschlossen sind, müssen abgetrennt werden.

SEHEN EINES ANDEREN PROGRAMMS WÄHREND DER AUFNAHME

Sollten zur gleichen Zeit zwei interessante Sendungen ausgestrahlt werden, können Sie eine davon ansehen und gleichzeitig die andere aufnehmen.

1. Die Aufnahme der einen Sendung mit den obigen Bedienschritten 1 bis 4 starten.
2. Den Fernseher mit dem Kanalwähler des Fernsehers auf den Kanal stellen, der angesehen werden soll.

ÜBERSPIELEN ZWISCHEN VIDEOREKORDERN

1. Die Video- und Audio-Ausgangsbuchsen (VIDEO AUS) ④⑤, ④⑥ von Videorekorder 1 an die Video- und Audio-Eingangsbuchsen (VIDEO IN und AUDIO IN) ④③, ④② von Videorekorder 2 anschließen.
2. Die Wiedergabe erfolgt auf Videorekorder 1 und die Aufnahme auf Videorekorder 2.
3. Auf dem Fernsehschirm kann das Wiedergabebild von Videorekorder 1 gesehen werden.

Siehe für diesen Anschluß das Diagramm unten.

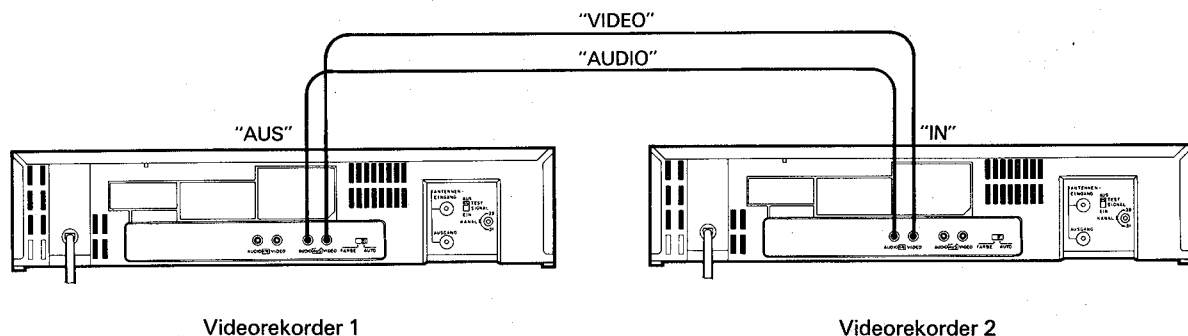
Hinweis:

Wenn das Überspielen beendet ist, ziehen Sie die Kabel aus den Buchsen.

VIDEOSCHNITT

1. Die Wiedergabetaste (WIEDERG.) ⑤ drücken und den Bildschirm beobachten, bis die exakte Stelle erreicht ist, wo die neue Aufnahme beginnen soll.
2. Die Pause/Standbild-Taste (PAUSE/STAND) ⑦ drücken. Dann wird auf dem Fernsehschirm das Standbild angezeigt.
3. Die Aufnahmetaste (AUFN.) ⑩ drücken. Auf dem Fernsehschirm erscheint das Programmmaterial, das aufgenommen werden soll.
4. Durch erneutes Drücken der Pause/Standbild-Taste (PAUSE/STAND) ⑦ beginnt die Aufnahme. Die neue Aufnahme wird ohne Unterbrechung direkt an die vorige angehängt.

Anschlüsse



Hinweis:

Beim Überspielen nimmt die Qualität der neuen Aufnahme geringfügig ab.

Schaltuhr/Bandzählwerk-Anzeige

Mit der Schaltuhr/Bandzählwerk-Taste (UHR/ZÄHLWERK) ②⑧ kann die Anzeige-Betriebsart umgestellt werden.

Schaltuhr-Anzeige

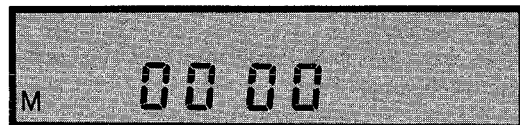


Bandzählwerk-Anzeige



Speicherfunktion

Wenn die Speichertaste (SPEICHER) ⑩ gedrückt wird, leuchtet die Anzeige und das Band wird beim Rückspulen und Schnellvorspulen gestoppt, wenn das Zählwerk etwa 0000 anzeigt.



Hinweis:

Wenn der Videorekorder in Bereitschafts-Betriebsart ist, wird die Speicher-Anzeige auf Schaltuhr-Anzeige umgestellt.

WIEDERGABE

WIEDERGABE VON VORBESPIELTEN KASSETTEN

1. Die Schritte 1 bis 2 unter „AUFNAHME VON FERNSEH-PROGRAMMEN“ durchführen.
2. Die Wiedergabetaste (WIEDERG.) ⑤ drücken.
3. Zum Beenden der Wiedergabe die Stoptaste (STOP) ⑨ drücken.
4. Das Band durch Drücken der Rücklauftaste (RÜCKL.) ④ zurückspulen.
5. Zum Herausnehmen der Kassette die Kassettenfach-Öffnungstaste (KASSETTE) ② drücken.

Bei der Wiedergabe von vorgespielten Kassetten oder Kassetten, die mit einem anderen Gerät aufgenommen wurden, können auf dem Fernsehbild horizontale Störzeilen auftreten. Diese Störungen können mit dem Spurlagenregler (SPURLAGE) ⑪ reduziert werden. Nach der Einstellung des Reglers dauert es ein bis zwei Sekunden, bis die neue Einstellung wirksam wird. Nach der Wiedergabe dieser bestimmten Kassette den Regler immer wieder auf die Mittelstellung zurückdrehen.

Dieses Gerät ist mit einem Bildregler (BILD) ⑫ ausgestattet. Durch Drehen des Reglers in Uhrzeigerichtung wird das Bild schärfer und durch Drehen in Gegenuhrzeigerichtung weicher.

BILDSUCHLAUF

1. Die Wiedergabetaste (WIEDERG.) ⑤ drücken (zum Starten der Wiedergabe).
2. Durch Drücken der Rücklauf- oder Vorlauftaste (RÜCKL. oder VORL.) ④, ⑥ läuft das Bild schneller (mit etwa der 7-fachen Normalgeschwindigkeit) in Rückwärts- bzw. Vorwärtsrichtung. Auf diese Weise können gesuchte Bandstellen schnell gefunden werden.

Hinweise:

- * Während des Bildsuchlaufs bewegen sich einige Störzeilen aufwärts und abwärts auf dem Bildschirm.
- * Wenn während des Bildsuchlaufs das Bild vertikal auf dem Fernsehschirm wandert, den V-Bildfangregler des Fernsehers einstellen.
- * Während des Bildsuchlaufs ist der Ton unterdrückt.

STANDBILD

1. Die Wiedergabetaste (WIEDERG.) ⑤ drücken (zum Starten der Wiedergabe).
2. Zum Anhalten des Bildes und Ansehen des Standbildes die Pause/Standbild-Taste (PAUSE/STAND) ⑦ drücken.
3. Durch erneutes Drücken der Pause/Standbild-Taste (PAUSE/STAND) ⑦ wird die normale Wiedergabe fortgesetzt.

Hinweise:

1. Nach etwa 5 Minuten wird die Standbild-Betriebsart automatisch ausgeschaltet und die Wiedergabe fortgesetzt.
2. Wenn in der Mitte des Standbildes Störungen erscheinen, kann versucht werden, durch Drücken der Bild-Taste (EINZELBILD) ⑧ die Störungen aus dem Bild bringen.

BILD-FORTSCHALTUNG

Zeitlupen-Wiedergabe mit 1/10 der Normalgeschwindigkeit kann durchgeführt werden, indem die Bild-Taste (EINZELBILD) ⑧ gedrückt gehalten wird.

1. Die Wiedergabetaste (WIEDERG.) ⑤ drücken (in Wiedergabe-Betriebsart).
2. Die Pause/Standbild-Taste (PAUSE/STAND) ⑦ drücken (in Standbild-Betriebsart).
3. Die Bild-Taste (EINZELBILD) ⑧ gedrückt halten. Wiedergabe mit 1/10 der Normalgeschwindigkeit wird durchgeführt.
4. Die Bild-Taste (EINZELBILD) ⑧ loslassen und dann die Pause/Standbild-Taste (PAUSE/STAND) ⑦ drücken. Der Videorekorder kehrt in Normal-Betriebsart zurück.

AUTOMATISCHE WIEDERGABE

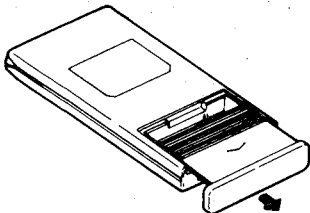
Die Rücklauftaste (RÜCKL.) ④ gedrückt halten und die Wiedergabetaste (WIEDERG.) ⑤ drücken. Wenn die Speichertaste (SPEICHER) ⑩ auf EIN steht, wird das Band bis zur Zählwerkanzeige "0000" zurückgespult, dann startet die Wiedergabe. Wenn die Speichertaste (SPEICHER) ⑩ auf AUS steht, wird das Band zum Bandanfang zurückgespult, dann startet die Wiedergabe.

Hinweise:

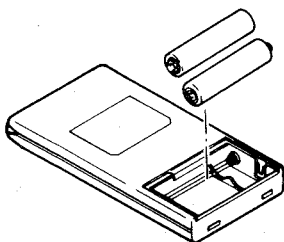
1. Beim Zurückspulen blinkt die WIEDERG.-Anzeigelampe.
2. Nach dem Zurückspulen wird die Kassette einmal wiedergegeben.

FERNBEDIENUNG

EINSETZEN DER BATTERIEN

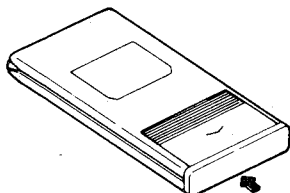


Den Batteriefachdeckel in Pfeilrichtung abschieben.



2 Batterien (Größe „R03“) einsetzen.

Hinweis: Die Batterien entsprechend der Polaritätsmarkierungen einsetzen.



Den Batteriefachdeckel schließen.

WIRKUNGSBEREICH DER FERNBEDIENUNG

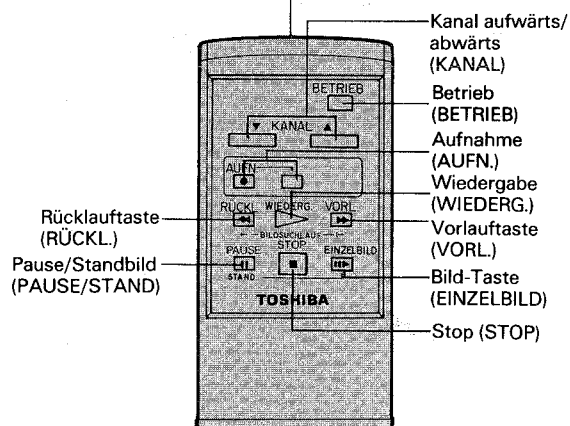
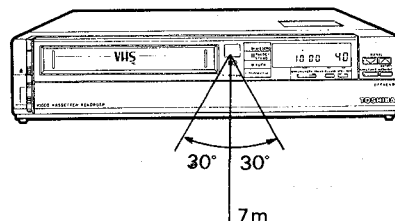
Die Fernbedienung muß „Sichtkontakt“ mit dem Infrarotstrahl-Empfangsfenster ❶ vorne am Videorekorder haben. Sie muß sich in einem Winkel von 30° nach beiden Seiten von der Mittellinie befinden. Auf die Frontseite des VTR gerichtet, beträgt die maximale Funktionsdistanz der Fernbedienungseinheit etwa 7 m.

TASTENFUNKTIONEN DER FERNBEDIENUNG

Die Funktionen der Tasten der Fernbedienung entsprechen den Tasten an der Frontplatte des Videorekorders. Mit den Tasten der Fernbedienung lassen sich 13 Funktionen bedienen, nämlich Kanal aufwärts/abwärts (KANAL), Betriebstaste (BETRIEB), Aufnahme (AUFN.), Rücklaftaste (RÜCKL.), Vorlaftaste (VORL.), Bildsuchlauf vorwärts/rückwärts, Wiedergabe (WIEDERG.), Pause/Standbild (PAUSE/STAND), Stop (STOP) und Bild (EINZELBILD).

Hinweise:

1. In den folgenden Fällen ist Fernbedienung nicht möglich:
 - In der Betriebsart Schaltuhr-Aufnahme.
 - Wenn sich keine Kassette im Kassettenfach befindet.
2. Die Tasten der Fernbedienung in Zeitabständen von etwa einer Sekunde drücken, damit ein ordnungsgemäßes Funktionieren gewährleistet ist.
3. Wenn die Fernbedienung für längere Zeit nicht verwendet werden soll, sollten die Batterien entnommen werden, um Beschädigungen durch Auslaufen der Batterien zu verhindern.
4. Die Fernbedienung nicht Wärme, Feuchtigkeit und Erschütterungen aussetzen.
5. Die automatische Wiedergabe kann nicht mit der Fernbedienung durchgeführt werden. Für automatische Wiedergabe müssen die Bedienelemente am Gerät betätigt werden.
6. Drücken Sie die Aufnahmetaste (AUFN.) gleichzeitig mit der rechten Taste.



SCHALTUHR

BEDIENELEMENTE FÜR SCHALTUHRBETRIEB

13 Einstelltaste (EINST)

- Dient zur Einstellung der Uhrzeit.
- Durch einmaliges Drücken dieser Taste schaltet das Gerät in die Uhrzeiteinstellung-Betriebsart. Diese Betriebsart wird durch nochmaliges Drücken der Taste wieder aufgehoben.

14 Betriebsarten-Wahlschalter

- UHR-Betriebsart
Zur Anzeige der Uhrzeit.
- START-Betriebsart
Zur Einstellung der Schaltuhr-Einschaltzeit.
- ENDE-Betriebsart
Zur Einstellung der Schaltuhr-Ausschaltzeit.

15 Aufzeichnungstaste (AUFZ.NR)

- Dient zur Eingabe der Programmnummer 1 bis 4.

16 Tag-Taste (TAG)

- Dient zur Eingabe des Wochentages.
- Durch einmaliges Drücken dieser Taste geht die Anzeige um einen Tag weiter. Wird diese Taste gedrückt gehalten, geht die Anzeige fortlaufend weiter. (Beispiel)

Ein Tag der ersten Woche, „SO“ → „MO“ → ... „SA“
↓
Ein Tag der nächsten Woche, „FOLG SO“ → „FOLG MO“ → ... „FOLG SA“
↓
Der gleiche Tag jeder Woche, „WCHTL SO“ → „WCHTL MO“ → ... → „WCHTL SA“
↓
Täglich, „SO. MO. DI ... SA“

17 Prüf-Taste (PROBE)

Dient zum Prüfen der gespeicherten Programmdaten. Wenn diese Taste gedrückt wird, beginnt der Programmsuchlauf und zeigt die Programminhalte 1 bis 4 (Start- und Endzeitpunkt) kontinuierlich im Leuchtdisplay.

Nach Anzeige der Programminhalte arbeitet das Display wieder als Uhr.

18 Stunden-Taste (STD)

- Dient zur Eingabe der Stundenziffern.
- Durch einmaliges Drücken der Taste erhöht sich die Stundenanzeige um Eins.
Wird die Taste gedrückt gehalten, erhöht sich die Stundenanzeige fortlaufend.

19 Minuten-Minus-Taste (MIN (-))

- Dient zur Einstellung der Minutenziffern.
- Wenn diese Taste einmal gedrückt wird, wird die Minute um 1 vermindert. Durch Gedrückthalten der Taste erfolgt eine schnelle Veränderung.

20 Minuten-Plus-Taste (MIN (+))

- Dient zur Einstellung der Minutenziffern.
- Wenn diese Taste einmal gedrückt wird, wird die Minute um 1 erhöht. Durch Gedrückthalten der Taste erfolgt eine schnelle Veränderung.

21 Lösch-taste (LÖSCHEN)

Dient zum Löschen der eingespeicherten Programme.

22 Schaltuhr-Taste (SCHALTUHR)

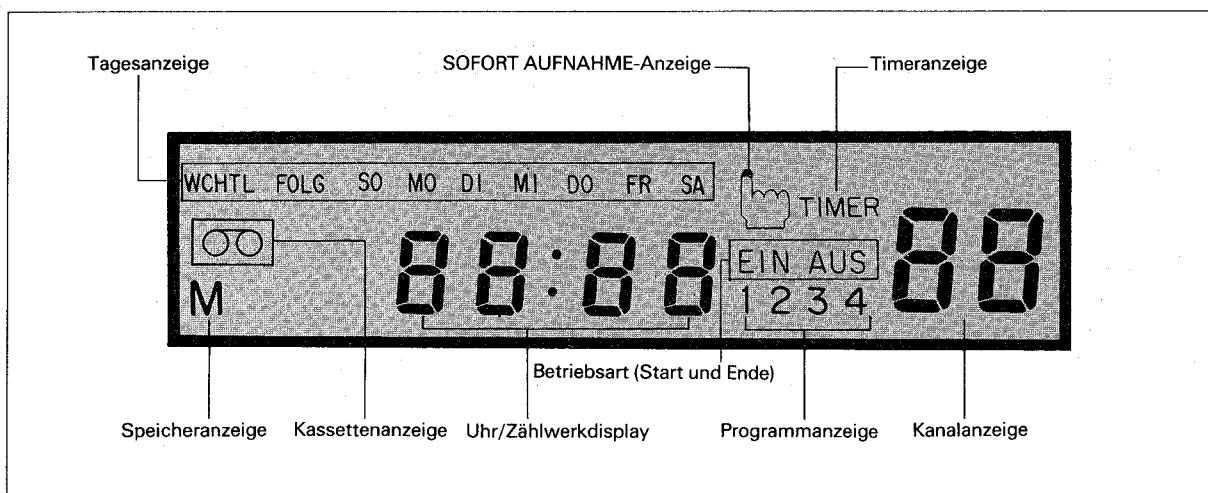
Dient zur Einstellung der Schaltuhr-Betriebsart.

23 Eintasten-Schaltuhraufnahme-Taste (SOFORT AUFNAHME)

- Dient für Aufnahmen von 30 Minuten oder Mehrfache davon in der normalen Betriebsart (max. 4 Stunden).

* Uhrzeit → 30 Min. → 60 Min. → → 240

- Dient zur Angabe der Timer-Aus-Zeit in Einheiten von 30 Minuten.
30 → 60 → 90 →



PROGRAMMIERBARE SCHALTUHR

- * Dieser Timer kann vier Programme für einen Tag der ersten Woche, für einen Tag der nächsten Woche, für den gleichen Tag jeder Woche oder für die gleiche Zeit an jedem Tag aufnehmen.
- * Wenn die Spannungsversorgung zum Videorekorder kurz unterbrochen wird, läuft die Uhr weiter und werden die programmierten Aufnahmen ausgeführt, außer wenn auf der Uhranzeige SO SA 0 : 00 blinkt.
- * Wenn auf der Uhranzeige SO SA 0 : 00 blinkt, müssen Uhreinrichtung und Programmierung erneut durchgeführt werden. (Nach einer kurzen Stromunterbrechung von etwa einigen Sekunden, leuchtet die Uhranzeige blinkend auf.) Der Doppelpunkt (:) blinkt bei kurzen Unterbrechungen der Spannungsversorgung. Durch zweimaliges Drücken der Einstelltaste (EINST) 13 wird die blinkende Doppelpunkt-Anzeige zurückgesetzt. Die gespeicherten Programme werden reserviert.
- * Die Uhr arbeitet im 24-Stunden-Betrieb.
- * Die Einstellung der Schaltuhr ist auch in der Bereitschaftsbetriebsart möglich.

Einstellung der programmierbaren Schaltuhr

1. Die Uhrzeit überprüfen und gegebenenfalls korrigieren. (siehe Seite 6)

2. Eine Kassette in das Kassettenfach einlegen (überprüfen, daß die Sicherheitszunge der Kassette vorhanden ist).
3. Den Betriebsarten-Wahlschalter 14 auf START stellen.
4. Die Programmnummer mit der Aufzeichnungstaste (AUFZ.NR) 15 angeben. (Eine aus der Programmnummern 1 bis 4 angeben.)
5. Den Wochentag, die Stunde und die Minute der Aufnahmezeit (SO → MO ... → SA, FOLG SO → FOLG MO → ... → FOLG SA, WCHTL SO → WCHTL MO → ... → WCHTL SA, SO.MO. ... SA) mit der Tag-Taste (TAG) 16, der Stunden-Taste (STD) 18, der MIN (+)-Taste 20 und der MIN (-)-Taste 19 einstellen.
6. Den Betriebsarten-Wahlschalter 14 auf ENDE stellen.
7. Den Endzeitpunkt mit der Stunden-Taste (STD) 18, der MIN (+)-Taste 20 und der MIN (-)-Taste 19 einstellen.
8. Das gewünschte Programm mit den Kanalwahltasten (KANAL) 24 einstellen.
9. Zum Fortsetzen der Vorwahl der Programme die Schritte 3 bis 8 wiederholen (maximal 4 Programme).
10. Den Betriebsarten-Wahlschalter 14 auf UHR zurückstellen.
11. Die Schaltuhr-Taste (SCHALTUHR) 22 drücken.

ZUM BESSEREN VERSTÄNDNIS DES 14-TAGE-TIMERS

Mit diesem Videorekorder ist 14-Tage-Voreinstellung möglich. Diese Funktion ist nützlich, aber wenn sie nicht richtig eingesetzt wird, ist wunschgemäße Aufnahme nicht möglich.

Vor dem Einsatz der 14-Tage-Timerfunktion die folgende Erklärung gründlich durchlesen. Die untenstehende Abbildung (1) zeigt, wie bei einer momentanen Uhrzeit von 10:00 die folgenden 14 Tage in die erste Woche und die folgende Woche unterteilt sind.

Denken Sie beim Erlernen der 14-Tage-Timerfunktion an dieses Schema.

Abb. (1)

SONNTAG	MONTAG	DIENSTAG	MITTWOCH	DONNERSTAG	FREITAG	SAMSTAG
		Gegenwärtige Zeit	10:00			
				(Erste Woche)		
				(Nächste Woche)		

Die Standardzeit für den 14-Tage-Timer ist der Zeitpunkt, wo die Schaltuhr-Taste gedrückt wird. Was passiert, wenn der Timer am Mittwoch der jetzigen Woche (Abb. (2)) zur Aufzeichnung des Fernsehprogramms am Donnerstag der nächsten Woche eingestellt wird und die Schaltuhr-Taste am Freitag der momentanen Woche (Abb. (3)) gedrückt wird? Es ist nicht möglich, das gewünschte Programm aufzuzeichnen. Siehe untenstehende Abbildung.

Abb. (2)

SONNTAG	MONTAG	DIENSTAG	MITTWOCH	DONNERSTAG	FREITAG	SAMSTAG
			● Eingestellte Uhrzeit			
				(Erste Woche)		
				■ (Nächste Woche)		

■ Gewünschtes Programm

Abb. (3)

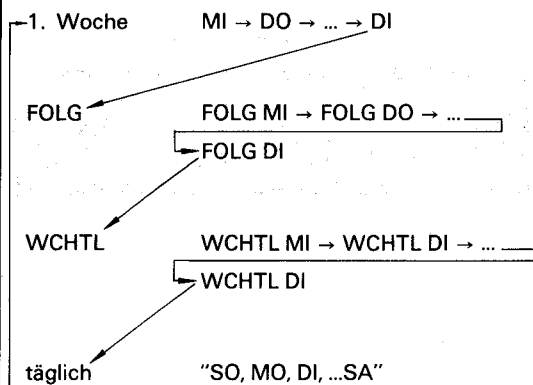
SONNTAG	MONTAG	DIENSTAG	MITTWOCH	DONNERSTAG	FREITAG	SAMSTAG
			● Eingestellte Uhrzeit		○ (Schaltuhr-Taste)	
					(Erste Woche)	
					■ (Nächste Woche)	
					□ (Tatsächlich aufgezeichnetes Programm)	

■ Gewünschtes Programm

DAS TAGESDISPLAY

Wenn die Tag-Taste (TAG) 16 gedrückt wird, wird das Tagesdisplay wiederholt, wie unten gezeigt.

Beispiel: Heute ist Mittwoch.

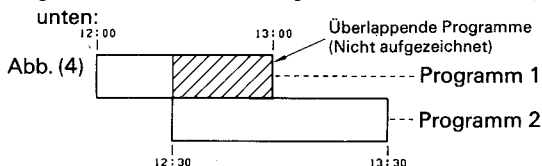


Hinweis:

Das Tagesdisplay ändert sich vom heutigen Tag an.

VORSICHTSMASSREGELN ZUM EINSATZ DES 14-TAGE-TIMERS

- Sicherstellen, daß die Uhrzeit richtig eingestellt ist.
- Wenn der Videorekorder von Timer-Betriebsart auf Normal-Betriebsart umgestellt werden soll, die Betriebstaste (BETRIEB) 3 oder Schaltuhr-Taste (SCHALTUHR) 22 drücken.
- Wenn der Videorekorder auf Timer-Betriebsart zurückgestellt wird, immer die Prüf-Taste (PROBE) 1 drücken, um sicherzustellen, daß das richtige Programm eingestellt ist. Andernfalls kann es sein, daß das Programm nicht aufgezeichnet werden kann, weil die Standardzeit für den 14-Tage-Timer sich auf den Zeitpunkt beim Drücken der Schaltuhr-Taste (SCHALTUHR) bezieht.
- Wenn voreingestellte Programme nicht durchgeführt werden, bleiben sie reserviert.
- Darauf achten, nicht die voreingestellten Zeitpunkte überlappen zu lassen. Wenn voreingestellte Programme überlappt werden, hat der Start-Zeitpunkt Priorität zur Ausführung, und die überlappenden Programme werden nicht aufgezeichnet. Siehe Abb. (4) unten:



Timer-Aufzeichnung

Im folgenden einige Beispiel zum leichteren Verständnis des Timers. Das Beispiel geht davon aus, daß der Timer mit vier Programmen (ein Tag der gleichen Woche, ein Tag der nächsten Woche, der gleiche Tag jeder Woche und täglich) eingestellt wird.

Beispiel: Heute ist Mittwoch, 9:00 Uhr.

Die Programme werden wie folgt eingestellt:

Programm 1. 1. Freitag 11:00 bis 11:30, Kanal 43

..... unwirksam nach Durchführung

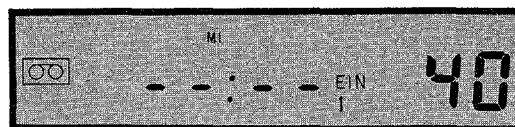
Programm 2. Nächster Dienstag 13:00 bis 13:15, Kanal 42..... unwirksam nach Durchführung

Programm 3. Wöchentlich Montag 8:00 bis 8:15, Kanal 46..... kontinuierlich wirksam nach Durchführung

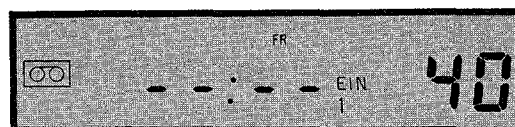
Programm 4. Täglich 19:00 bis 19:15, Kanal 43

.. kontinuierlich wirksam nach Durchführung

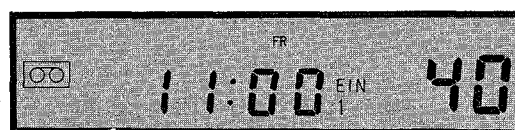
1)-1



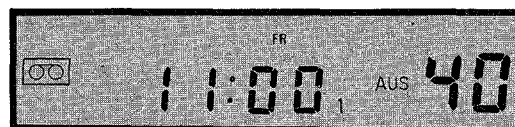
1)-2



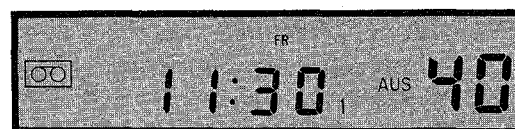
1)-3



1)-4



1)-5



1)-6



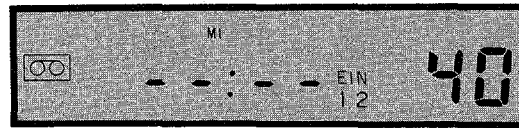
Verfahren 1)

1. Den Betriebsarten-Wahlschalter 14 auf „START“ stellen.
2. Die Tag-Taste (TAG) 16 drücken, um „FR“ einzustellen.
3. Die Stunden-Taste (STD) 18, MIN (-)-Taste 19 und die MIN (+)-Taste 20 auf Startzeit einstellen „11 : 00“
4. Den Betriebsarten-Wahlschalter 14 auf „ENDE“ stellen.
5. Die MIN (-)-Taste 19 und die MIN (+)-Taste 20 auf Endzeit einstellen „11 : 30“
6. Die Kanalwahltaste (KANAL) 24 drücken, um den gewünschten Kanal einzustellen „43“

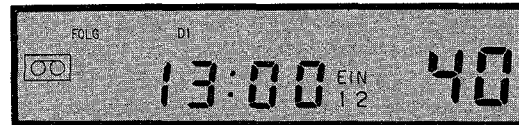
Verfahren 2)

1. Den Betriebsarten-Wahlschalter ⑭ auf „START“ stellen.
2. Die Aufzeichnungstaste (AUFZ.NR) ⑮ drücken, um „2“ einzustellen.
3. Die Tag-Taste (TAG) ⑯ auf „FOLG DI“ stellen.
4. Die Stunden-Taste (STD) ⑰, MIN (-)-Taste ⑱ und die MIN (+)-Taste ⑳ auf Startzeit einstellen „13:00“
5. Den Betriebsarten-Wahlschalter ⑭ auf „ENDE“ stellen.
6. Die MIN (-)-Taste ⑱ und die MIN (+)-Taste ⑳ auf Endzeit einstellen „13:15“
7. Die Kanalwahltaste (KANAL) ㉔ drücken, um den gewünschten Kanal einzustellen „42“

2)-2



2)-4



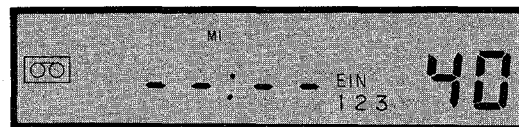
2)-7



Verfahren 3)

1. Den Betriebsarten-Wahlschalter ⑭ auf „START“ stellen.
2. Die Aufzeichnungstaste (AUFZ.NR) ⑮ drücken, um „3“ einzustellen.
3. Die Tag-Taste (TAG) ⑯ auf „WCHTL MO“ stellen.
4. Die Stunden-Taste (STD) ⑰, MIN (-)-Taste ⑱ und die MIN (+)-Taste ⑳ auf Startzeit einstellen „8:00“
5. Den Betriebsarten-Wahlschalter ⑭ auf „ENDE“ stellen.
6. Die MIN (-)-Taste ⑱ und die MIN (+)-Taste ⑳ auf Endzeit einstellen „8:15“
7. Die Kanalwahltaste (KANAL) ㉔ drücken, um den gewünschten Kanal einzustellen „46“

3)-2



3)-4



3)-7



Verfahren 4)

1. Den Betriebsarten-Wahlschalter ⑭ auf „START“ stellen.
2. Die Aufzeichnungstaste (AUFZ.NR) ⑮ drücken, um „4“ einzustellen.
3. Die Tag-Taste (TAG) ⑯ auf „SO, MO, ... SA“ stellen.
4. Die Stunden-Taste (STD) ⑰, MIN (-)-Taste ⑱ und die MIN (+)-Taste ⑳ auf Startzeit einstellen „19:00“
5. Den Betriebsarten-Wahlschalter ⑭ auf „ENDE“ stellen.
6. Die MIN (-)-Taste ⑱ und die MIN (+)-Taste ㉑ auf Endzeit einstellen „19:15“
7. Die Kanalwahltaste ㉒ drücken, um den gewünschten Kanal einzustellen „43“
8. Den Betriebsarten-Wahlschalter ⑭ auf „UHR“ stellen.
9. Die Schaltuhr-Taste (SCHALTUHR) ㉓ drücken.

Hinweise:

1. Wenn ein Programm vorgewählt werden soll, den Betriebsarten-Wahlschalter nach Durchführung von Schritt 6 bei Verfahren 1) auf Stellung „UHR“ stellen und dann die Schaltuhr-Taste drücken.
2. Wenn keine Kassetten eingelegt ist, ist Timer-Aufzeichnung nicht möglich. In diesem Fall erscheint die Anzeige „E“, wenn die Schaltuhr-Taste (SCHALTUHR) ㉓ gedrückt wird. Wenn die Löschschutzzunge der Kassette abgebrochen ist, ist Timer-Aufzeichnung ebenfalls unmöglich. In diesem Fall wird die Kassette automatisch ausgeworfen. (Abb. 1)
3. Bei Timer-Aufzeichnung können die Vorwahl-Inhalte (Programmnummer, Kanal, Wochentag oder Timer-Ein/Aus-Zeit) nicht geändert werden.
4. Der End-Zeitpunkt kann alle 30 Minuten mit der Eintasten-Schaltuhraufnahme-Taste (SOFORT AUFNAHME) voreingestellt werden.

Prüfen der Timer-Einstellung

Die Prüf-Taste (PROBE) ⑰ drücken.

Dann erscheinen die Programminhalte 1 bis 4 (Startzeit und Endzeit), die vorher gespeichert sind, kontinuierlich in der Schaltuhr/Bandzählwerk-Anzeige. Wenn der Programm-Suchlauf das Ende erreicht, kehrt das Display zur Anzeige der momentanen Uhrzeit zurück.

Löschen der Timer-Einstellung

1. Den Betriebsarten-Wahlschalter ⑭ auf START stellen.
2. Die Prüf-Taste (PROBE) ⑰ drücken, um die zu löschen-de Programmnummer anzuzeigen.
3. Die Lösch-taste (LÖSCHEN) ㉑ drücken. Timer-Aus-Zeit und Kanal werden ebenfalls gelöscht.

Hinweis:

Die Timer-Einstellung kann nur gelöscht werden, wenn der Betriebsarten-Wahlschalter ⑭ auf START steht.

Verwendung des Videorekorders nach Drücken der schaltuhr-Taste (SCHALTUHR).

1. Die Betriebstaste (BETRIEB) ③ drücken, um einzuschalten.

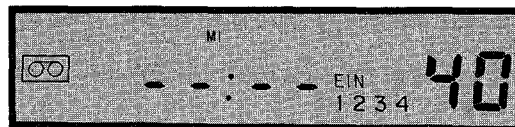
Rückstellen des Videorekorders auf Timer-Betriebsart

1. Die Prüf-Taste (PROBE) ⑰ drücken, um Programme zu überprüfen.
2. Die Schaltuhr-Taste (SCHALTUHR) ㉓ drücken.

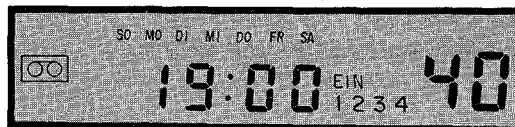
Hinweis:

Die Standardzeit für den Timerbetrieb ist der Zeitpunkt des Drückens der Schaltuhr-Taste (SCHALTUHR).

4)-2



4)-4



4)-7



4)-8



Hinweis: Während der Einstellung geht die Uhrzeit vor.

4)-9

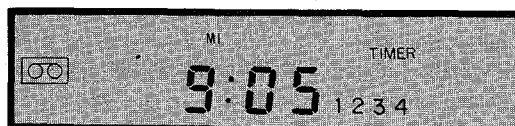
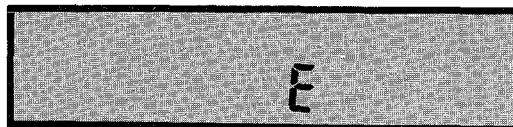


Abb. 1



SCHALTUHR-AUFNAHME MIT EINEM TASTENDRUCK

Hinweise:

1. Jedesmal, wenn die Eintasten-Schaltuhraufnahme-Taste (SOFORT AUFNAHME) **23** gedrückt wird, wird die Aufnahmezeit um 30 Minuten verlängert. Die längste Aufnahmezeit beträgt 4 Stunden (achtmaliges Drücken der Taste). (Die Einstellung der Eintasten-Schaltuhraufnahme kann nur in Schritten von 30 Minuten durchgeführt werden.)
2. Die Eintasten-Schaltuhraufnahme ist nur möglich, wenn das Gerät mit Spannung versorgt wird und der Schaltuhr-Wahlschalter **11** auf UHR steht.

Beispiel: Aufnahme von Kanal 42 für 1-1/2 Stunden, beginnend zur gegenwärtigen Zeit 22:05 am Donnerstag

1. Kanal 42 durch Drücken der Kanalwahltaste (KANAL) **24** wählen. (Abb. 1)
2. Zur Einstellung der Aufnahmedauer die Eintasten-Schaltuhraufnahme-Taste (SOFORT AUFNAHME) **23** drücken.
Erstes Drücken: 22:35 (30 Minuten)
Zweites Drücken: 23:05 (1 Stunde)
Drittes Drücken: 23:35 (1 Stunde und 30 Minuten) (Abb. 2)
3. Danach innerhalb von 9 Sekunden die Schaltuhr-Taste (SCHALTUHR) **22** drücken. (Abb. 3)

Abb. 1

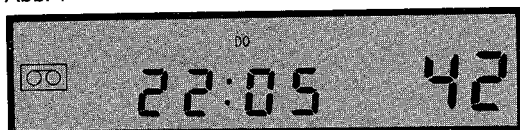


Abb. 2

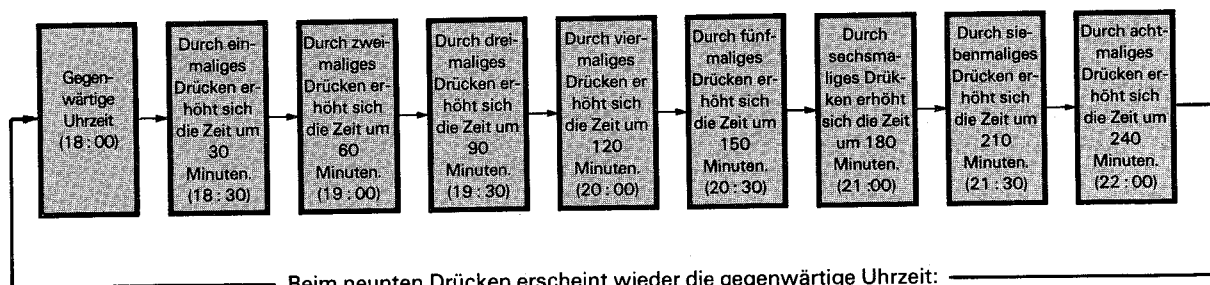
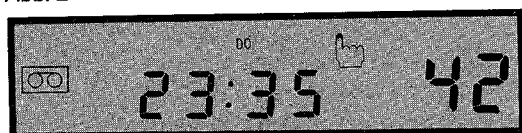
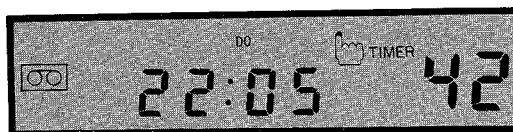


Abb. 3



Beispiel: Einstellung von Kanal 40 für Aufnahme am Samstag um 20:02 für 1 Stunde für Programm 1, Zeitpunkt der Einstellung: Dienstag 8:21

1. Für Einstellung von Programmnummer, Kanal und Schaltuhr-Einschaltzeit siehe die Schritte 1 bis 6 unter „Timer-Aufzeichnung“.
2. Den Betriebsarten-Wahlschalter **14** auf ENDE stellen.
3. Die Eintasten-Schaltuhraufnahme-Taste (SOFORT AUFNAHME) **23** zweimal drücken.
4. Den Betriebsarten-Wahlschalter **14** auf UHR stellen.
5. Zur Beendigung der Einstellung die Schaltuhr-Taste (SCHALTUHR) **22** drücken.
Die TIMER-Anzeige leuchtet.

Fehleranzeige: Wenn die Schaltuhr-Taste (SCHALTUHR) **22** gedrückt wird, ohne daß die Schaltuhr-Einschaltzeit und/oder -Ausschaltzeit eingestellt ist oder ohne daß eine Kassette eingelegt ist, leuchtet die Anzeige „E“ (während die Schaltuhr-Taste (SCHALTUHR) **22** gedrückt wird).

SECTION 2

ADJUSTMENT PROCEDURES

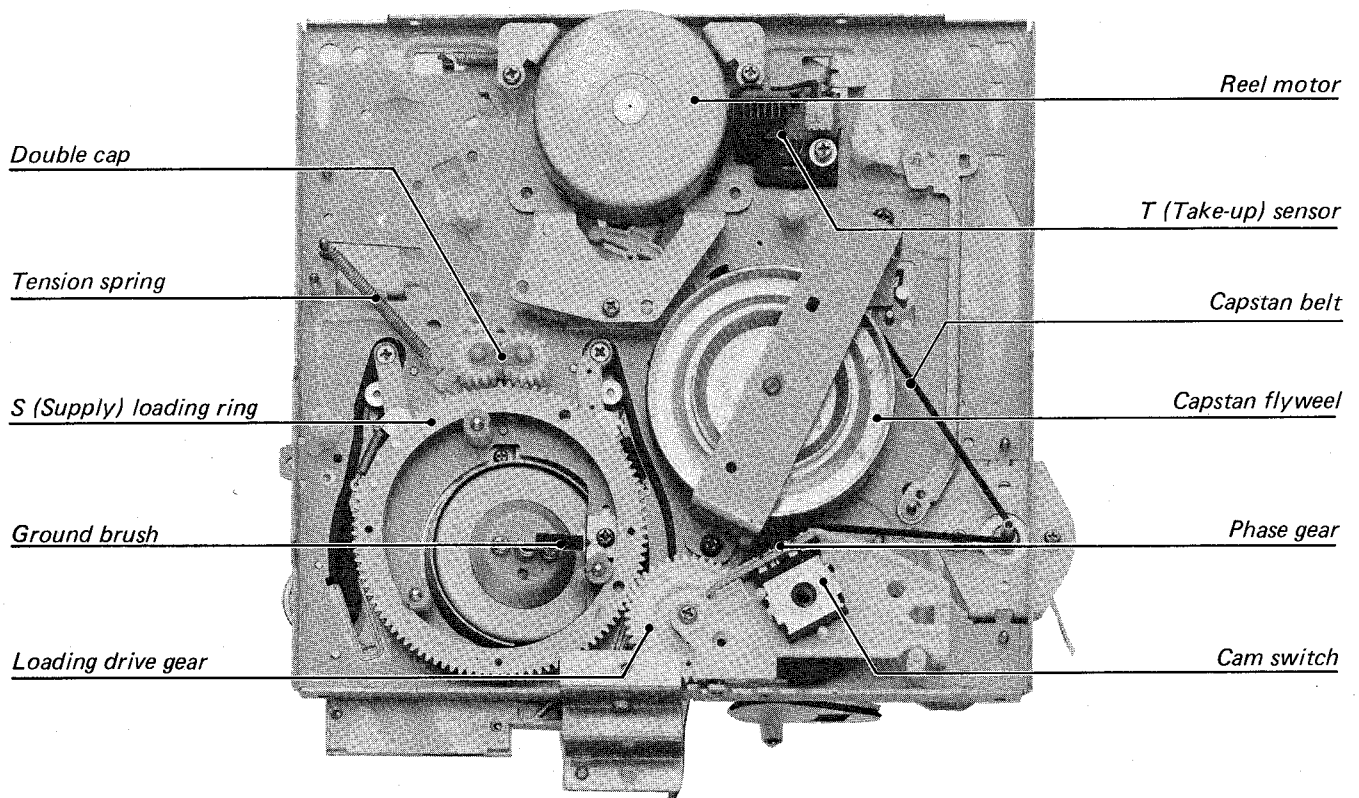
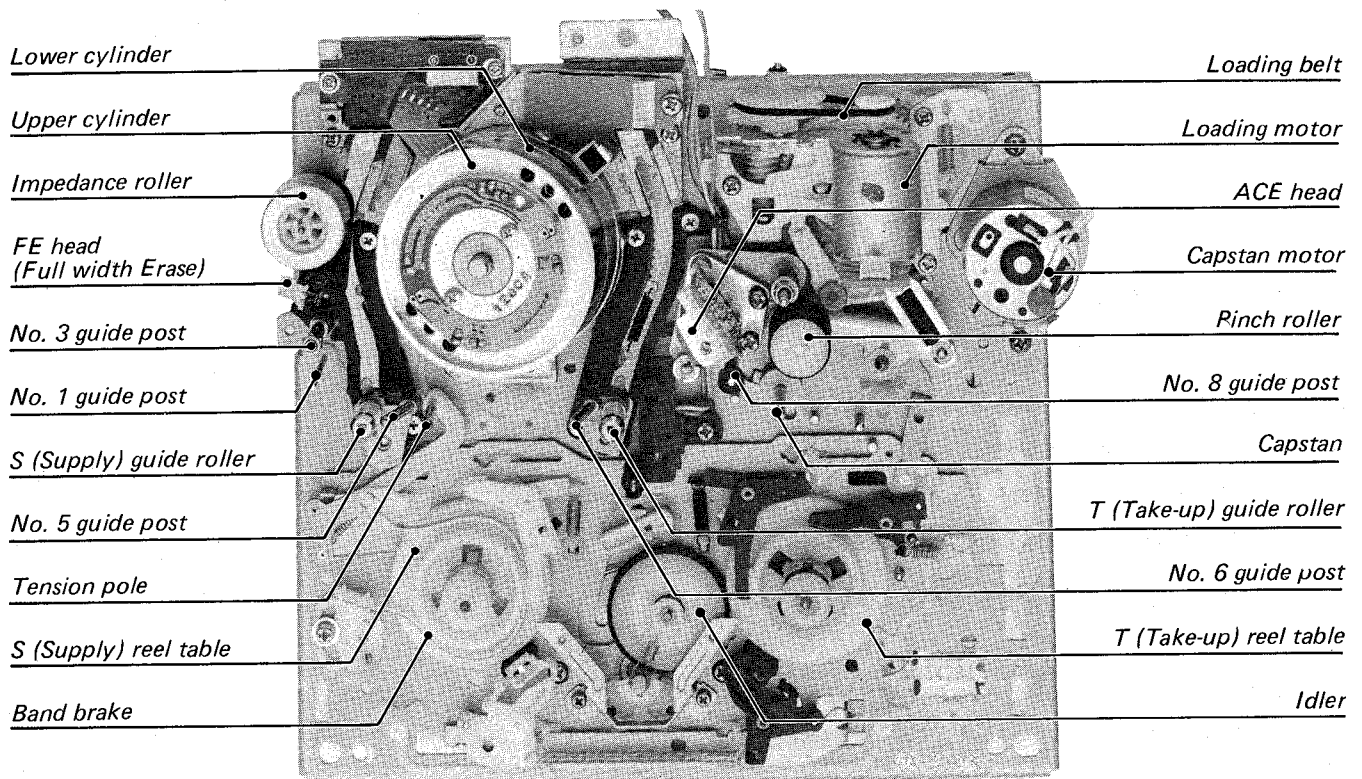
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1. MECHANICAL ADJUSTMENT

1-1. Mechanical Parts Location

1-1-1 Top View

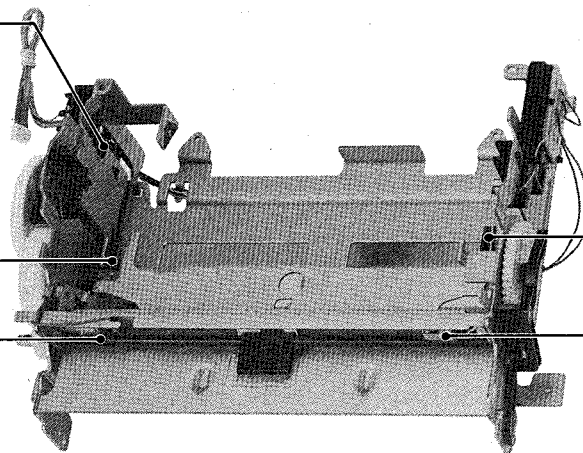


1-1-3 Front Loading Mechanism

Cassette down switch

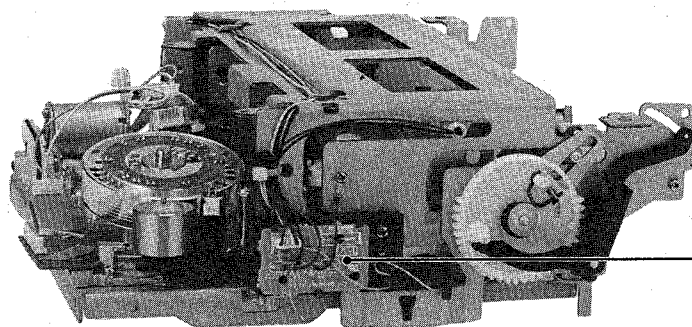
Cassette detection switch (Right)

Slot out switch



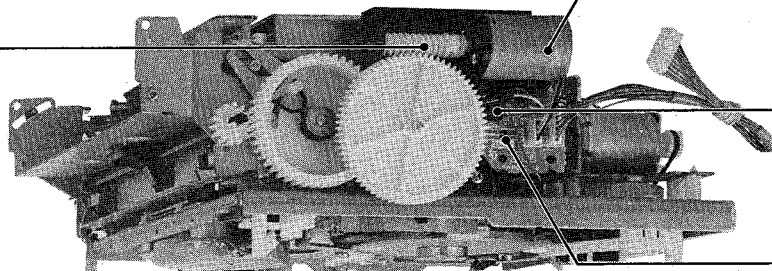
Cassette detection switch (Left)

Accidental erase prevention switch



Tape end detector

Worm gear



FL (Front Loading) motor

Cassette down switch

Tape start detector

1-2. Servicing Jig List

Table 1-2-1

Name	Part code	Q'ty	Sketch No.
Alignment tape (MH-2)	70909094	1	①
Torque gauge	70909098	1	②
Back tension cassette gauge	70909103	1	③
Height gauge	70909113	1	④
Taper nut driver	70909162	1	⑤
Torque cassette gauge (KT-300NR)	70909199	1	⑥
Dental mirror	70954003	1	⑦

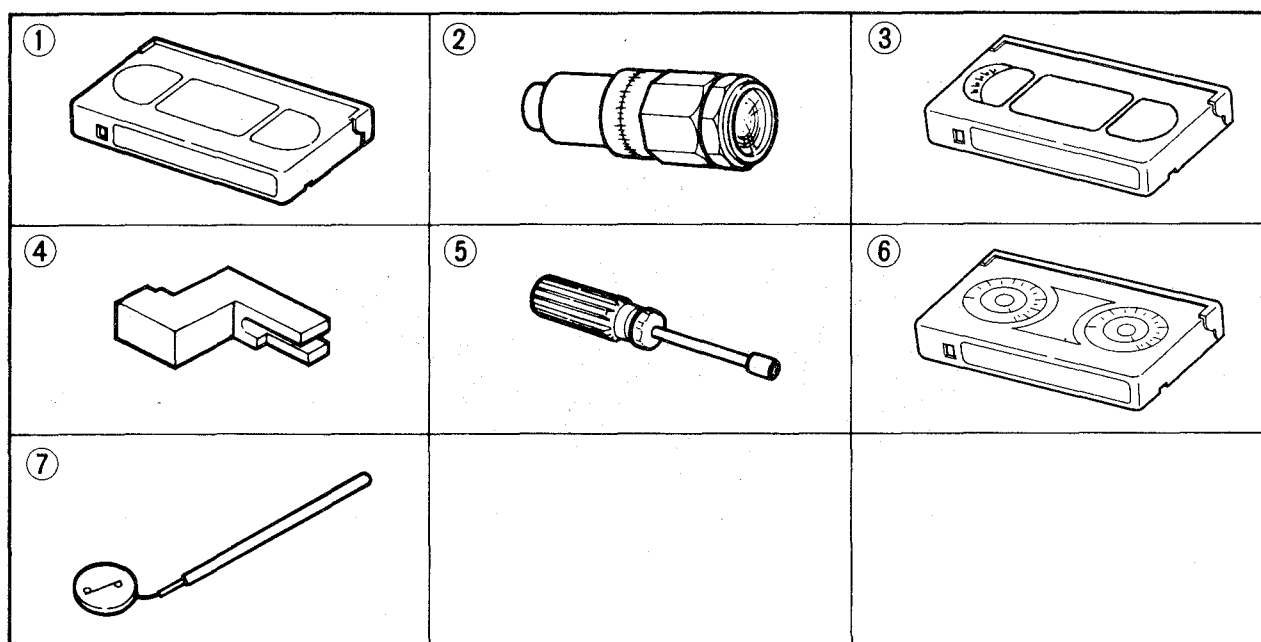


Fig. 1-2-1

1-3. Main Parts Replacement

1-3-1 Front Loading

(1) Front loading assembly

< Replacement >

- 1) Disconnect the relay cable connector from the Logic P.C. board.
- 2) Loosen 4 mounting screws on the deck top shield plate, and remove the shield plate.
- 3) Remove 2 screws securing the front loading assembly on the base.
- 4) First, pull the front loading assembly forward, unhook claws from the holes on the main base, and then take out the loading assembly upward, and replace it.

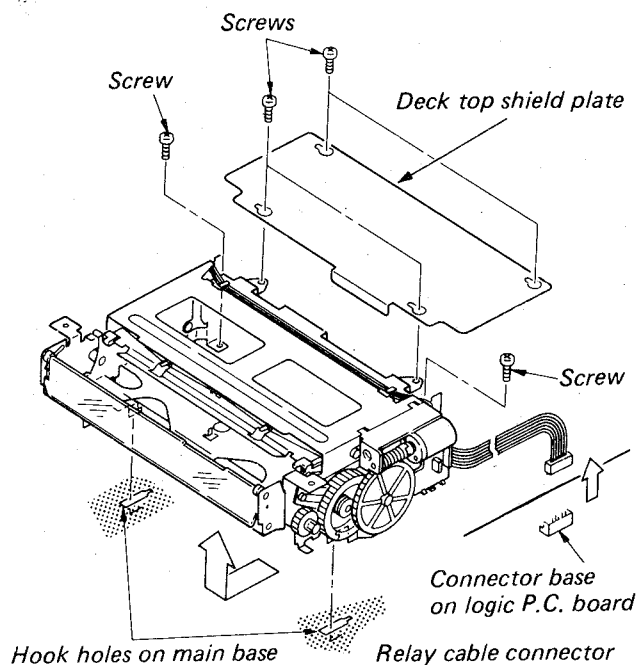


Fig. 1-3-1 Front loading assembly replacement

(2) Door

< Replacement >

- 1) Slide the door rightward and remove the left door shaft from the guide bracket while warping the door slightly forward. Next, disengage the right door shaft.
- 2) Remove a door spring from the right door shaft and replace it.
- 3) Insert the door spring into the right door shaft of the new door (in direction shown by the arrow).
- 4) Insert the tip of door spring into the spring hook (hole) on the guide bracket, and insert the right door shaft into the guide bracket.
- 5) Insert the left door shaft into the guide bracket while warping the door slightly forward. In this case, make sure that the door lever pin is positioned as shown in Fig. 1-3-4.

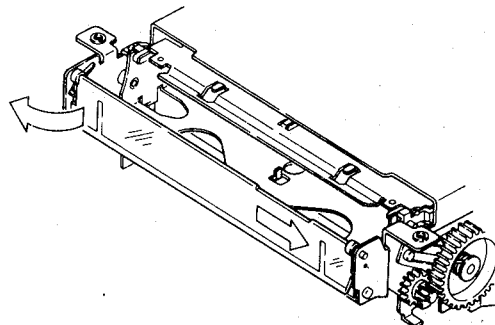


Fig. 1-3-2 Door replacement (1)

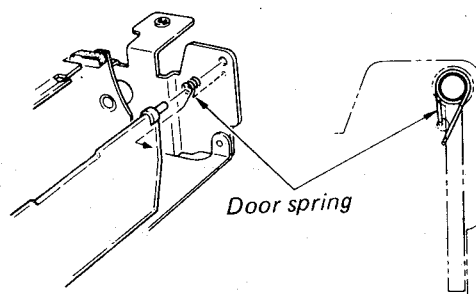


Fig. 1-3-3 Door replacement (2)

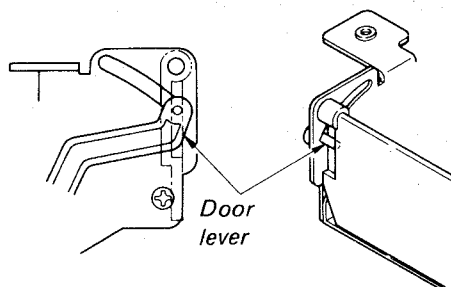


Fig. 1-3-4 Door replacement (3)

1-3. Main Parts Replacement

1-3-1 Front Loading

(1) Front loading assembly

< Replacement >

- 1) Disconnect the relay cable connector from the Logic P.C. board.
- 2) Loosen 4 mounting screws on the deck top shield plate, and remove the shield plate.
- 3) Remove 2 screws securing the front loading assembly on the base.
- 4) First, pull the front loading assembly forward, unhook claws from the holes on the main base, and then take out the loading assembly upward, and replace it.

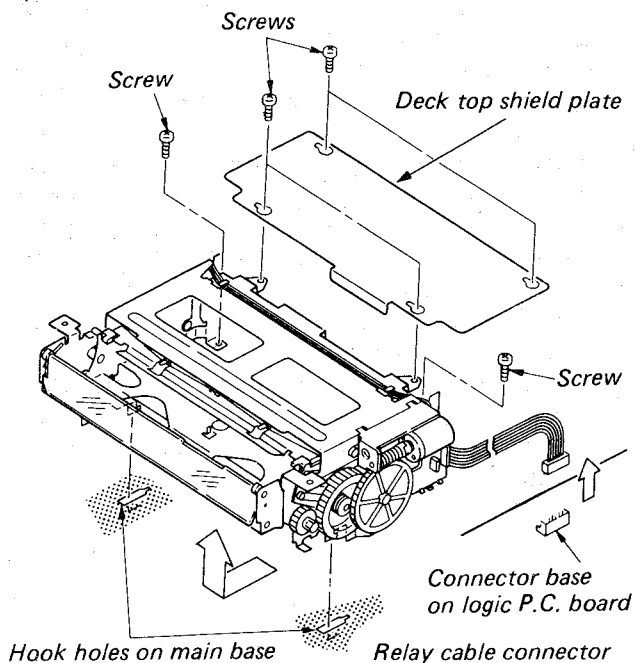


Fig. 1-3-1 Front loading assembly replacement

(2) Door

< Replacement >

- 1) Slide the door rightward and remove the left door shaft from the guide bracket while warping the door slightly forward. Next, disengage the right door shaft.
- 2) Remove a door spring from the right door shaft and replace it.
- 3) Insert the door spring into the right door shaft of the new door (in direction shown by the arrow).
- 4) Insert the tip of door spring into the spring hook (hole) on the guide bracket, and insert the right door shaft into the guide bracket.
- 5) Insert the left door shaft into the guide bracket while warping the door slightly forward. In this case, make sure that the door lever pin is positioned as shown in Fig. 1-3-4.

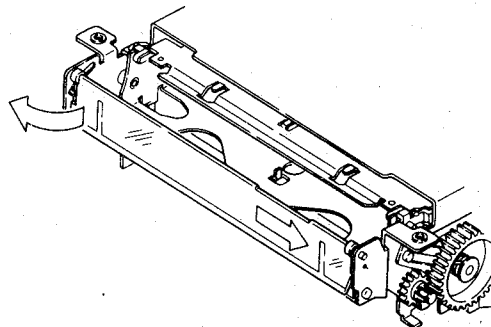


Fig. 1-3-2 Door replacement (1)

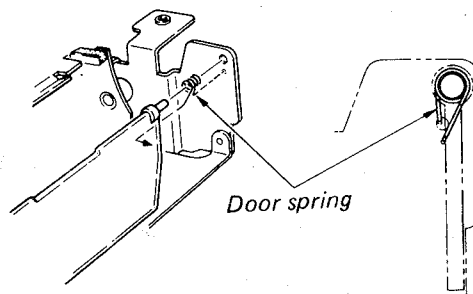


Fig. 1-3-3 Door replacement (2)

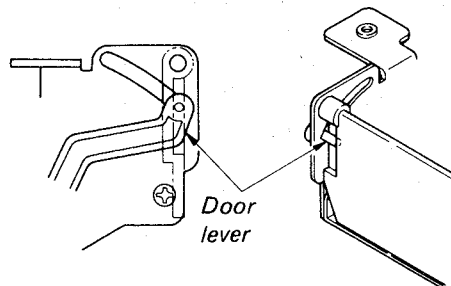


Fig. 1-3-4 Door replacement (3)

(3) Cassette detection switches, L, R

< Replacement >

- 1) Remove the front loading assembly from the chassis.
- 2) Place the front loading assembly upside down.
- 3) Unsolder leads from the switch terminals using a soldering iron. In this case, the unsoldering work will be made easily if the cassette holder is moved down by rotating the coupling section of the worm gear and the motor. (Do not touch your hand to gear teeth.)
- 4) Remove screws securing the switches and replace the switches.
- 5) When mounting new switches, perform the above steps in reverse order.

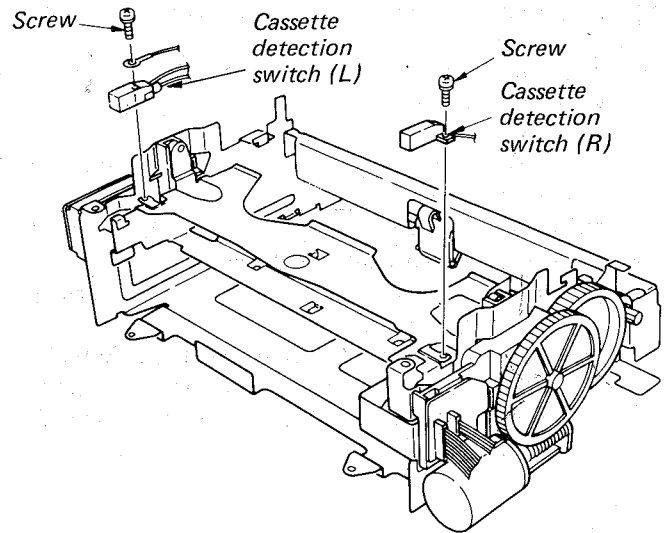


Fig. 1-3-5 Replacement of cassette detector

(4) Cassette down switch

< Replacement >

- 1) Remove the front loading assembly from the chassis.
- 2) Remove the FL P.C. board (R) unhooking the mold claws on the guide R.
- 3) Remove the screw securing the switch and take out the switch.
- 4) Unsolder the leads from the switch terminals using a soldering iron.
- 5) When remounting a new switch, perform the above steps in reverse order.

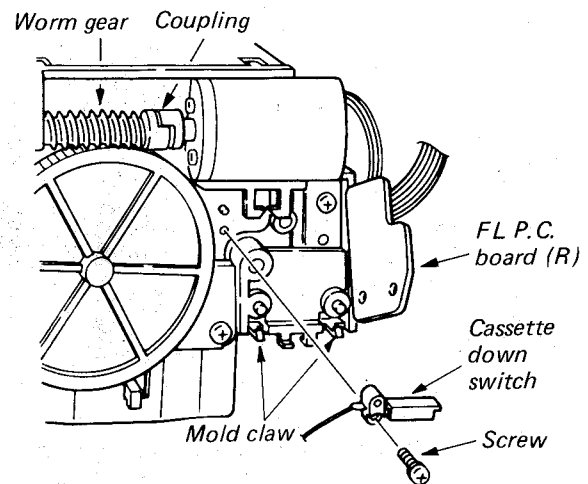


Fig. 1-3-6 Cassette down switch replacement

(5) Slot out switch and accidental erase prevention switch

- 1) Remove the front loading assembly from the chassis.
- 2) Place the loading assembly with the door facing upward.
- 3) Unsolder the leads from the switch terminals, using the soldering iron.
- 4) Remove the screw securing the switch.
- 5) When mounting the switch, perform the above steps in reverse order.

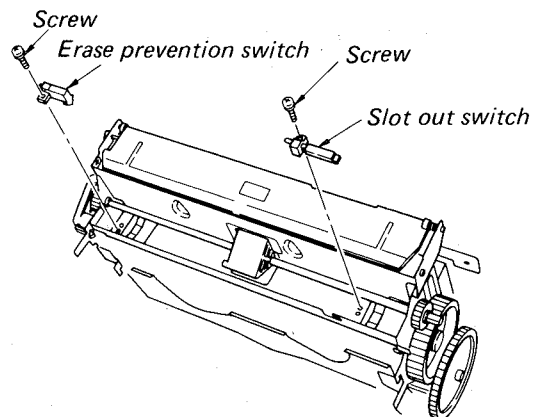


Fig. 1-3-7 Replacement of slot out switch and erase prevention switch

(6) FL motor assembly

< Replacement >

- 1) Remove the front loading assembly from the chassis.
- 2) Unsolder the leads from the motor terminals, using the soldering iron.
- 3) Remove the screws securing the FL motor assembly on the guide R and remove the assembly.
- 4) When mounting the assembly, perform the above steps in reverse order.

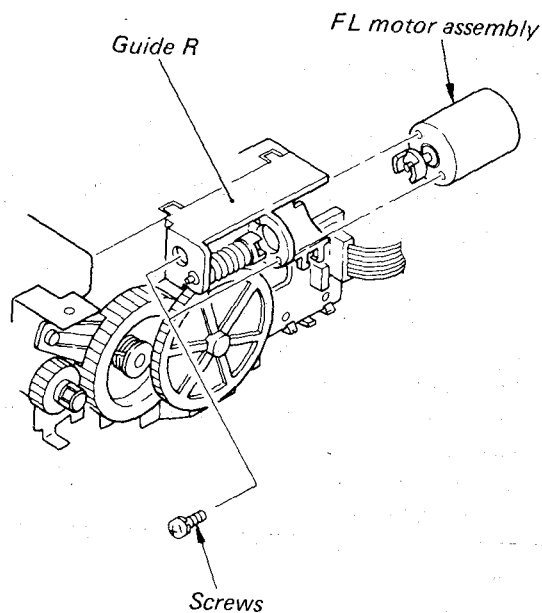


Fig. 1-3-8 Replacement of motor assembly

(7) Photo transistor

< Replacement >

- 1) Remove the front loading assembly from the chassis.
- 2) Remove the FL P.C. board (R) unhooking the mold claws on the guide R.
- 3) Unsolder the photo transistor from the FL P.C. board, using the soldering iron.
- 4) Bend leads of a new photo transistor as shown in Fig. 1-3-11.
- 5) When remounting the transistor, perform the above steps in reverse order.
- 6) The replacement method will apply to both the photo transistors on the left and right FL P.C. boards.

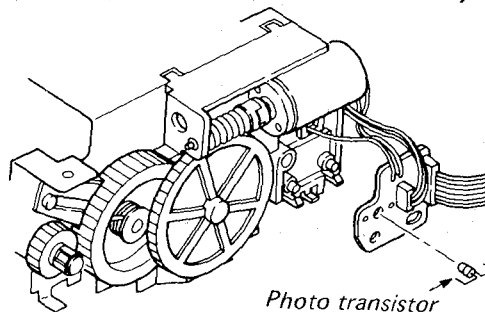


Fig. 1-3-9 Replacement of photo transistor on FL P.C. board (R)

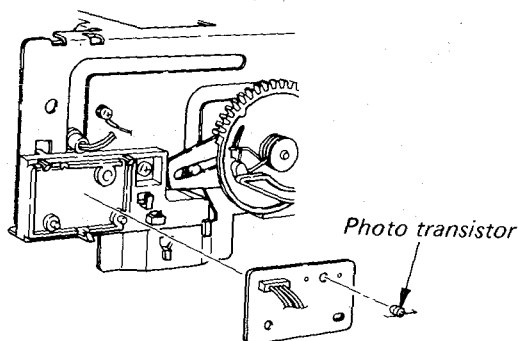


Fig. 1-3-10 Replacement of photo transistor on FL P.C. board (L)

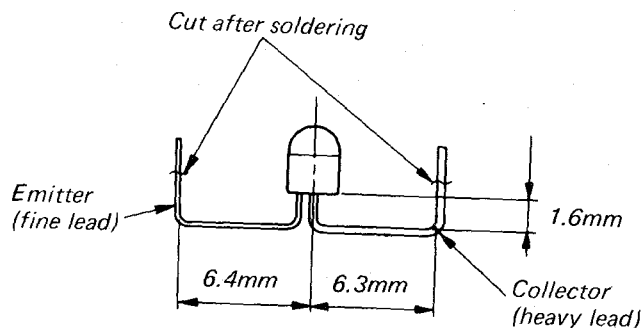


Fig. 1-3-11 Forming of photo transistor leads

1-3-2 Cylinder

(1) Upper Cylinder Assembly

< Inspection >

- 1) Check video heads damaged or worn out.
- 2) Check video heads clogging.
(Replace the upper cylinder assembly if the clogging is not remedied after cleaning.)

< Replacement >

- 1) Unsolder the relay terminals ⑥ (at the marks Δ , 2 pairs — in total 4 locations) on the head relay P.C. board ①.
The solder will be removed easily using a desoldering wire.
- 2) Remove two screws ② and remove the upper cylinder assembly.
- 3) Clean a new upper cylinder assembly ③ and the surface of the flange for mounting ⑤, using a cleaning kit.
- 4) Align phases of the white part of P.C. board ① and P.C. board ④ and then mount the upper cylinder ③. (Tightening torque ; 3 – 4 kg-cm.)
- 5) Perform the tape transport adjustment.

(2) Cylinder motor

< Inspection >

- 1) Apply power to the cylinder motor separately.
- 2) If the motor does not rotate, replace the rotor or the stator.

< Rotor replacement >

- 1) Remove the ground cap ①.
- 2) Remove two rotor screws ② and replace the rotor ③.
(Tightening torque ; 3 – 4 kg-cm.)

Note: Mount a new rotor, matching the phase decision holes of rotor and preliminary pressure boss ④.
(Fig. 1-3-14, 15)

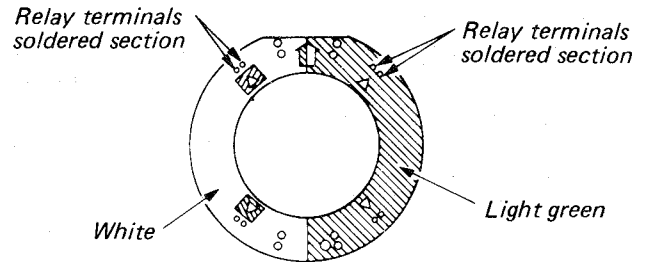


Fig. 1-3-12 Head relay P.C. board ①

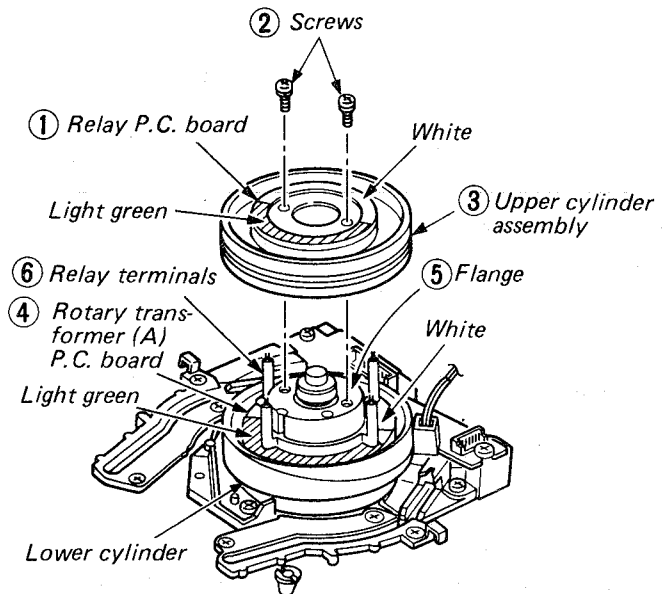


Fig. 1-3-13 Upper cylinder replacement

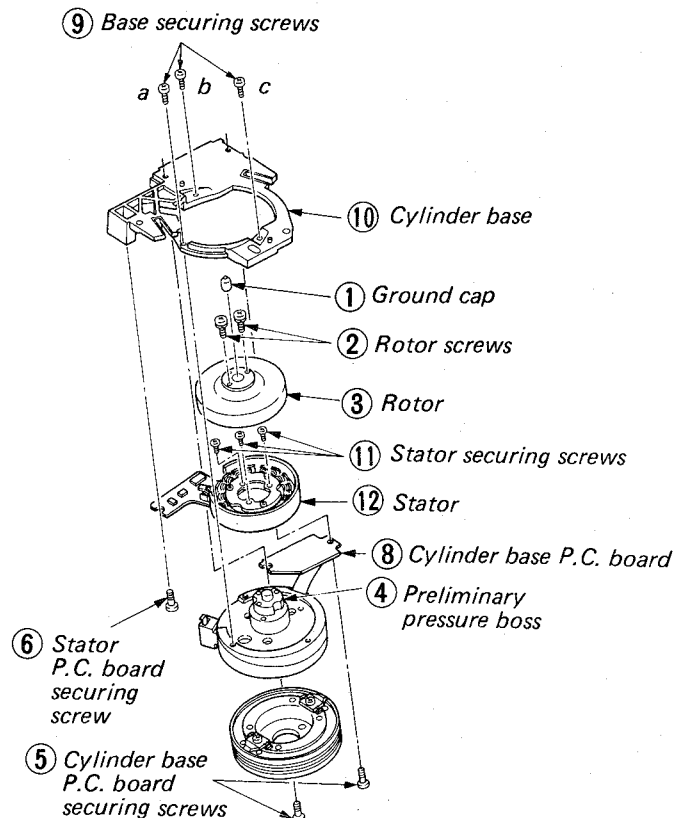


Fig. 1-3-14 Cylinder motor replacement

< Stator replacement >

- 1) Remove the cylinder complete assembly. (Refer to 1-3-2(3))
- 2) Remove two cylinder base P.C. board securing screws ⑤ and stator P.C. board securing screw ⑥. (Fig. 1-3-16)

Note: In this case, take care not to damage patterns of the R.T relay P.C. board. Also handle the cylinder base P.C. board ⑧ carefully so that the cylinder is not damaged with the P.C. board.

- 3) Remove three base securing screws ⑨ and remove the cylinder base ⑩ (Fig. 1-3-14).
- 4) Remove the rotor screws ② and the rotor ③. (Fig. 1-3-14)

Note: Follow the procedures under "< Rotor replacement >".

- 5) Remove the stator securing screws ⑪.
- 6) Pull out the stator ⑫ and replace it. (Tightening torque 1.5 – 2.5 kg)
- 7) When mounting the cylinder complete assembly, perform the above steps in reverse order.

Note: Sequence of tightening base securing screws ⑨ : tighten the screw a first, b and c in any order. (tightening torque is 3 – 4 kg-cm) (Fig. 1-3-14)

- 8) Perform the tape transport adjustment.

(3) Cylinder assembly

< Inspection >

- 1) Check to see that rotating surface of the lower cylinder has no damage such as scratches, crack, etc.
 - 2) Check to see smooth rotation of the upper cylinder.
- If abnormality is found, replace the cylinder(s).

< Replacement >

- 1) Remove the 6P connector (Video heads) ①, 5P connector (Cylinder motor) ②, and the dew heater ③.
- 2) Remove three screws ④.
- 3) Remove the cylinder assembly ⑤.

Note: In this case, move the impedance roller ⑥ in direction shown by the arrows.

- 4) Align position of a new cylinder to the cylinder base ⑦, taking care not to touch the video heads directly and not to damage the cylinder surface. When mounting the cylinder complete assembly, perform the above steps in reverse order.
- 5) Perform the tape transport adjustment.

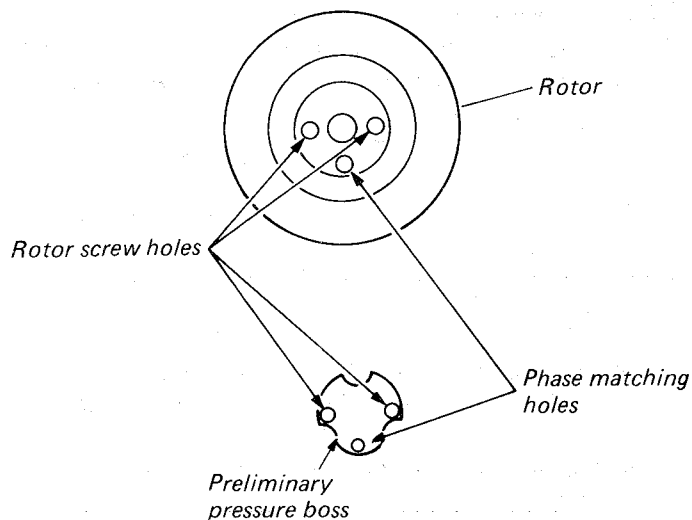


Fig. 1-3-15 Phase matching between rotor and preliminary pressure boss

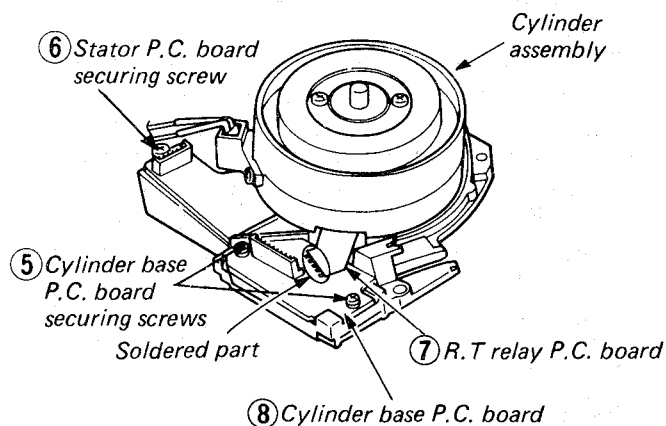


Fig. 1-3-16 Relay P.C. board and cylinder base P.C. board

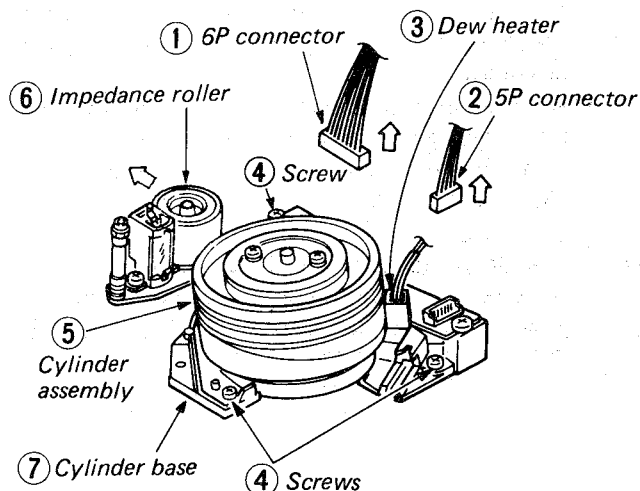


Fig. 1-3-17 Cylinder assembly replacement

1-3-3 Transport system parts replacement

(1) ACE Head assembly replacement

- 1) Disconnect a 6P connector from the ACE P.C. board ⑧.
- 2) Turn the ACE height adjusting nut ⑦ counterclockwise and remove the nut in order to remove ACE base assembly ⑤. (Refer to Fig. 1-3-18).

Note: Note positions of the ACE base ① and the taper nut ③.

- 3) Remove the E-ring ⑨ and the ACE azimuth adjusting screws ② in order to remove the ACE head assembly.
- 4) Remove the ACE P.C. board ⑧ from the ACE head assembly ⑪.
- 5) Replace the ACE head assembly, according to the reverse procedures.
- 6) Rotate the ACE height adjustment nut ⑦ until the ACE base and the upper position of the taper nut have the same position as noted in the step 2) above.
- 7) After mounting, perform the tape transport adjustment, starting from the first step.

Note: Since direct mounting of the ACE torsion spring is difficult, first insert the tip of the spring into the hole on the main base and then hook the opposite tip of the spring to the ACE base ① which has been inserted into the ACE post ⑫.

(2) Guide sleeve replacement

< No. 3 guide sleeve replacement >

- 1) Rotate the No. 3 guide nut ① counterclockwise and remove the No. 3 guide nut ① and flange ② as shown in Fig 1-3-22. When replacing a new flange, perform the above steps in reverse order.
- 2) After the replacement, preset height of the lower flange as shown in Fig. 1-3-19, using the guide height gauge.
- 3) After completion of preset, perform adjustments by following the procedures for Linearity Adjustment, item 4) of the Tape Transport Adjustment. (Refer to 1-4-4 (3))

Note: The flange ② arranged in upper and lower positions is a common part and can be used either place and upside down. (Fig. 1-3-22)

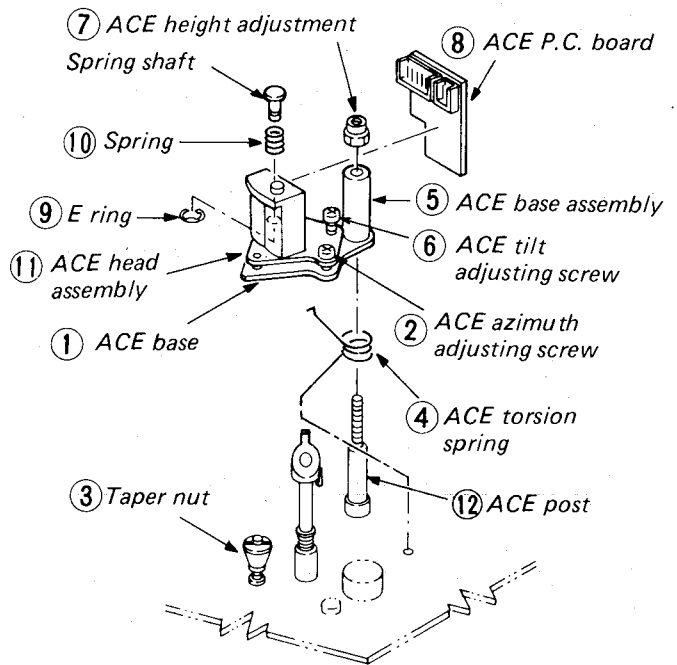


Fig. 1-3-18 Replacement of ACE head assembly

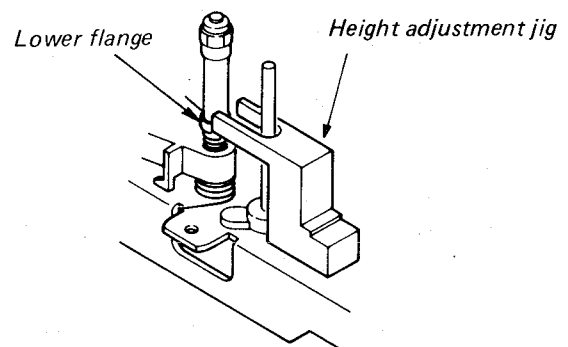


Fig. 1-3-19 No. 3 guide preset

< No. 8 guide sleeve replacement >

- 1) Remove No. 8 cap ① through the spring ⑦ in this sequence as shown in Fig. 1-3-20. When reassembling, perform the above steps in reverse order.
- 2) After completion of the replacement, preset height of the lower flange as shown in Fig. 1-3-21 using the guide height gauge.

Note: This adjustment is a basic reference of tape transport system, so extreme care should be paid in the adjustment.
When mounting the No. 8 guide cap ①, mount it with its slant surface facing to the cassette side.

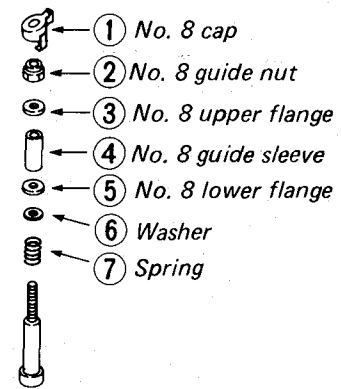


Fig. 1-3-20 No. 8 guide replacement

- 3) After completion of the preset adjustment, perform adjustments by following the procedures for the linearity adjustment, item 4) of the tape transport adjustment. (Refer to 1-4-4 (3))

(3) FE head replacement

- 1) Disconnect the 2P connector of the FE head.
- 2) Remove the FE head mounting screw ⑤ and the FE head ⑥ will be removed. Refer to Fig. 1-3-22.
- 3) Replace the new FE head and tighten the FE head mounting screw ⑤.
- 4) Connect 2P connector.
- 5) The replacement of the FE head causes little change in linearity. But confirm whether the associated adjustments have been not upset, starting check from the linearity adjustment, item 4) of the tape transport adjustment. (Refer to 1-4-4 (3))

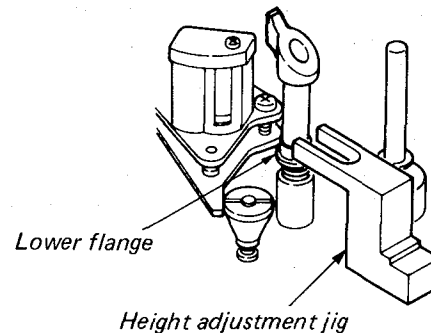


Fig. 1-3-21 No. 8 guide preset

(4) Impedance roller replacement

- 1) Remove the washer ⑦ and replace the impedance roller ⑧ as shown in Fig. 1-3-22.

Note: The polyslider must be inserted between the impedance roller ⑧ and the entrance lever ⑩, take care not to miss it. An impedance roller with scratches may damage the tape, so carefully handle it.
If your fingers touch the surface of the impedance roller, clean the surface with alcohol.

- 2) After replacement of the impedance roller, perform the adjustment from the linearity adjustment, item 4) in the tape transport adjustment. (Refer to 1-4-4 (3))

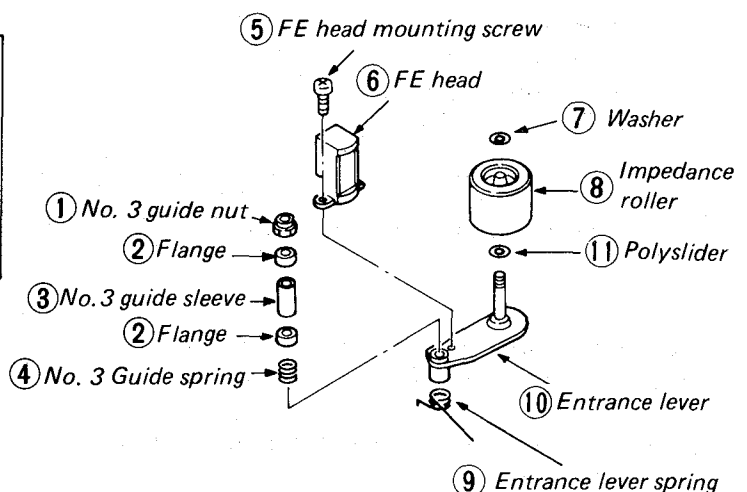


Fig. 1-3-22 Replacement of No. 3 guide and FE head

(5) S, T Guide rollers replacement

Same replacement procedures will be applied for both S- and T-guide rollers.

- 1) Loosen the set screw ② shown in Fig. 1-3-23.
- 2) Turn the guide roller ① counterclockwise and remove it.
- 3) As the O-ring may stick to the guide roller removed, remove the O-ring and insert it on a new guide roller.
- 4) When remounting, perform the above steps in reverse order.

Note: When tightening the set screw ②, temporarily tighten it with light pressure. If it is tightened too hard, associated adjustments can not be made. The S-guide roller has a red mark on upper flange and the T-guide roller has a black mark on upper flange. Do not exchange them when remounting.

- 5) After completion of the replacement, perform adjustment from the linearity adjustment item 4) in the tape transport adjustment. (Refer to 1-4-4 (3))

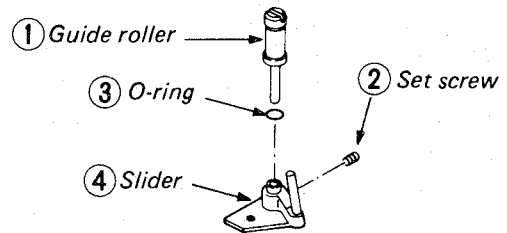
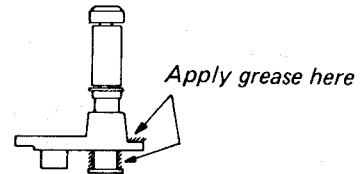
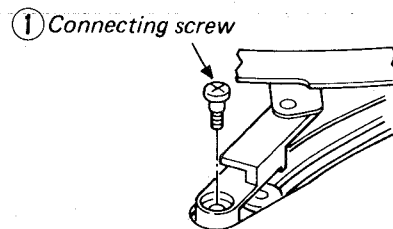


Fig. 1-3-23 Guide roller replacement

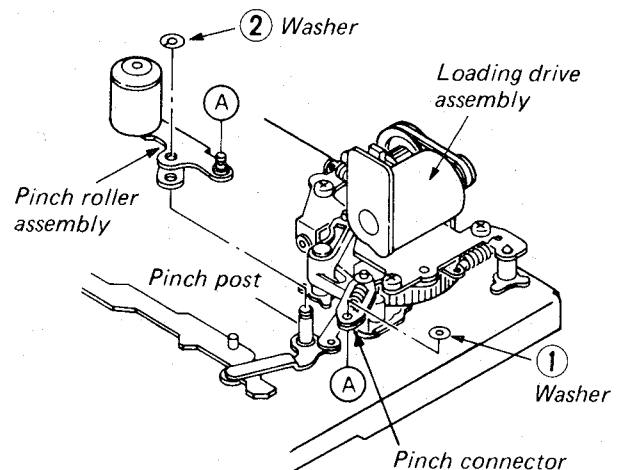


(6) S, T Sliders replacement

- 1) Remove the cylinder assembly.
- 2) Place the VTR vertically and remove the bottom cover.
- 3) Remove the connecting screw ① shown in Fig. 1-3-24.
- 4) Move the slider up to the loading position turning loading motor with your hand, and the slider can be removed.
- 5) Remove the guide roller and reinstall it in a new slider according to the steps stated in (5) above.
- 6) When replacing the slider, perform the above steps in reverse order.
- 7) After completion of the replacement, perform adjustment from tape transport system adjustment. (Refer to 1-4-4 (3))

Note: When the slider is replaced, always apply grease to the slider as shown in Fig. 1-3-24.

Fig. 1-3-24 S, T slider replacement



1-3-4 Pinch roller assembly replacement

- 1) Remove the washer ① and disconnect the pinch connector from the pinch roller assembly.
- 2) Remove the washer ② and remove the pinch roller assembly upward.
- 3) Clean the pinch post and apply grease on it.
- 4) Replace the pinch roller assembly according to the above steps in reverse order.
- 5) After completion of the replacement, perform adjustment from 1-4-4 (3).

Fig. 1-3-25 Pinch roller replacement

1-3-5 Loading motor replacement

- 1) Remove the motor P.C. board from the motor, taking care not to damage wire leads.
 - 2) Remove the washer ① and disconnect the pinch connector.
 - 3) Remove the cam lever stopper and the washer ②, and remove the cam lever assembly upward.
 - 4) Turn the gear pulley in direction shown by the arrow until it stops to set the FF/REW mode. (Refer to Fig. 1-3-27)
 - 5) Remove the screws ③ and remove the loading drive assembly.
 - 6) Remove the loading belt and the screws ④, and remove the motor.
 - 7) Replace the motor.
- When replacing with a new motor, perform the above steps in reverse order, taking care of polarities, (+ polarity should be located on upside).
- 8) When mounting the loading drive assembly on the main base, first push the logic slider rightward (shown by the arrow) until it stops, and then mount the drive assembly.
 - 9) Confirm timing of the phase gear, refer to the item 1-4-1.

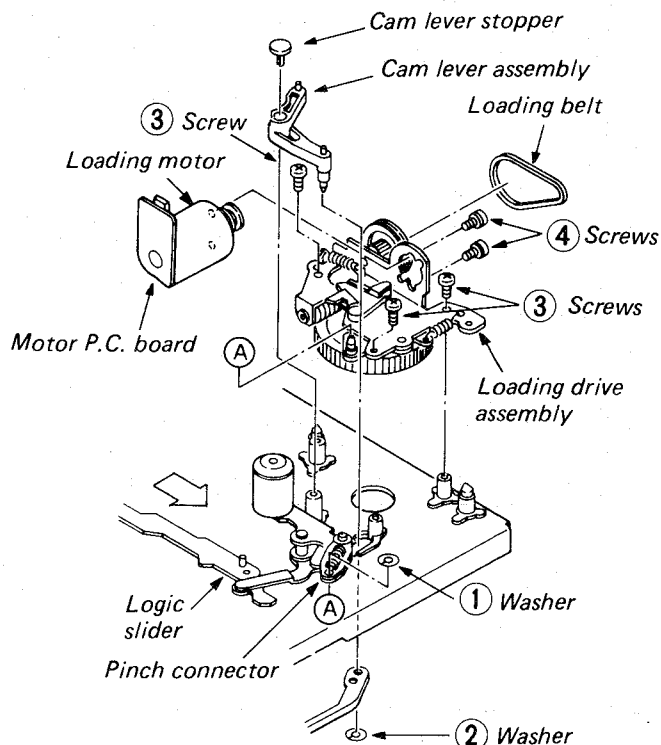


Fig. 1-3-26 Loading motor replacement

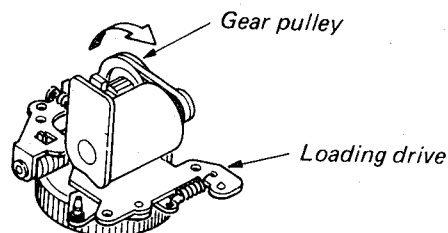


Fig. 1-3-27 Loading drive - FF mode

1-3-6 Band brake assembly replacement

- 1) Remove the S-soft brake assembly.
- 2) Remove a tension spring from a tension lever.
- 3) Remove the screw ① and remove the tension lever and the band brake assembly from the main base.
- 4) Remove the band brake assembly from the tension lever and replace the band brake assembly.
- 5) Clean the shaft of the tension lever and then apply one or two drops of oil. When replacing with a new band brake assembly, perform the above steps in reverse order.
- 6) After completion of the replacement, check position of the tension pole and its adjustment (refer to 1-4-2) and check the backtension (refer to 1-4-3).

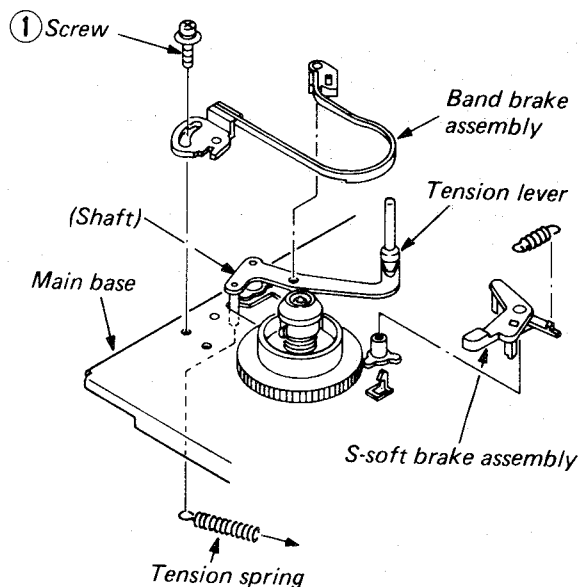


Fig. 1-3-28 Band brake assembly replacement

1-3-7 Cam switch replacement

- 1) Remove the screw ① and the cam switch bracket.
- 2) To remove the cam switch, move it upward with a screwdriver while opening the claw of the cam switch bracket.
- 3) Perform the phase matching adjustment (timing check), referring to the item 1-4-1.
- 4) Replace the cam switch and mount it on the cam switch bracket.
- 5) When mounting the cam switch on the phase gear shaft, mount the cam switch while pushing the external rim of the cam switch in the direction shown by the arrow.
(If the hole D of the cam switch and the cutout D of the phase gear shaft are not matched, (overlapped), turn the cam switch until the hole D matches.)

(Deck bottom side)

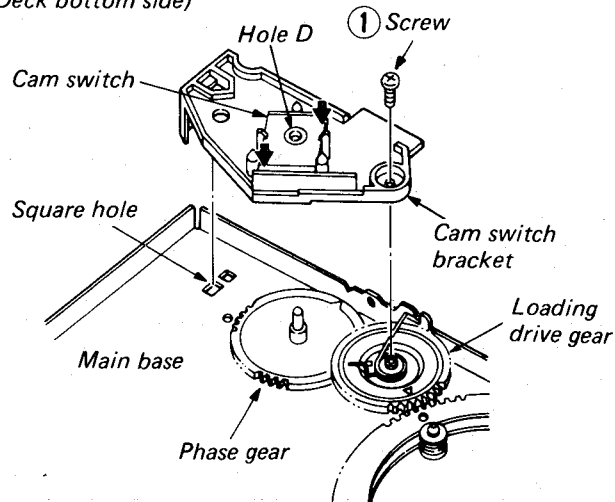


Fig. 1-3-29 Cam switch replacement

1-3-8 T-Sensor Assembly Replacement

- 1) Disconnect 3P and 6P connectors.
- 2) Remove the screw ①.
- 3) Remove the sensor assembly ②.
- 4) When reinstalling a new sensor, perform the above steps in the reverse order.

Note: Since the Hall element is glued on the sensor holder, take care the hall element is not torn off during installation.

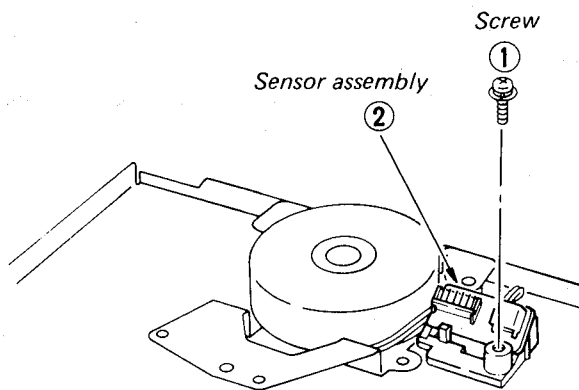


Fig. 1-3-30 T-sensor assembly replacement

1-3-9 Main brake assembly replacement

- 1) The brake assembly has the mold claws which allow one touch installation or removal.

Note: When replacing, take care not to touch the brake pad surface.

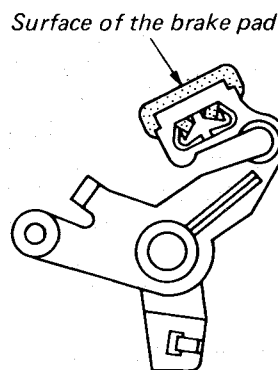


Fig. 1-3-31 Main brake assembly replacement

1-3-10 Ground brush replacement

- 1) Remove a screw ① and the brush.
- 2) Clean the ground cap with alcohol.
- 3) Replace the brush.

Mount a new brush so that it can contact the center of the ground cap.

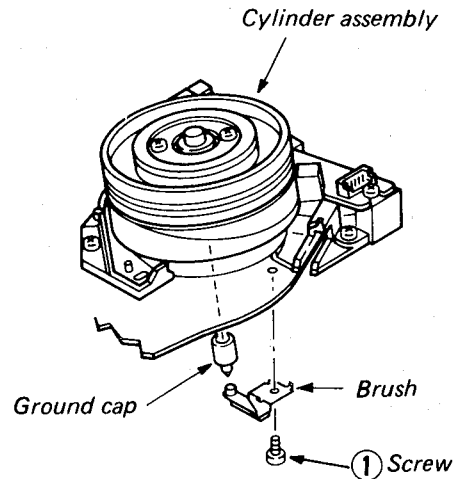


Fig. 1-3-32 Brush replacement

1-3-11 Reel table replacement

(1) Supply reel table assembly

- 1) Remove the S-soft brake spring ⑨ from the S-soft brake ① (Refer to Fig. 1-3-33).
- 2) Remove the S-soft brake ①.
- 3) Remove the tension spring ② from the tension lever ③.
- 4) Remove the screw ④, then remove the tension lever ③ and the band brake assembly ⑤.

Note: Take care not to damage the mold claw of the band brake.

- 5) Remove the washer ⑥, then remove the S-reel table assembly ⑦ upward paying attention not to miss the spacers.

Note: Move the S-brake assembly in the direction shown by the arrow before removing the reel table. Take care not to touch the pad surface of the S-brake. (Fig. 1-3-34)

- 6) After cleaning the reel shaft ⑧ with a cleaning kit, lubricate it with one or two drops of oil (lubrication kit).
- 7) When reinstalling the S-reel table assembly, temporarily move the S-brake assembly in the direction shown by the arrow, using a tweezers. (Fig. 1-3-34)
- 8) Replace the spacers and the retainer assembly on the reel shaft when the reel table mounts on the deck.
- 9) Mount the washer ⑥.
- 10) Mount the tension lever ③ and band brake assembly ⑤.

Note: The mold claw of the band brake can be engaged smoothly into the hole of tension lever by pushing it slightly. Take care not to deform the mold claw and the tension lever by forcing them.

- 11) Hook the tension spring ② onto the tension lever ③.

Note: In this case, take care not to give permanent deformation to the spring.

- 12) Mount the S-soft brake ①.
- 13) Mount the soft brake spring ⑨.

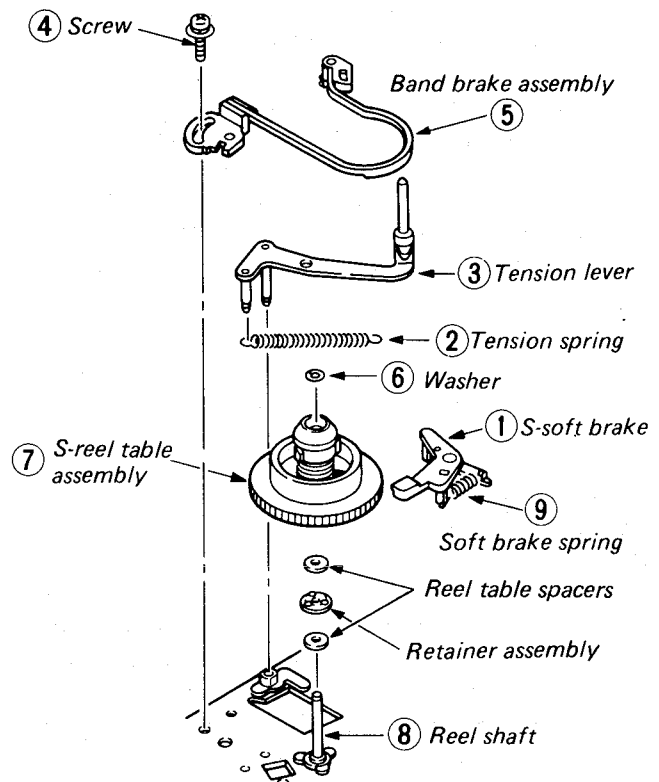


Fig. 1-3-33 Supply reel table assembly replacement

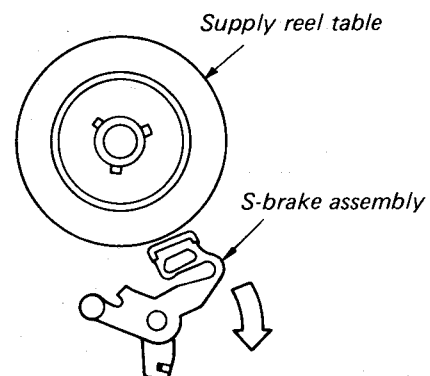


Fig. 1-3-34 S-brake assembly

(2) Take-up reel table assembly

- 1) Remove the reverse brake spring ① from the reverse brake assembly ②.
- 2) Remove the reverse brake assembly ② from the main base.
- 3) Remove the T-soft brake spring ③ from T-soft brake assembly ④.
- 4) Remove the T-soft brake assembly ④ from the main base.
- 5) Remove the washer ⑤, then move the T-brake assembly ⑩ in the direction shown by the arrow before removing the T-reel table assembly ⑥. Take care not to touch the pad surface of T-brake assembly ⑩.
- 6) As the bearing is stained with oil, the reel table spacers ⑦, thrust washer ⑧, may stick to the T-reel table assembly and be removed with it. Take care not to miss them.
- 7) Clean the reel shaft ⑨ using a cleaning kit, and apply one or two drops of oil (lubrication kit) after the reel shaft has dried.
- 8) Replace the take-up reel table with a new one.
- 9) When mounting the take-up reel table ⑥, move the T-brake assembly ⑩ in the reverse direction shown by the arrow with tweezers.
- 10) Replace the spacers and the thrust washer on the reel shaft when the reel table mounts on the deck.

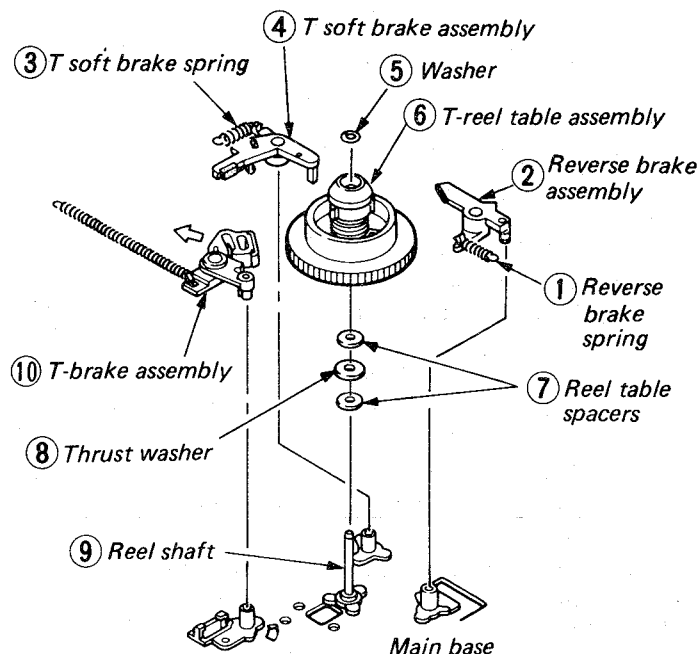


Fig. 1-3-35 Take-up reel table assembly replacement

1-3-12 Idler assembly replacement

Assume the front loading assembly is removed.

1) Removal of reel motor assembly (Fig. 1-3-36)

Turn over the set, and remove three screws ① and screw ⑤. Disconnect the 3P connector of the reel motor from the T-sensor assembly ④. Move the idler assembly ③ in the direction shown by the arrow, then lift the reel motor assembly ② upward to remove it. After the reel motor was replaced, be sure to make adjustment of the reel torque referring to the item (2) in 1-4-3.

Note:

- Before remounting, always clean knurling surface of the motor pulley, using the cleaning kit. This is to prevent oil, dust, etc. from sticking on surface of the idler rubber.
- Screws ① and ⑤ are different in length.

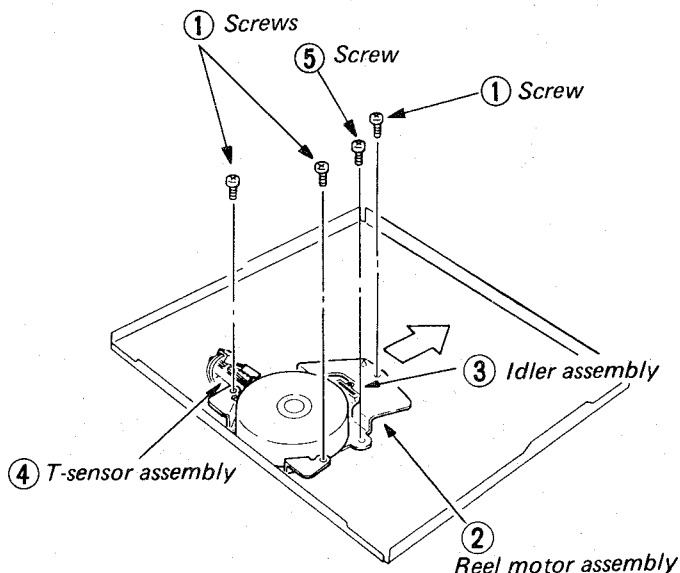


Fig. 1-3-36 Removal of reel motor assembly

2) Removal of idle stop bracket (Fig. 1-3-37)

Remove two screws ①, then remove the idle stop bracket.

3) Remove the T-reel table assembly as previously stated. (Refer to 1-3-11 (2))

4) Remove the polyslider ①. (Fig. 1-3-38)

5) Remove the idle spring ② from the post.

6) Move the idler assembly ③ in the direction as shown by the arrow. (Fig. 1-3-38)

7) Confirm that the idler assembly ③ is not caught with the main base. Lift the idler assembly upward.

8) When mounting, perform the above steps in reverse order.

9) When mounting the idler assembly, be sure to grease. (refer to the Fig. 1-3-40.)

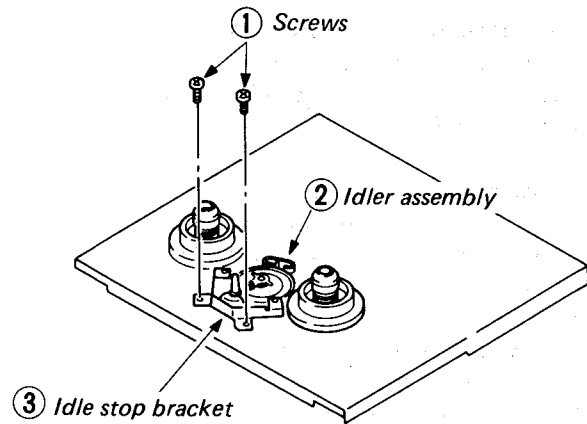


Fig. 1-3-37 Removal of idle stop bracket

Note: Be sure to confirm that grease does not stain the rubber when the idler swings. Excessive amount of grease applied may stain the rubber.

10) Be sure to clean the idler rubber with the cleaning kit.

Note: Make sure that the idler rubber is not stained with oil and dust. If stained, tape winding trouble may occur.

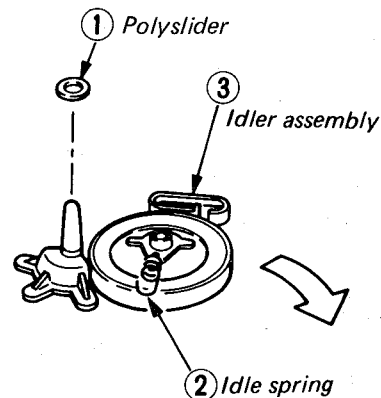


Fig. 1-3-38 Idler assembly replacement (1)

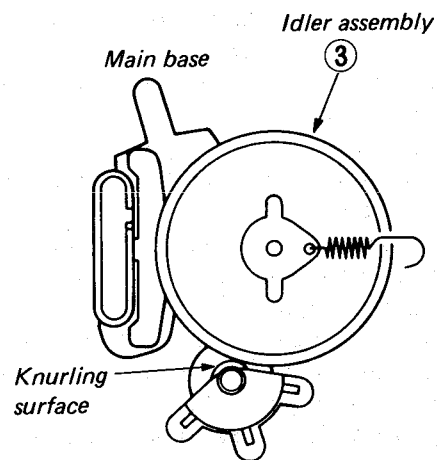


Fig. 1-3-39 Idler assembly replacement (2)

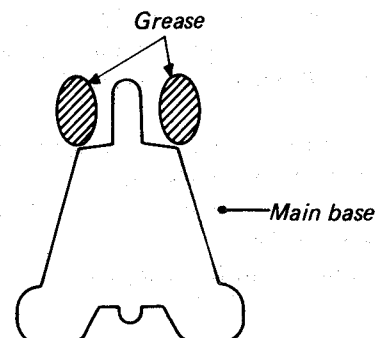


Fig. 1-3-40 Idler assembly replacement (3)

1-3-13 Capstan motor replacement

Before proceeding to this work remove the top cover, front panel, bottom plate, deck top shield plate, and the front loading assembly.

< Replacement >

- (1) Disconnect wire harnesses for the capstan motor assembly and the FG coil assembly from the servo P.C. board.
- (2) Remove two screws ①.
- (3) Remove the capstan bracket assembly ②.
- (4) Remove the capstan belt ③.
- (5) Remove the capstan sleeve cap ④.
- (6) Remove the capstan flywheel assembly ⑤.
- (7) Remove three screws ⑥.
- (8) Remove the FG coil assembly ⑦.
- (9) Remove two screws ⑧.
- (10) Remove the capstan motor assembly ⑨.

Note:

- Do not remove screws other than specified.
- Particularly, removing mounting screws for the capstan sleeve may affect serious influence on tape travel performance.

< Installation >

- (1) Perform the above steps in reverse order when re-assembling.
- (2) The terminal of the FG coil assembly is of one touch type and is locked into the receptacle rectangular opening on the main base. Fix the terminal securely by pushing it as far as possible.
(Confirm that the FG coil is not separated from the capstan sleeve.)
- (3) When rethreading the capstan belt, position the belt with the mark faced outside and matched to the travel direction.
- (4) Perform adjustments so that capstan flywheel thrust clearance of 0.05 – 0.2 mm is obtained.
 - a) Loosen the adjusting screw ⑩.
 - b) Tighten the screw clockwise slowly with force of about approx. 1kg until it stops. Then return the screw by 90 degrees. (Refer to Fig. a)
 - c) Apply screw lock adhesive on the screw.
- (5) When mounting the capstan sleeve cap, do not place it up side down.
Insert the capstan sleeve cap on the capstan shaft and then press down until it touches the capstan sleeve lightly. (Do not apply excessive force.) (Refer to Fig. b)
- (6) Clean following locations, using the cleaning kit.
 - a) Inside of the capstan belt
 - b) Outside surface of the capstan flywheel
 - c) Motor pulley
 - d) Capstan shaft (touching a tape)

Note: Magnetic particles sticking on the capstan fly-wheel assembly and the FG coil assembly may cause undesirable interference, take care to clean them off.

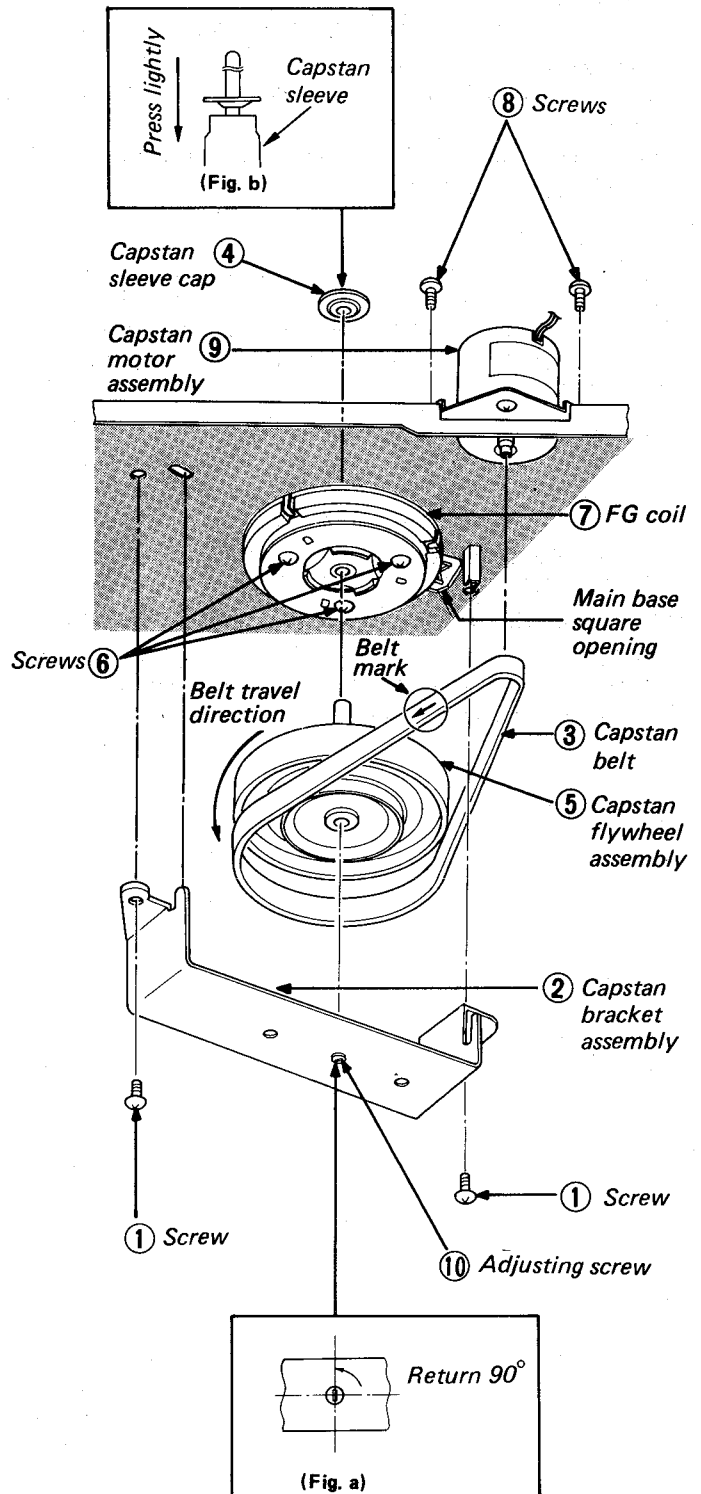


Fig. 1-3-41 Capstan motor replacement

1-4. Check and Adjustment

1-4-1 Timing Check

(1) Cam gear and phase gear

1) Make sure through the C-hole on the main base that the holes on the cam gear and the loading drive base are coincided.

If not, rotate the gear pulley assembly of the loading drive fully in the direction shown by the arrow to set FF mode. (Refer to Fig. 1-3-27)

2) Confirm the arrow mark of the phase gear is also coincided with the V-slot. If not coincided, adjust the timing by remounting the phase gear.

(2) Loading ring and loading drive gear

1) Make sure through the main base hole that holes of the S-loading ring and the T-loading ring are overlapped as shown by the arrow A. If they are not overlapped, adjust the location by removing the loading ring gear B.

2) Also make sure that the B-hole on the S-loading ring is coincided with the delta mark on the loading drive gear under the condition in the step 1) above. If they are not coincided, adjust the timing (location) by remounting the loading drive gear.

(When remounting the loading drive gear, make sure one end of the bias spring is hooked on the main base cutout and the other end is hooked on the boss of the loading drive gear.)

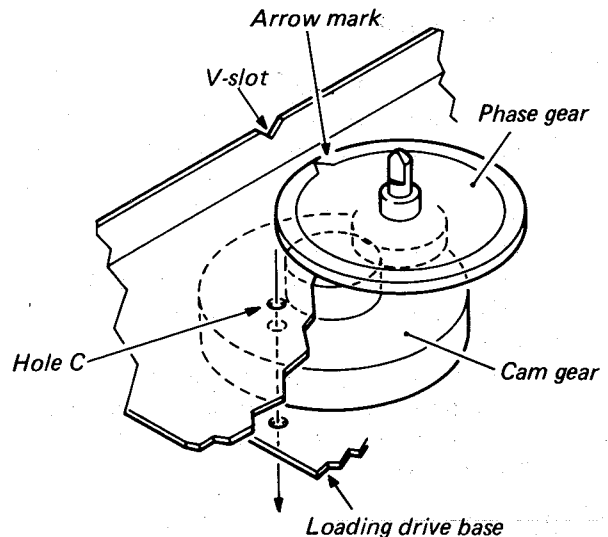


Fig. 1-4-1 Cam gear/phase gear

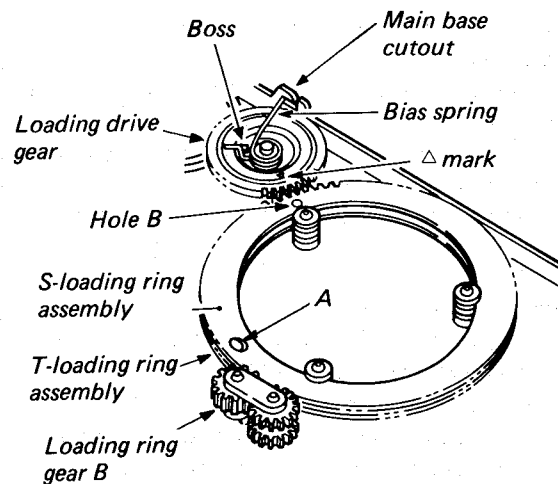


Fig. 1-4-2 Loading ring assembly/loading drive gear

1-4-2 Check and Adjustment of Tension Pole Position

(1) Set the deck to play mode with the front loading assembly removed.

(2) Make sure the center of the tension pole is in alignment with the left edge of No. 1 guide post ($\pm 1\text{mm}$) as illustrated.

(3) If necessary, loosen the screw ① and adjust the mounting position of the band bracket.

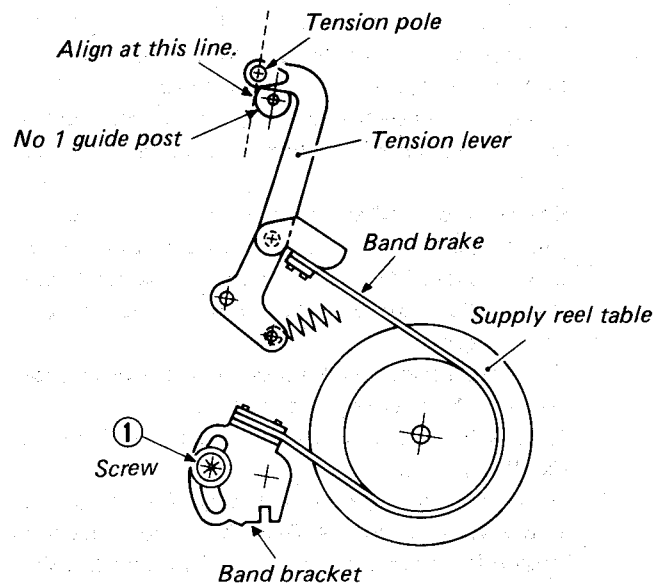


Fig. 1-4-3 Tension pole position

1-4-3 Reel Torque

(1) Reel torque

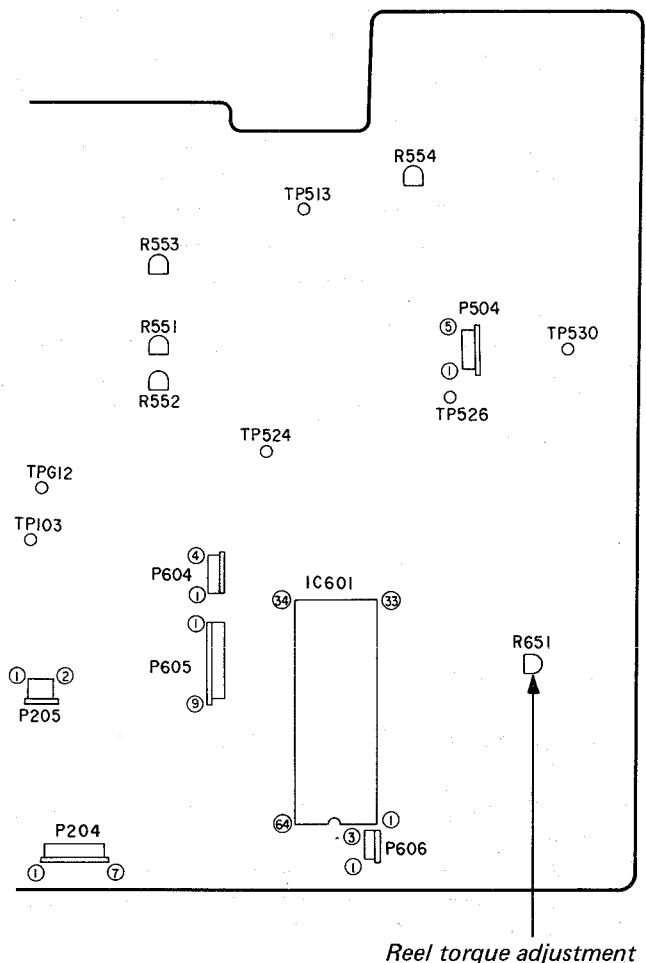
- 1) Record/Playback (take up side) mode
Too little torque does not rewind the tape to the end. If too large, the tape may face the risk of being extended under extraordinary tension.
- 2) FF mode (take up side)
REW mode (supply side)
Too little torque does not rewind the tape to the end or takes too much time for rewinding.
- 4) Inspection
Rewind the torque cassette up to the end, then check the torque shows the figure as shown below.
Record/Playback 70 — 90g-cm
FF/REW over 600g-cm

NOTE:

- If the reel torques are out of limits, clean the rubber surface of the idler assembly, the reel motor pulley, the reel table assembly, etc.
- Replace the idler assembly, if its rubber is hardened or worn out.
- Replace the brake pad of the main brake, if it is worn out.
- If the specified torque value is not obtained, replace the reel idler assembly.

(2) Reel torque adjustment

- 1) First, record a TV broadcast program on entire torque cassette tape (KT-300NR).
- 2) Set the VTR to the PLAY mode.
Push the STILL/PAUSE button as soon as the play mode has been set. Wait several seconds and then set the VTR to the PLAY mode again.
Read the right torque meter and adjust R651 so that the PLAY take-up torque of 80 ± 10 g-cm is obtained. If above value is not obtained, replace the reel motor assembly or idler assembly. (Refer to item 1-3-12, and Figs. 1-3-36 through 1-3-40)
- 3) When the reel motor assembly or the idler assembly was replaced, confirm and adjust the reel torque.
- 4) Confirmation and adjustment of the back tension will be performed with the front loading mechanism removed from the set and terminals 4 and 9 of P605 short-circuited, using a back tension cassette gauge.
First, make sure that the tension pole is positioned correctly by referring to item 1-4-2.
Load a back tension cassette and set the VTR to the PLAY mode.
Make sure the meter is indicating 16 — 26 gf-cm. If the value is out of limit, first make sure the tension lever spring is normal, and then replace the band brake assembly as required. (Refer to item 1-3-6)



Main PC Board

**PRECAUTIONS FOR USE OF TORQUE CASSETTE
(KT-300NR)**

1. Before loading a torque cassette in a VTR, always remove tape slack. The tape slack will be removed by rotating the reel in its take-up direction. (Particularly, the torque cassette is prone to be slacken because of no reel brake provided.)
2. When the torque cassette is slotted in, confirm the following:
 - a) Tape does not run on to No. 8 cap or exceeds the cap. If the tape runs on or exceeds the cap, do not eject the tape but bring the tape to its correct position, taking care not to damage the tape.
 - b) Make sure the tape is not slackened, if slackened, operate the VTR in FF or REW mode and then stop the tape. Then make sure the tape is not slackened again.
 - c) After above confirmation, proceed to adjustments and confirmation.
3. Cautions for removal of torque cassette
 - a) When removing the torque cassette from the VTR, set the VTR to the STOP mode and wait for several seconds. Then, make sure the tape is not slackened. Push the EJECT button to remove the cassette.
 - b) When removing the torque cassette from the VTR, also make sure the tape is not slackened inside the cassette lid before pulling the cassette from the VTR. If the tape is slackened inside the lid, carefully bring the tape in place and then pull the cassette.
4. Cautions for playback operation
 - a) When making adjustments and confirmation in the PLAY mode, first push the PLAY key, and then push STILL/PAUSE key to set the STILL mode. Run the VTR for several seconds in the STILL mode. Release the STILL mode and set the PLAY mode.
Then, perform the adjustments and confirmation works.
5. If above precautions 1, 2, 3 and 4 are not performed properly, the tape may be damaged and correct measurement can not be performed.
6. Do not use worn out or damaged tape, if used they may damage video heads on the cylinder. In such a case always replace the tape with new one.
The replacement tape is of E-120 type, 6.01m \pm 0.3m in length.

1-4-4 Tape Transport System

The tape transport system has been precisely adjusted in the factory, so no check and alignment are necessary except the followings:

- Noises observed on the screen
- Tape damage
- Parts, shown in the adjustment procedures for the tape transport system, item 1-3-3, were replaced.

< Adjustment reference >

Lower flange height of No. 8 guide is used as the basic reference for the transport adjustment, so do not move the No. 8 guide except replacing the No. 8 guide sleeve. When the adjustment is needed, perform the adjustment with extreme care, using the height adjustment jig. Refer to item 1-3-3 (2).

(1) Location of tape transport adjustment

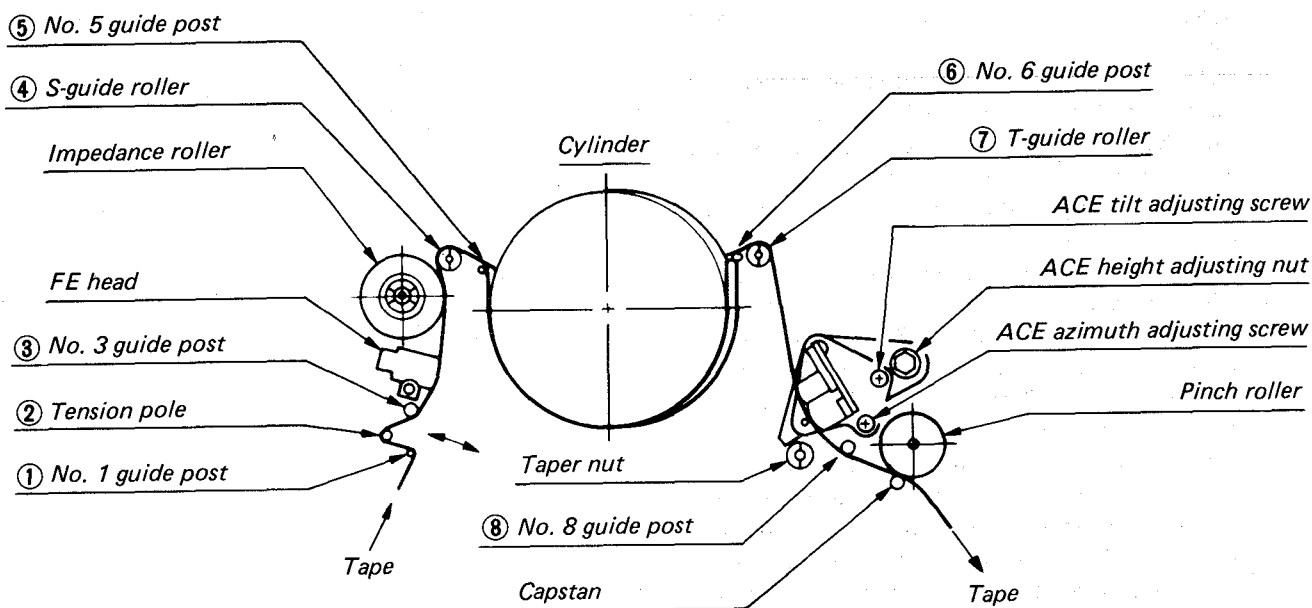


Fig. 1-4-4 Locations of tape transport adjustment

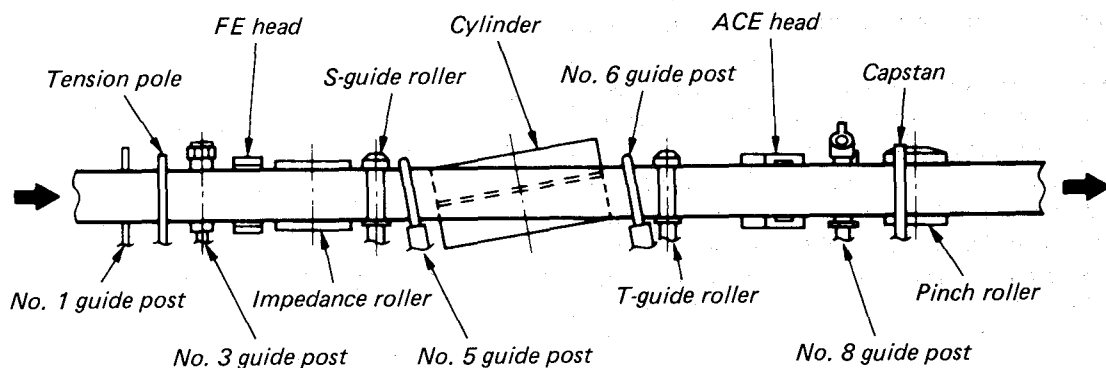
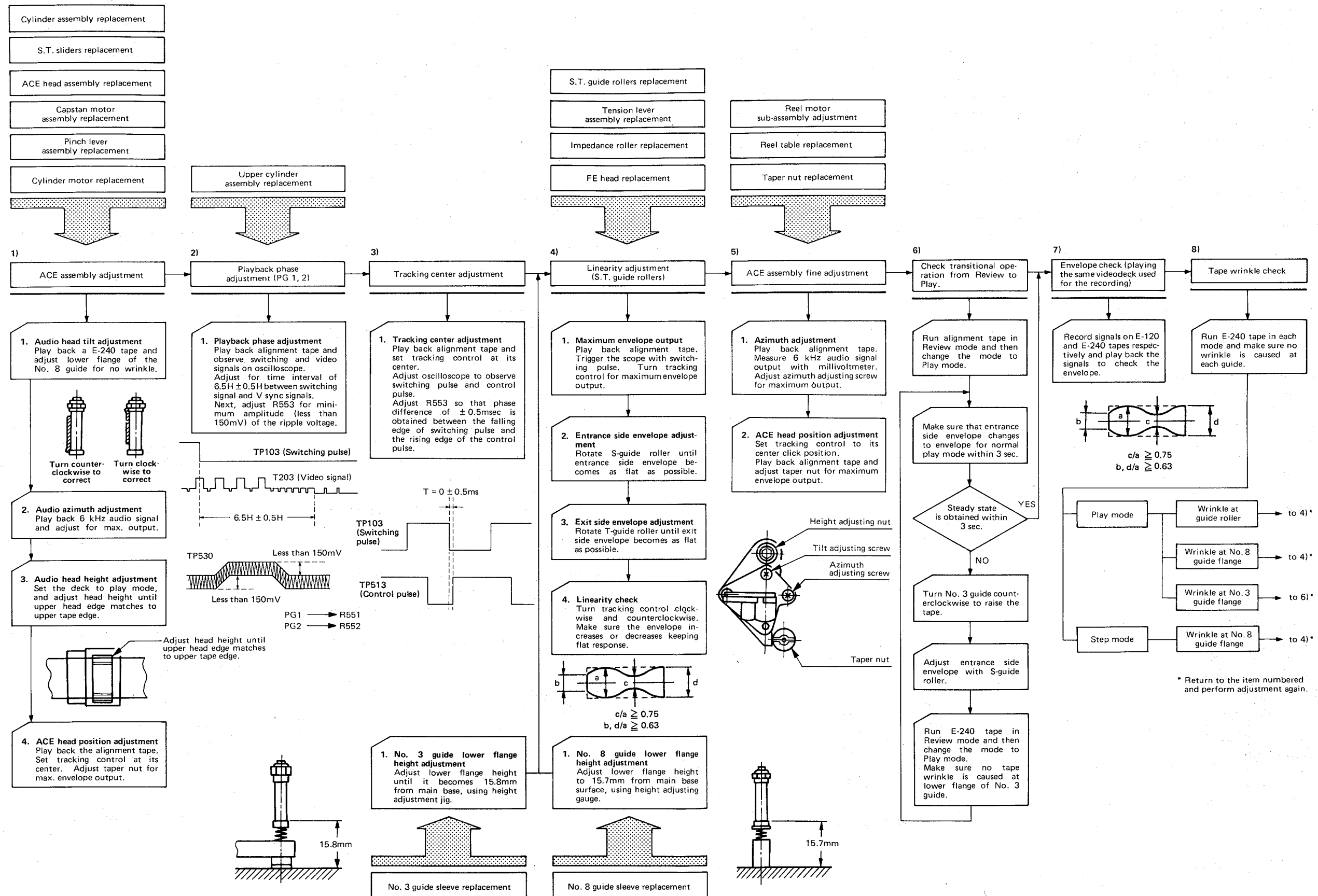


Fig. 1-4-5 Tape travel diagram

(2) Tape transport system adjustment flow chart



(3) Tape transport system adjustment

● Pre-adjustment

When the part(s) listed in table 1-4-1 is replaced, perform required adjustments by referring to procedures for the tape transport system.

When the part(s) listed in table 1-4-1 is replaced, the tape path may be changed and may damage alignment tape. To prevent this, first run a E-240 tape and make sure excessive tape wrinkle does not occur at each tape guide.

1) If tape wrinkle is observed at the No. 3 and the No. 8 guides, make sure of the preset height of these guides again.

2) If tape wrinkle is observed at the S, T-guide rollers, turn the S, T-guide rollers for no wrinkle.

● Adjustment procedures

1) ACE head assembly adjustment

a. ACE tilt adjustment

a.1) Play back a E-240 tape and observe running condition of the tape at the lower flange of No. 8 guide.

a.2) Adjust the ACE tilt adjusting screw until tape wrinkle is caused at the lower flange of No. 8 guide as shown in Fig. 1-4-7(a).

a.3) Turn the ACE tilt adjusting screw counter-clockwise until the tape travels along the lower flange as shown in Fig. 1-4-7(b).

b. Audio azimuth adjustment

b.1) Play back the alignment tape MH-2, 6 kHz portion of audio signals.

b.2) Connect a millivoltmeter to the audio line output terminal.

b.3) Turn the ACE azimuth adjusting screw to obtain maximum audio output.

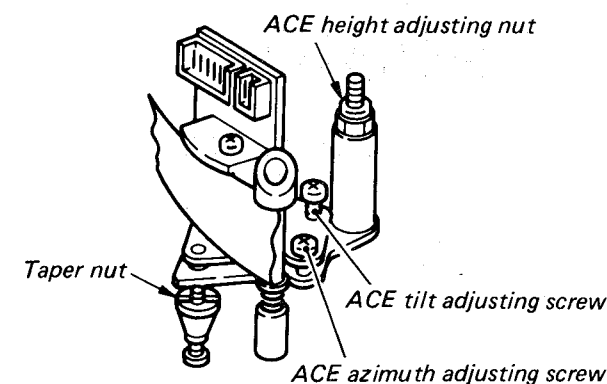


Fig. 1-4-6 ACE head assembly

Table 1-4-1

Part replacement	Adjustment procedure
<ul style="list-style-type: none"> ● Cylinder complete assembly ● S, T Sliders ● ACE head assembly ● Capstan motor assembly ● Pinch lever assembly ● Cylinder motor 	From item 1)
<ul style="list-style-type: none"> ● Upper cylinder 	From item 2)
<ul style="list-style-type: none"> ● S, T guide rollers ● Tension lever assembly ● Impedance roller ● FE head ● No. 3 guide sleeve ● No. 8 guide sleeve 	From item 4)
<ul style="list-style-type: none"> ● Reel motor sub-assembly ● Reel table (S, T) ● Taper nut 	From item 5)

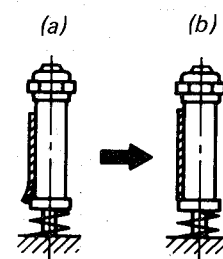


Fig. 1-4-7 No. 8 guide check

c. Audio head height adjustment

c.1) Run the alignment tape (MH-2) in the play back mode.

c.2) Observe surface of the audio head using a dental mirror.

c.3) White ceramic is provided on both sides of the audio and control heads of the ACE head assembly.

Turn the ACE height adjusting nut so that upper tape edge matches to the lower edge of the ceramic on the upper audio head.

If the above method is defficient, play back the 1 kHz portion of the alignment tape (MH-2) and adjust for maximum audio output.

d. ACE head position pre-adjustment

Note: Before proceeding with this adjustment, remove adhesive cement applied on the taper nut.

d.1) Play back the alignment tape (MH-2).

d.2) Adjust the taper nut for maximum envelope output after the tracking control set at its center position.

2) Playback phase adjustment (PG1, PG2 adjustment)

a. Play back the alignment tape (MH-2).

b. Observe a video signal on an oscilloscope display triggered with the switching pulse.

c. Adjust R551 for time interval of $6.5 \pm 0.5H$ between switching signal and V sync pulse. (Fig. 1-4-9 (a))

d. Next, adjust R552 for minimum amplitude (less than 150mV) of the ripple voltage observed at TP530. (Fig. 1-4-9(b))

3) Tracking center adjustment (Subtracking)

a. Play back the alignment tape (MH-2).

b. Adjust R553 so that phase difference of 0 ± 0.5 msec is obtained between the falling edge of the switching pulse and the rising edge of the control pulse. (Fig. 1-4-10)

Note: In this case, adjust the tracking control at the click position.

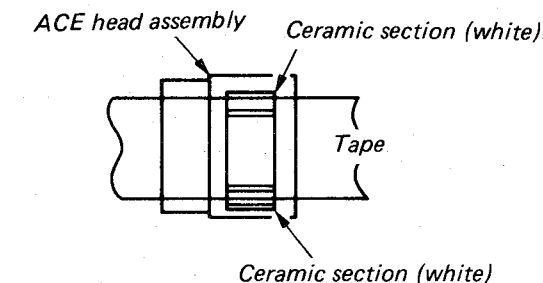


Fig. 1-4-8 Head height

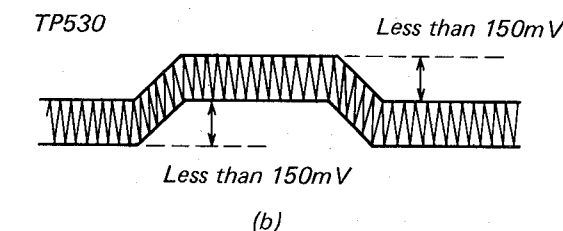
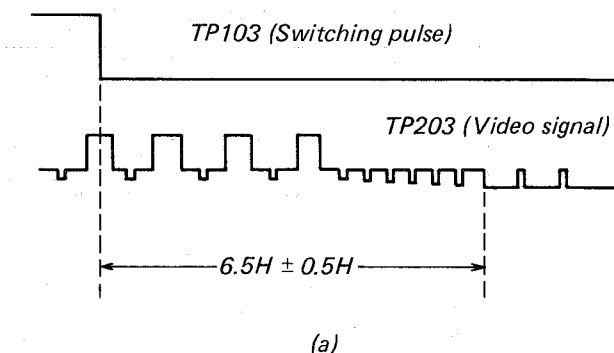


Fig. 1-4-9 Playback phase adjustment

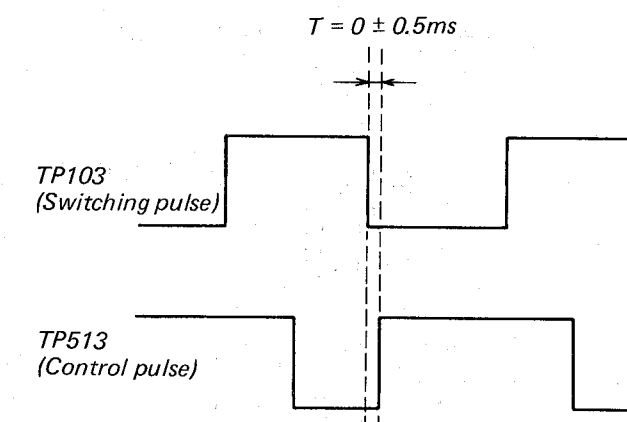


Fig. 1-4-10 Tracking center adjustment

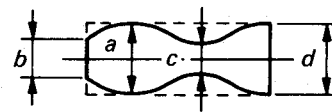
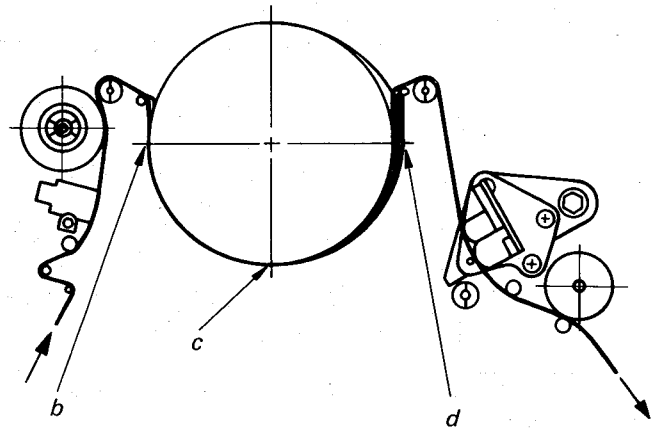
4) Linearity adjustment (S, T guide rollers adjustment)

- Play back a stair step signal on the alignment tape (MH-2).
- Observe the signal envelope on an oscilloscope display triggered by the switching pulse.
- Make sure the envelope waveform (in its maximum output) meets the specification shown in Fig. 1-4-11. If not, adjust as follows:

Note:

- a = maximum output of the envelope
- b = minimum output of the envelope at the entrance side
- c = minimum output of the envelope at the center point
- d = minimum output of the envelope at the exit side

- If the A section in Fig. 1-4-12 does not meet the specification, adjust the S-guide roller in up or down direction.
- If the B section in Fig. 1-4-12 does not meet the specification, adjust T-guide roller in up or down direction.
- After completion of the adjustment(s), turn the tracking control and make sure the envelope varies almost flat.
- If the envelope varies as shown in Fig. 1-4-13, adjustment of the S, T-guide rollers may be upset, and perform the adjustment again.



$$c/a \geq 0.75 : b, d/a \geq 0.63$$

Fig. 1-4-11 Envelope waveform specification

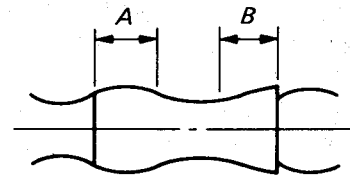


Fig. 1-4-12 Adjustment points

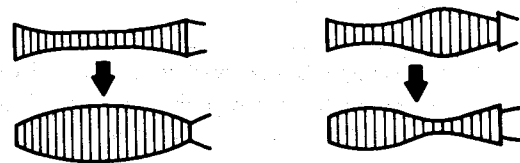


Fig. 1-4-13 Abnormal variation of the waveform

5) ACE head assembly adjustment

a. Tape wrinkle check at the lower flange of No. 8 guide.

- a.1) If tape wrinkle is observed at the lower flange of No. 8 guide, adjust the ACE tilt adjusting screw counterclockwise as shown in Fig. 1-4-6 until the wrinkle disappears.
- a.2) If a gap is observed between the lower flange of No. 8 guide and the lower edge of tape, adjust the ACE tilt adjusting screw clockwise until the tape travels along the lower flange.

Note: This adjustment should be made using a beginning part of E-240 tape.

b. Azimuth adjustment

- b.1) Play back the 6 kHz audio signal on the alignment tape (MH-2).
- b.2) Adjust the ACE azimuth adjusting screw for maximum audio output as shown in Fig. 1-4-6.

c. ACE head position adjustment

- c.1) Play back the stair step signal on the alignment tape (MH-2).
- c.2) Place the tracking control at its center click position.
- c.3) Trigger an oscilloscope with the switching pulse and observe the envelope waveform of CH-2 output.
- c.4) Turn the taper nut counterclockwise until the ACE base reaches the lower taper end of the taper nut as shown in Fig. 1-4-14.
- c.5) Turn the taper nut slowly counterclockwise and fix the taper nut at the position where the envelope reaches a first peak level.
- c.6) Play back the stair step signal on the alignment tape (MH-2).
- c.7) Make sure the envelope is maximum with the tracking control set to the center click position.

Note: If no envelope is observed with the tracking control set to the center position, perform the envelope adjustment to obtain maximum envelope, again.

- c.8) Play back the stair step signal on the alignment tape (MH-2) and make sure the audio output is maximum.

Note: After completion of the ACE head position adjustment, the ACE base must be positioned at approximately the center of the taper nut as shown in Fig. 1-4-15.

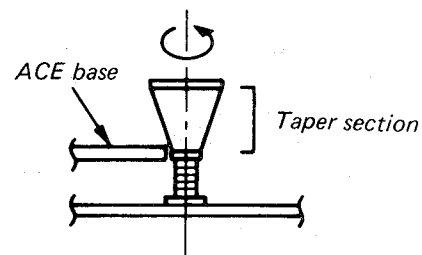


Fig. 1-4-14 Taper nut and ACE base

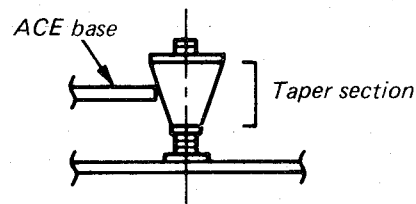


Fig. 1-4-15 Position of taper nut after adjustment

6) Check for transitional operation from Review to Play

- Play back the alignment tape (MH-2) in Review mode and observe the envelope with an oscilloscope.
- Switch the Review mode to the Play mode. When switched to the Play mode, make sure the entrance side envelope becomes to an approximate steady state within 3 seconds as shown in Fig. 1-4-16. If it does not rise within 3 seconds, adjust as follows:

Entrance side envelope

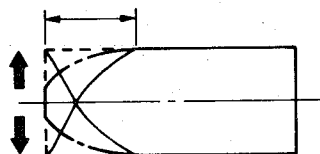


Fig. 1-4-16 Envelope rising when operation mode is switched from review to play mode

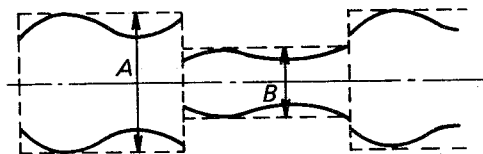
- Turn the No. 3 guide nut counterclockwise to adjust the lower flange height as shown in Fig. 1-3-22. Make sure the tape travels along the lower flange.
- Play back a stair step signal. Since entrance side linearity varies as the height of No. 3 guide varies, adjust the S-guide roller to correct the linearity.
- Change operation mode from the Review to the Play mode again and make sure the entrance side envelope rises within 3 seconds. If not, perform the adjustment again from the item c..
- Play back the E-240 tape in the Play mode and make sure no tape wrinkle occurs at the lower flange of the No. 3 guide.

If the tape is raised too high at the No. 3 guide, the tape will be damaged. So if tape wrinkle occurs, turn the No. 3 guide nut clockwise until the wrinkle disappears and then perform adjustment from the item d.

Note: If the rising characteristic is poor in Review mode, screen noises may occur in synchronous editing recording.
Perform the adjustment carefully.

7) Envelope check

- Make recordings on E-120 and E-240 tapes and make sure the playback output envelope meets the specification shown in Fig. 1-4-11.
- In playing the same video deck used for the recording using the E-120 the envelope should meet the specification shown in Fig. 1-4-17.
- If the performance does not meet both specifications a. and b., replace the upper cylinder assembly.
- Confirm operation of the synchronous editing, using a beginning portion of a E-120 tape.
- If picture noises are observed at the starting position of the editing, adjust the preset height of the No. 3 guide again. (Fig. 1-3-19)



- $B/A \geq 0.55$
- $B \geq 120mV$

Fig. 1-4-17 Envelope output and output level difference

8) Tape wrinkle check

- Play back the E-240 tape in the playback, Cue, Review and the frame feeding mode, and observe tape wrinkle at each guide.
- If excessive tape wrinkle is observed at the mode shown below, perform the associated adjustments also shown below.
 - Play back mode
 - Tape wrinkle at the S, T-guide roller section
 - Item 4: Linearity adjustment
 - Tape wrinkle at No. 8 guide flange
 - Item 4: Linearity adjustment
 - Tape wrinkle at No. 3 guide flange
 - Item 6: Rising characteristic check in mode change from Review to Play mode.
 - Frame feeding mode
 - Tape wrinkle at No. 8 guide
 - Item 4: Linearity adjustment

2. ELECTRICAL ADJUSTMENT

< Test equipments required >

- (1) Color TV (Monitor)
- (2) Oscilloscope, 2 CHs, 15 MHz or higher with delay system
- (3) Frequency counter (7 digits or higher)
- (4) Millivoltmeter
- (5) Digital voltmeter
- (6) Multimeter (20K ohm/V)
- (7) Audio generator
- (8) Audio attenuator
- (9) Alignment tapes
Part code: MH-2: 70909094
- (10) Alignment screw driver (jig)
- (11) Color pattern generator
- (12) Video sweep generator

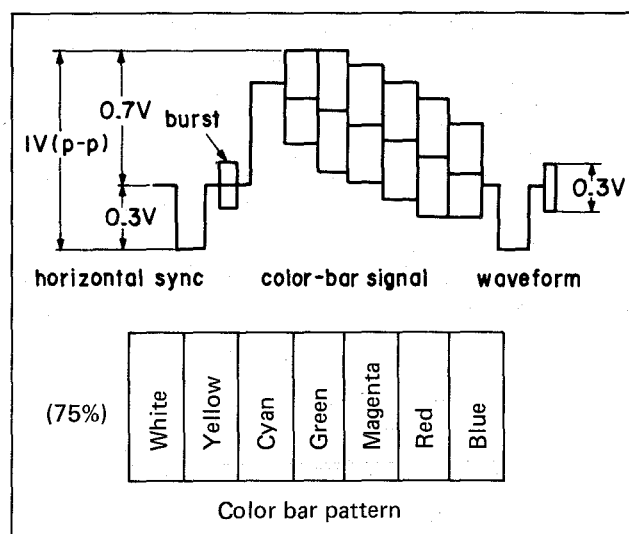


Fig. 2-1-1

< Color bar signal >

Color bar signals of 75% recorded on the test tapes are shown in Fig. 2-1-1.

< Specified input and output levels, and impedance >

Video input: Negative sync, standard composite video signal 1Vp-p, 75 ohm

Video output: Same as the video input. 1Vp-p, 75 ohm

Audio input: -10 dBs, 50k ohm

Audio output: -7 dBs, less than 10k ohm

< Alignment sequence >

Proceed the alignments in the sequence as shown in Fig. 2-1-2.

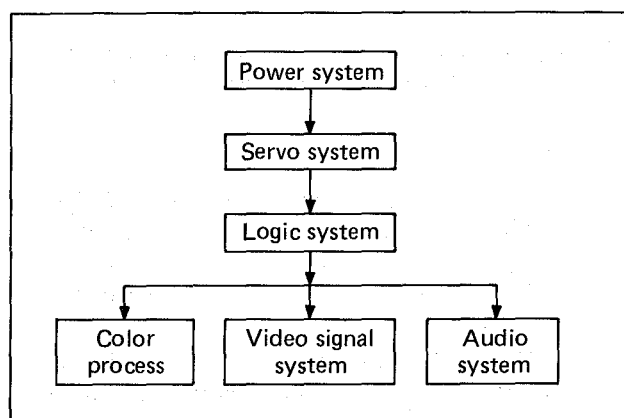
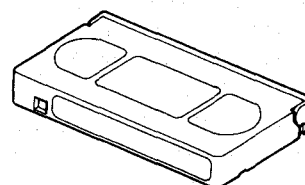


Fig. 2-1-2

Alignment tape specifications

Alignment tape MH-2



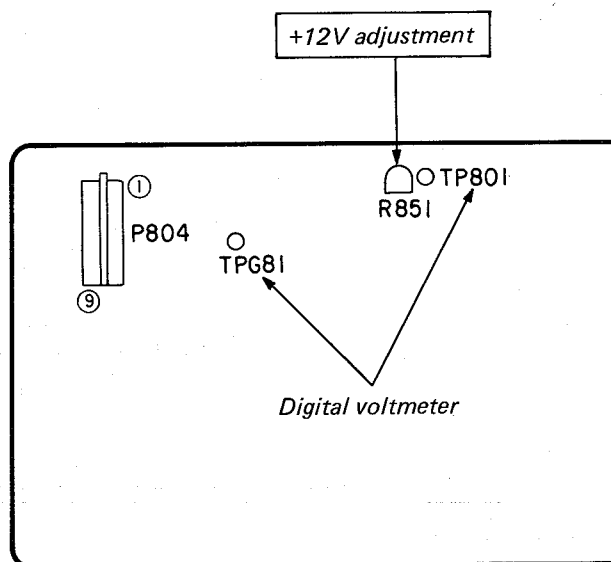
MH-2

Segment	Playback Time	Video Signal	Audio Signal	Applications
1	10 minutes	Stairstep	6 kHz	<ul style="list-style-type: none"> Interchangeability check and adjustments. Servo circuit checks and adjustments. Audio head azimuth adjustments.
2	5 minutes	(none)	3 kHz	<ul style="list-style-type: none"> Tape speed checks. Wow and flutter checks.
3	10 minutes	Color bar	1 kHz 0 dB	<ul style="list-style-type: none"> Video signal playback circuit checks and adjustments. Audio signal playback circuit checks and adjustments.
4	3 minutes	RF sweep	(none)	<ul style="list-style-type: none"> Video head resonance checks. <p>Marker: 2 MHz, 4 MHz, 5 MHz.</p>

2-1. Power Supply Circuit

2-1-1 +12V adjustment

- (1) Connect the power plug to AC input rated voltage.
- (2) Set the VTR to REC mode.
- (3) Connect the digital voltmeter between TP801 (+12V) and TPG81 (GND).
- (4) Adjust variable resistor R851 to obtain voltage reading of $12.0 \pm 0.1V$.

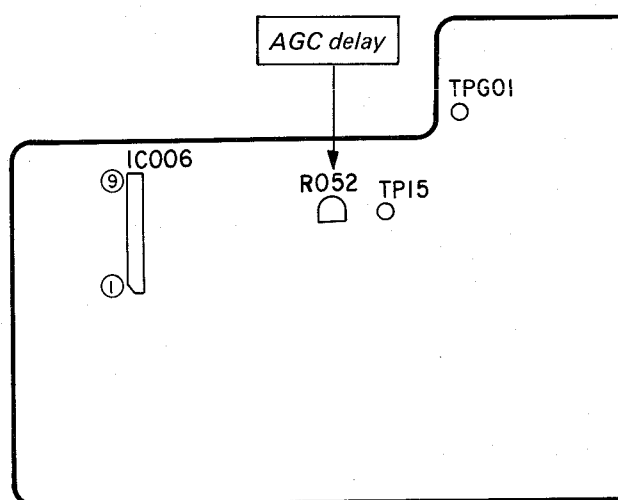


Power 1 PC Board

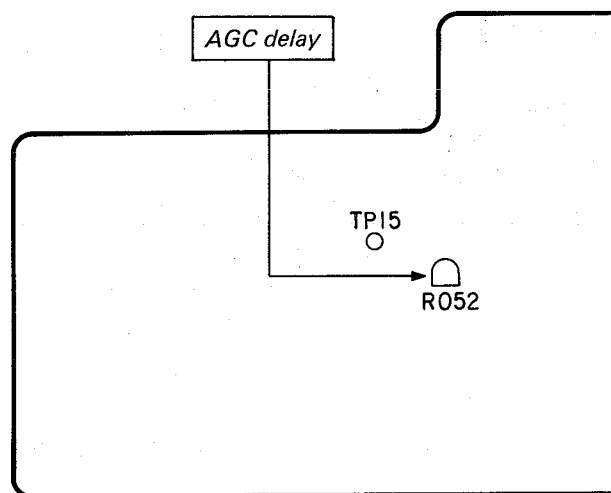
2-2. PIF Selector Circuit

2-2-1 AGC delay

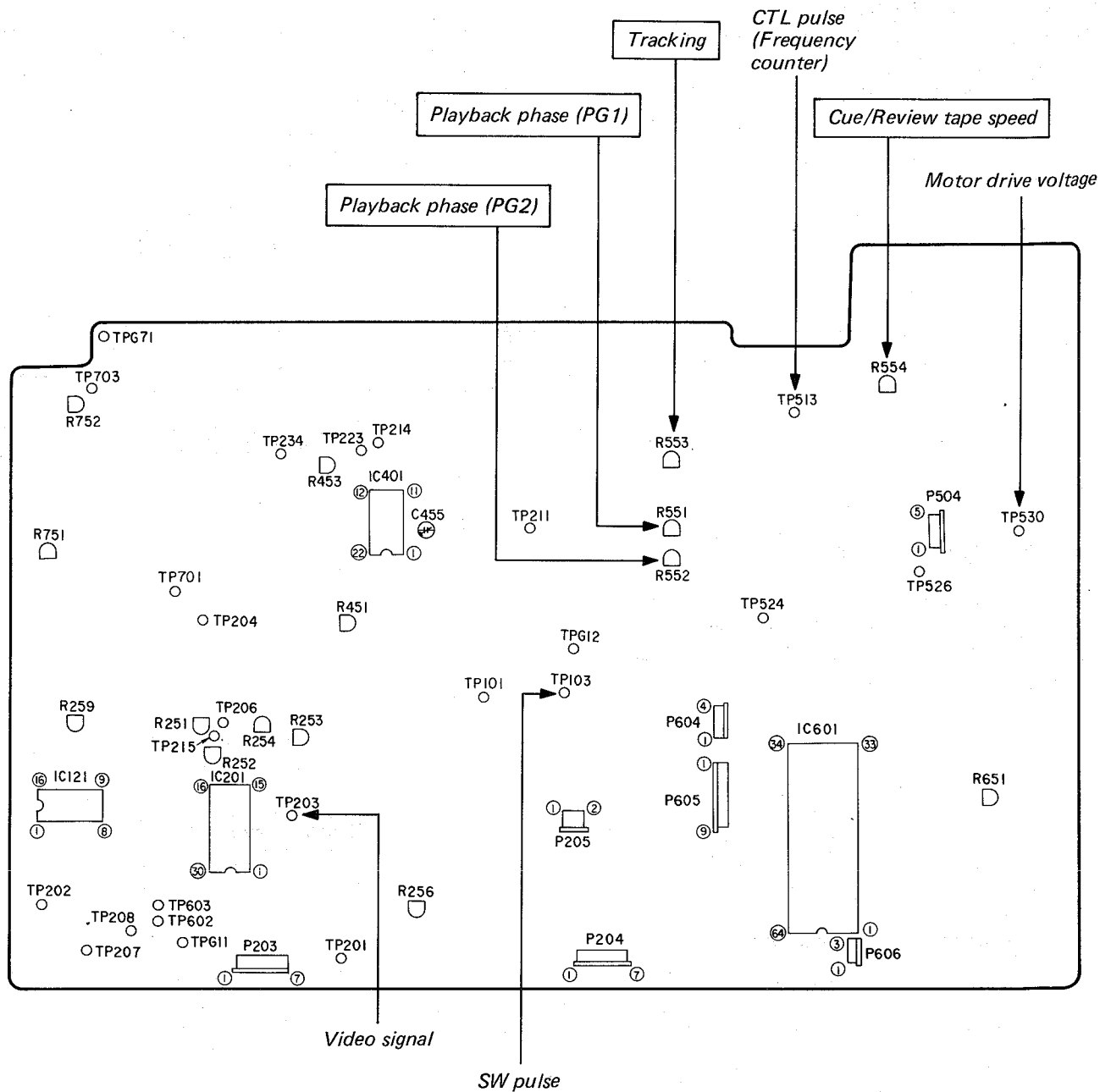
- (1) Temporarily turn R052 fully clockwise.
- (2) Turn R052 slowly counterclockwise for minimum noise and sound buzz.



PIF PC Board
(V-81/83G model)



PIF PC Board
(V-81/83W model)

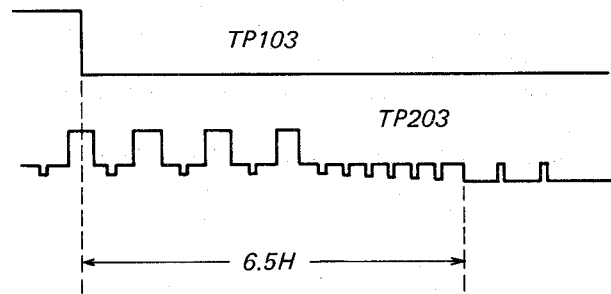


Main (Video, Servo, Logic, Audio) PC Board

2-3. Servo Circuit

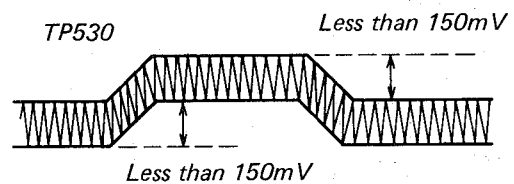
2-3-1 Playback phase (PG1)

- (1) Playback the alignment tape (MH-2).
(Tracking control knob at its center click position)
- (2) Set the oscilloscope to the chop mode, and externally trigger the scope with the SW pulse.
Connect the A-CH input to the SW pulse (TP103) and the B-CH to the video signal (TP203).
- (3) Adjust R551 to position the falling edge of the SW pulse at $6.5H \pm 0.5H$ from the V-sync front edge of the video signal.



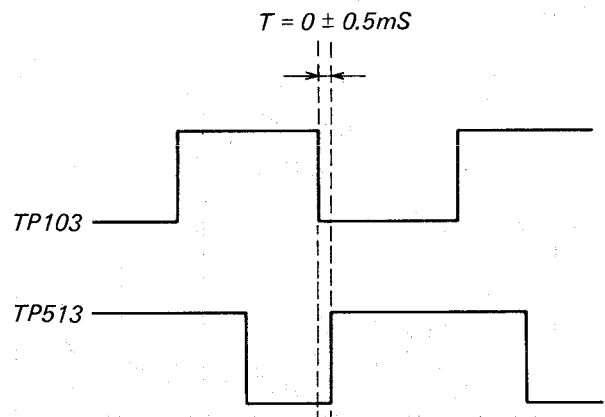
2-3-2 Playback phase (PG2)

- (1) Always perform this adjustment after the adjustment 2-3-1 has been completed.
- (2) Play back a recorded tape.
- (3) Set the oscilloscope to the chop mode and connect the A-CH input to TP103 (SW pulse) and the B-CH to TP530 (cylinder motor drive voltage). Trigger the A-CH with the SW pulse.
- (3) Adjust R552 for minimum voltage ripple (less than 150mV).



2-3-3 Tracking

- (1) Place the tracking control in the center click position.
- (2) Play back a recorded tape.
- (3) Set the oscilloscope to the chop mode.
- (4) Connect the A-CH input to TP103 (SW pulse) and the B-CH to TP513 (CTL pulse). Trigger the oscilloscope with the SW pulse.
- (5) Adjust R553 so that T becomes $0 \pm 0.5\text{ms}$ as illustrated.



2-3-4 Cue/Review tape speed

- (1) Run a recorded tape in the cue mode.
- (2) Connect a frequency counter to TP513 (CTL pulse).
- (3) Adjust R554 until frequency reading of $179 \text{ Hz} \pm 2 \text{ Hz}$ is obtained.
- (4) Set the VTR to the review mode and make sure that the frequency reading is $170 \text{ Hz} \pm 4 \text{ Hz}$.
- (5) If the frequency reading is out of limit, readjust R554 so that the frequency meets both specifications.

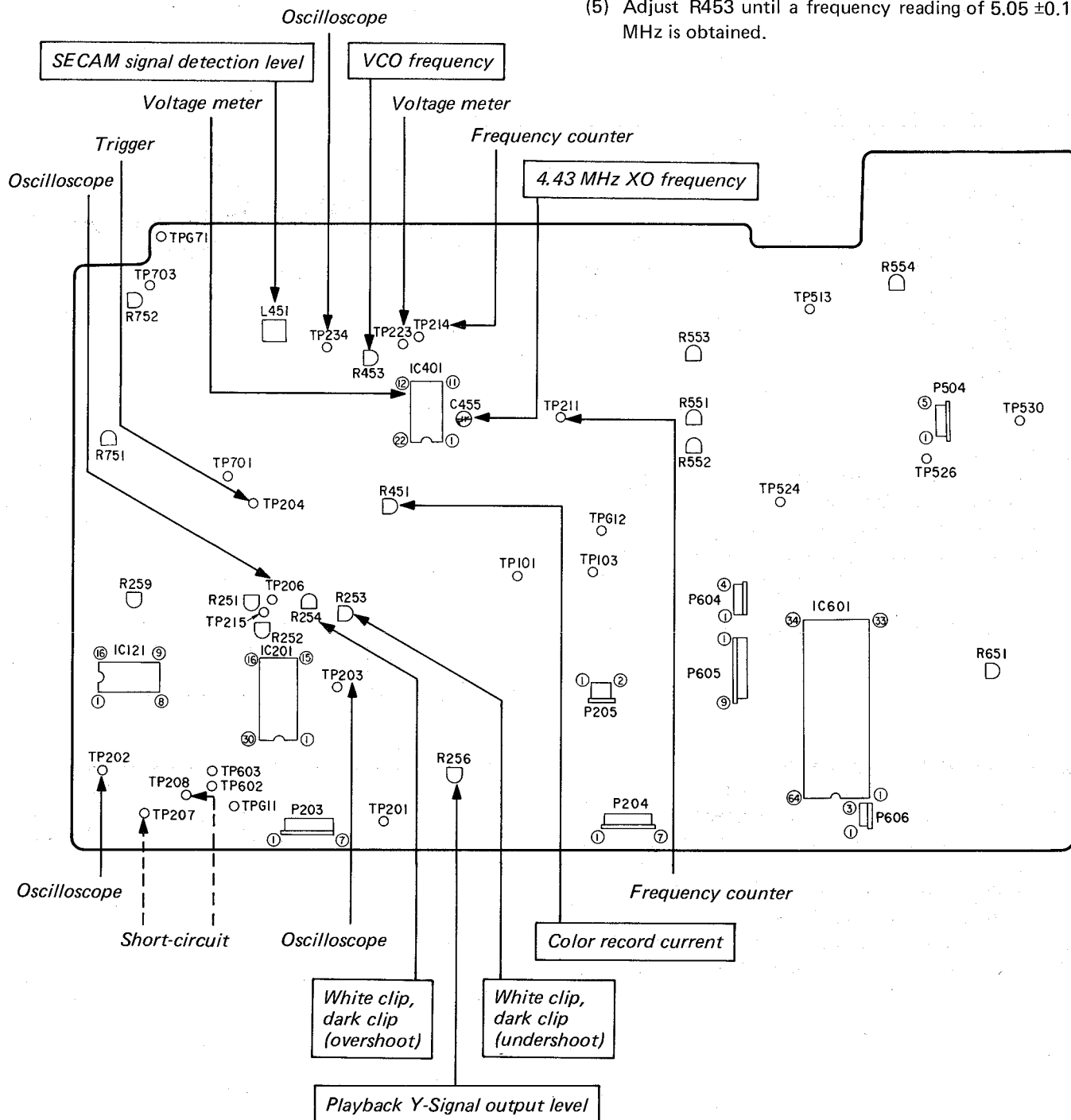
2-4. Video Circuit

2-4-1 4.43 MHz XO frequency

- (1) Play back the alignment tape (color bar signal).
- (2) Connect a frequency counter to TP211 and set the measurement range to a position which gives reading accuracy of 1 Hz.
- (3) Adjust C455 trimmer until the frequency reading of 4.433619 MHz \pm 25 Hz is obtained.

2-4-2 VCO frequency

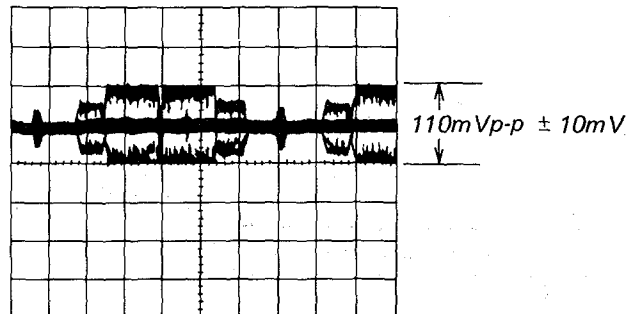
- (1) Feed the color bar signal to the line input terminal. Do not push any operation buttons.
- (2) Measure the voltage of 5V line. (Ev)
- (3) Apply DC voltage of $1/2E_v \pm 0.02V$ to TP223 (pin ⑬ of IC401).
- (4) Connect the frequency counter to TP214 and set the measurement range to a position that gives reading accuracy of 1kHz.
- (5) Adjust R453 until a frequency reading of 5.05 ± 0.15 MHz is obtained.



Main (Video, Servo, Logic, Audio) PC Board

2-4-3 Color record current

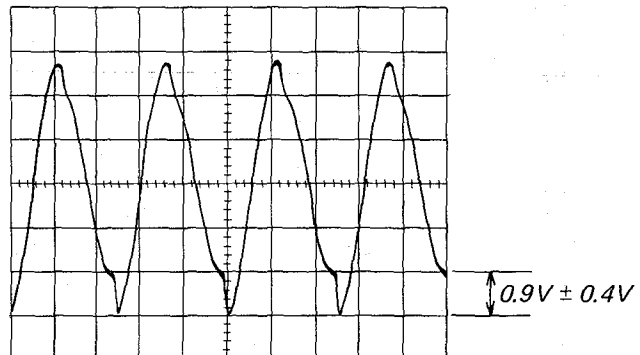
- (1) Feed the color bar signal to the line input terminal, and set the VTR to the record mode.
- (2) Connect the oscilloscope to TP202 and trigger the scope with a composite sync signal (TP204).
Adjust the oscilloscope so that it can display a waveform of approx. 2H.
- (3) Short-circuit between TP207 and TP208.
- (4) Adjust R451 to obtain a red signal amplitude of $110\text{mVp-p} \pm 10\text{mV}$.



Horizontal axis: $10\mu\text{s/div.}$
Vertical axis: 50mV/div.

2-4-4 SECAM signal detection level

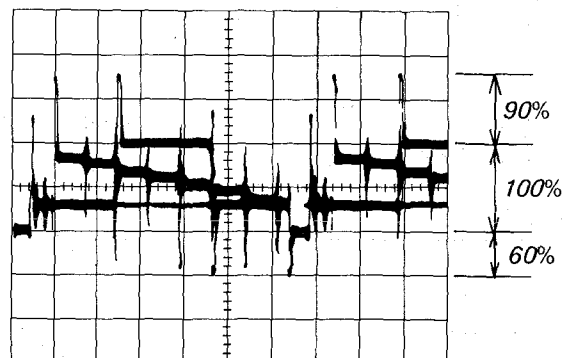
- (1) Feed the SECAM color bar signal to the line input terminal and set the VTR to the record mode.
- (2) Connect the oscilloscope to TP234.
- (3) Adjust L451 to obtain a detection output waveform of $0.9 \pm 0.4\text{V}$ at the peak.



Horizontal axis: $50\mu\text{s/div.}$
Vertical axis: 1V/div.

2-4-5 White clip, dark clip

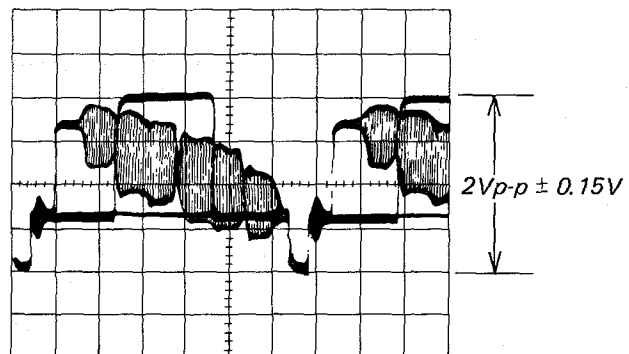
- (1) Feed the color bar signal to the line input terminal. Do not push any operation buttons.
- (2) Connect the oscilloscope to TP206 and trigger the scope with a composite sync signal at TP204.
Adjust the scope so that it can display a waveform of approx. 2H.
- (3) Adjust R254 so that amplitude of overshoot appearing on the video signal side shows $90 \pm 5\%$ of a Y signal amplitude of 100%.
- (4) Adjust R253 so that an undershoot appearing on the sync tip side shows $60 \pm 5\%$ of a Y signal amplitude of 100%.



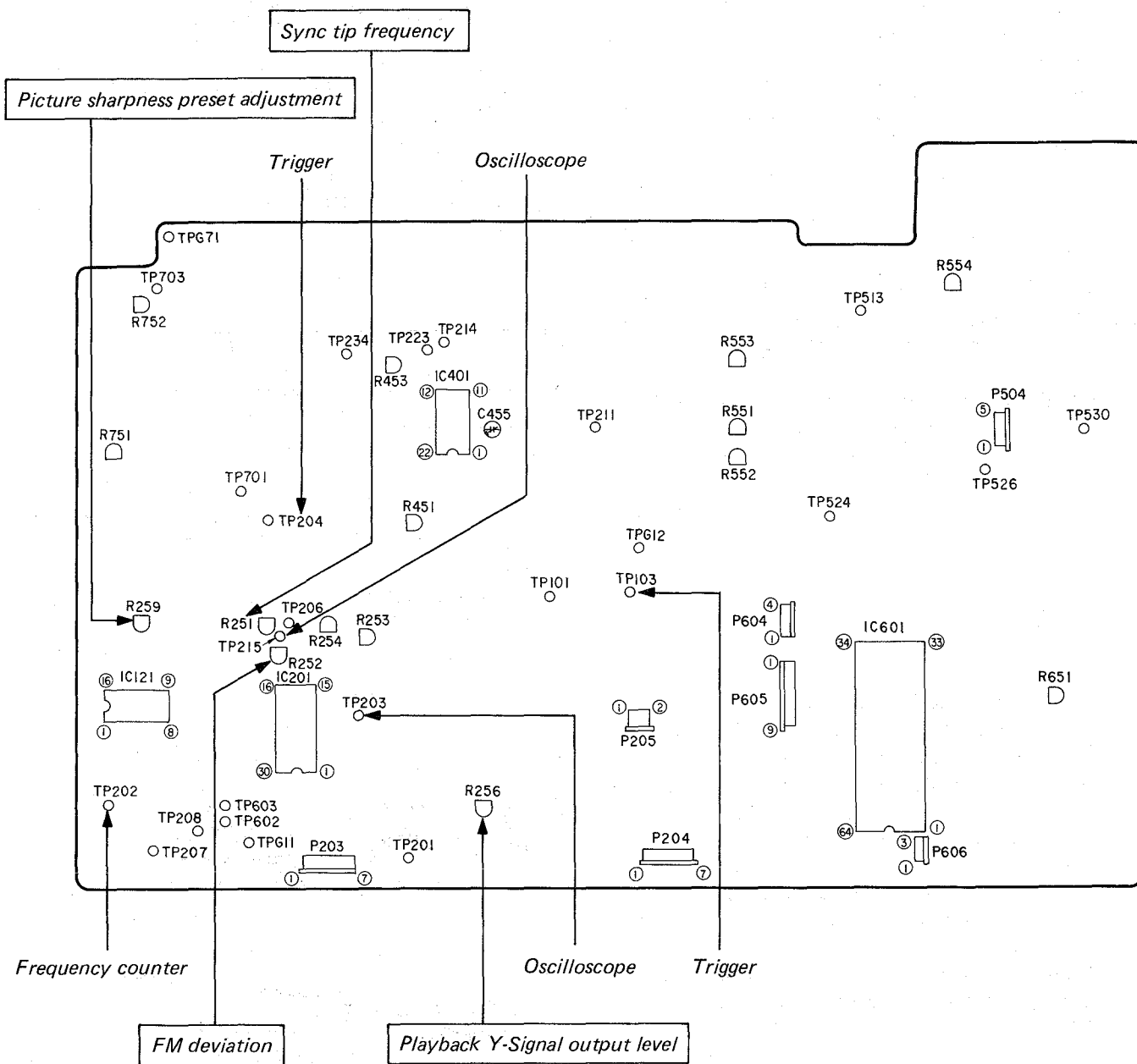
Horizontal axis: $10\mu\text{s/div.}$
Vertical axis: Adjust as illustrated, using a calibrator.

2-4-6 Playback Y-Signal output level

- (1) Play back the alignment tape (color bar signal).
- (2) Connect the oscilloscope to TP203 and trigger the scope with a composite sync signal (TP204).
Adjust the scope so that it can display a waveform of approx. 2H.
- (3) Adjust R256 to obtain $2.0 \text{ Vp-p} \pm 0.15\text{Vp-p}$ between the sync tip and 100% white level.



Horizontal axis: $10\mu\text{s/div.}$
Vertical axis: 0.5V/div.



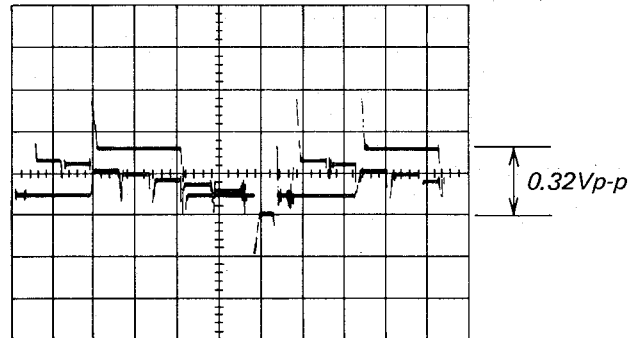
Main (Video, Servo, Logic, Audio) PC Board

2-4-7 FM deviation

- (1) Feed the color bar signal to the line input terminal.
- (2) Connect the oscilloscope to TP215 and trigger the scope with a composite sync signal at TP204. Adjust the scope to display a waveform of approx. 2H
- (3) Adjust R252 to obtain the amplitude of approx. 0.32Vp-p between the sync tip and the white peak. After adjusting R256 (playback Y signal output level) with the method 2-4-5, repeat above the adjustment, and then adjust R252 (FM deviation control) so that the play back Y signal output level at TP203 shows 2.0Vp-p \pm 0.2Vp-p.

2-4-8 Sync tip frequency

- (1) Short circuit line input terminal to ground with phone jack and set the VTR to REC mode.
- (2) Connect the frequency counter to TP202.
- (3) Adjust R251 to obtain frequency of 3.90 MHz \pm 0.1 MHz.



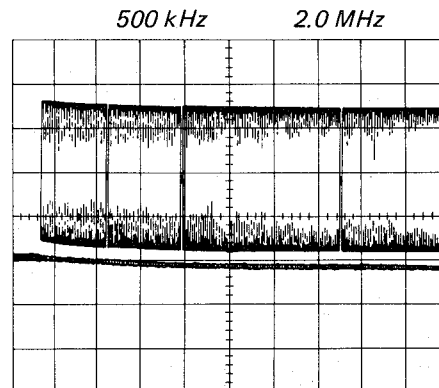
Horizontal axis: 10 μ s/div.
Vertical axis: 0.2mV/div.

2-4-9 Picture sharpness preset adjustment

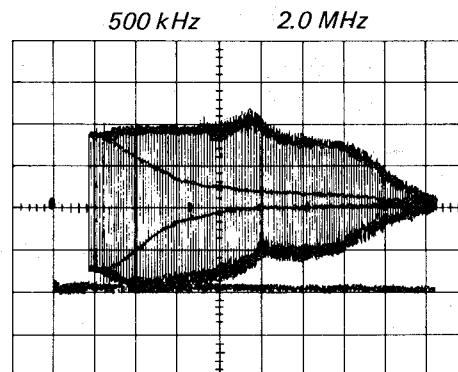
- (1) Place the picture sharpness control in its center click position.
- (2) Feed the video sweep signal to the line input terminal.
- (3) Load a blank tape and set the VTR to the record mode.
- (4) Connect the oscilloscope to TP203 and trigger the scope with a vertical sync signal at TP103. Set the scope so that it can display a waveform for more than one vertical scanning period.
- (5) Play back the tape recorded in the step (3) above. Adjust R259 so that 2.0 MHz level shows -3 ± 1 dB referred to the 500 kHz reference level as illustrated.

Note: For example, if the 500 kHz level has been adjusted to show 4 scales, the 2.0 MHz level should be 2.8 ± 0.2 scales.

- (6) Make sure that clockwise rotation of the picture sharpness control will increase the level in the step (5) above, and counter clockwise rotation will decrease the level.
Reset the knob at its center click position.



Horizontal axis: 2ms/div.
Vertical axis: Adjust as illustrated, using a calibrator.



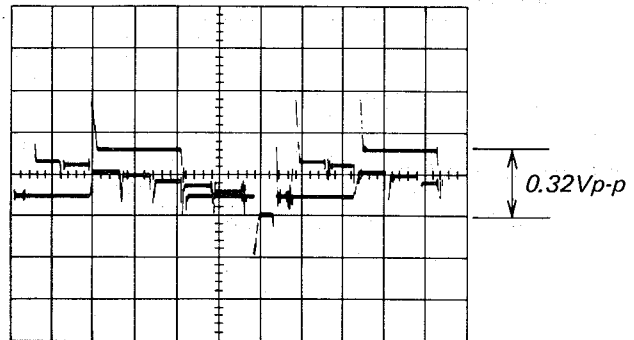
Horizontal axis: 2ms/div.
Vertical axis: Adjust as illustrated, using a calibrator.

2-4-7 FM deviation

- (1) Feed the color bar signal to the line input terminal.
- (2) Connect the oscilloscope to TP215 and trigger the scope with a composite sync signal at TP204. Adjust the scope to display a waveform of approx. 2H
- (3) Adjust R252 to obtain the amplitude of approx. 0.32Vp-p between the sync tip and the white peak. After adjusting R256 (playback Y signal output level) with the method 2-4-5, repeat above the adjustment, and then adjust R252 (FM deviation control) so that the play back Y signal output level at TP203 shows 2.0Vp-p ± 0.2 Vp-p.

2-4-8 Sync tip frequency

- (1) Short circuit line input terminal to ground with phone jack and set the VTR to REC mode.
- (2) Connect the frequency counter to TP202.
- (3) Adjust R251 to obtain frequency of 3.90 MHz ± 0.1 MHz.



Horizontal axis: 10 μ s/div.
Vertical axis: 0.2mV/div.

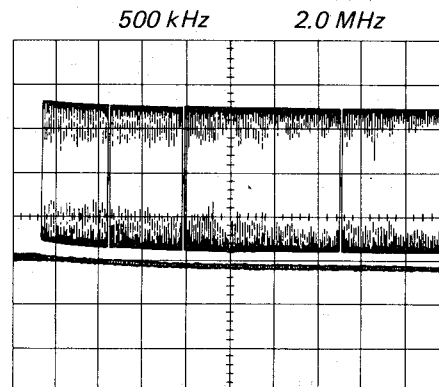
2-4-9 Picture sharpness preset adjustment

- (1) Place the picture sharpness control in its center click position.
- (2) Feed the video sweep signal to the line input terminal.
- (3) Load a blank tape and set the VTR to the record mode.
- (4) Connect the oscilloscope to TP203 and trigger the scope with a vertical sync signal at TP103. Set the scope so that it can display a waveform for more than one vertical scanning period.
- (5) Play back the tape recorded in the step (3) above. Adjust R259 so that 2.0 MHz level shows -3 ± 1 dB referred to the 500 kHz reference level as illustrated.

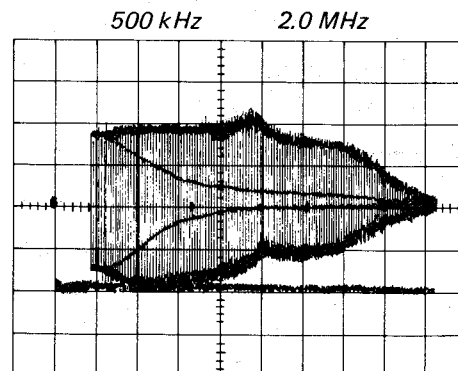
Note: For example, if the 500 kHz level has been adjusted to show 4 scales, the 2.0 MHz level should be 2.8 ± 0.2 scales.

- (6) Make sure that clockwise rotation of the picture sharpness control will increase the level in the step (5) above, and counter clockwise rotation will decrease the level.

Reset the knob at its center click position.



Horizontal axis: 2ms/div.
Vertical axis: Adjust as illustrated, using a calibrator.



Horizontal axis: 2ms/div.
Vertical axis: Adjust as illustrated, using a calibrator.

2-5. Audio Circuit

Notes:

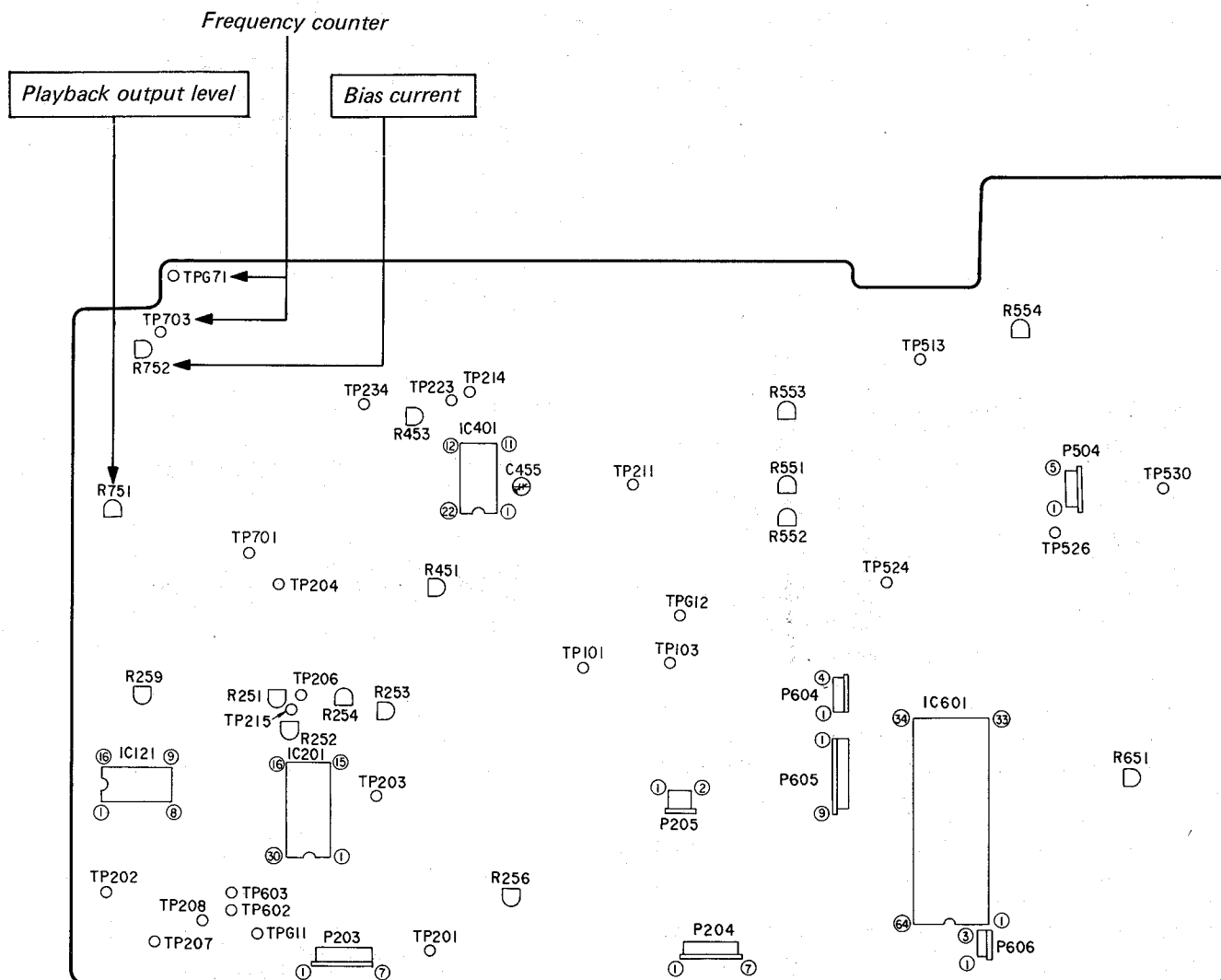
- Adjustments for the playback frequency response and playback output level may not be performed if the audio control head is improperly positioned on the audio track. In such a case, perform the azimuth adjustment and height adjustment perfectly, and then proceed the adjustments 2-4-1 — 2-4-5.
- When using alignment tapes other than those specified below always make sure that interchangeability is assured for the tapes before proceeding the adjustments.

2-5-1 Playback output level

- (1) Terminate to the audio line output terminal with a 47k ohm resistor and playback the alignment tape (MH-2).
- (2) Adjust R751 until output level obtains $-7 \text{ dBs} \pm 0.5 \text{ dBs}$.

2-5-2 Record/Erase oscillator frequency

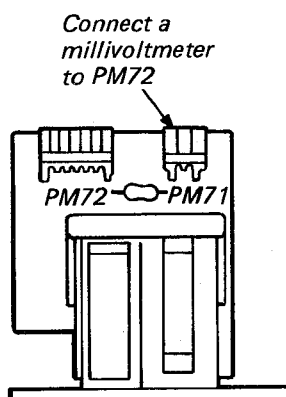
- (1) Connect the frequency counter across TP703 and TPG71 (ground).
- (2) Set the VTR to record mode and check that the frequency counter shows $68 \text{ kHz} \pm 6.8 \text{ kHz}$.



Main (Video, Servo, Logic, Audio) PC Board

2-5-3 Bias current

- (1) Short circuit the audio line input terminal, creating no input signal condition. Connect a millivoltmeter to PM72 ① – ② (GND).
- (2) Set the VTR to the record mode and adjust R752 to obtain 2.5mV rms.



2-5-4 Record/playback frequency characteristics

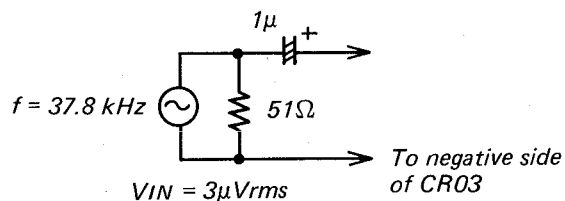
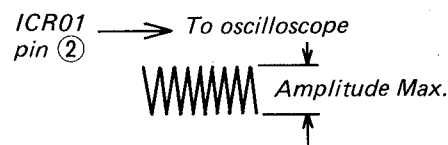
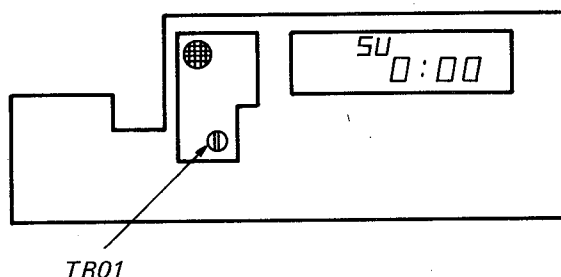
- (1) Terminate the audio line output terminal with a 47k ohm resistor.
- (2) Apply 400 Hz and 8 kHz signals of -25 dBs to audio line input terminal, and record the signal.
- (3) Playback the signals just recorded and check that the output of 8 kHz is 0 dB \pm 4 dB referred to the output of 400 Hz.
- (4) If the 8 kHz output is higher than that of 400 Hz by more than 4 dB, adjust the bias current to a value higher than 2.5 mVrms; and if the 8 kHz output is lower than that by less than -4 dB, adjust the bias current to a value lower than 2.5mV rms.

2-5-5 Record/playback output level

- (1) Terminate the audio line output terminal with a 47k ohm resistor.
- (2) Feed 400 Hz, -10 dBs signal to the audio line input terminal and record the signal.
- (3) Reproduce the signal just recorded and make sure the playback output level is -7 dBs \pm 3 dB.

2-6. Wireless Remote Control Circuit

- (1) Connect the oscilloscope across pin ② of ICR01 and ground. (Use a probe of 10 : 1.)
- (2) Feed a signal of 37.8 kHz with amplitude of $3\mu\text{Vrms}$ across pin ⑧ of ICR01 and (-) side of CR03 through the network as shown.
- (3) Adjust TR01 for the maximum amplitude on the scope display.



SECTION 3

SERVICING DIAGRAMS

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1. Inspection Procedure

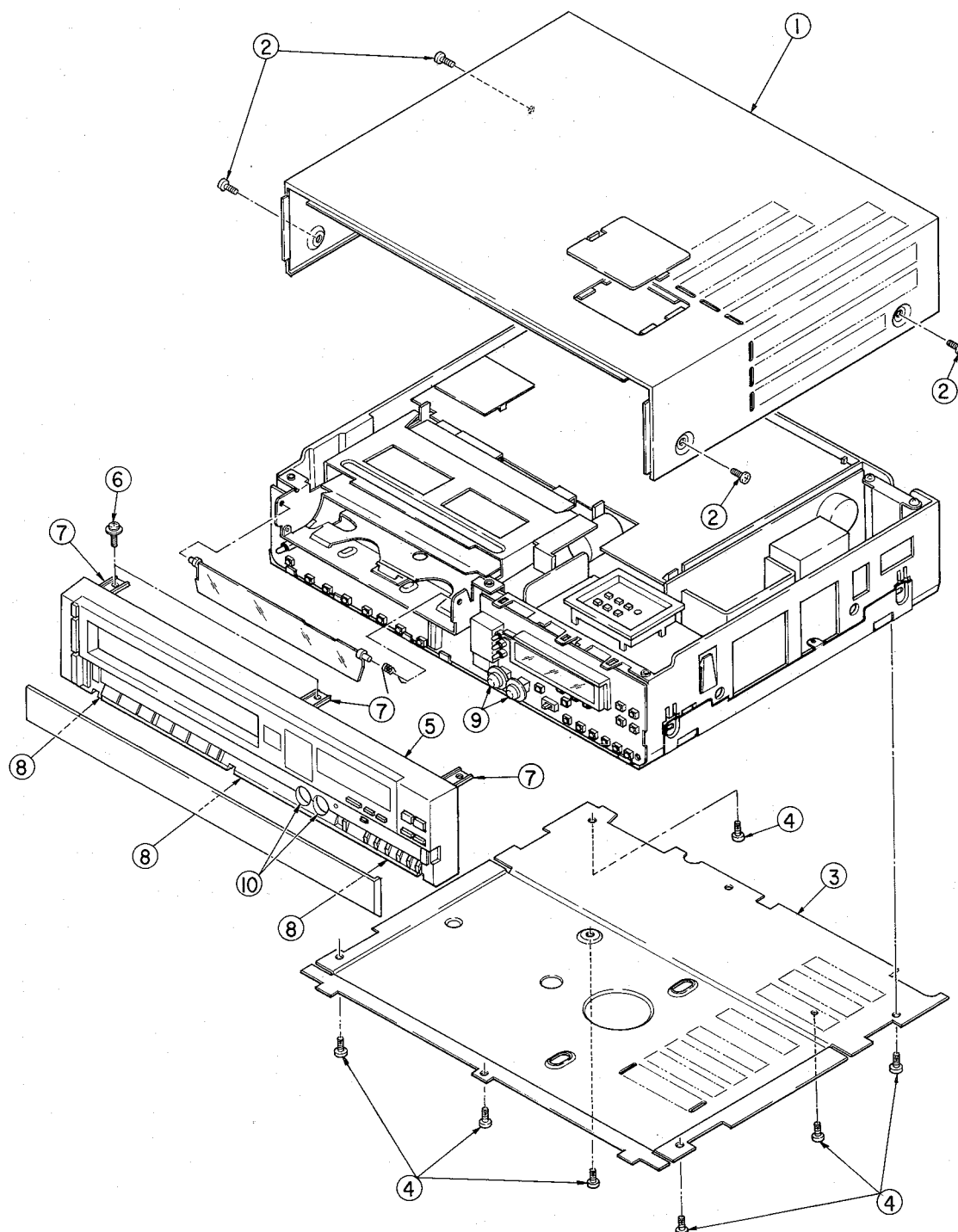
Operation steps		Items to confirmed	Inspection block	Page	
				Block Diagram	Circuit Diagram
1. AC Plug-in	Time setting Program timer setting	Clock display Time setting operation	Power (AC system) Timer counter (V-81G/W) Timer counter (V-83G/W)	13	39
				18	51
				19	55
2. Power SW ON	Timer/counter, memory, AFC operation, EE picture & tone quality	Mode display lamp TV receive condition Channel select operation, AFC operation level, EE picture quality, Tone Signal level	Power Logic RF, reception (V-81/83G) RF, reception (V-81/83W) Video (EE, Rec mode) Audio (EE, Rec mode)	13	39
				24	59
				15	43
				16	47
				33	71
				36	75
3. Cassette-in and Cassette-out	Cassette-in Cassette loading Eject Cassette-out	F/L mecha. operation Cassette loading operation Eject operation Indicator lamp Abnormal sound	Logic	24	59
4. Key enter Operation Remote-control	REC, PLAY Cue/Review Still, Frame feeding/slow FF/REW Auto play (REW ON → PLAY ON)	Indicator lamp Each mode operation (Tape drive operation Abnormal sound Auto play operation	Logic Remote control block	24	59
				77	78
5. Special Functions Auto Power ON Auto Rewind	Cassette-in at Power OFF REC/PLAY/CUE	Power ON, Cassette down Rewind automatically after tape wound	Power Logic	13	39
				24	59
6. Playback Function Picture Quality Tone Quality Others	PLAY (Test tape: MH-2) Cue/Review Still/Slow	Resolution, S/N Hue, Saturation, Color unevenness, Color dropout, Sound distortion, Level variation, Picture noise, Jitter, Picture swing, Skew distortion, Flicker, Beat	Video PLAY system Audio PLAY system Servo system	33	71
				36	75
				30	65
7. REC/PLAY Functions Picture Quality Tone Quality Others	REC/PLAY	Resolution, S/N Hue, Saturation, Color unevenness, Color dropout, Sound distortion, Level variation, Picture noise, Jitter, Picture swing, Skew distortion, Flicker, Beat	Video PLAY system Audio PLAY system Servo system	33	71
				36	75
				30	65

How to use the table

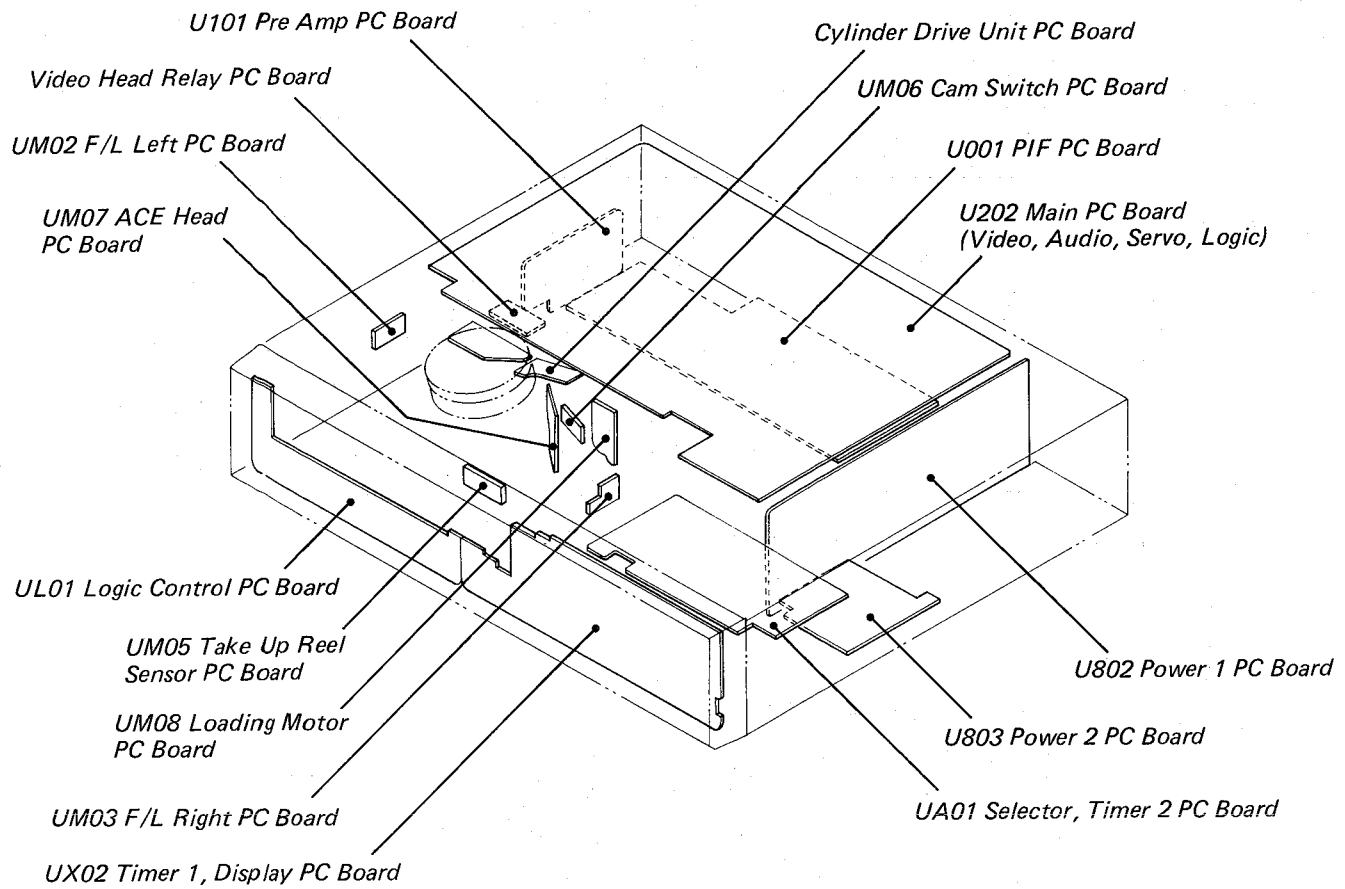
1. When inspecting a defective VTR, proceed according to the steps shown in the table.
2. Check the items to be confirmed for each operation step.
3. If a problem is found on the item, check waveforms (level) referring to the block diagram relating to the items.
4. Use PC board pattern diagram and schematic diagram to examine the circuit precisely.
5. After completion of the repair work, check steps 1 ~ 7 again.

2. Removal of Cabinet

- (1) Disconnect power cord plug from AC outlet.
- (2) Remove 4 screws ② securing top cover ①.
- (3) Remove the top cover ① by sliding it backward.
- (4) Remove 7 screws ④ securing bottom cover ③, then remove the bottom cover.
- (5) Remove 2 screws ⑥ securing front panel ⑤.
- (6) Remove the front panel ⑤.

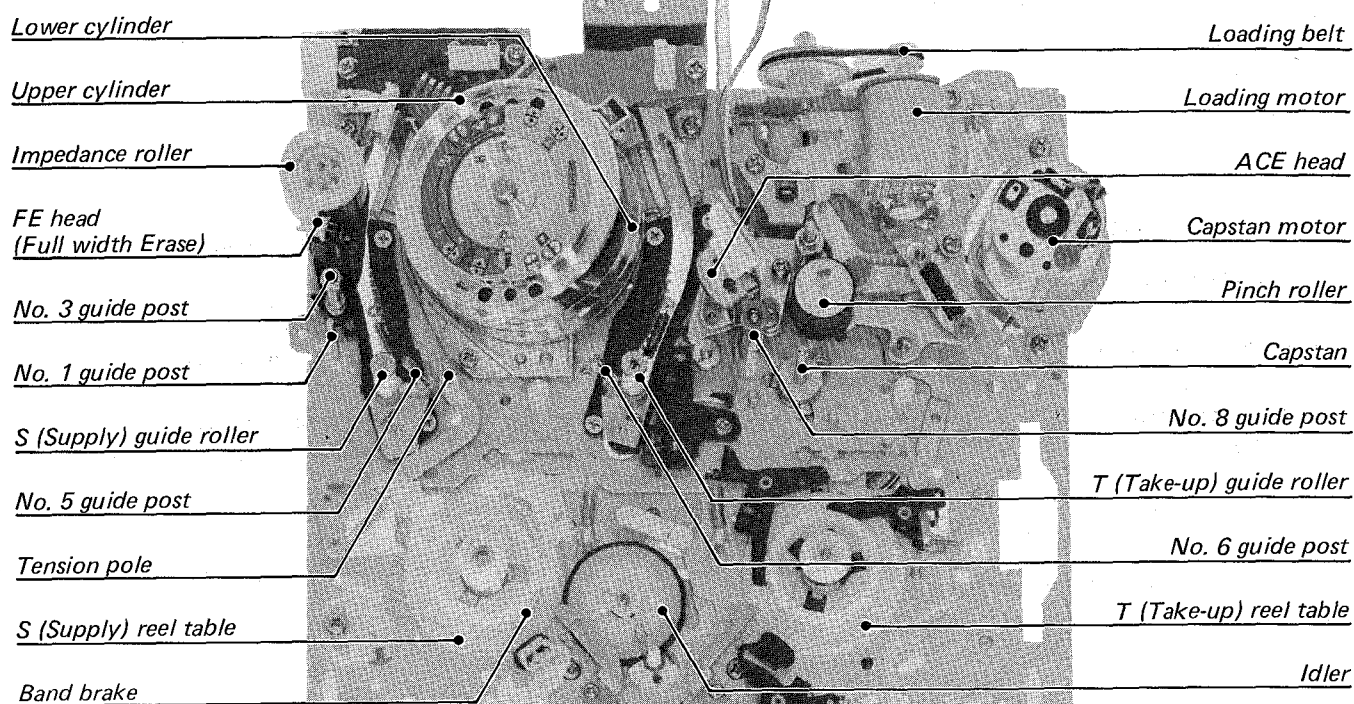


3. Electrical Units Location Diagram

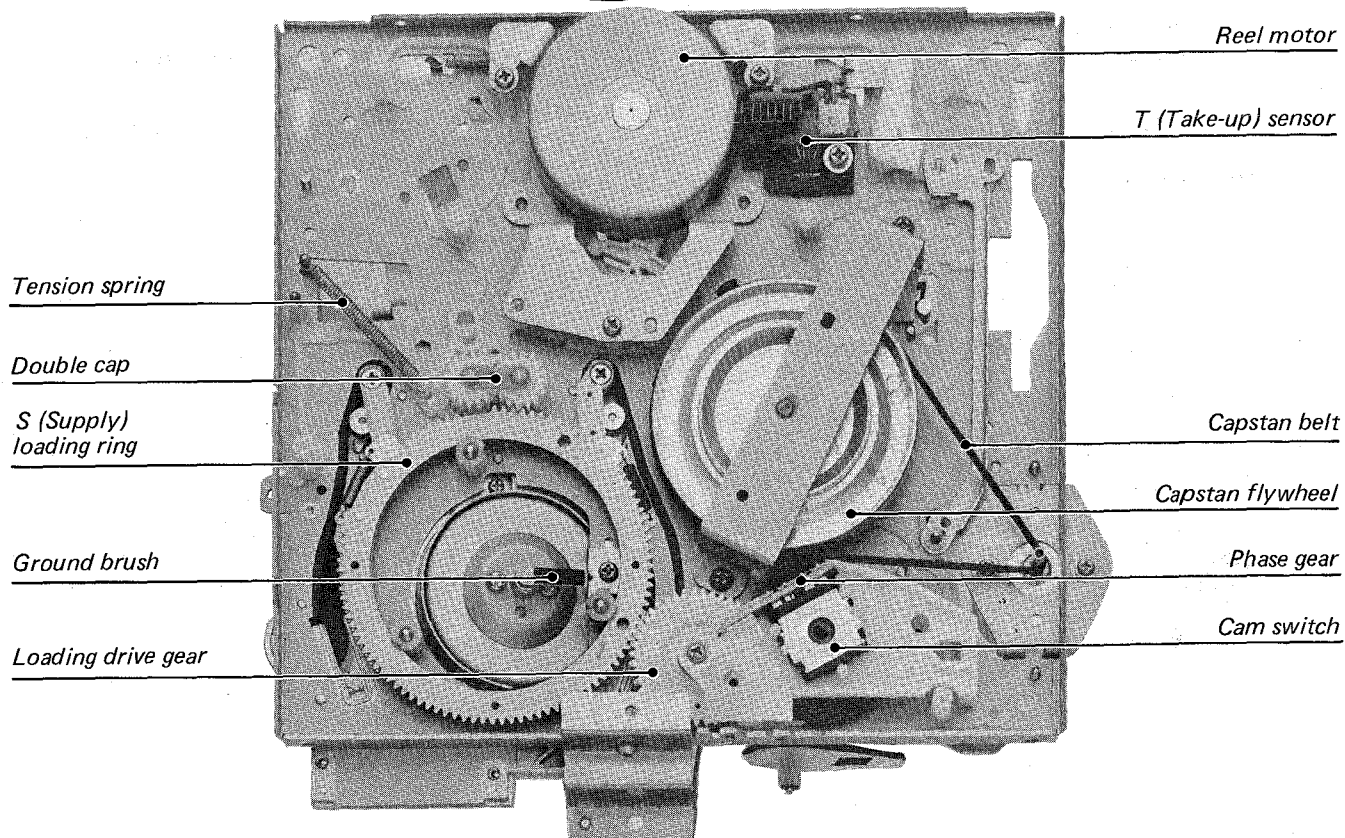


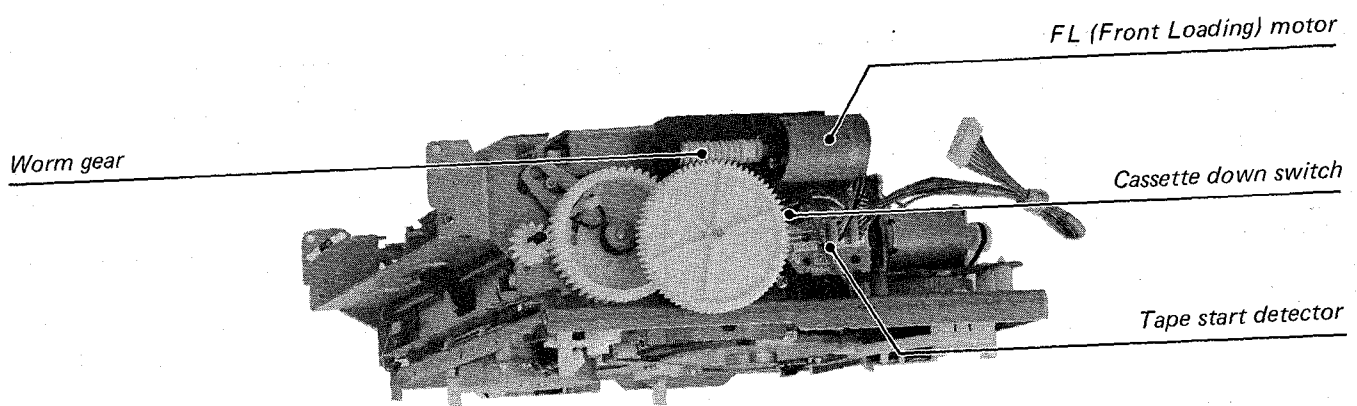
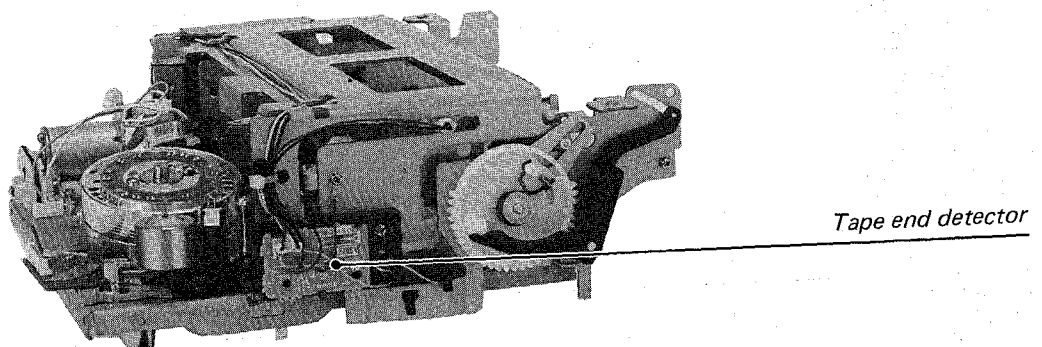
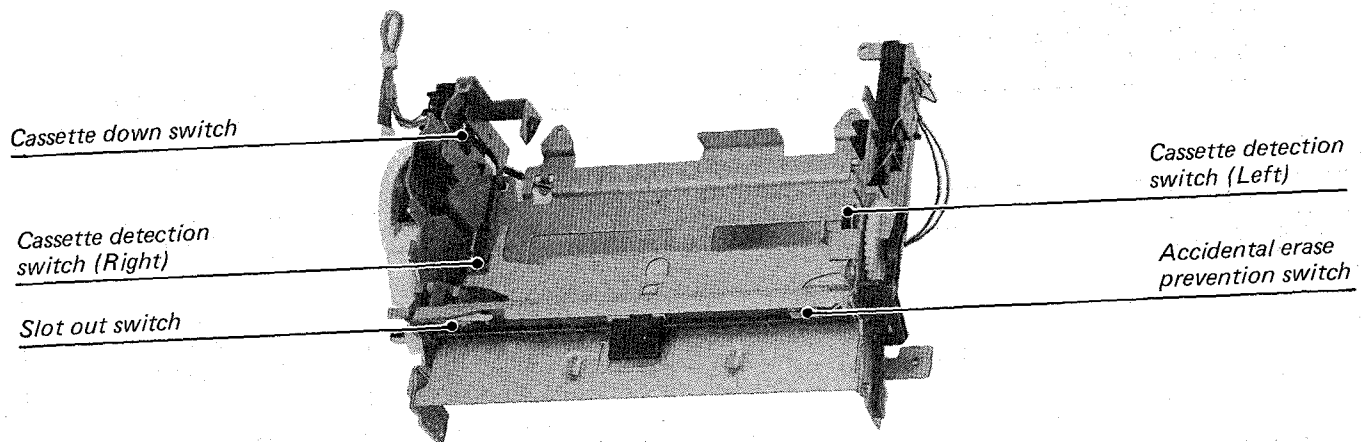
4. Mechanical Parts Location

Top View



Bottom View





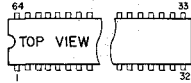
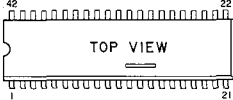
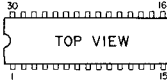
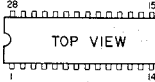
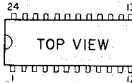
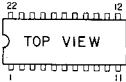
5. Part Configuration and their Symbols

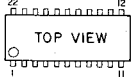
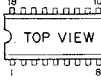
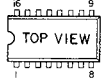

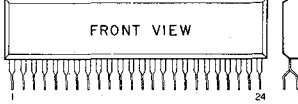
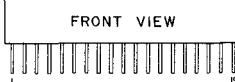
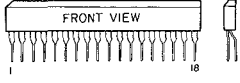
NOTE:

Precautions for Part Replacement

- In the schematic diagram, parts marked \triangle (ex. \triangle F801) are critical part to meet the safety regulations, so always use the parts bearing specified part codes (SN) when replacing them.
- Using the parts other than those specified shall violate the regulations, and may cause troubles such as operation failures, fire, etc.





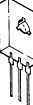
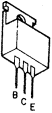

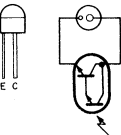
1. IC's

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CX20097, CX20105, CX7989, TA7788AP, TCP4633-9822X, TCP4633-9831X, TC6360P, TD6314P-01, TD6314P-05, TL8702P, TMP4315-0135X, TMP4320-6358Y, TMP4320-6391Y, TMP4320-6445Y, TMP4320-6448Y, TMP4320-6451Y, TMP4320-6453Y, TMP4320-6454Y, TMP4320-6455Y, TMP4320-6457Y, TMP4320-6458Y, TMP47C410-6775, TMP47C410-6783, TMP47C410AN6784	
M50430-085SP, TA7744P, TA8605N	
CX20026	
TA8606N	
AN6366NK, AN6367K, BA7267S	

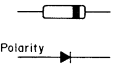
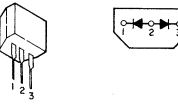
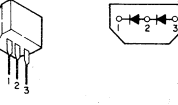
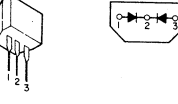
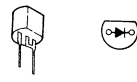
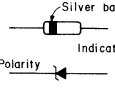
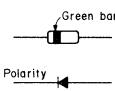
Name	Shape
LA7090	
BA668A, BU2763S, MN6163A, TA7743P	
CXA1011P, LA1231N, SN7442AN, SN7442AN, TA7607AP, TA7742P, TA7745P, TA7772P, TA86079, TC4015PB, TC4028BP, TC4051BP, TC4052BP, TC4053BP, TC4512BP, TC4538BP, TC5067BP, TC74HC42P, TD62504P, TL8610P	
CX7982, TA75339P, TA75902P, TA7741P, TC4001BP, TC4013BP, TC4030BP, TC4066BP	
M51643L	
HK-001A	
BA7025L	



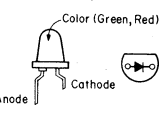
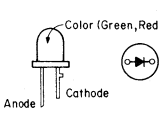
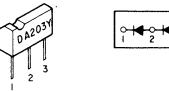
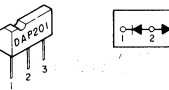

2. Transistors

Name	Shape
TA7328AP	
BA6209	
TA7277AP, TA7277BP, TA7288P	
μPC1474HA, BA6138, TA7325P, TA7337P, TA7339P, TA7348P, TA7351P, TA7365P, TA75393S, TA75458S	
TA7267P	
BA222, TA7140P, TA7302P, TA7347P, TA7361P	
SKT7221	
PST520C, PST520D	
LQT-50X-1	

Name	Shape
2SA562RM-Y, 2SCA1015Y, 2SC1815-Y, 2SC1923-O, 2SC1923, 2SC1959-Y, 2SC2878-A, 2SC2878-B, 2SC388ATH, 2SD970GR	
2SK30ATH-R, 2SK30ATH-Y, 2SK30ATM-GR	
2SA1020-Y, 2SA966-Y, 2SC2236-Y, 2SC2655-Y	
RN1201, RN1202, RN1203, RN1204, RN1205, RN1206, RN2201, RN2202, RN2203, RN2204, RN2205, RN2206, 2SA1048-Y, 2SC2458-BL, 2SC2458-GR, 2SC2458-Y	
2SD549	
2SA968-Y, 2SB435-Y, 2SB834-O, 2SC3678, 2SD1052AFA, 2SD235-GR, 2SD553-Y, 2SD686, 2SD880-Y	
2SD1273-Q, 2SD1405-BL, 2SD1407-O, 2SD1407-Y, 2SD1409, 2SD1415	
PN202S-R, TH, PN202S-RS	

3. Diodes

Name	Shape
1S1553, 1S1554 (TV), 1S1555 (TV), 1S2236	
1SS200	
1SS227	
1SS201	
μPC574J	
05Z10-Y, 05Z11-Y, 05Z12-Y, 05Z12-Z, 05Z15-Z, 05Z2.2-Z, 05Z2.7-Y, 05Z20-Z, 05Z3.6-Z, 05Z3.9-X, 05Z3.9-Y, 05Z5.1-X, 05Z5.1-Z, 05Z5.6-Y, 05Z5.6-Z, 05Z6.2-Y, 05Z6.2-Z, 05Z6.8-Y, 05Z7.5-Y, 05Z8.2-X, 05Z8.2-Y, 05Z9.1-X, 05Z9.1-Y	
1SS176	

Name	Shape
ERC01-02FL	
ERA12-02 (White band) S1S3M (Red band) S2K20C (Red band) S5295G (Yellow band) TVR-4J (Gray band) 1S1832 (Yellow band) 1S1885 (Light Blue) 1S878AFA (Cyan band) 30DF1(FC) (Silver band)	
TLUG163, TLUR163, TLUR164	
TLG113A, TLR113AD	
DA203	
DAP201	
PH302	

4. Solid resistor indication

Resistor	1/8W film	P type film	U type film	Solid	Oxide film	Metal film	Cement	Fuse	Tolerance	±2%	±5%	±10%	±20%
Symbol	None	P	U	S	R	W	W	RF	Symbol	G	J	None	None

● All film type and oxide film type resistors used are ±5%, so the tolerance symbol was not indicated for them.

5. Capacitor indication

Description	Symbol	Capacitance, unit	Capacitance allowance
Electrolytic	±11	μF	Not indicated
Special electrolytic			Indicated
Plastic film	11	μF: indicated with numbers below decimal point	Indicated below ±5% (J), indicated below ±0.5pF, not indicated for others
Ceramic		pF: indicated with numbers over decimal point	
Trimmer	11	pF	Not indicated

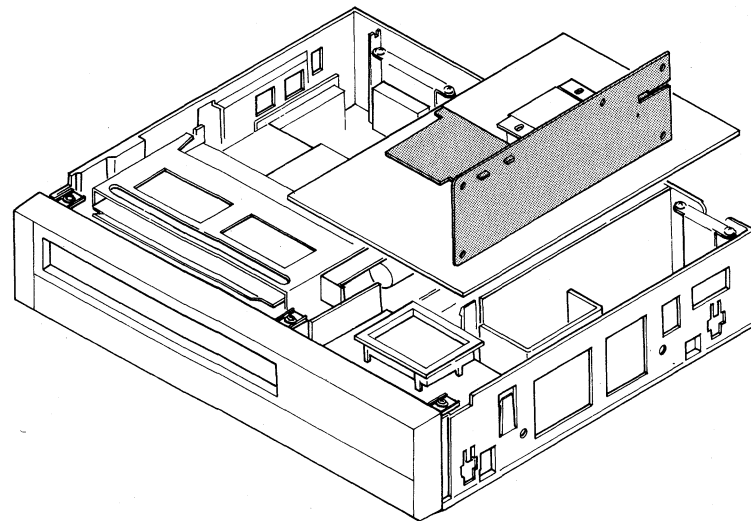
Note: No working voltage is indicated for capacitors rated at 50V except electrolytic capacitors.

6. Waveform and voltage measurement

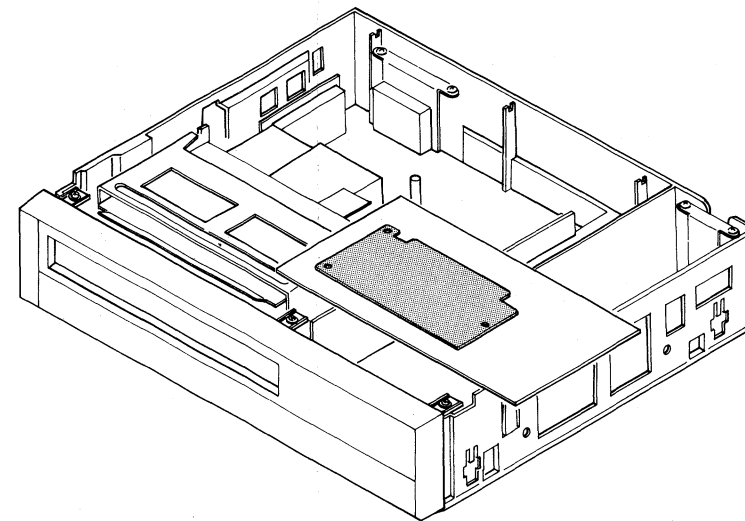
- Measurement of waveform and voltage at each section in the color circuits was conducted with sufficient service color bar signal being received and reproduced in normal conditions.
- Waveforms and voltage values for the remaining circuit were measured with a broadcasting signal normally received, so they may vary slightly according to the programs being received. Use them as a measure for servicing.
- All voltage values except the waveforms are expressed in DC and measured by a digital voltmeter.

6. Standing PC Boards for Servicing

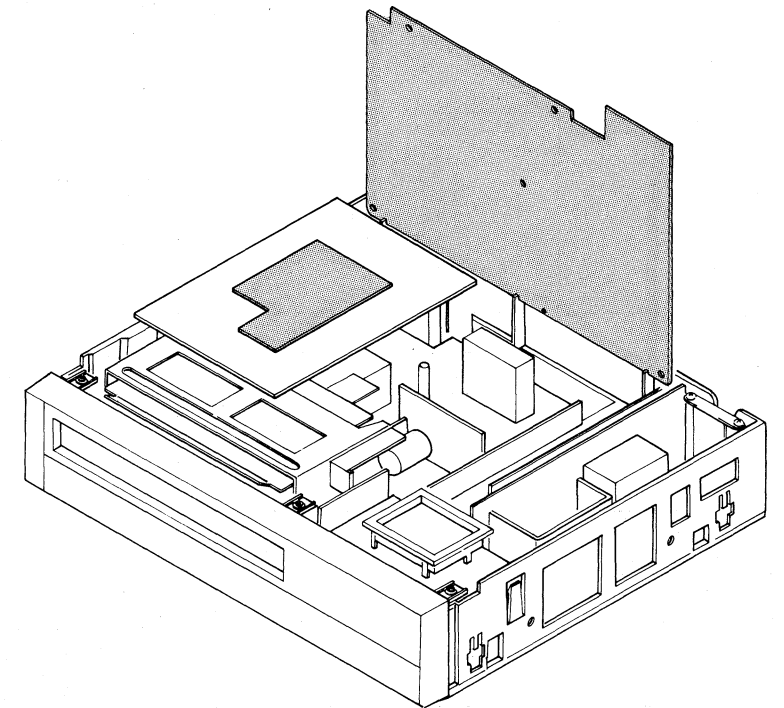
Power Supply PC Board



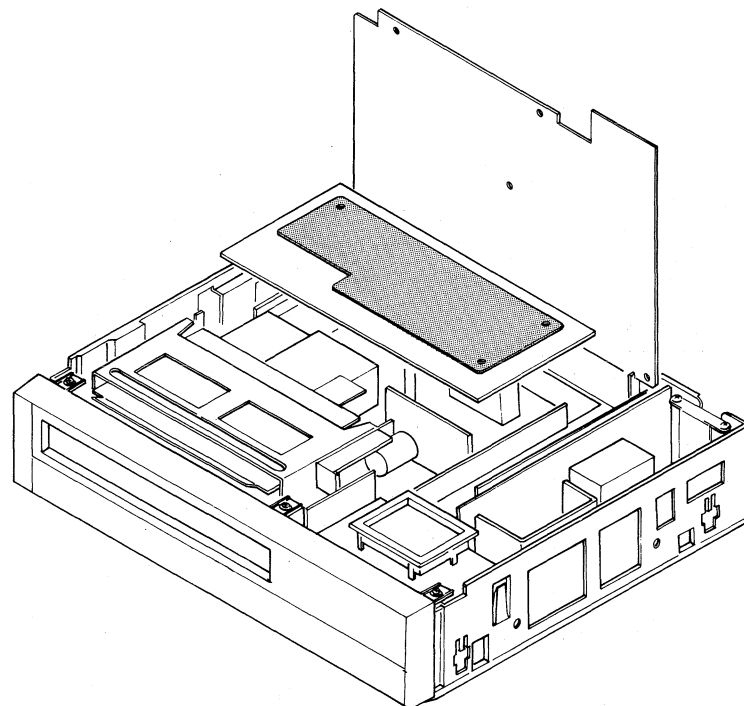
Selector, Timer 2 PC Board



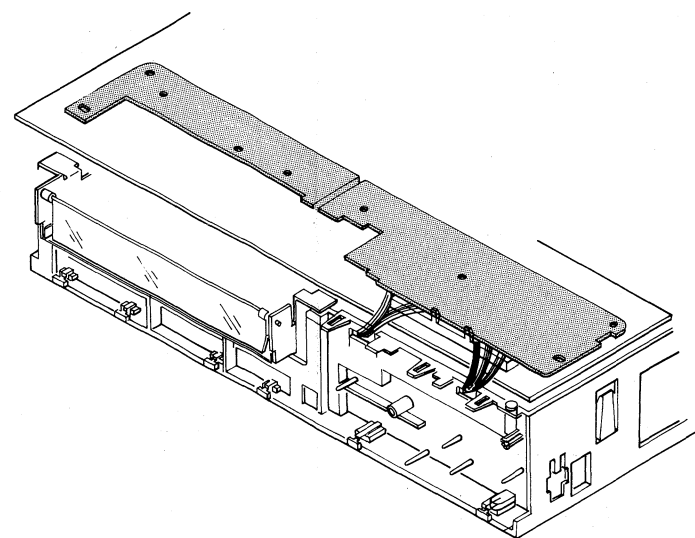
Main (Video, Audio, Servo, Logic), Pre Amp PC Board



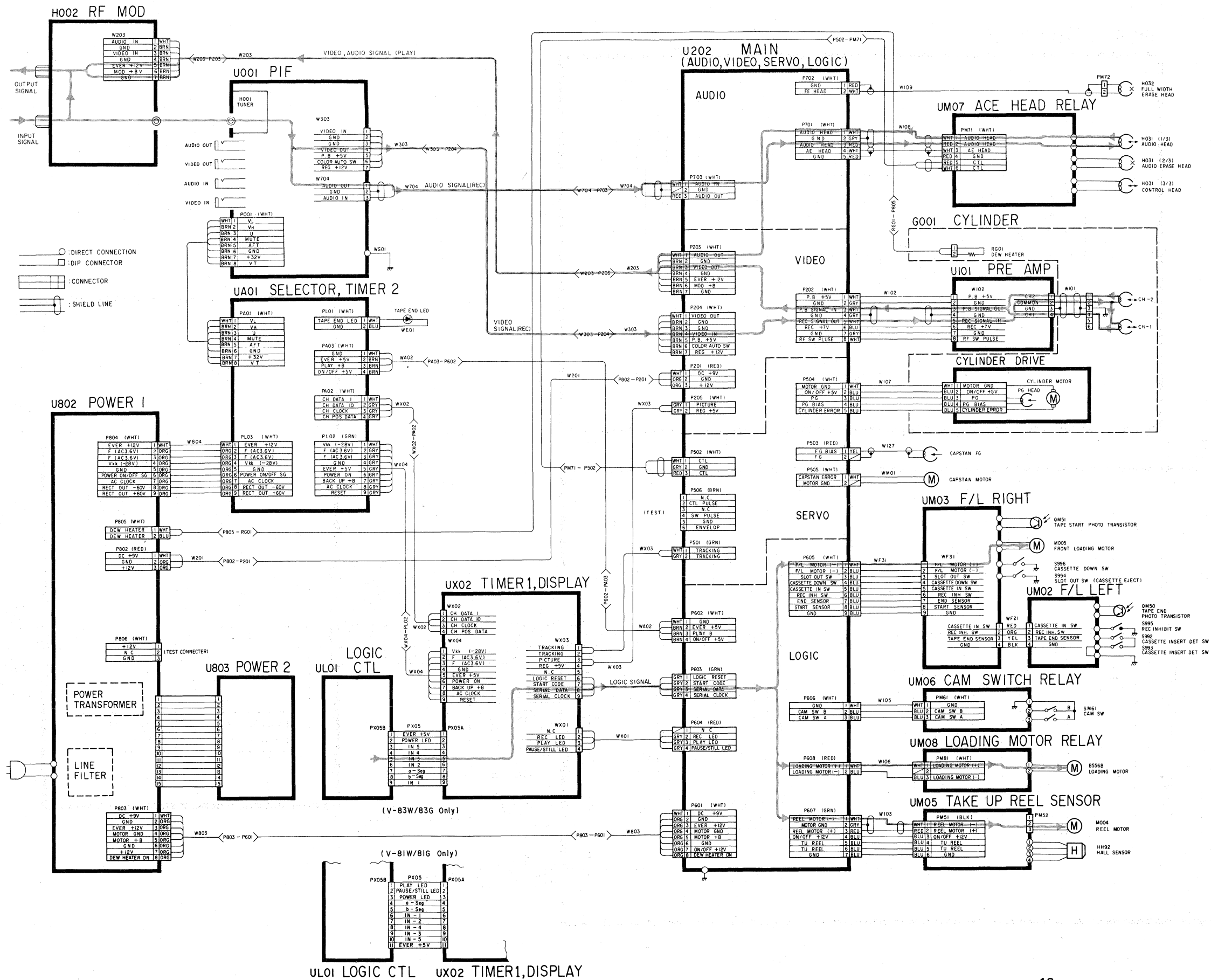
PIF PC Board



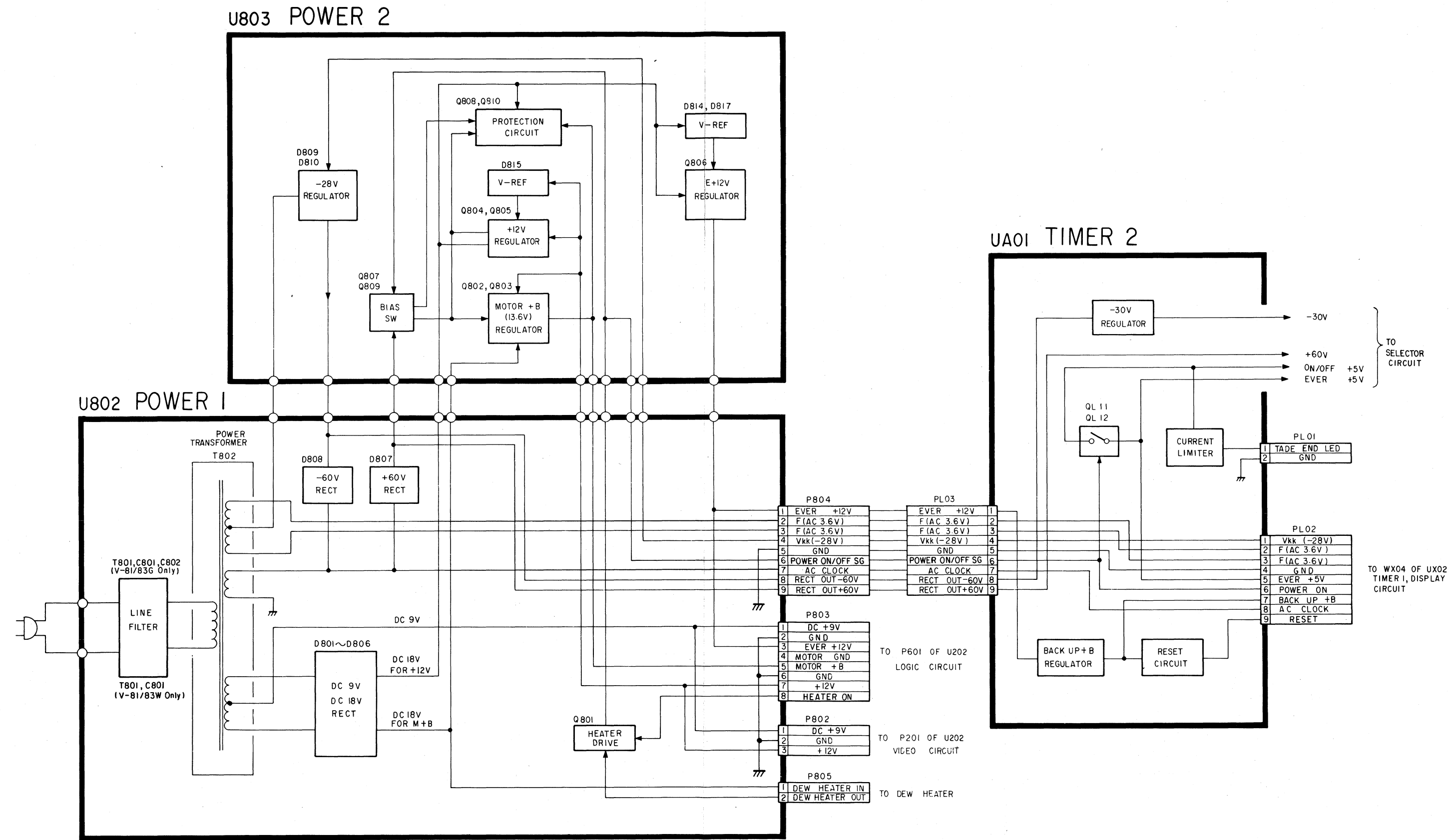
Timer 1, Logic Control Switch PC Board



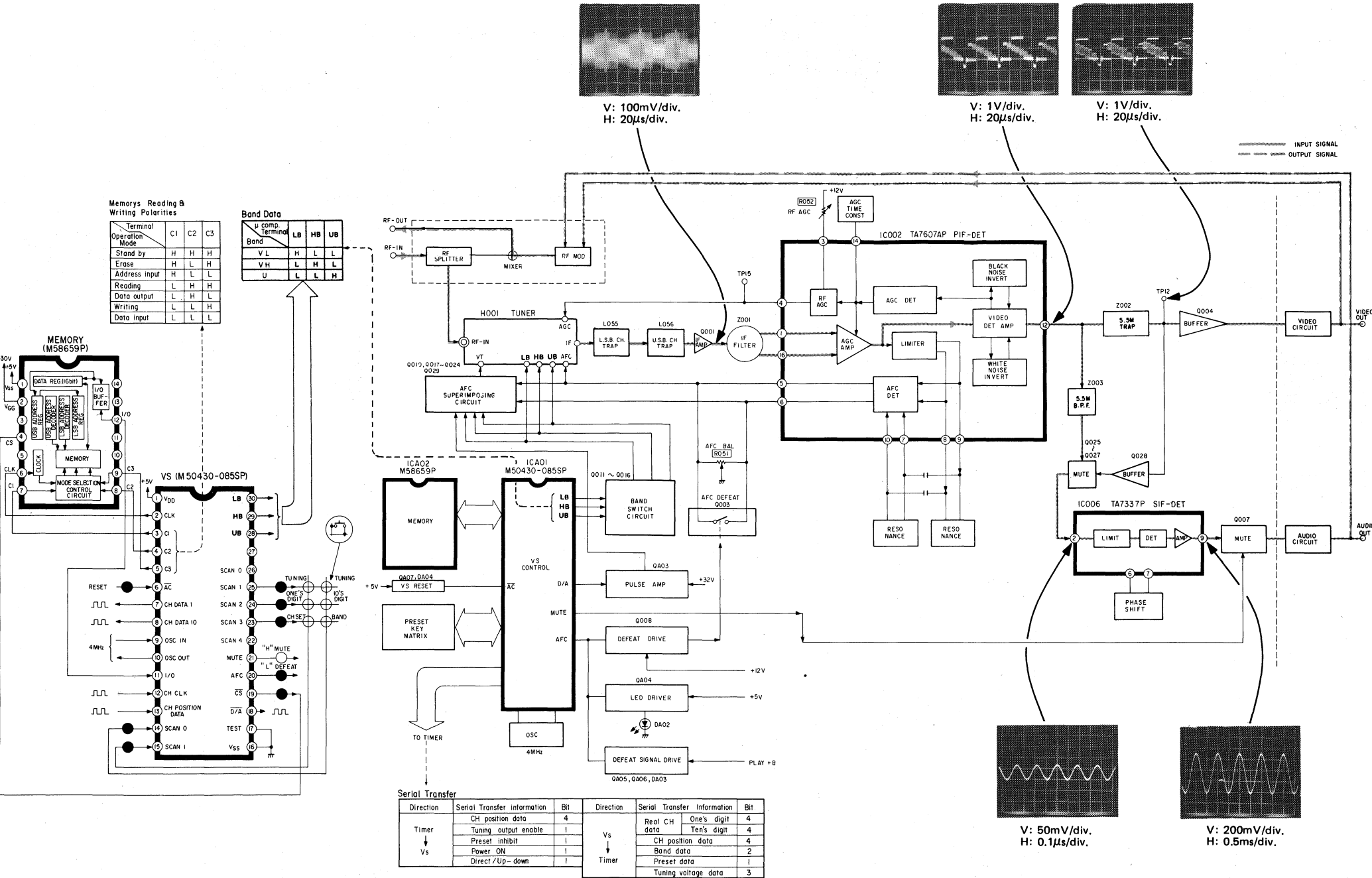
7. Printed Wiring Board and Schematic Diagram



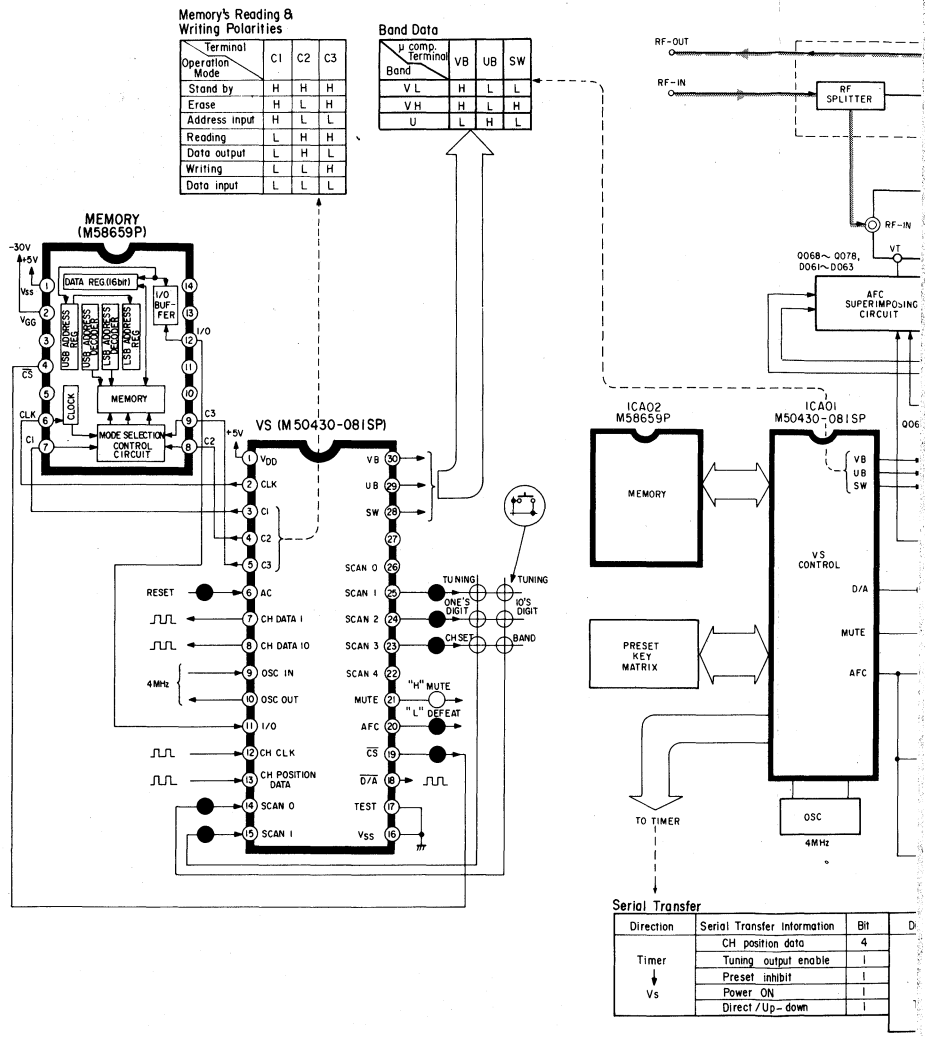
8-1. Power Supply Block Diagram



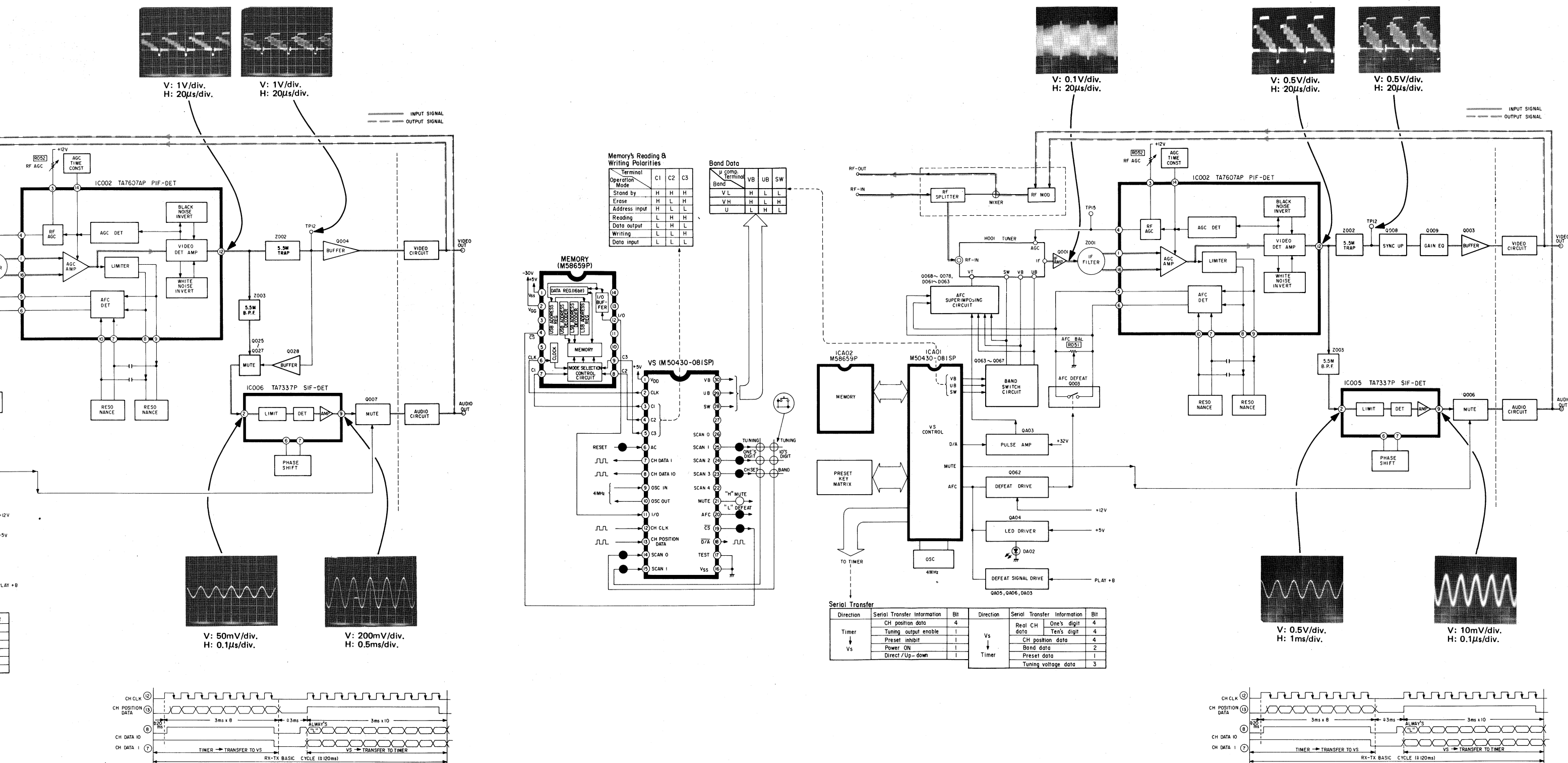
9-1. PIF, Selector Block Diagram (V-81/83G)



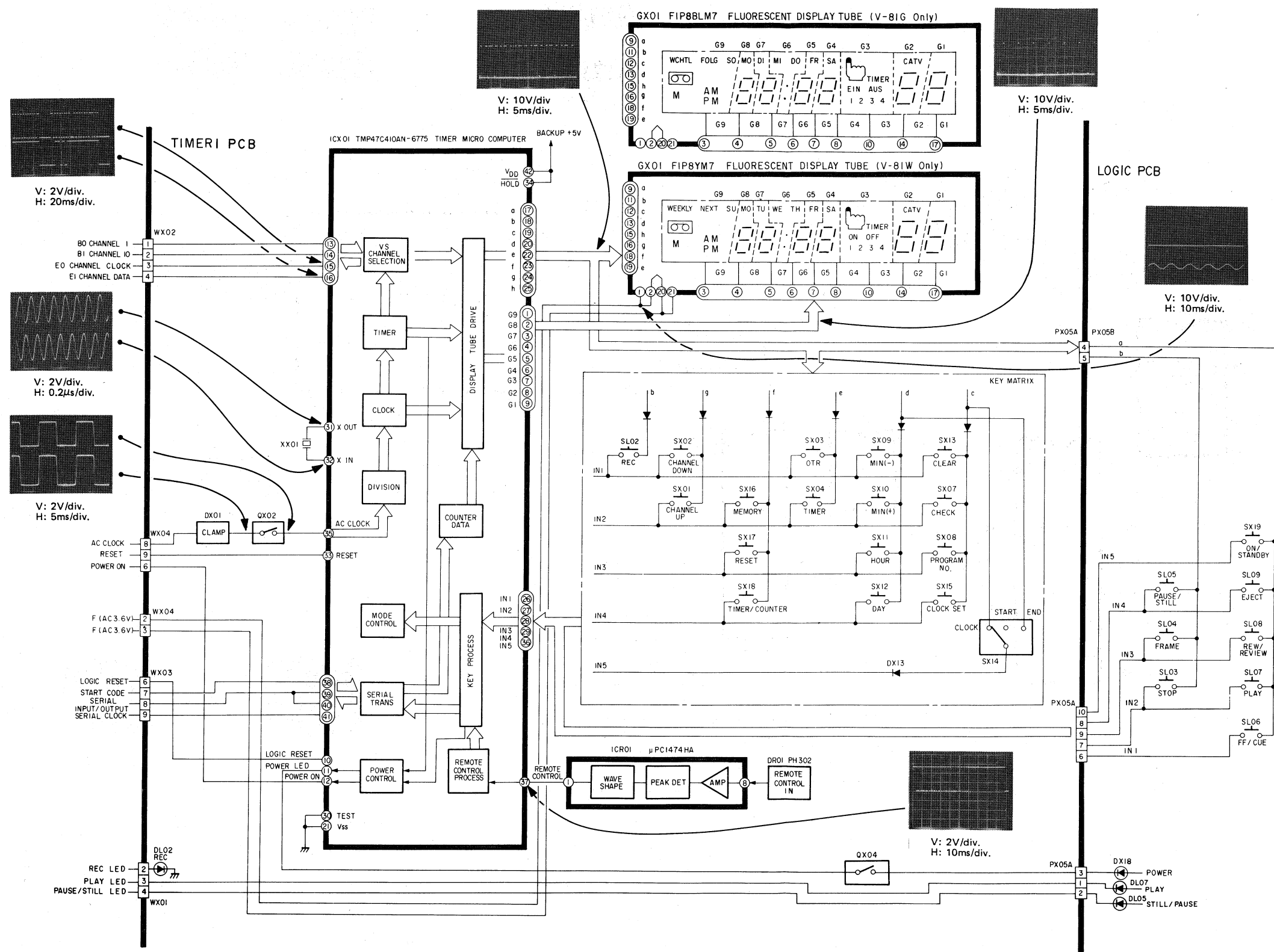
9-2. PIF, Selector Block Diagram (V-81/83W)



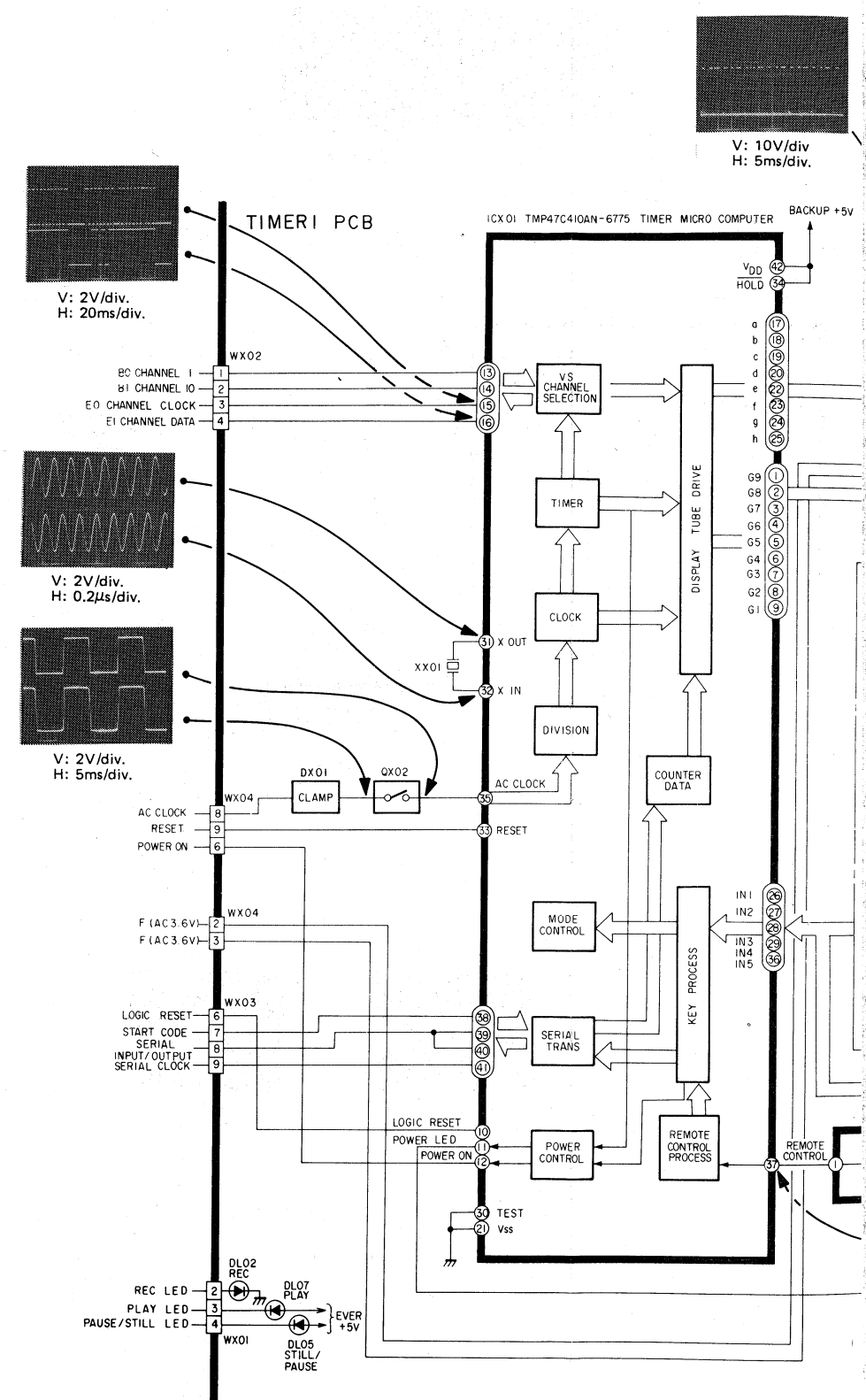
9-2. PIF, Selector Block Diagram (V-81/83W)



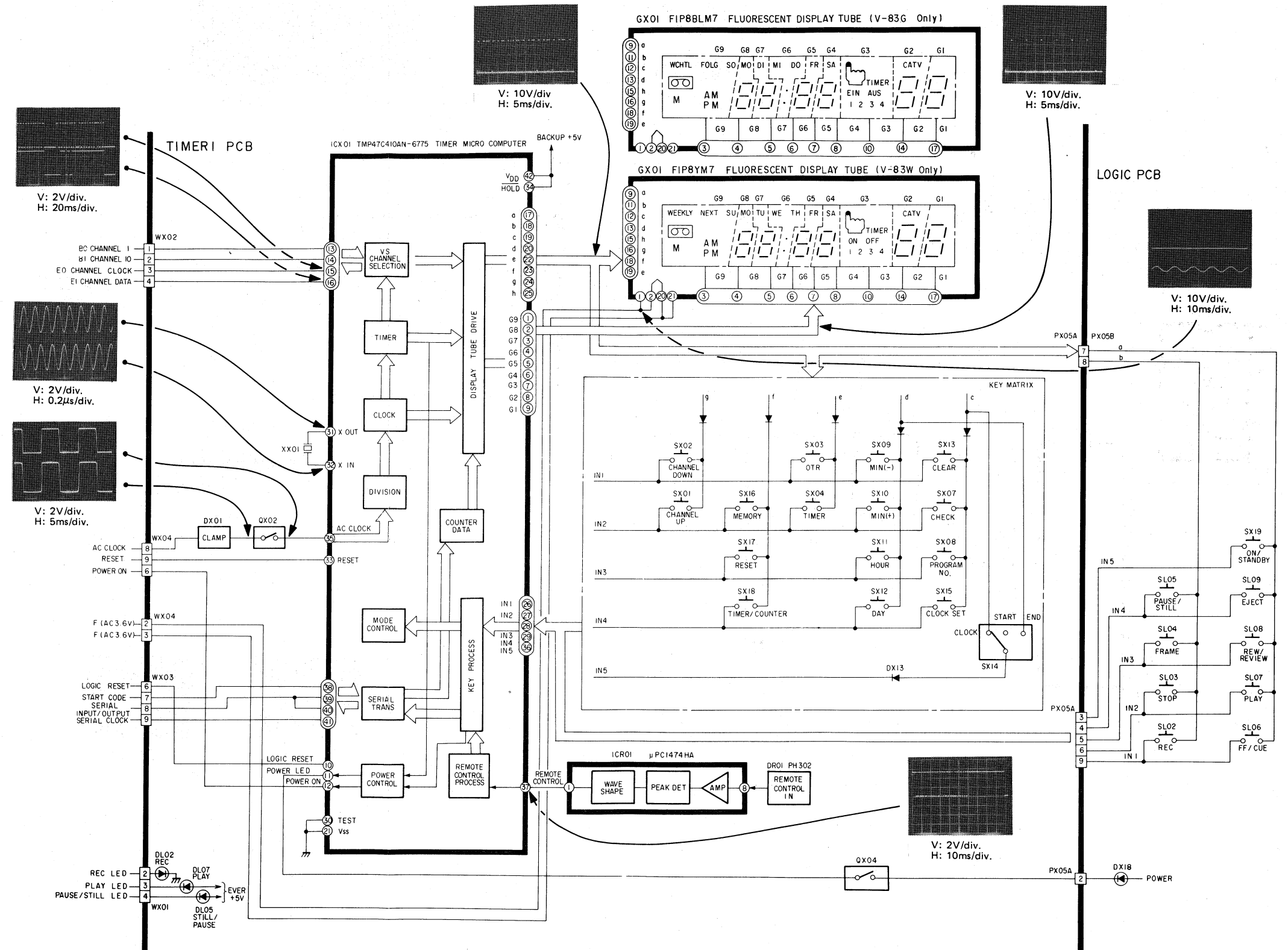
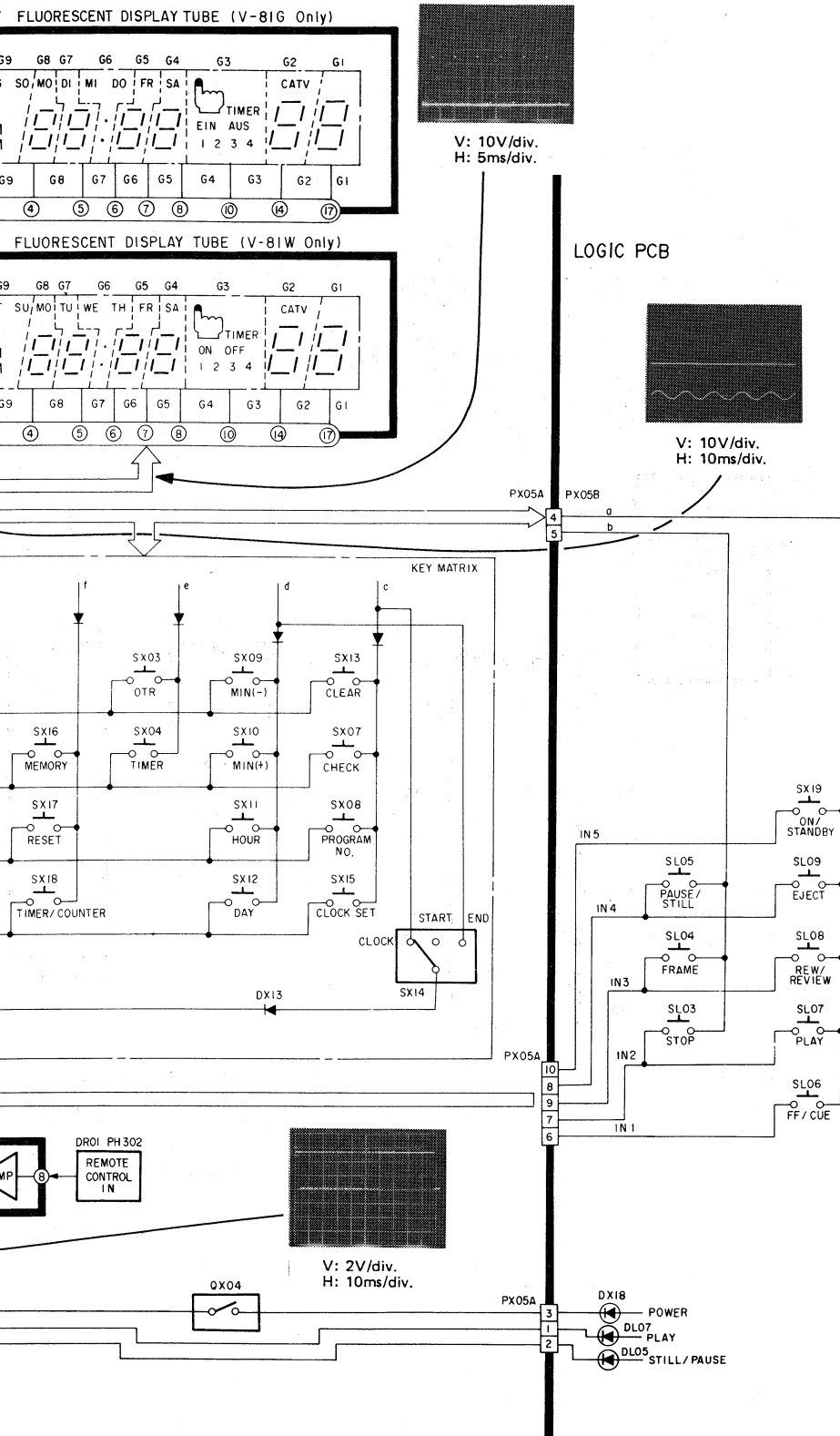
10-1. Timer 1, Display Block Diagram (V-81G/W)

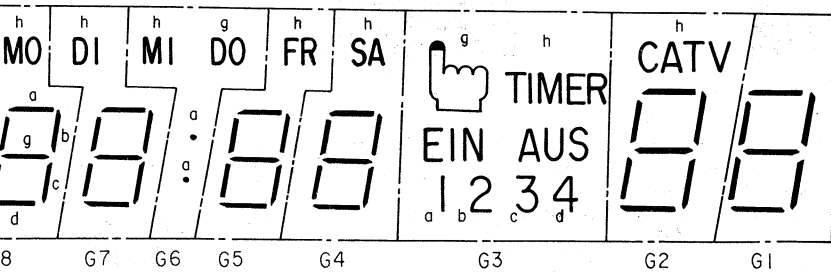


10-2. Timer 1, Display Block Diagram (V-83G/W)

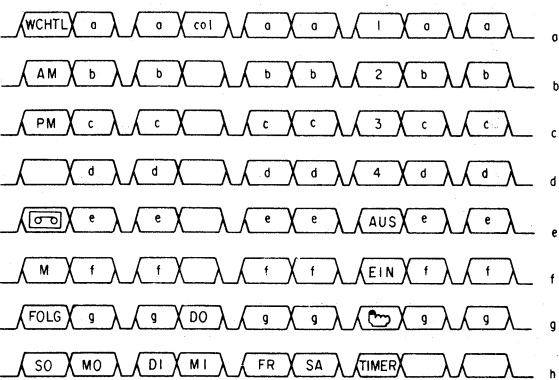
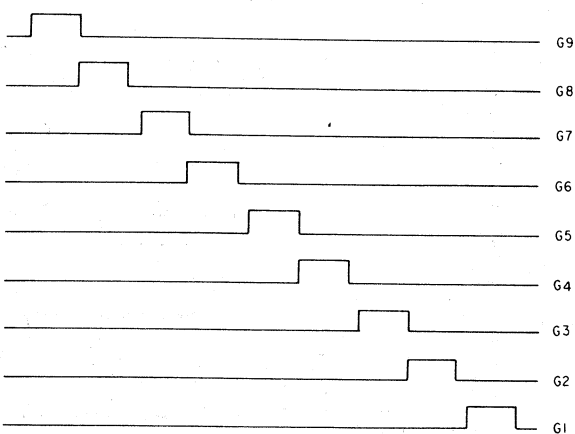


10-2. Timer 1, Display Block Diagram (V-83G/W)



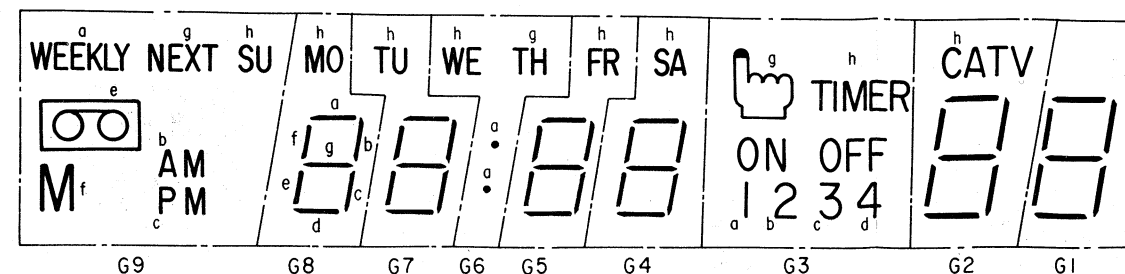


Grid							
	G ₃	G ₄	G ₅	G ₆	G ₇	G ₈	G ₉
1	1	a	a	:	a	a	WCHTL
2	2	b	b		b	b	
3	3	c	c		c	c	
4	4	d	d		d	d	
AUS	e	e			e	e	
EIN	f	f			f	f	M
DO	g	g			g	g	FOLG
TIMER	SA	FR	MI	DI	MO	SO	



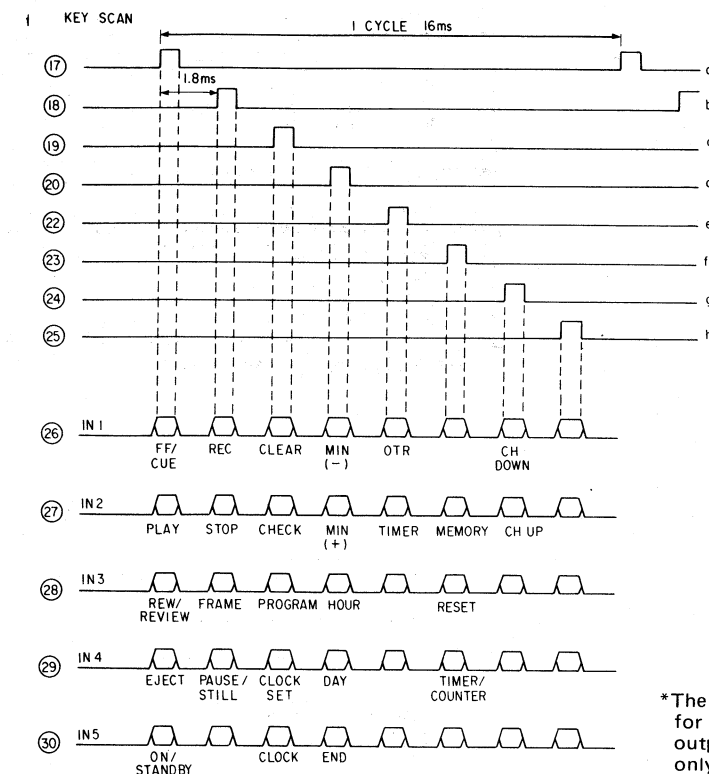
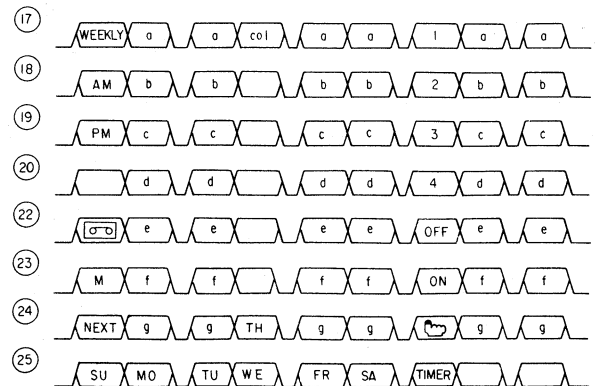
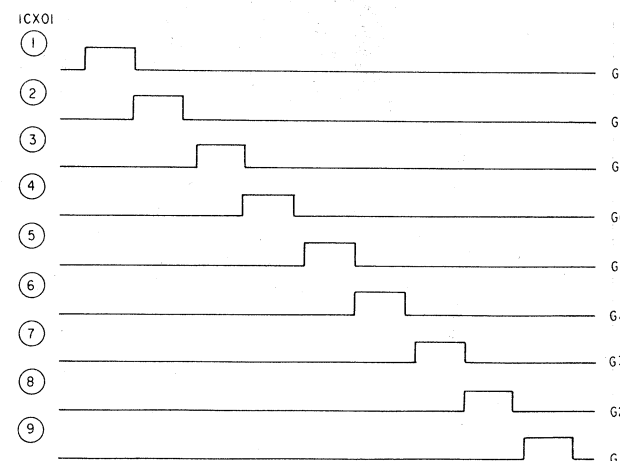
* The time chart shows outputs for the display tube only and outputs for the key scanning are omitted.

V-81/83W GX01 FIP8YM7

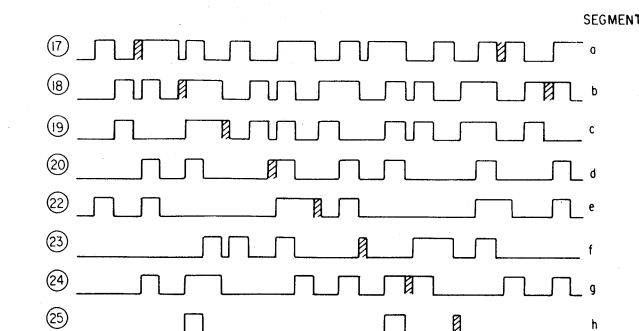
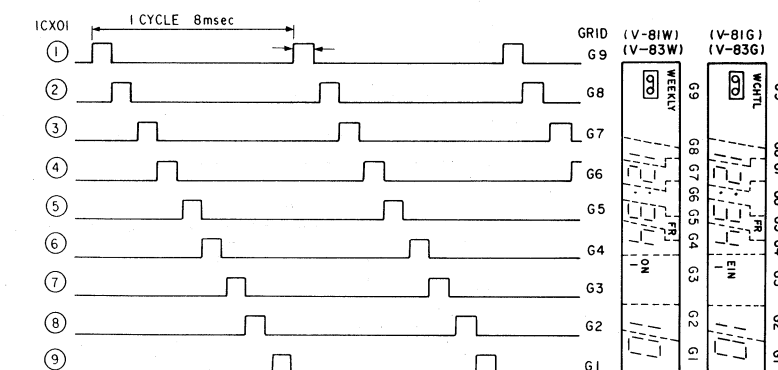


Display Pattern

Seg	Grid								
	G ₁	G ₂	G ₃	G ₄	G ₅	G ₆	G ₇	G ₈	G ₉
a	a	a	1	a	a	:	a	a	WEEKLY
b	b	b	2	b	b		b	b	
c	c	c	3	c	c		c	c	
d	d	d	4	d	d		d	d	
e	e	e	OFF	e	e		e	e	
f	f	f	ON	f	f		f	f	M
g	g	g	TH	g	g	TH	g	g	NEXT
h			TIMER	SA	FR	WE	TU	MO	SU



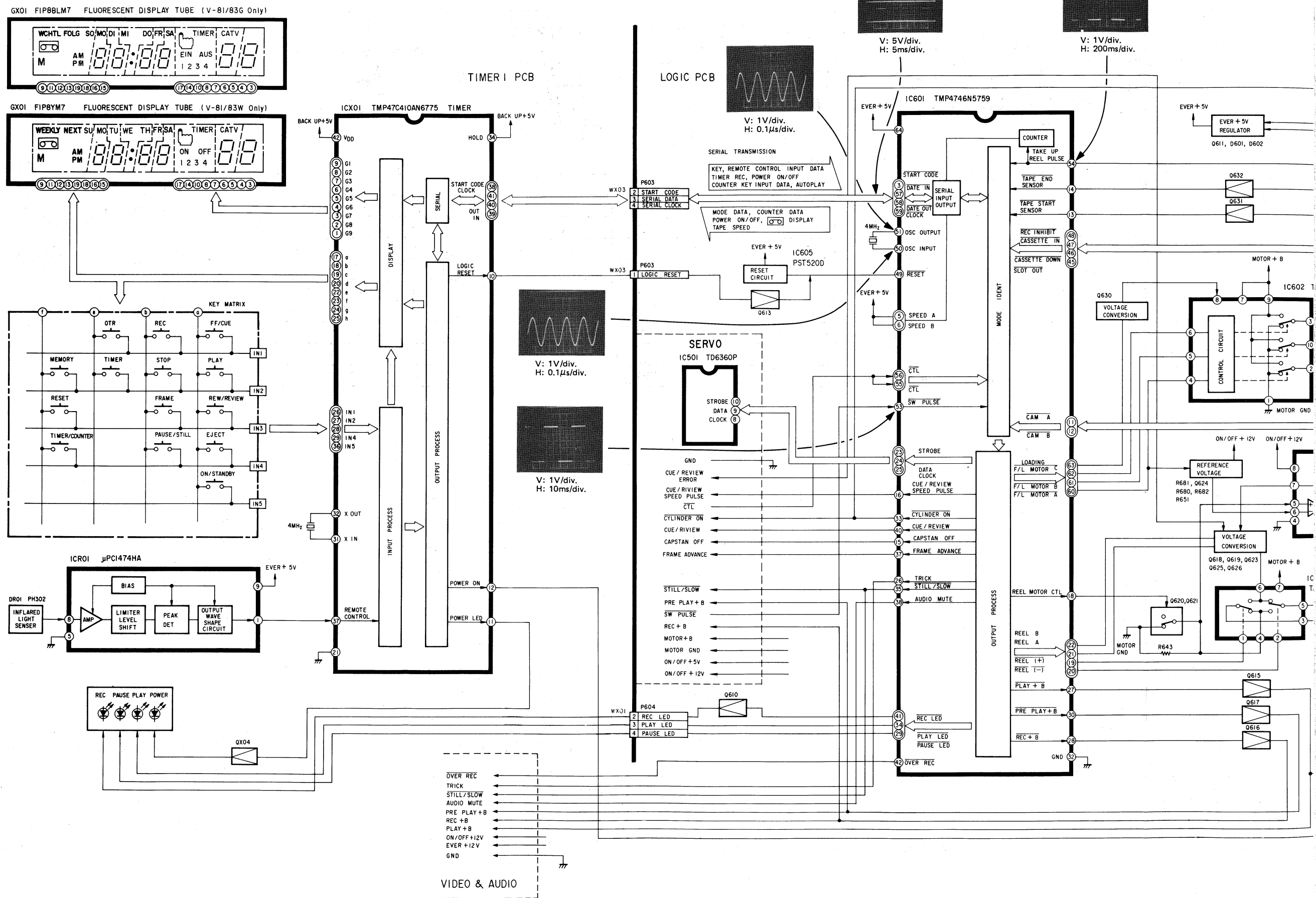
*The time chart shows outputs for the key scanning only and outputs for the display tube only are omitted.

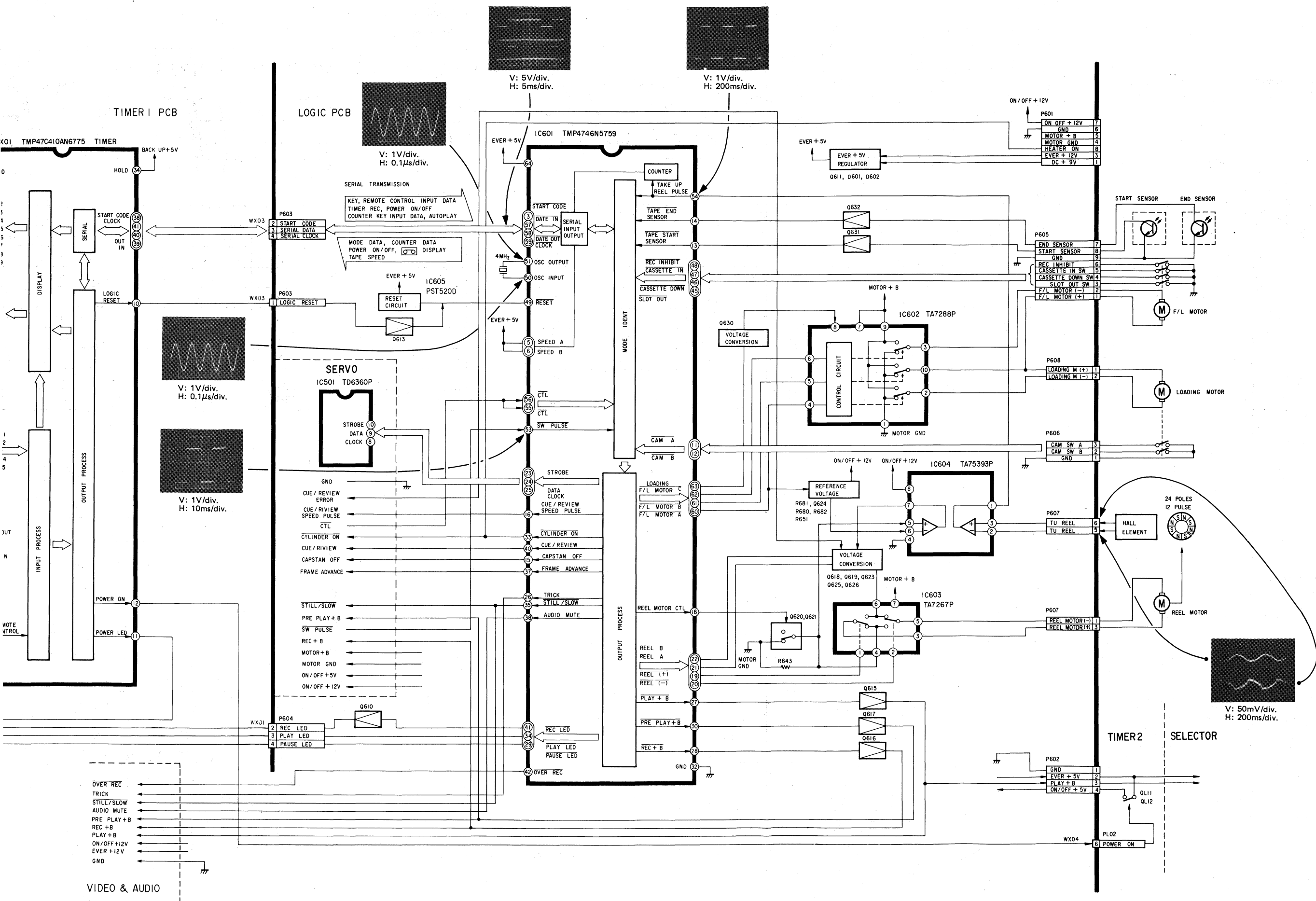


Display tube timing chart (Ex. 12:34 10 ch)

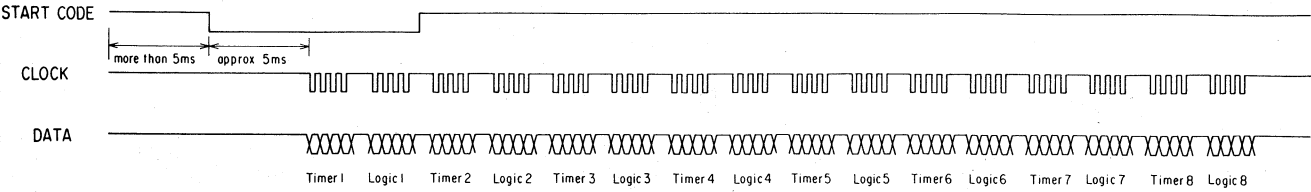
...Stands for key scanning and is developed at every two grid outputs.

11-1. Logic Block Diagram





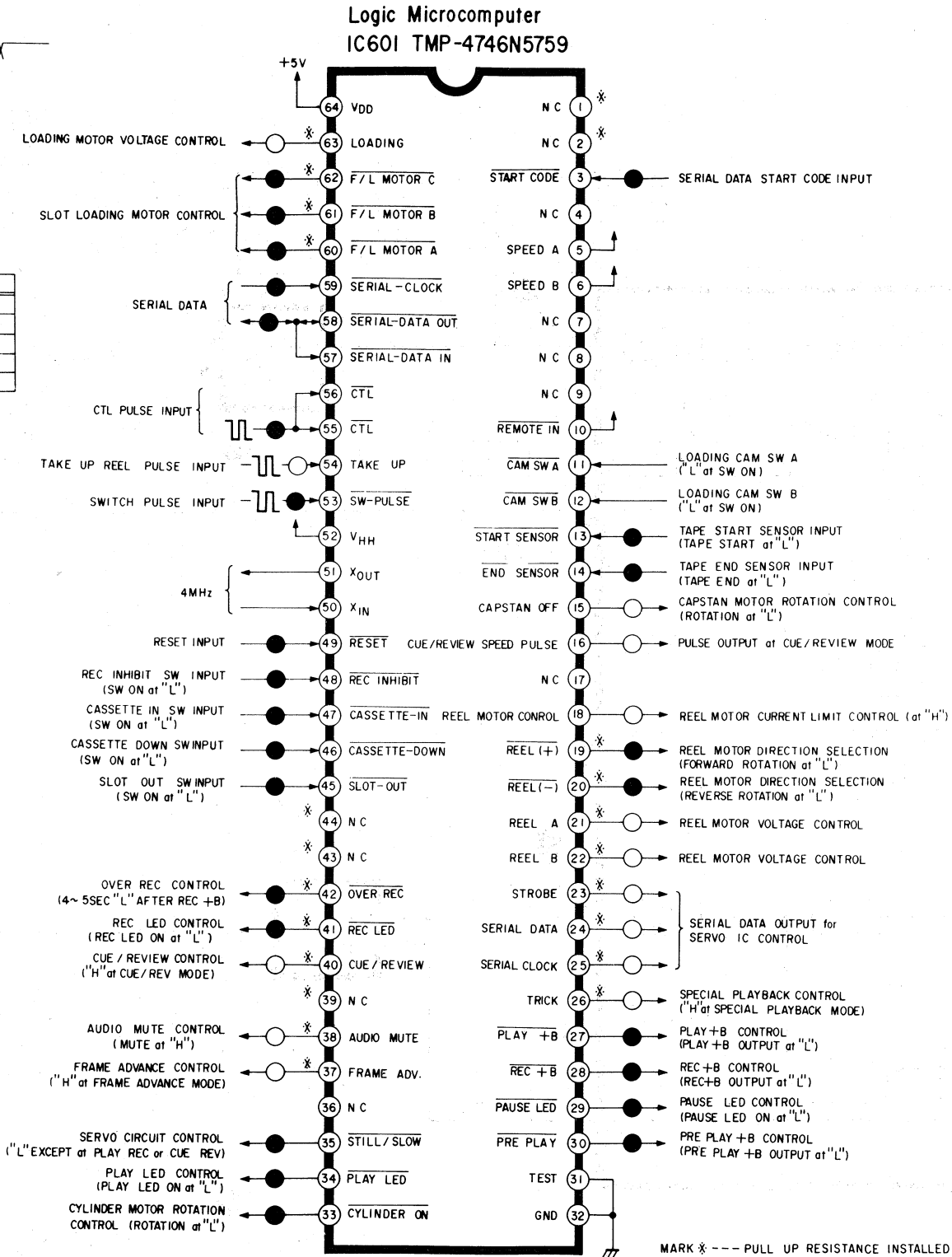
Serial Transmission



Period: 30ms		
Direction	Data	
Timer → Logic	Power ON/OFF	Timer 2
	Key & remote control input	Timer 2·3
	Timer recording	Timer 2·3
	Auto PLAY mode	Timer 1
	Counter memory mode	Timer 1
	Counter reset	Timer 2·3
Logic → Timer	Counter (back-up)	Timer 4 ~ 7
	Mode data	Logic 2·3
	Power ON/OFF	Logic 2
	Counter	Logic 4 ~ 7
	TAPE speed (PLAY)	Logic 1
	display	Logic 1
	REC INHIBIT	Logic 1

MODE	A	B	C
STOP	H	H	H
SLOT IN	L	H	L
SLOT OUT	L	H	H
LOADING	H	L	L
UNLOADING	H	L	H

Microcomputer's Pin Terminal Functions



IC601 (TMP-4746N5759)

Terminal	Mode	Active
15	CAP OFF	H
16	SPEED PULSE	-
18	RM CL	H
19	REEL (+)	L
20	REEL (-)	L
21	REEL A	H
22	REEL B	H
26	TRICK	H
27	PLAY +B	L
28	REC +B	L
29	PAUSE LED	L
30	PRE PLAY +B	L
33	DRUM ON	L
34	PLAY LED	L
35	STILL SLOW	L
37	Frame feeding	H
38	AUDIO MUTE	H
40	Q/R	H
41	REC LED	L
42	OVER REC	L
60	FLM A	-
61	FLM B	-
62	FLM C	-
63	Loading	H

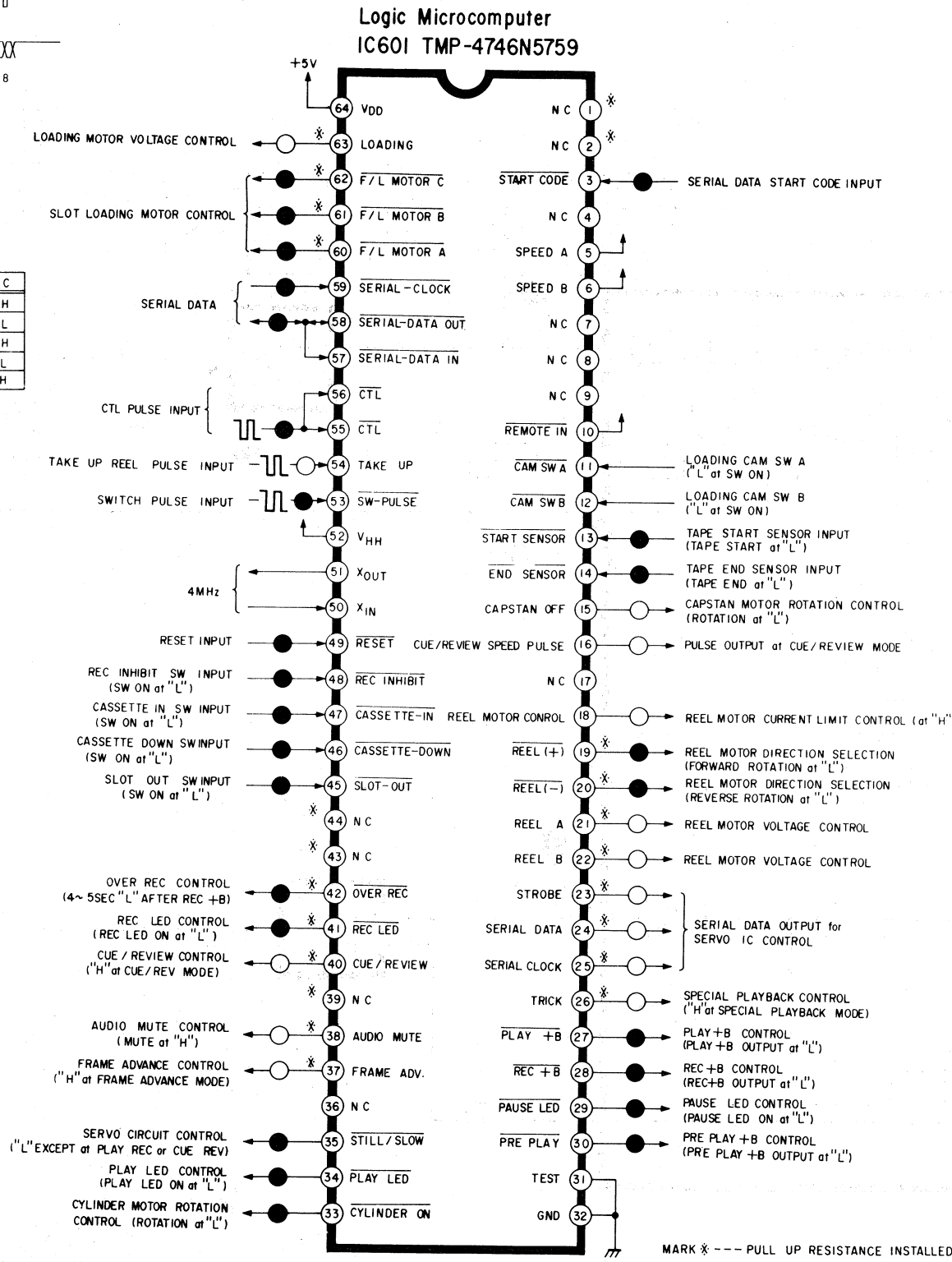
Logic Mode Shift Table

MODE	SLOT IN	SLOT OUT	STOP	TAPE START	TAPE END
KEY INPUT					
STOP	○	X	-	Start FF	-
FF	△	X	○	○	AUTO REW
REW	△	X	○	STOP (Short FF)	○
PLAY	△	X	○	○ (Short FF)	AUTO REW
PAUSE/STILL	X	X	X	X	X
Frame Matching	X	X	X	X	X
REC	△	△	○	○ (Short FF)	AUTO REW
Timer REC	X	X	○	○ (Short FF)	Power OFF
EJECT	○	-	○	○	○
TAPE END	-	-	-	EJECT	-
Reel NG Take Up	-	X	X	-	-
POWER	After Motor OFF Power OFF	After Motor OFF Power OFF	Power OFF	Power OFF	Power OFF
COUNTER RESET	○	○	○	○	○
COUNTER MEMORY	○	○	○	○	○
Cylinder Rotation NG	-	-	-	-	-

Note: * When pushed continuously, unit enter SLOW mode.
** Mode changes when PLAY +B is only ON.
△ Same as normal mode shift.
○ Directly shifted to the specified mode.
X Not shifted.
Operations except EJECT can be controlled by the remote control.

Microcomputer's Pin Terminal Functions

XXXXX XXXXX
Timer B Logic 8



IC601 (TMP-4746N5759) Output Signal Polarities

Mecha. Position (Cam Position)	MODE	Active	Slot-In	Slot-Out	Load-ing	Un-load-ing	FF	REW	STOP	CUE	RE-VIEW	PLAY	STILL	Frame feeding	REC	REC PAUSE	Reverse	Note
15	CAP OFF	H	H	H	H	H	H	H	H	H	H	L	H	L	L	H	H	
16	SPEED PULSE	-	L	L	L	L	L	L	L	L	L	L	L	L	L	L	L	Controlled by every other falling edge of CTL pulses.
18	RM CL	H	L	L	L	H	L	L	L	L	L	H	L	L	H	L	L	
19	REEL (+)	L	H	H	L	H	L	H	H	L	H	L	L	L	L	H	H	
20	REEL (-)	L	H	H	L	H	L	H	H	L	H	L	L	L	L	H	L	
21	REEL A	H	L	L	L*	L*	L*	L*	L*	L*	L*	L*	L*	L*	L*	L*	L*	*PWM at starting
22	REEL B	H	L	L	L	L	L	L	L	L	L	L	L	L	L	L	L	
25	TRICK	H	L	L	L	L	L	L	L	L	L	L	L	L	L	L	L	
27	PLAY +B	L	H	H	H	H	H	H	H	L	L	L	L	L	L	H	H	
28	REC +B	L	H	H	H	H	H	H	H	L	L	L	L	L	L	L	L	
29	PAUSE LED	L	H	H	H	H	H	H	H	L	L	L	L	L	L	L	L	Δ: Depending on mode
30	Pre PLAY +B	L	H	H	H	H	H	H	H	L	L	L	L	L	L	L	L	
33	DRUM ON	L	H	H	L	L	L	L	L	L	L	L	L	L	L	L	L	
34	PLAY LED	L	H	H	H	H	H	H	H	L	L	L	L	L	L	L	L	Δ: Depending on mode 1Hz L/H at AUTO PLAY
35	STILL SLOW	L	L	L	L	L	L	L	L	L	L	L	L	L	L	L	L	
37	Frame feeding	H	L	L	L	L	L	L	L	L	L	L	L	L	L	L	L	
38	AUDIO MUTE	H	L	L	L	L	L	L	L	L	L	L	L	L	L	L	L	
40	O/R	H	L	L	L	L	L	L	L	L	L	L	L	L	L	L	L	
41	REC LED	L	H	H	H	H	H	H	H	L	L	L	L	L	L	L	L	Δ: Depending on mode
42	OVER REC	L	H	H	H	H	H	H	H	L	L	L	L	L	L	L	L	t = 4 ~ 5 sec.
60	FLM A	-	L	L	L	L	L	L	L	L	L	L	L	L	L	L	L	
61	FLM B	-	L	L	L	L	L	L	L	L	L	L	L	L	L	L	L	
62	FLM C	-	L	L	L	L	L	L	L	L	L	L	L	L	L	L	L	
63	Loading	H	L	L	L	L	L	L	L	L	L	L	L	L	L	L	L	

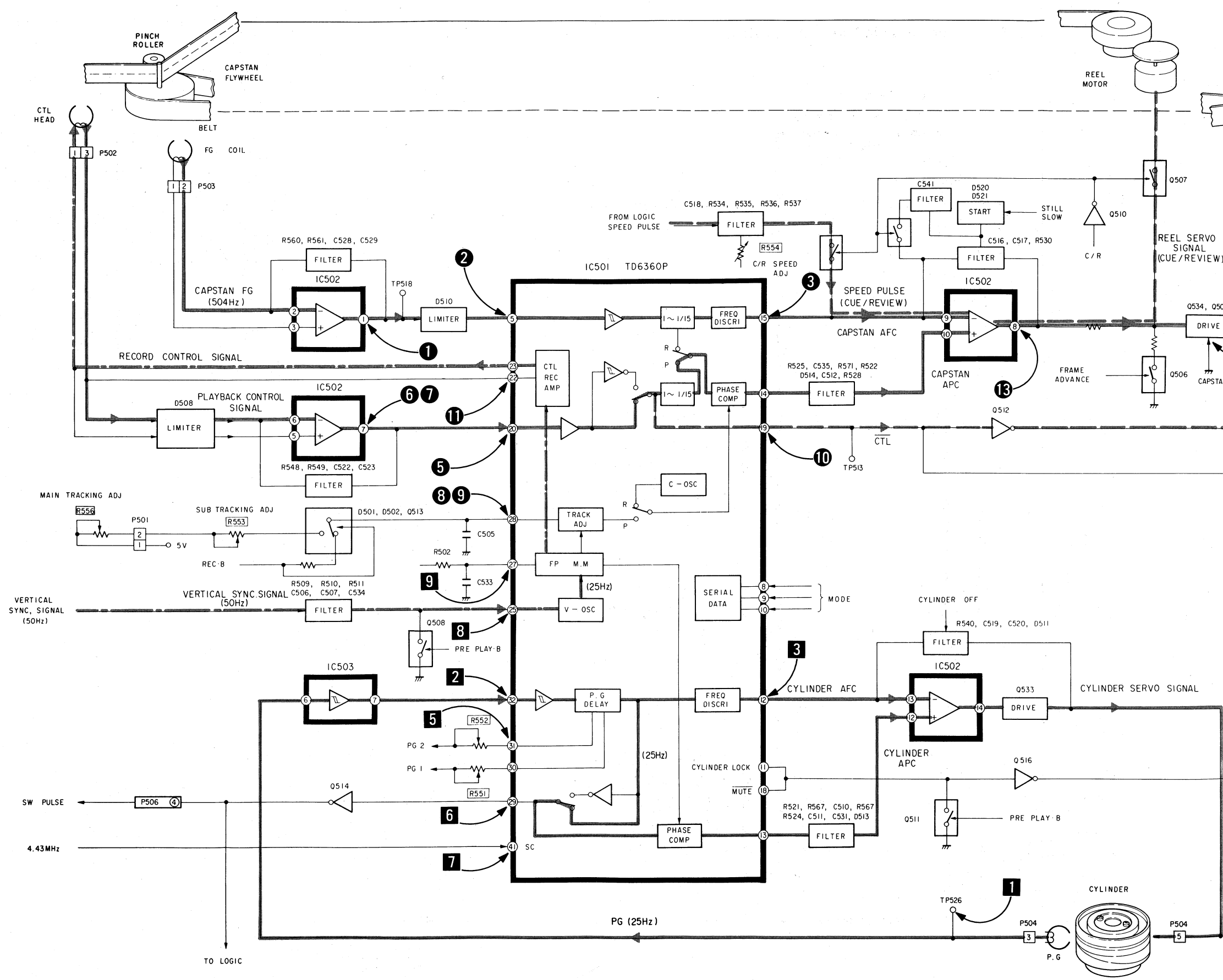
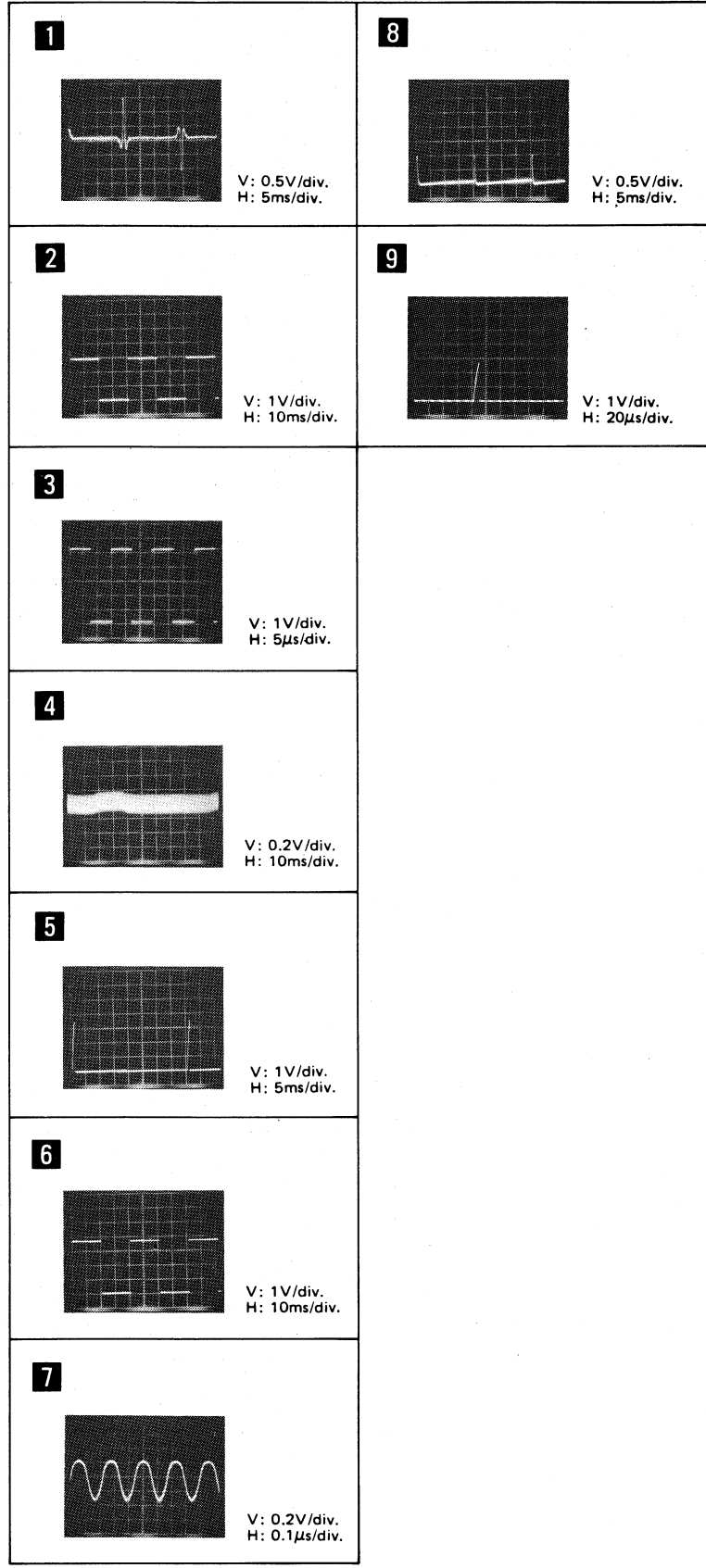
Logic Mode Shift Table

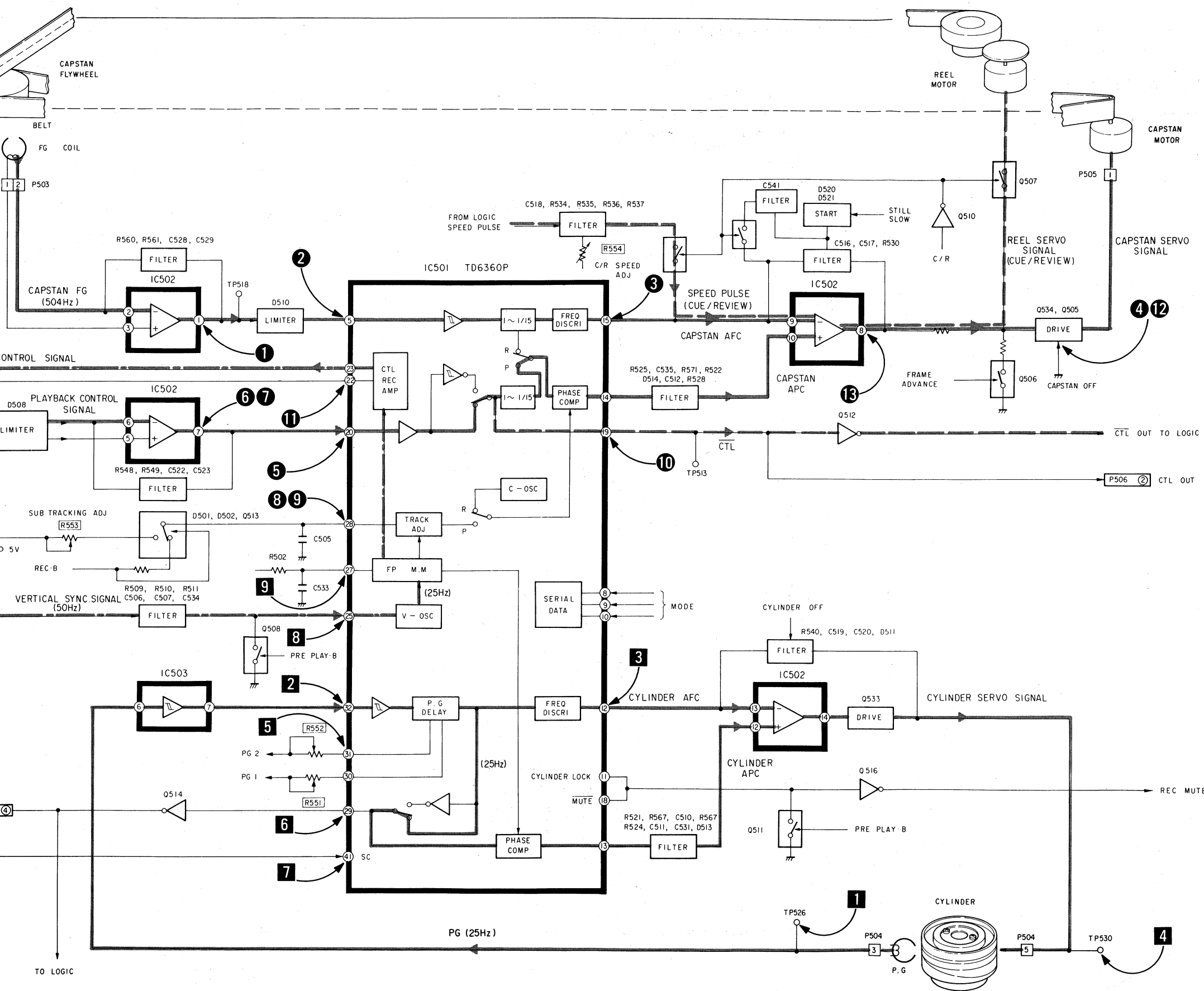
MODE	SLOT IN	SLOT OUT	STOP	TAPE START	TAPE END	FF	REW	CUE	REVIEW	PLAY	STILL	Frame Matching	REC	Timer REC	REC PAUSE	RE-VERSE	LOAD-ING	UNLOAD-ING	Power OFF
STOP	○	×	-	Start FF	-	○	○	○	○	○	○	○	○ (Un-loading)	×	○ (No Un-loading)	○	○	Δ	×
FF	Δ	×	○	○	AUTO REW	-	○	×	CUE	CUE**	CUE**	-	×	×	×	Δ	×	Δ	×
REW	Δ	×	○	STOP (Short FF)	○	○	-	RE-VIEW	×	RE-VIEW**	RE-VIEW**	-	×	×	×	Δ	Δ	Δ	×
PLAY	Δ	×	○	○ (Short FF)	AUTO REW	○	○	○	○	-	×	-	×	×	×	Δ	Δ	Δ	×
PAUSE/STILL	×	×	×	×	×	×	×	×	×	STILL	PLAY	-	REC PAUSE	×	REC	Δ	Δ	Δ	×
Frame Matching	×	×	×	×	×	×	×	×	×	○*	-	-	×	×	×	Δ	Δ	Δ	×
REC	Δ	Δ	○	○ (Short FF)	AUTO REW	×	×	×	×	×	REC PAUSE	-	-	×	×	Δ	Δ	Δ	×
Timer REC	×	×	○	○ (Short FF)	Power OFF	○	○	○	○	○	○	-	○	-	○	○	○	Δ	×
EJECT	○	-	○	○	○	○	○	○	○	○	○	-	×	×	×	Δ	Δ	Δ	×
TAPE END	-	-	-	EJECT	-	AUTO REW	×	AUTO REW	×	AUTO REW	AUTO REW	AUTO REW	AUTO REW	POWER OFF	AUTO REW	AUTO REW	Unloading	Δ	-
TAPE START	-	-	Short FF	-	EJECT	Short FF	STOP (Short FF)	×	STOP (Short FF)	×	×	×	×	×	×	Reverse OFF	Short FF	Short FF	
Reel NG Take Up	-	×	×	-	-	STOP	STOP	STOP	STOP	STOP	×	STOP	STOP	POWER OFF	×	×	×	×	-
POWER	After Motor OFF Power OFF	After Motor OFF Power OFF	Power OFF	Power OFF	Power OFF	After STOP Power OFF	After STOP Power OFF	After STOP Power OFF	After STOP Power OFF	After STOP Power OFF	After STOP Power OFF	After STOP Power OFF	After STOP Power OFF	STOP	After STOP Power OFF	After STOP Power OFF	After Motor OFF Power OFF	After Motor OFF Power OFF	Power ON
COUNTER RESET	○	○	○	○	○	○	○	○	○	○	○	×	○	○	○	○	○	○	×
COUNTER MEMORY	○	○	○	○	○	○	○	○	○	○	○	×	○	○	○	○	○	○	×
Cylinder Rotation NG	-	-	-	-	-	×	×	STOP	STOP	STOP	STOP	STOP	STOP	Power OFF	STOP	STOP	STOP	STOP	

Note: * When pushed continuously, unit enter SLOW mode.
** Mode changes when PLAY +B is only ON.
Δ Same as normal mode shift.
○ Directly shifted to the specified mode.
× Not shifted.
Operations except EJECT can be controlled by the remote controller VC-73.

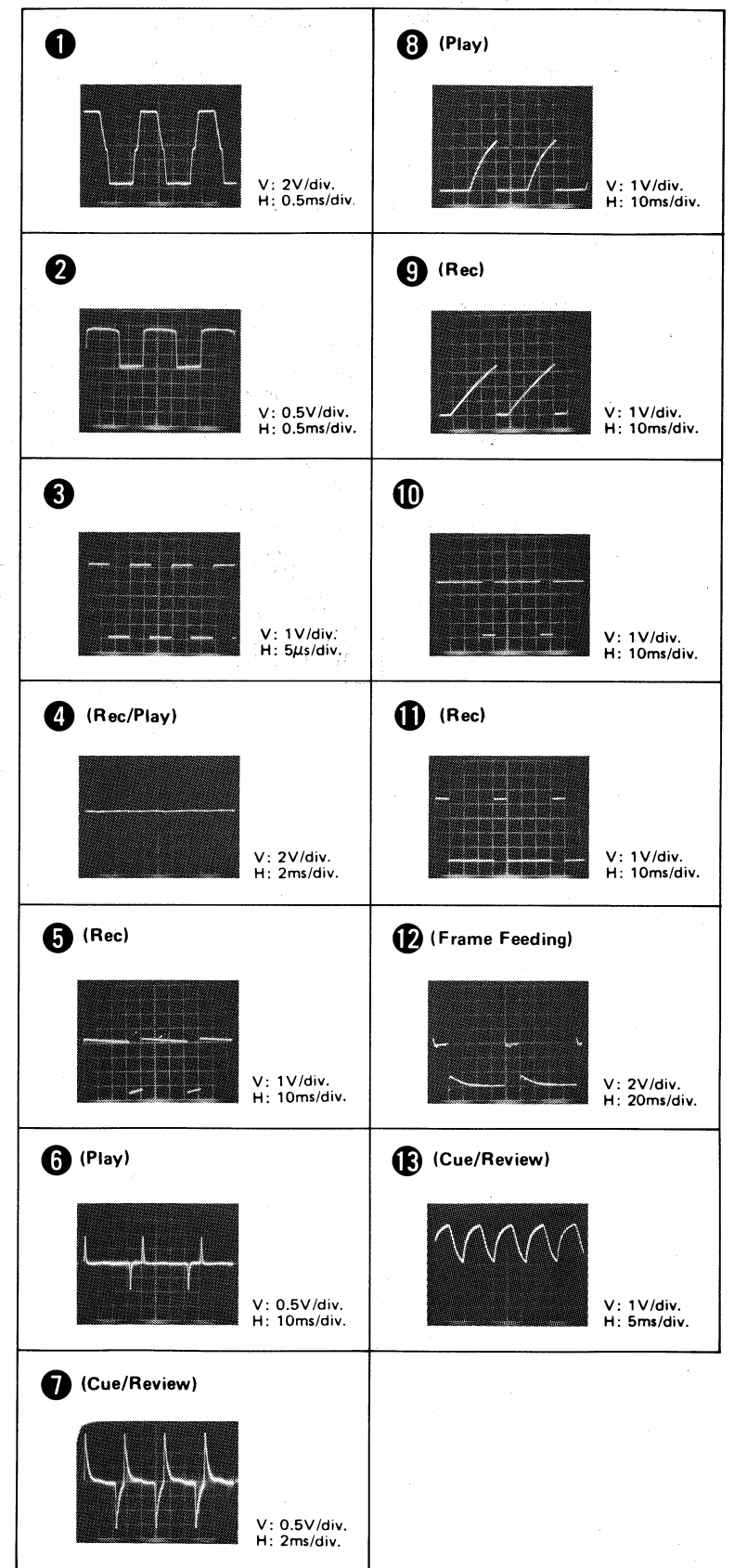
12-1. Servo Block Diagram

Cylinder Servo Signal Line



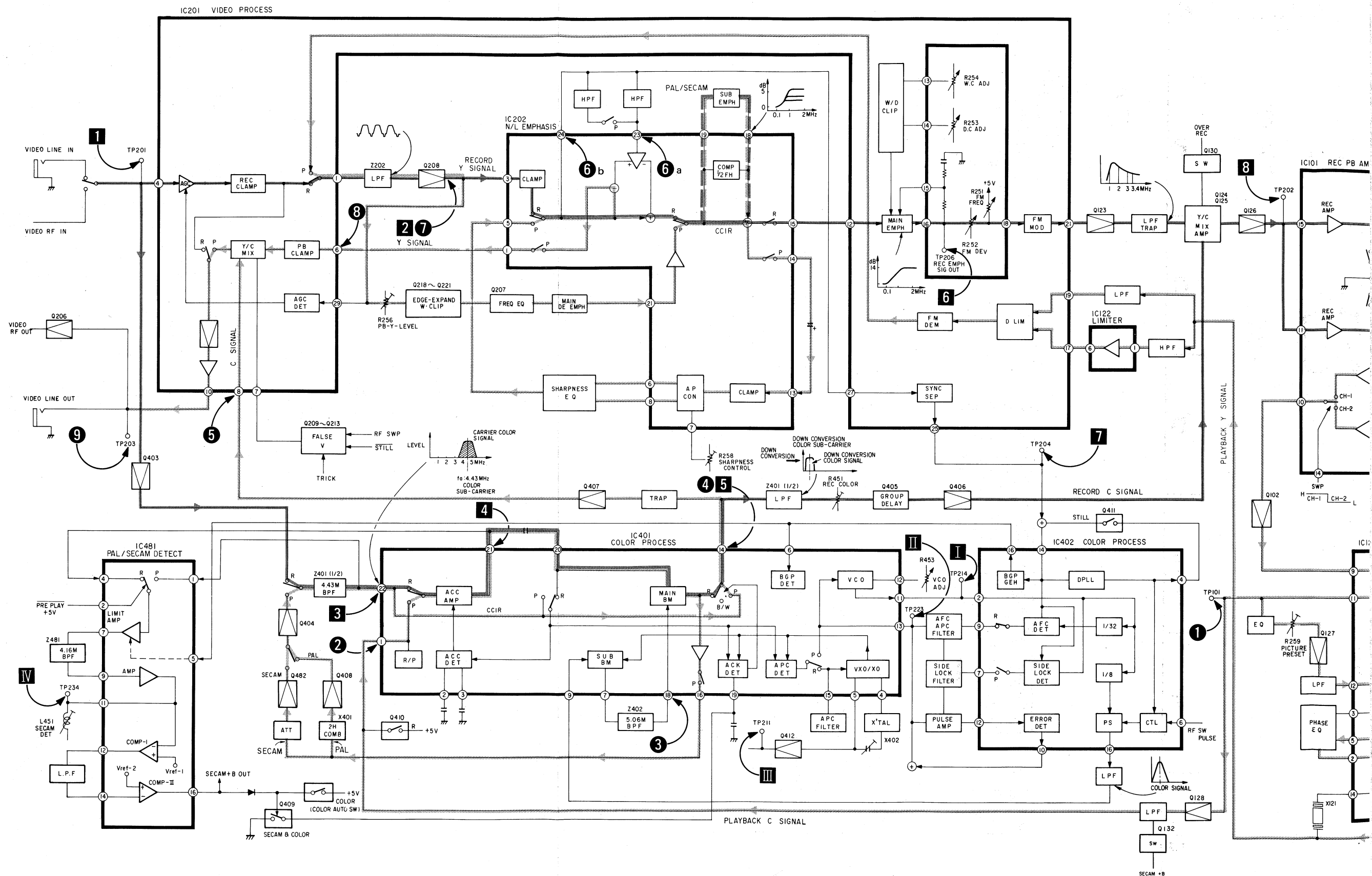
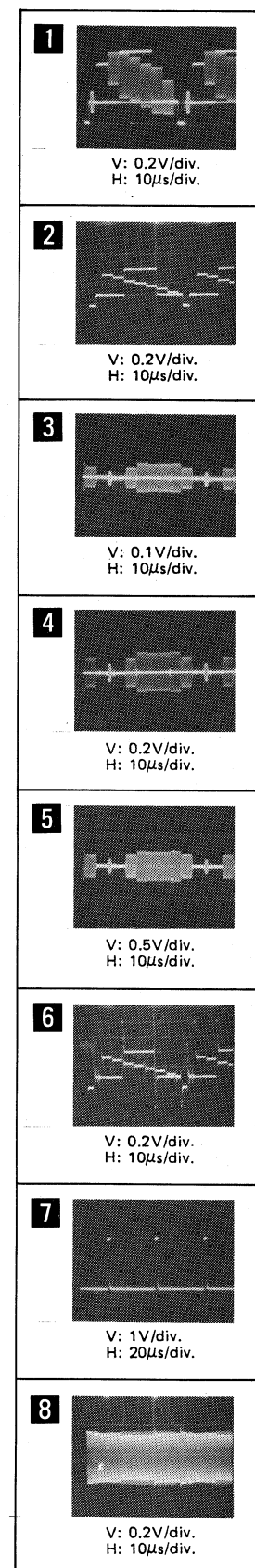


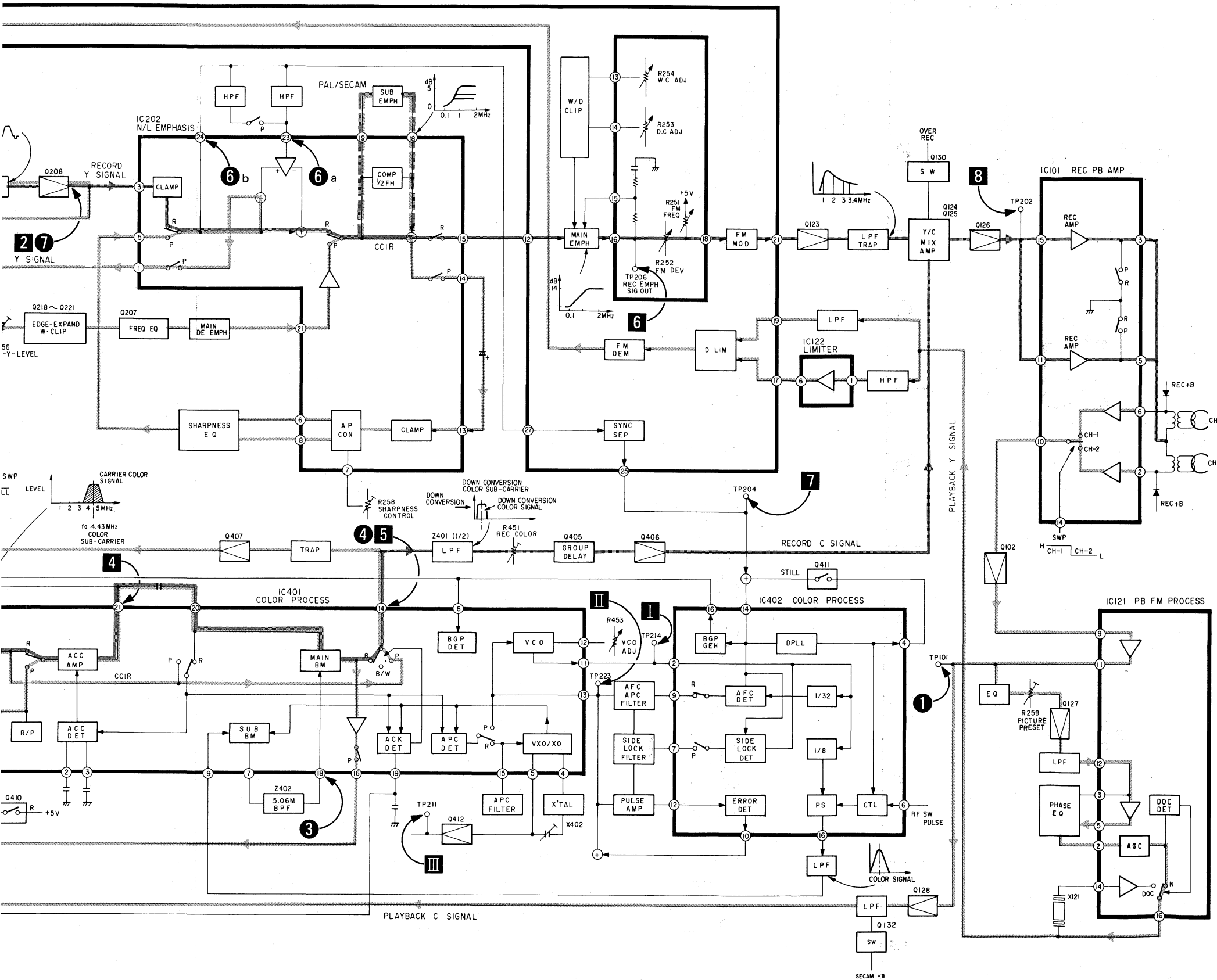
Capstan Servo Signal Line



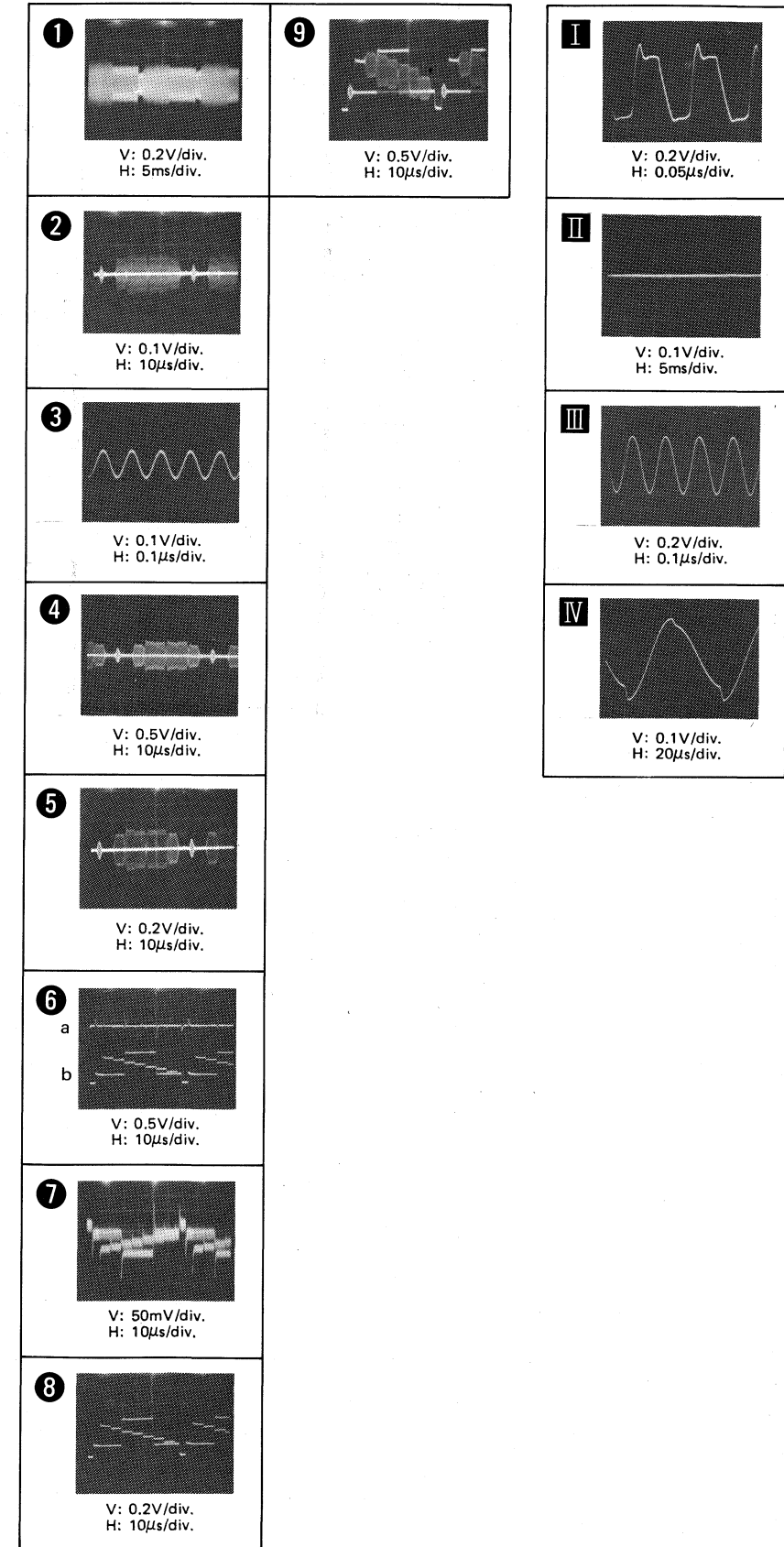
13-1. Video Block Diagram

Record Mode

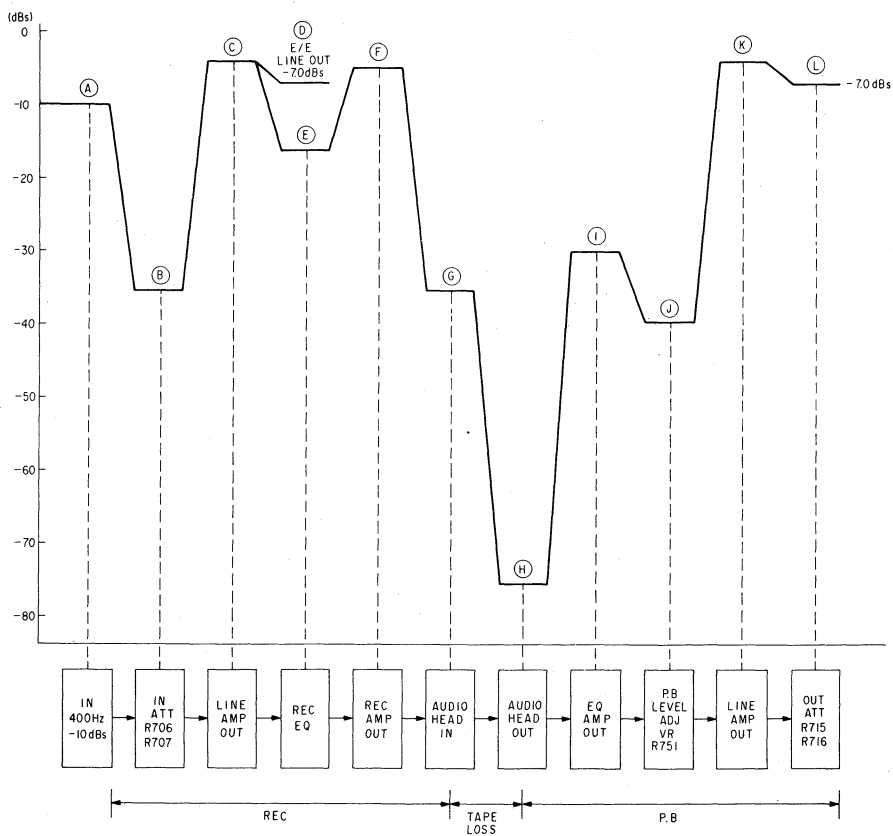
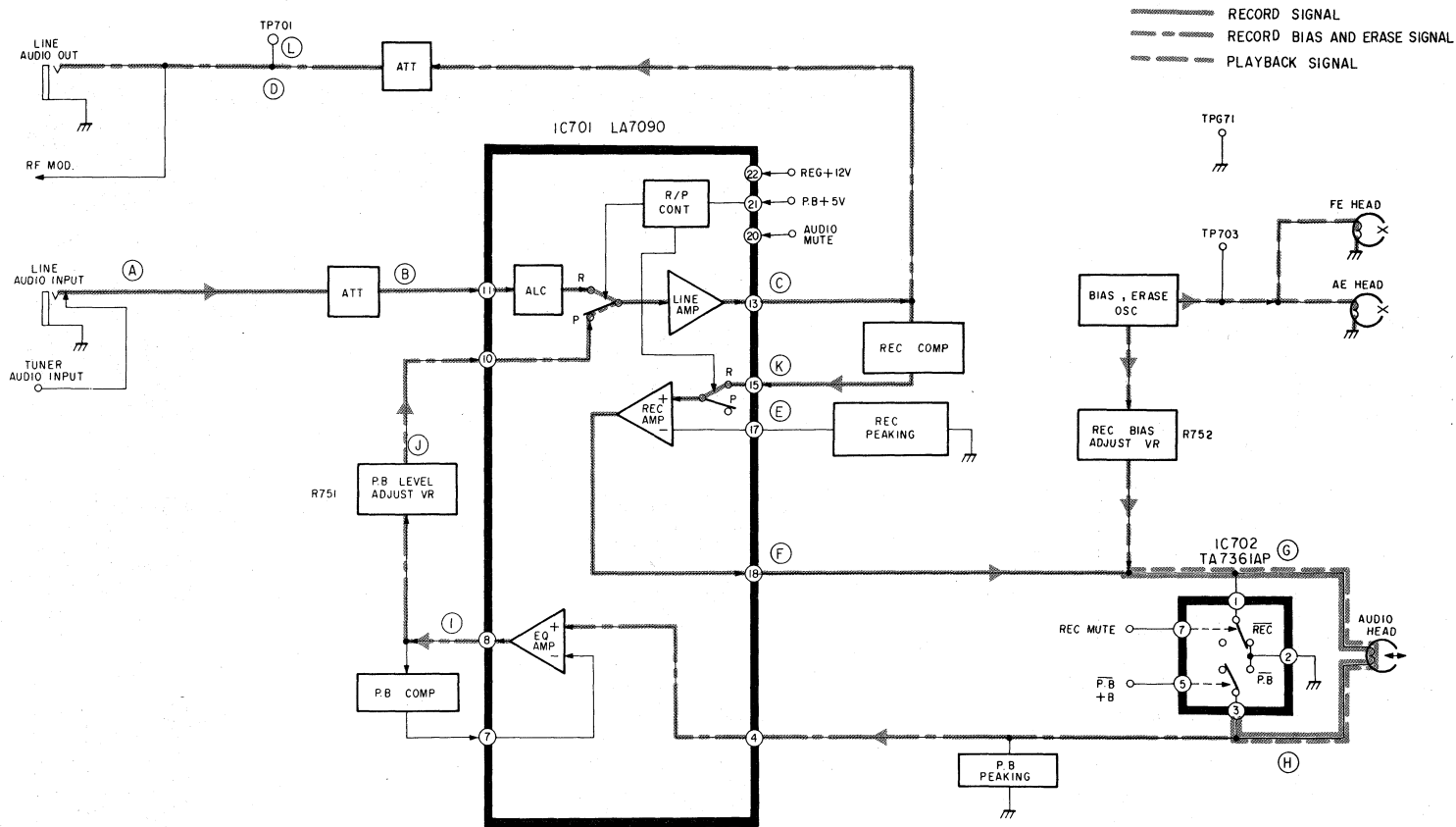




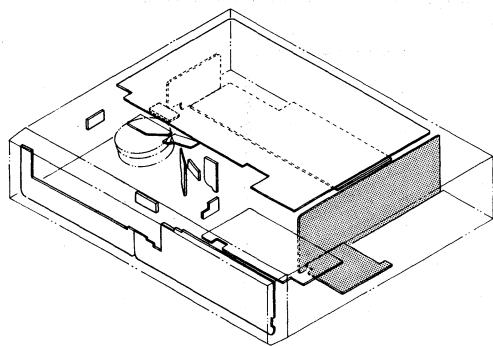
Playback Mode



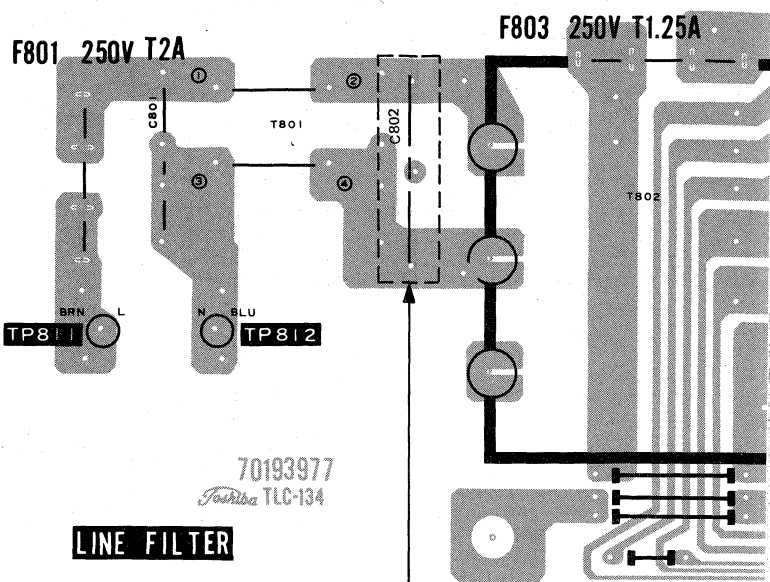
14-1. Audio Block Diagram



8-2. Power Supply PC Board



U802 Power 1 PC Board



V-81/83G only

Location of Diodes

Symbol No.	Location
D801	C-7
D802	C-7
D803	C-7
D804	C-7
D805	C-7
D806	C-7
D807	D-7
D808	D-7
D809	F-9
D810	F-9
D814	E-8
D815	F-8
D816	E-8
D817	F-8
D818	F-9
D819	E-9
D820	F-9
D821	F-8
D822	E-10

Location of VR's

Symbol No.	Location
R851	B-8

Voltage and Location of Transistors

	Q801			Q802			Q803			Q804			Q805		
	E	C	B	E	C	B	E	C	B	E	C	B	E	C	B
STAND-BY	0	0.7	1.3	0.9	19.9	0.9	0	0	0.7	0	19.7	0	0	0	0
EE	0	0.7	1.3	13.6	18.7	14.6	12.0	15.3	12.6	12.0	18.3	13.2	5.6	13.7	6.2
PLAY	0	18.3	0.4	13.5	18.3	14.8	12.0	15.3	12.6	12.0	18.4	13.2	5.6	13.6	6.2
REC	0	17.7	0.4	13.5	17.7	14.8	12.0	15.3	12.6	12.0	17.3	13.2	5.6	13.7	6.2
LOCATION	C-9			E-9			E-10			F-8			F-8		

	Q806			Q807			Q808			Q809			Q810		
	E	C	B	E	C	B	E	C	B	E	C	B	E	C	B
STAND-BY	12.1	18.6	12.8	0	63.9	0	0	0	4.2	64.1	0	64.1	0	0	0
EE	12.0	17.2	12.7	0	0	0.6	0	0	6.0	27.6	27.6	27.0	0	27.6	0
PLAY	12.0	17.3	12.7	0	0	0.6	0	0	6.0	27.6	27.6	26.9	0	27.6	0
REC	12.0	16.3	12.6	0	0	0.6	0	0	6.0	27.4	27.4	26.8	0	27.4	0
LOCATION	E-9			F-9			E-9			F-10			E-9		

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8-2. Power Supply PC Board

A

B

C

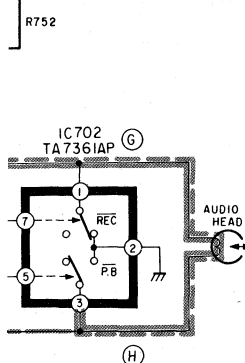
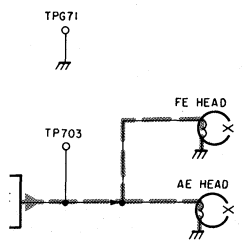
D

E

F

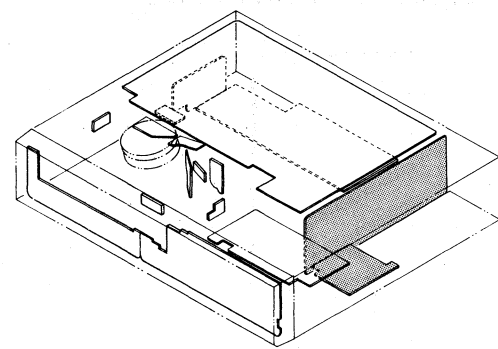
G

RECORD SIGNAL
RECORD BIAS AND ERASE SIGNAL
PLAYBACK SIGNAL



rms

DE
IAS OSC
SURE
3 BASE
GND1



Location of Diodes

Symbol No.	Location
D801	C-7
D802	C-7
D803	C-7
D804	C-7
D805	C-7
D806	C-7
D807	D-7
D808	D-7
D809	F-9
D810	F-9
D814	E-8
D815	F-8
D816	E-8
D817	F-8
D818	F-9
D819	E-9
D820	F-9
D821	F-8
D822	E-10

Location of VR's

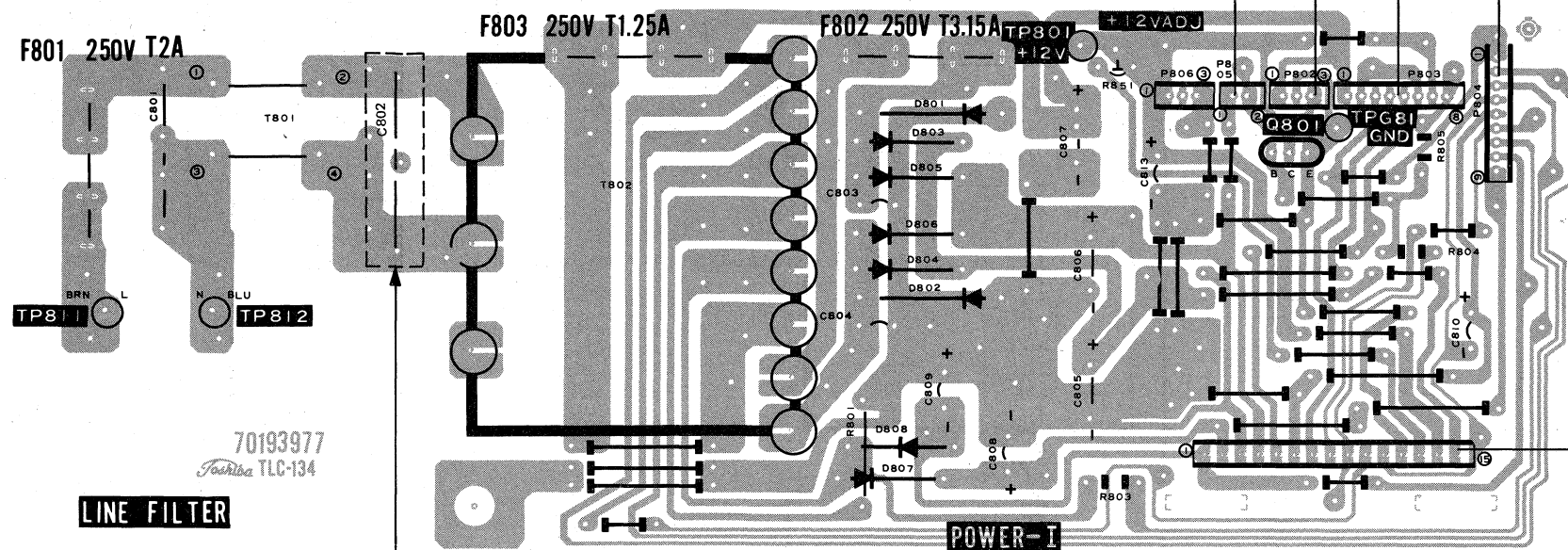
Symbol No.	Location
R851	B-8

Voltage and Location of Transistors

	Q801			Q802			Q803			Q804			Q805		
	E	C	B	E	C	B	E	C	B	E	C	B	E	C	B
STAND-BY	0	0.7	1.3	0.9	19.9	0.9	0	0	0.7	0	19.7	0	0	0	0
EE	0	0.7	1.3	13.6	18.7	14.6	12.0	15.3	12.6	12.0	18.3	13.2	5.6	13.7	6.2
PLAY	0	18.3	0.4	13.5	18.3	14.8	12.0	15.3	12.6	12.0	18.4	13.2	5.6	13.6	6.2
REC	0	17.7	0.4	13.5	17.7	14.8	12.0	15.3	12.6	12.0	17.3	13.2	5.6	13.7	6.2
LOCATION	C-9			E-9			E-10			F-8			F-8		

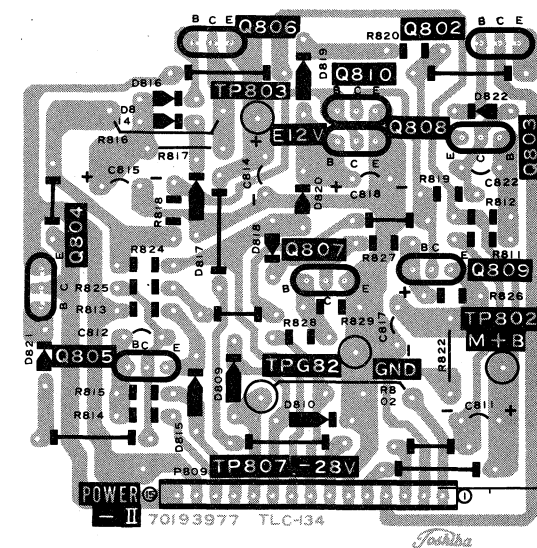
	Q806			Q807			Q808			Q809			Q810		
	E	C	B	E	C	B	E	C	B	E	C	B	E	C	B
STAND-BY	12.1	18.6	12.8	0	63.9	0	0	0	4.2	64.1	0	64.1	0	0	0
EE	12.0	17.2	12.7	0	0	0.6	0	0	6.0	27.6	27.6	27.0	0	27.6	0
PLAY	12.0	17.3	12.7	0	0	0.6	0	0	6.0	27.6	27.6	26.9	0	27.6	0
REC	12.0	16.3	12.6	0	0	0.6	0	0	6.0	27.4	27.4	26.8	0	27.4	0
LOCATION	E-9			F-9			E-9			F-10			E-9		

U802 Power 1 PC Board

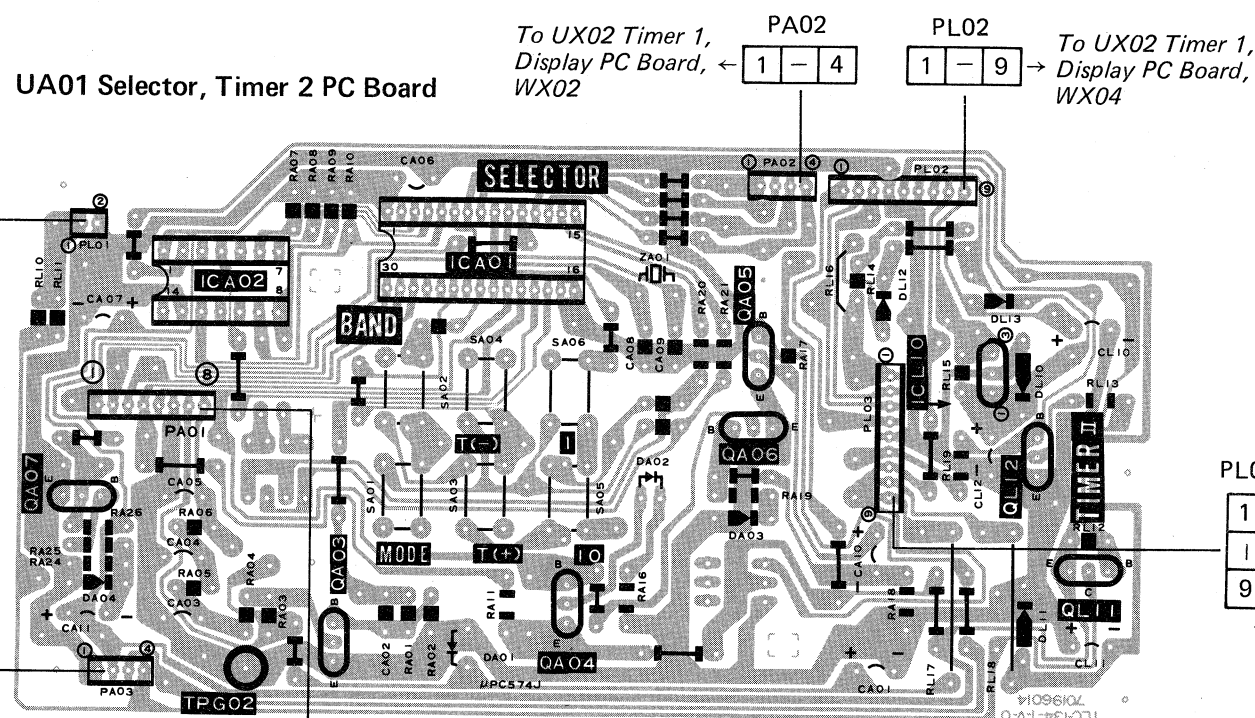
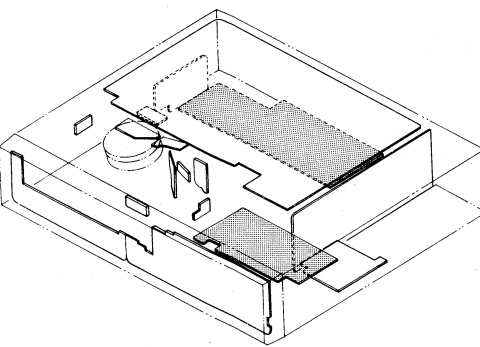


V-81/83G only

U803 Power 2 PC Board



9-3. PIF, Selector, Timer 2 PC Board (V-81/83G)



Voltage and Location of Transistors

Symbol No.	Voltage(Unit:V)			Location
	E	C	B	
QL11	5.0	5.0	4.2	C-8
QL12	0	0	5.4	C-8

Symbol No.	PLAY			PLAY			Location
	E	C	B	E	C	B	
Q005	0	OPEN	0	0	0	0	F-3
Q301	12.0	12.0	11.1	12.0	0	12.0	F-4
Q302	0	0	0.7	0	12.0	0	F-5
Q303	0	0.7	0	0	0	0	F-5

Symbol No.	AFC ON		AFC OFF		Location
	S	D	S	D	
Q003	6.6	6.6	6.6	6.6	D-7
	0	0	0	0	
	0	0	0	0	

Symbol No.	MUTE ON		MUTE OFF		Location
	E	C	E	C	
Q007	0	0	0	0	D-3
	0	0	0	0	
	0	0	0	0	

Symbol No.	AFC ON		AFC OFF		Location
	S	D	S	D	
Q008	0	0	0	0	D-7
	0	0	0	0	
	0	0	0	0	

Symbol No.	AFC ON		AFC OFF		Location
	E	C	E	C	
Q004	5.0	5.0	5.0	5.0	C-6
	0	0	0	0	
	0	0	0	0	

Location of Transistors

Symbol No.	Location
Q001	E-6
Q004	E-4
Q009	E-8
Q010	E-8
Q011	E-8
Q012	E-8
Q013	F-8
Q014	F-8
Q015	F-8
Q016	F-8
Q017	D-7
Q018	E-7
Q019	E-7
Q020	E-7
Q021	E-7
Q022	E-7
Q023	F-8
Q024	F-7
Q025	E-3
Q026	E-3
Q027	D-2
Q028	F-3
Q029	E-7
Q030	F-7
Q031	C-5
Q032	C-5
Q033	C-5
Q034	C-5
Q035	C-5
Q036	C-5
Q037	C-5
Q038	C-5
Q039	C-5
Q040	C-5
Q041	C-5
Q042	C-5
Q043	C-5
Q044	C-5
Q045	C-5
Q046	C-5
Q047	C-5
Q048	C-5
Q049	C-5
Q050	C-5
Q051	C-5
Q052	C-5
Q053	C-5
Q054	C-5
Q055	C-5
Q056	C-5
Q057	C-5
Q058	C-5
Q059	C-5
Q060	C-5
Q061	C-5
Q062	C-5
Q063	C-5
Q064	C-5
Q065	C-5
Q066	C-5
Q067	C-5
Q068	C-5
Q069	C-5
Q070	C-5
Q071	C-5
Q072	C-5
Q073	C-5
Q074	C-5
Q075	C-5
Q076	C-5
Q077	C-5
Q078	C-5
Q079	C-5
Q080	C-5
Q081	C-5
Q082	C-5
Q083	C-5
Q084	C-5
Q085	C-5
Q086	C-5
Q087	C-5
Q088	C-5
Q089	C-5
Q090	C-5
Q091	C-5
Q092	C-5
Q093	C-5
Q094	C-5
Q095	C-5
Q096	C-5
Q097	C-5
Q098	C-5
Q099	C-5
Q100	C-5

Location of VR'S

Symbol No.	Location
R051	F-7
R052	F-4

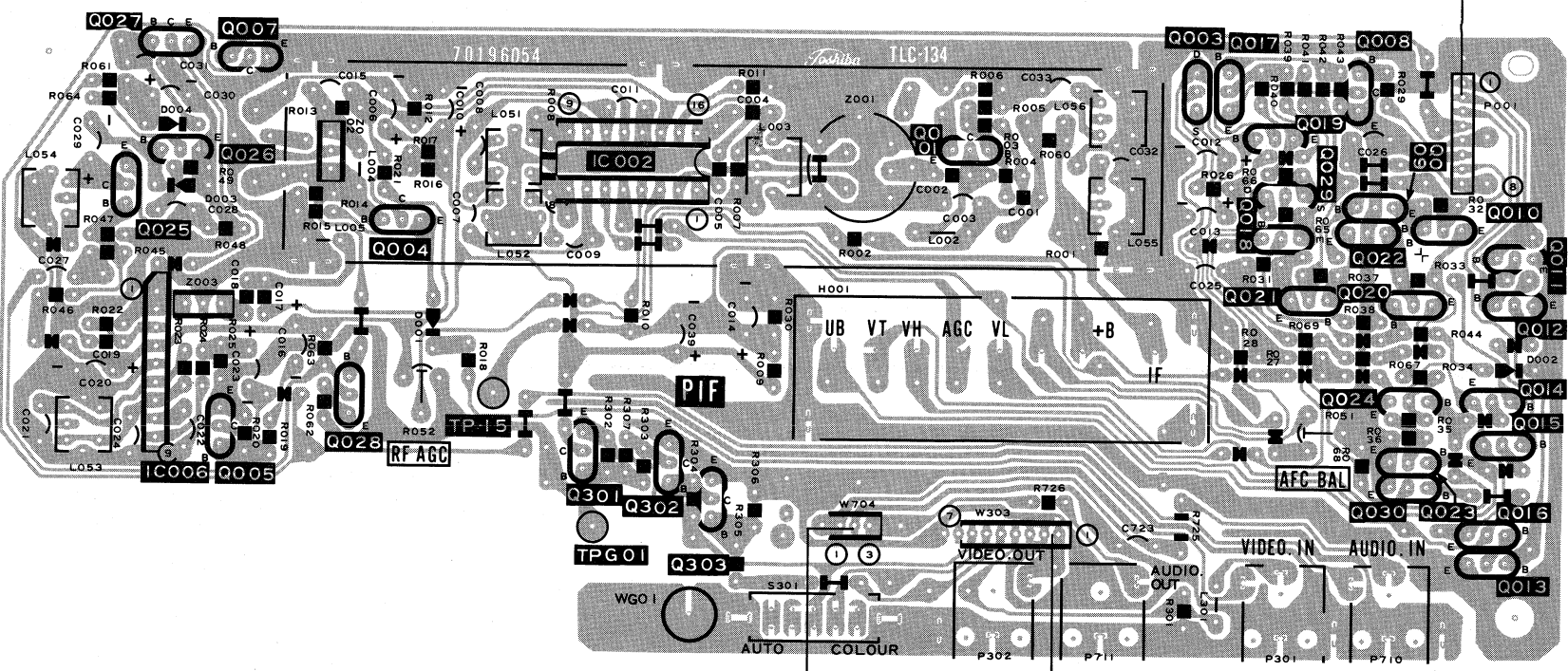
Location of IC'S

Symbol No.	Location
IC002	E-4
IC006	F-3
ICA01	B-6
ICA02	B-5
ICA10	B-7

Location of Diodes

Symbol No.	Location
D001	E-4
D002	F-8
D003	E-3
D004	E-3
DA01	C-6
DA02	C-6
DA03	C-7
DA04	C-4
DL10	B-8
DL11	C-8
DL12	B-7
DL13	B-8

U001 PIF PC Board



To U202 Audio PC Board, P703 ← W704 1 2 3
W303 7 1 → To U202 Video PC Board, P204

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PIF

PIF

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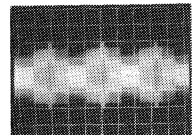
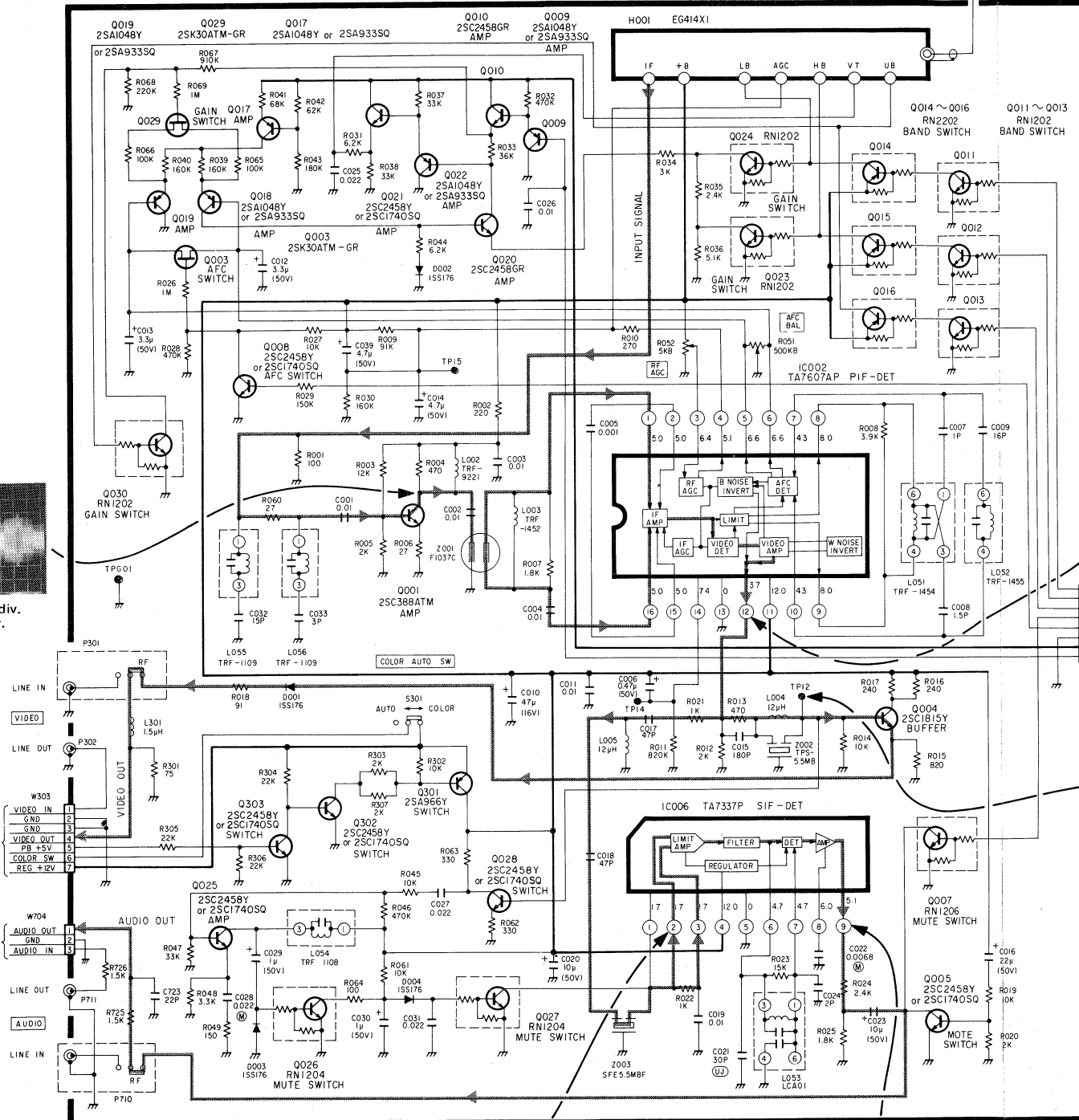
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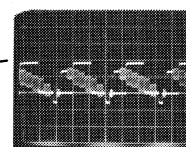
9-4. PIF, Selector, Timer 2 Circuit (V-81/83G)

U001 PIF

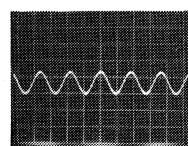


V: 100mV/div.
H: 20μs/div.

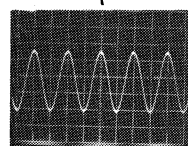
V: 1V/div.
H: 20μs/div.



V: 1V/div.
H: 20μs/div.



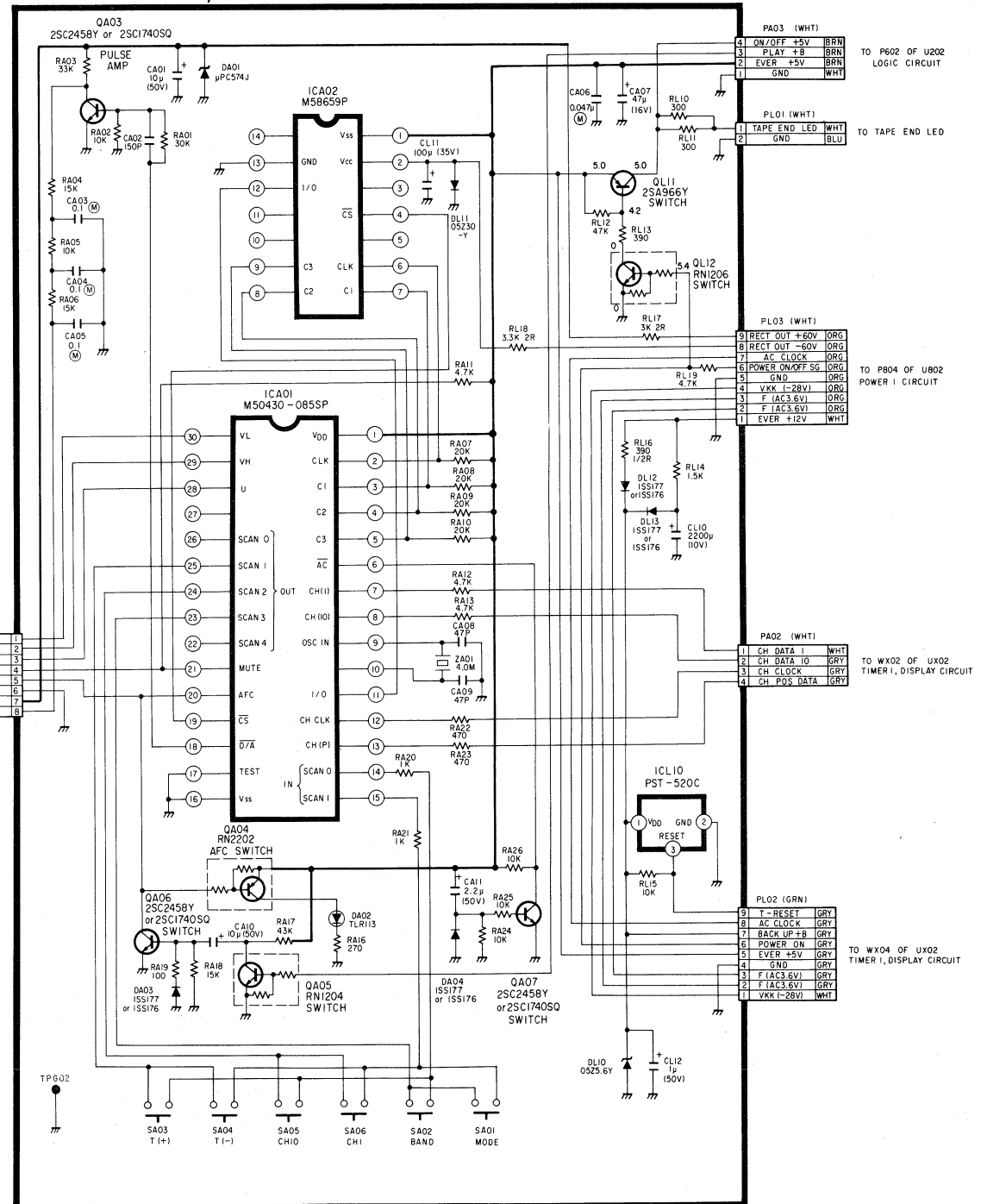
V: 50mV/div.
H: 0.1μs/div.



V: 200mV/div.
H: 0.5ms/div.

UA01 SELECTOR, TIMER 2

V: RECORD



	E	C	B	E	C	B
Q001	12.0V	12.0V	11.1V	12.0V	0V	12.0V
Q002	0V	0V	0.7V	0V	12.0V	0V
Q003	0V	0.7V	0V	0V	0V	0V
Q005	0V	0V	0V	0V	0V	0V

	E	C	B
Q003	6.6V	6.6V	6.6V
D	6.6V	6.6V	6.6V
G	0V	7.1V	0V

	E	C	B
Q007	0V	0V	0V
C	0V	0V	0V
B	4.5V	0V	0V

	E	C	B
Q008	0V	0V	0V
C	0V	11.5V	0V
B	0.6V	0V	0V

	E	C	B
Q004	0V	0V	0V
C	0V	11.5V	0V
B	0.6V	0V	0V

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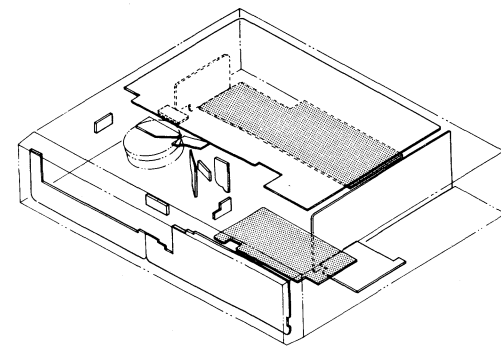
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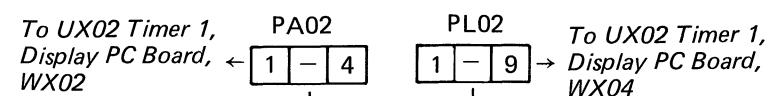
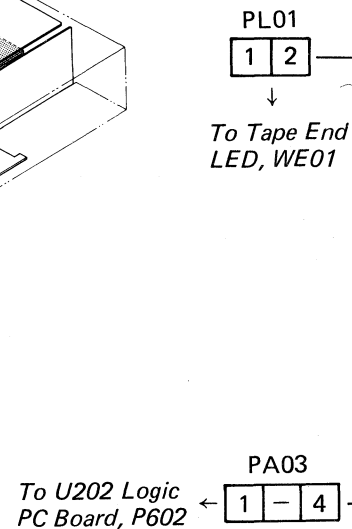
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9-5. PIF, Selector, Timer 2 PC Board (V-81/83W)



UA01 Selector, Timer 2 PC Board



Voltage and Location of Transistors

Symbol No.	Voltage(Unit:V)			Location
	E	C	B	
QL11	5.0	5.0	4.2	C-8
QL12	0	0	5.4	C-8

	PLAY			PLAY			Location
	E	C	B	E	C	B	
Q007	0	OPEN	0	0	0	0	E-3
Q301	12.0	12.0	11.1	12.0	0	12.0	F-3
Q302	0	0	0.7	0	12.0	0	F-4
Q303	0	0.7	0	0	0	0	F-4

Q003

	AFC ON	AFC OFF	Location
S	8.5	6.3	
D	4.1	6.2	
G	0	6.8	

Q006

	MUTE ON	MUTE OFF	Location
E	0	0	
C	0	OPEN	
B	4.5	0	

Q008

	AFC ON	AFC OFF	Location
E	0	0	
C	0	11.5	
B	0.7	0	

QA04

	AFC ON	AFC OFF	Location
E	5.1	5.1	
C	OPEN	5.0	
B	4.6	0	

Location of Transistors

Symbol No.	Location
Q001	E-7
Q009	E-3
Q061	F-7
Q062	F-7
Q063	F-8
Q064	F-8
Q065	F-8
Q066	F-7
Q067	F-7
Q068	E-7
Q069	E-8
Q070	E-8
Q071	E-8
Q072	E-7
Q073	E-7
Q074	E-7
Q075	E-8
Q076	F-8
Q077	D-7
Q078	E-8
QA03	C-5
QA05	B-7
QA06	C-7
QA07	C-4

Location of VR's

Symbol No.	Location
R051	E-6
R052	E-4

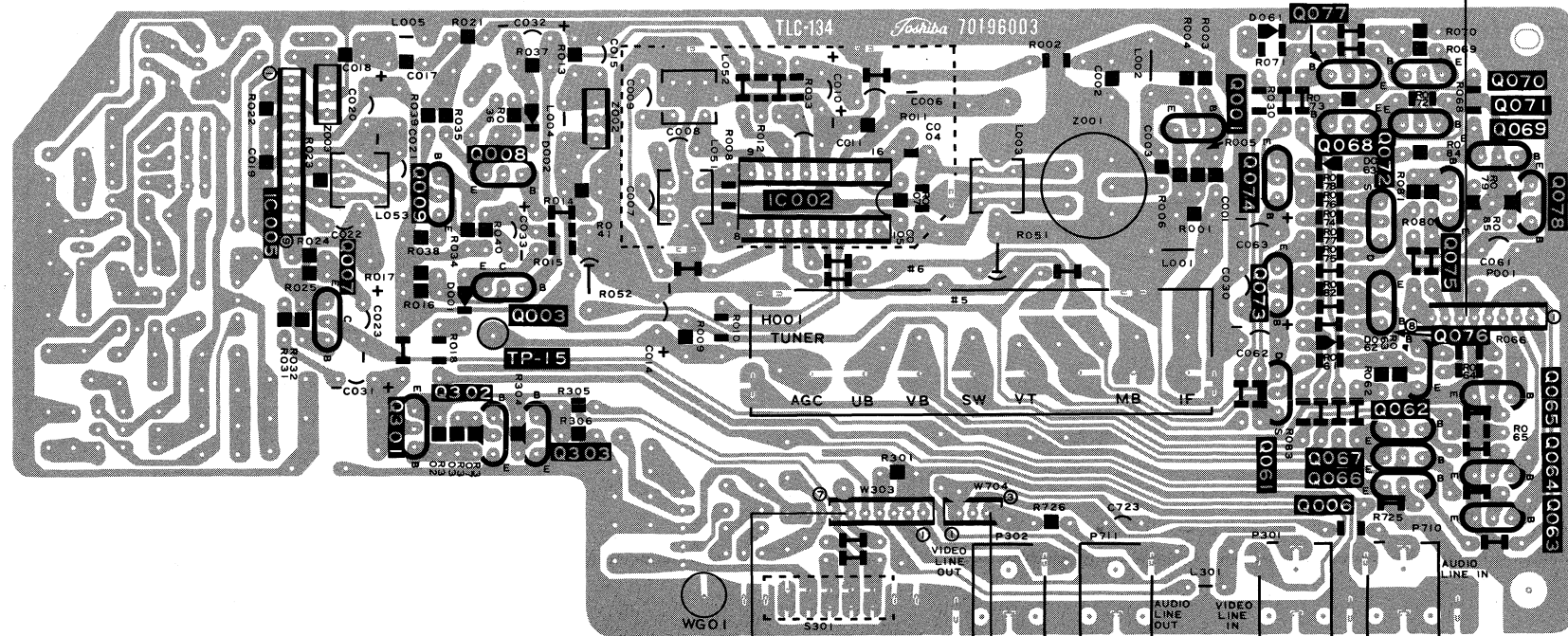
Location of IC's

Symbol No.	Location
IC002	E-5
IC005	E-3
ICA01	B-6
ICA02	B-5
ICL10	B-7

Location of Diodes

Symbol No.	Location
D001	E-4
D002	E-4
D061	D-7
D062	F-7
D063	E-7
DA01	C-6
DA02	C-6
DA03	C-7
DA04	C-4
DL10	B-8
DL11	C-8
DL12	B-7
DL13	B-8

U001 PIF PC Board



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PIF

PIF

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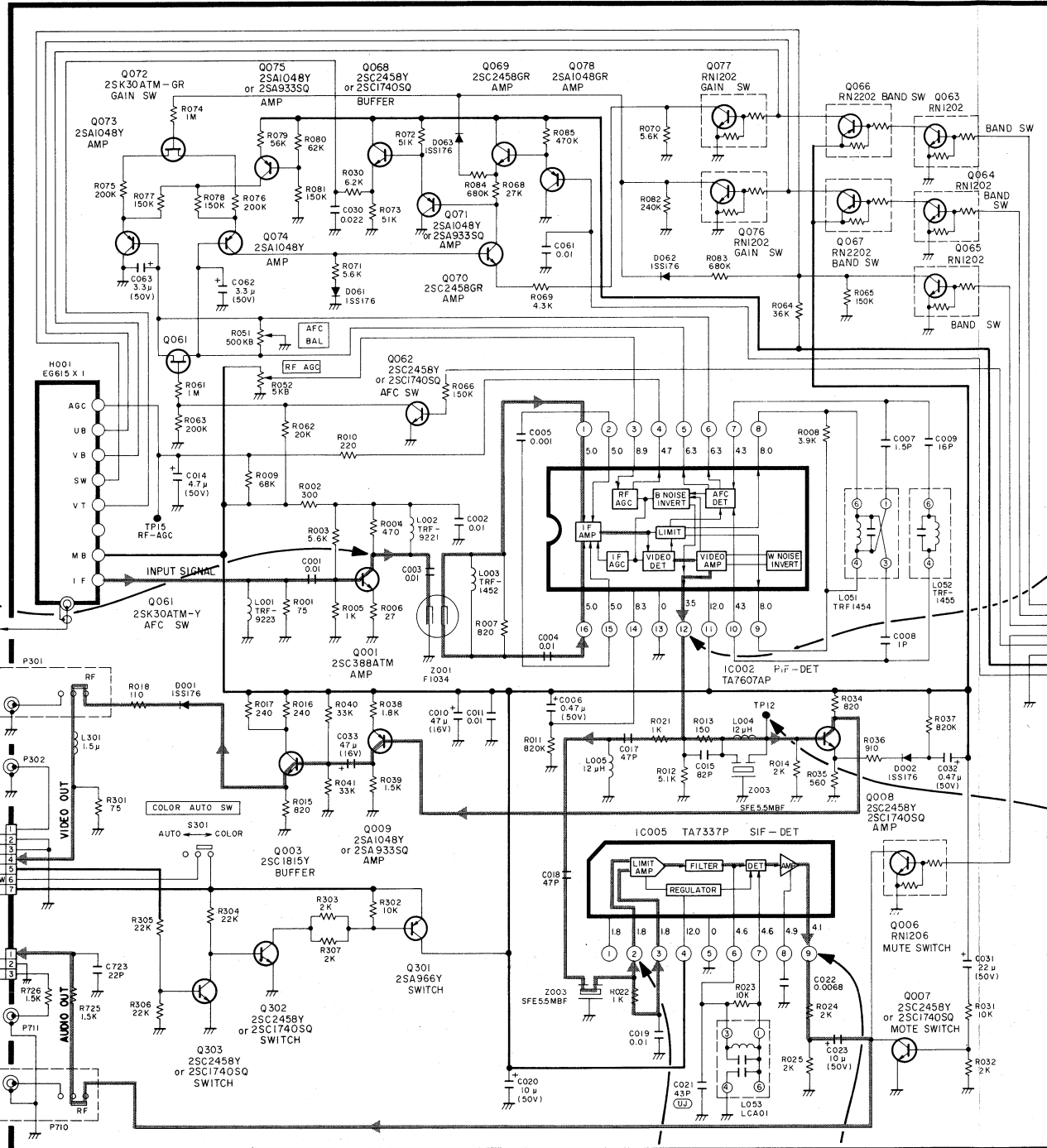
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9-6. PIF, Selector, Timer 2 Circuit (V-81/83W)

U001 PIF

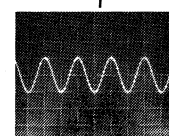


V: 0.1V/div.
H: 20μs/div.

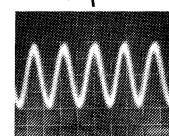
TO ANTENNA
TERMINAL

TO P204 OF U202
VIDEO CIRCUIT

TO P703 OF U202
AUDIO CIRCUIT

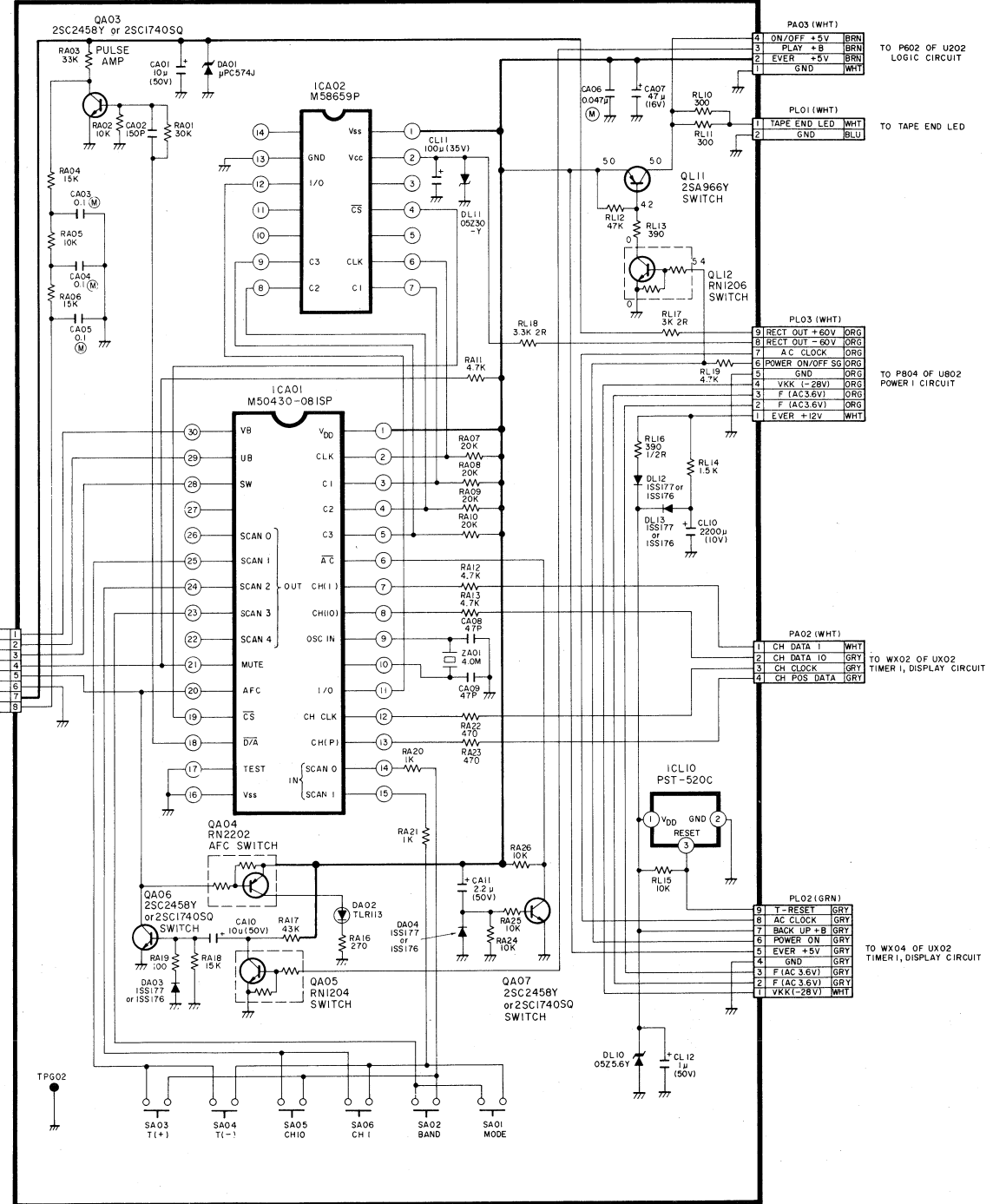


V: 0.5V/div.
H: 1ms/div.



V: 10mV/div.
H: 0.1μs/div.

UA01 SELECTOR, TIMER 2



V: 0.5V/div.
H: 20μs/div.

V: 0.5V/div.
H: 20μs/div.

	E	PLAY	C	B	E	PLAY	C	B
Q301	12.0V	12.0V	11.1V	12.0V	0V	12.0V	0V	12.0V
Q302	0V	0V	0.7V	0V	12.0V	0V	0V	0V
Q303	0V	0.7V	0V	0V	0V	0V	0V	0V
Q007	0V	OPEN	0V	0V	0V	0V	0V	0V

	AFC ON	AFC OFF
S	8.5V	6.3V
D	4.1V	6.2V
G	0V	6.6V

	MUTE ON	MUTE OFF
E	0V	0V
C	0V	OPEN
B	4.5V	0V

	AFC ON	AFC OFF
E	5.1V	5.1V
C	0V	11.5V
B	0.7V	0V

	AFC ON	AFC OFF
E	5.1V	5.1V
C	0V	11.5V
B	4.6V	0V

V: RECORD (V)

A

B

C

D

E

F

G

10-3. Timer 1, Display, Logic Control Switch PC Board (V-81G/W)

Voltage and Location of Transistors

Symbol No.	Voltage(Unit:V)			Location
	E	B	C	
QX02	—	—	5.2	E-9
QX04	0	0	4.7	E-6

Location of Diodes

Symbol No.	Location
DL02	D-3
DL05	B-6
DL07	B-5
DR01	F-5
DX01	E-9
DX02	E-8
DX03	E-8
DX04	D-8
DX07	E-9
DX09	E-7
DX12	D-7
DX13	D-7
DX14	D-7
DX15	D-5
DX16	B-6
DX17	B-6
DX18	B-4

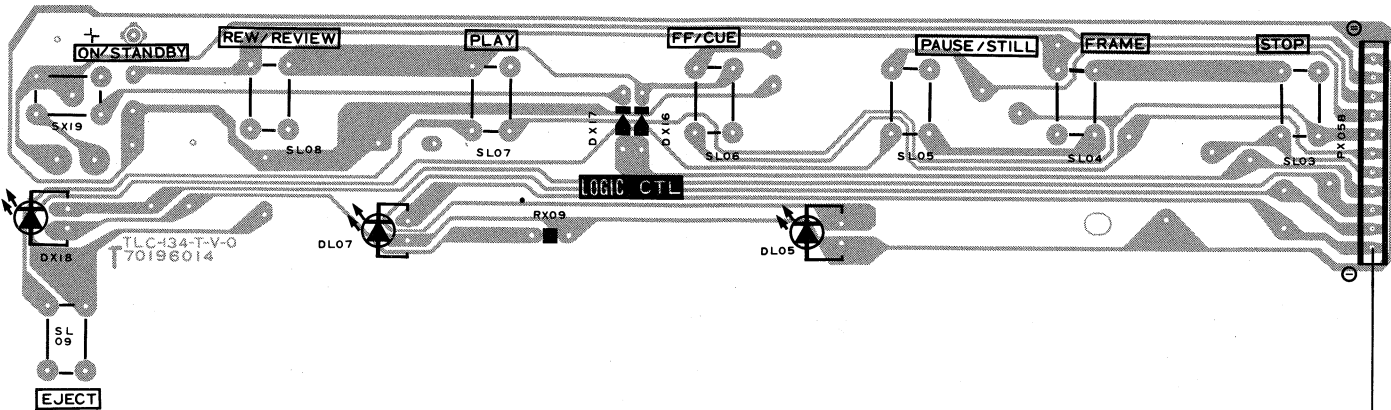
Location of VR'S

Symbol No.	Location
R258	D-6
R556	D-5

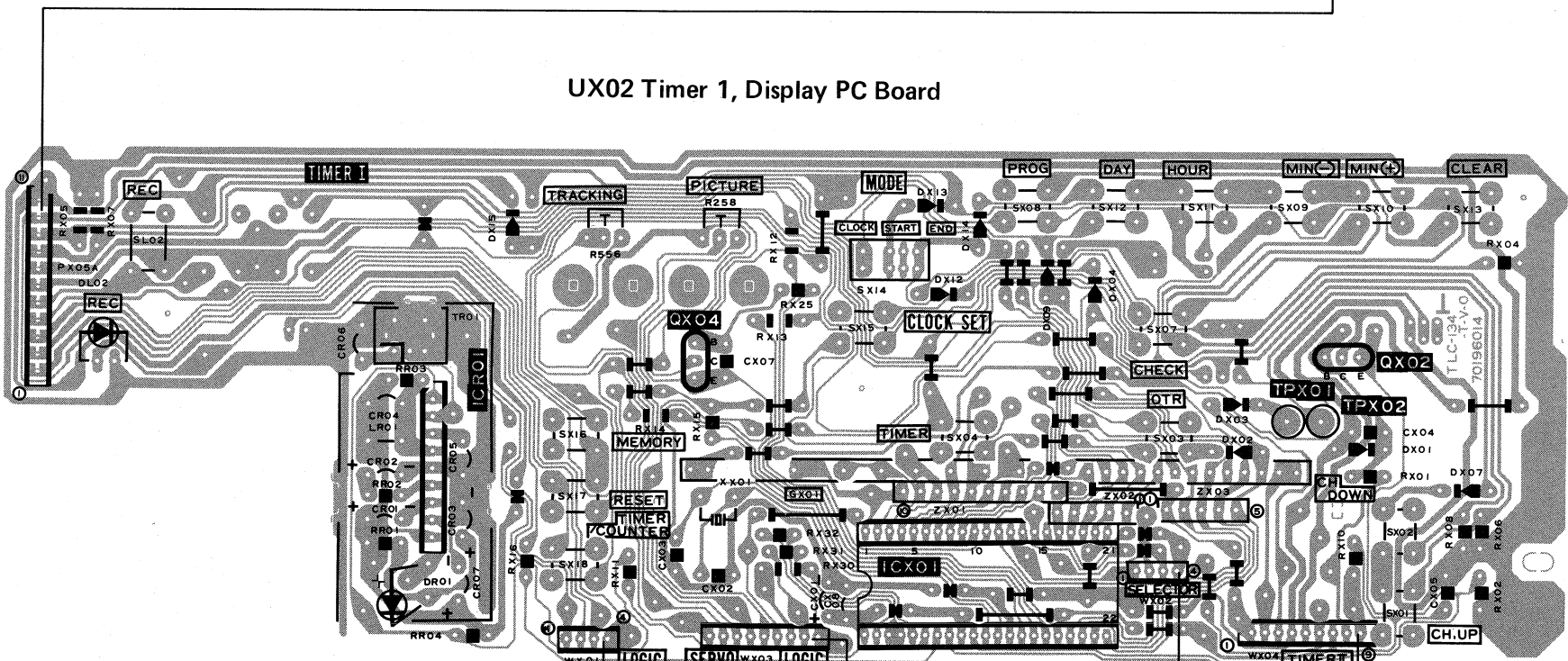
Location of IC'S

Symbol No.	Location
ICX01	F-7
ICR01	E-5

UL01 Logic Control Switch PC Board



UX02 Timer 1, Display PC Board



To U202 Logic
PC Board, P604

WX01
1 - 4

WX03
1 - 9

WX04
1 - 9

To UA01 Selector,
Timer 2 PC Board,
PL02

WX02
1 - 4

To UA01 Selector,
Timer 2 PC Board,
PA02

To U202 Servo
PC Board, P501

To U202 Video
PC Board, P205

To U202 Logic
PC Board, P603

1

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4

5

TIMER

TIMER

6

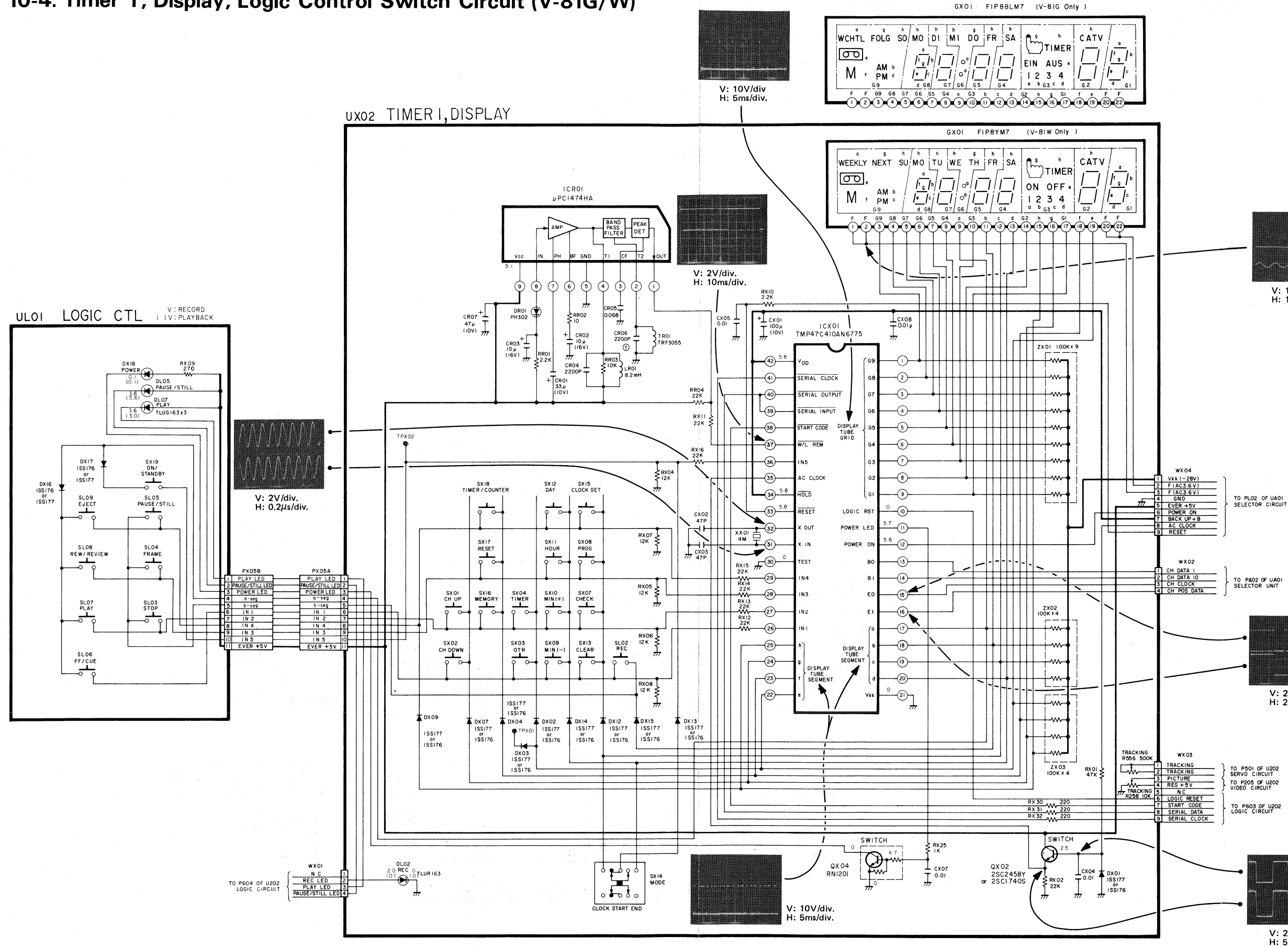
7

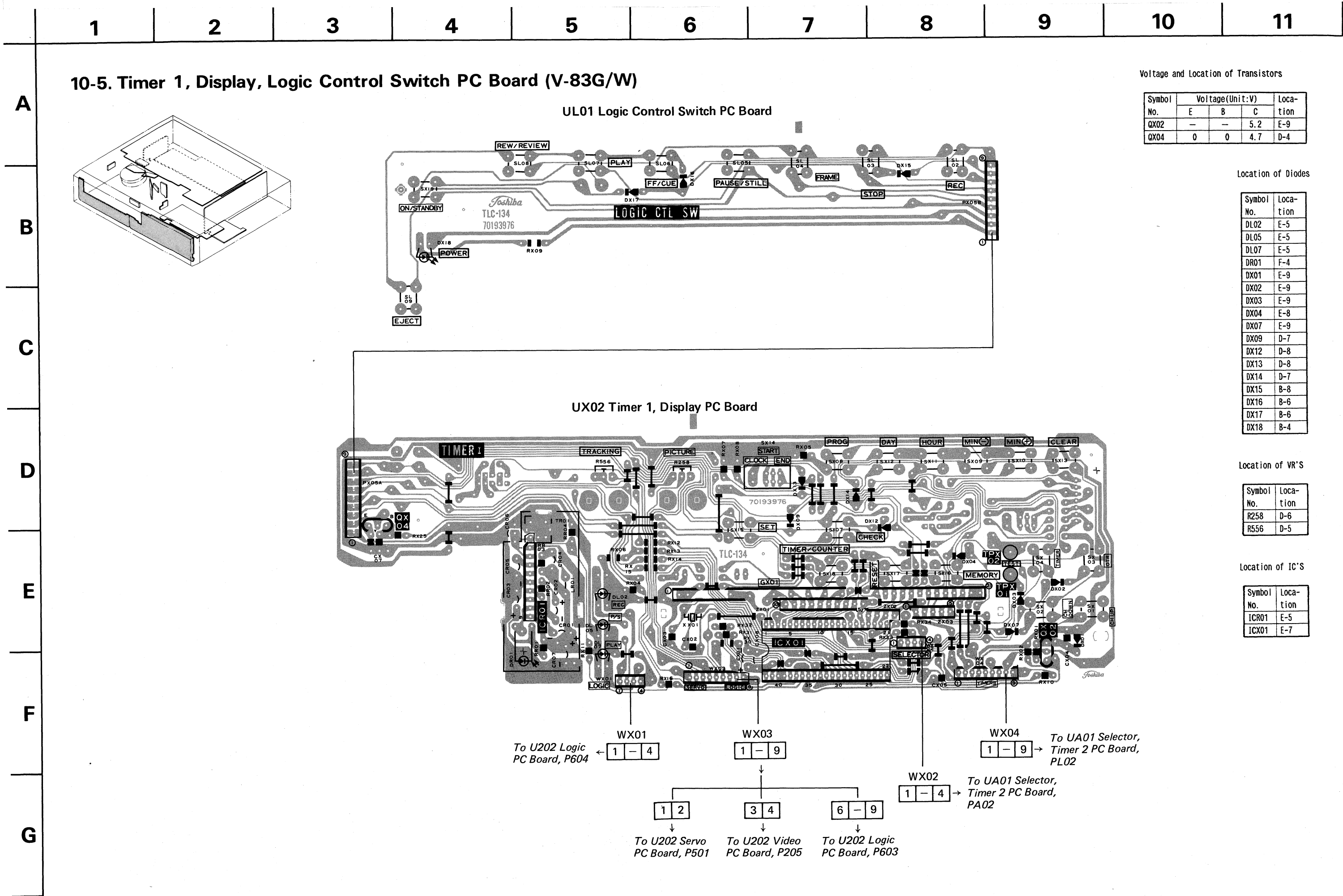
8

9

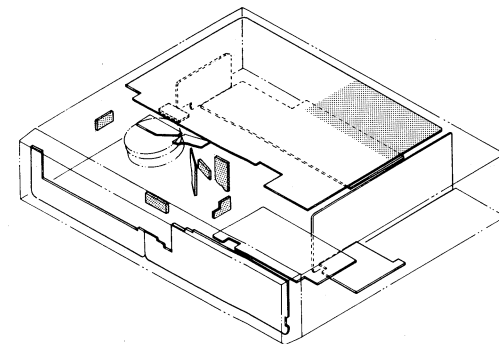
10

10-4. Timer 1, Display, Logic Control Switch Circuit (V-81G/W)





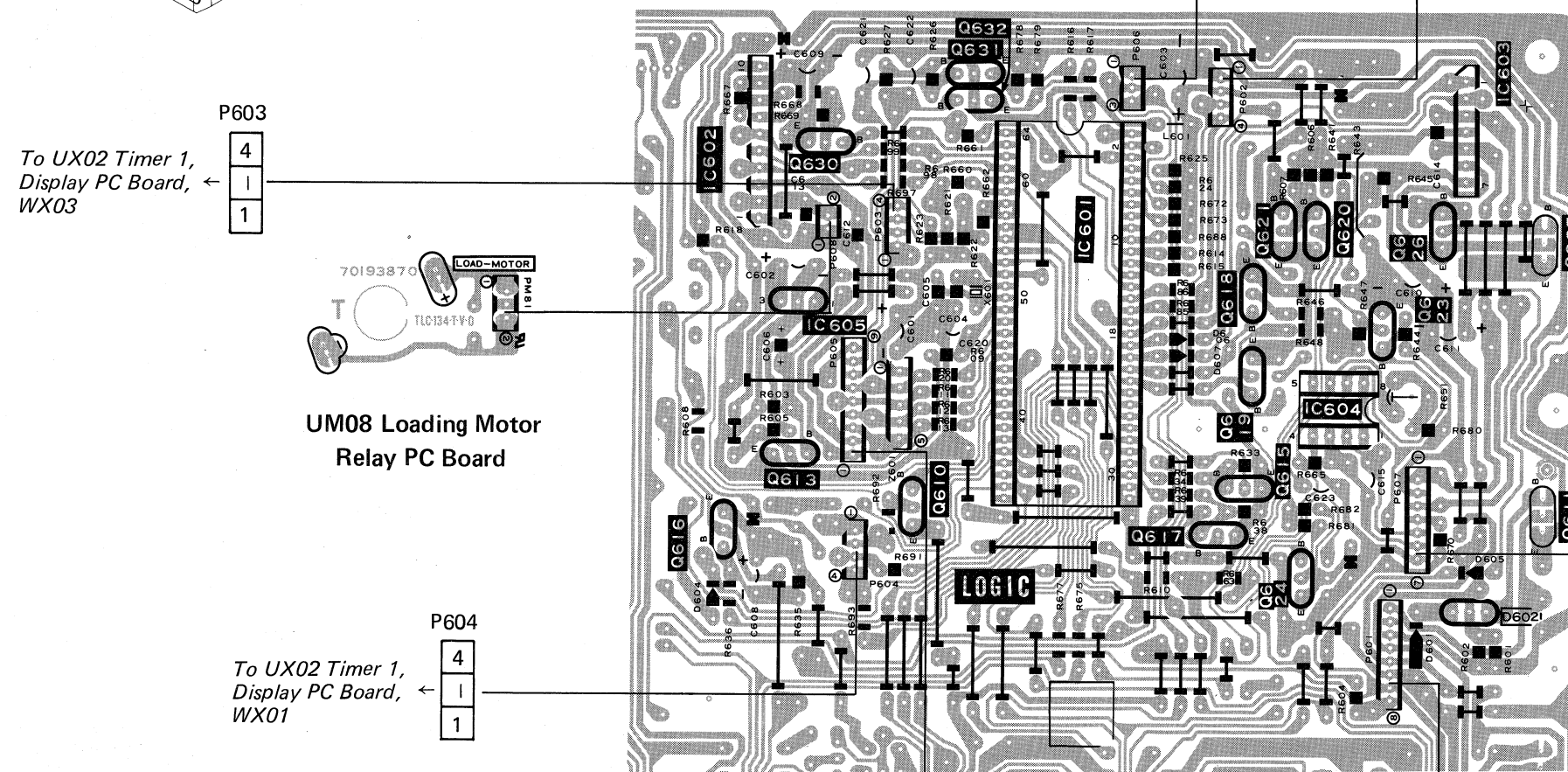
11-2. Logic PC Board



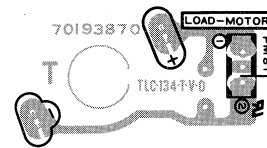
UM06 Cam Switch Relay PC Board



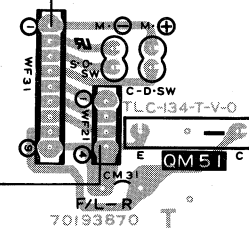
U202 Logic PC Board



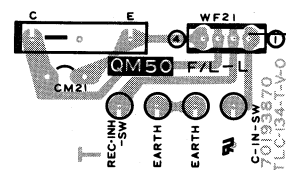
UM08 Loading Motor Relay PC Board



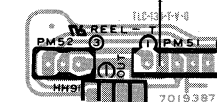
UM03 F/L Right PC Board



UM02 F/L Left PC Board



UM05 Take Up Reel Sensor PC Board



Voltage and Location of Transistors

Symbol No.	Voltage(Unit:V)			Loca- tion
	E	C	B	
QG10	5.1	5.0(0)	0.1(5.1)	D-5
QG11	5.2	8.9	6.5	D-8
QG13	0	5.1	0	D-4
QG15	5.1	0(5.1)	5.1(4.5)	D-7
QG16	12.0	11.9(0)	11.2(12.0)	E-4
QG17	5.1	0.3(5.1)	5.1(4.5)	E-6
QG18	0	2.3	1.0	D-6
QG19	0	3.4	0	D-6
QG20	0	0.4	0.1	C-7
QG21	0	0.1	1.8	C-6
QG23	0	3.7	0.2	D-7
QG24	0	0	4.9	E-7
QG25	13.2	3.1	12.6	C-8
QG26	3.1	12.6	3.7	C-7
QG30	0	7.9	0	C-4
QG31	4.3	5.2	4.9	C-5
QG32	4.2	5.2	4.8	B-5

Location of Diodes

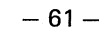
Symbol No.	Loca- tion
D601	E-7
D602	E-7
D604	E-4
D605	E-7
D606	D-6
D607	D-6

Location of VR's

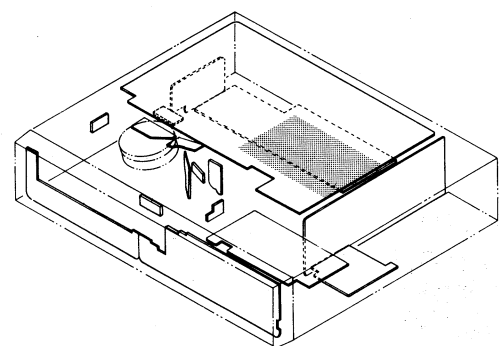
Symbol No.	Loca- tion
R651	D-7

Location of IC's

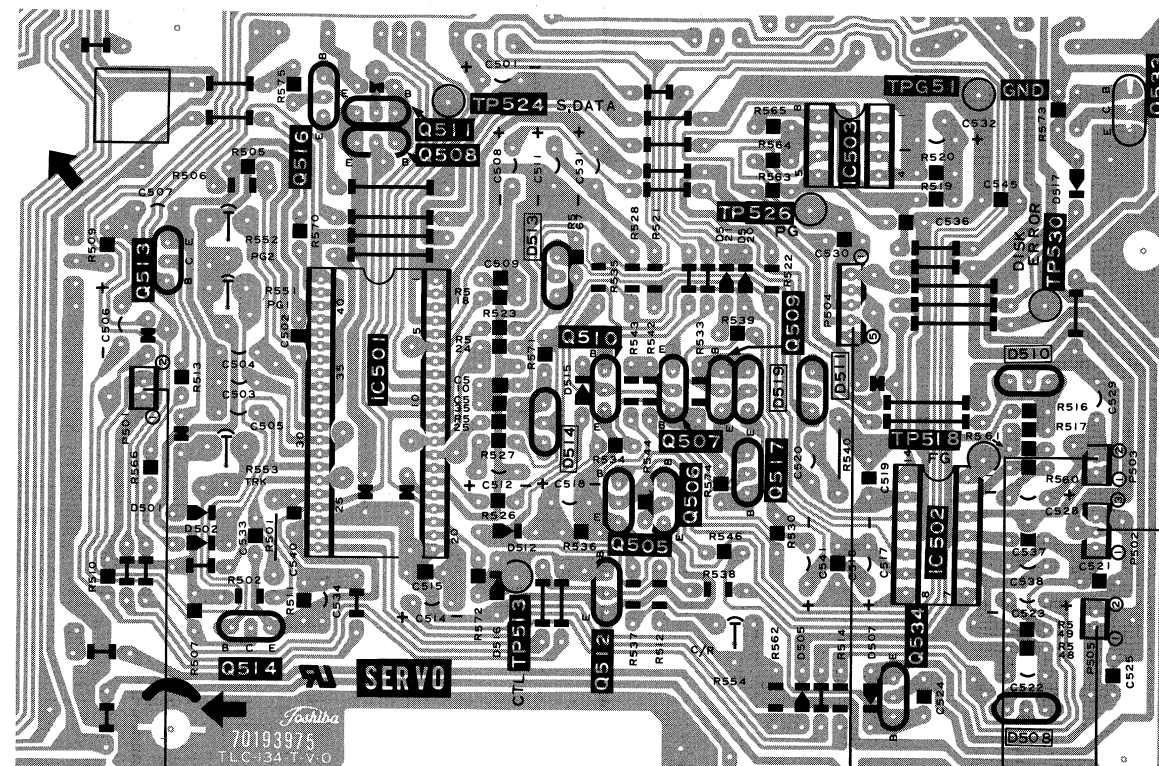
Symbol No.	Location
IC601	C-6
IC602	C-7
IC603	C-7
IC604	D-7
IC605	D-5



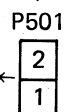
12-2. Servo PC Board



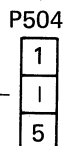
U202 Servo PC Board



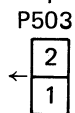
To UX02 Timer 1,
Display PC Board,
WX03



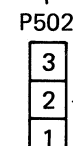
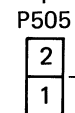
To Cylinder Drive, W107



To Capstan FG



To Capstan Motor



To UM07 ACE Head
Relay, PM71

Voltage and Location of Transistors

V:REC
(V):PLAY

Symbol No.	Voltage(Unit:V)			Loca- tion
	E	C	B	
Q505	0	7.41(7.41)	0.01(0.01)	D-5
Q506	0	7.41(7.41)	0.01(0.01)	D-6
Q507	7.27(7.27)	7.41(7.41)	7.22(7.20)	D-6
Q508	0	0	0.4(5.04)	C-4
Q509	6.35(6.36)	2.53(2.52)	6.74(6.72)	D-6
Q510	0	7.22(7.20)	0.06(0.05)	D-5
Q511	0	5.12(0.01)	0.04(5.05)	C-4
Q512	0	2.53(3.58)	3.14(3.15)	D-5
Q513	0	0.01(2.38)	11.97(0.51)	C-4
Q514	0	3.63(3.61)	2.06(2.06)	E-4
Q516	4.59(5.10)	0.01(5.10)	5.12(0.01)	C-4
Q517	6.4(6.4)	1.8(1.8)	6.4(6.4)	D-6
Q533	3.95(3.92)	13.54(13.56)	5.18(5.04)	C-7
Q534	6.79(6.79)	13.56(13.56)	7.39(7.39)	E-6

Location of IC's

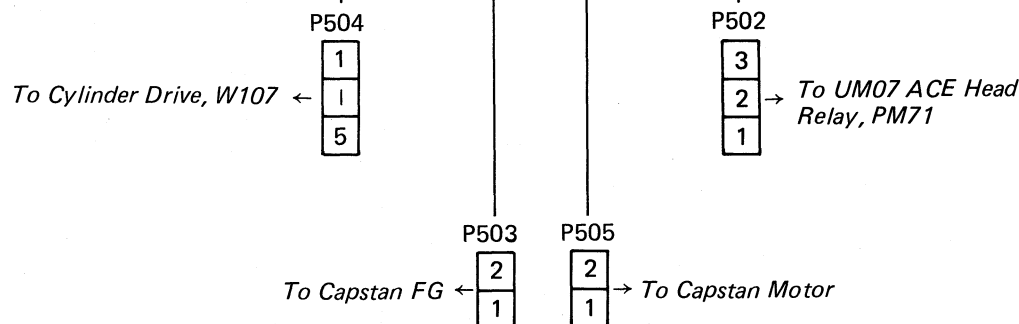
Symbol No.	Loca- tion
IC501	D-5
IC502	D-7
IC503	C-6

Location of Diodes

Symbol No.	Loca- tion
D501	D-4
D502	D-4
D505	E-6
D507	E-6
D508	E-7
D510	D-7
D511	D-6
D512	D-5
D513	C-5
D514	D-5
D515	D-5
D516	D-5
D517	C-7
D519	D-6
D520	C-6
D521	C-6

Location of VR's

Symbol No.	Loca- tion
R551	C-4
R552	C-4
R553	D-4
R554	E-6



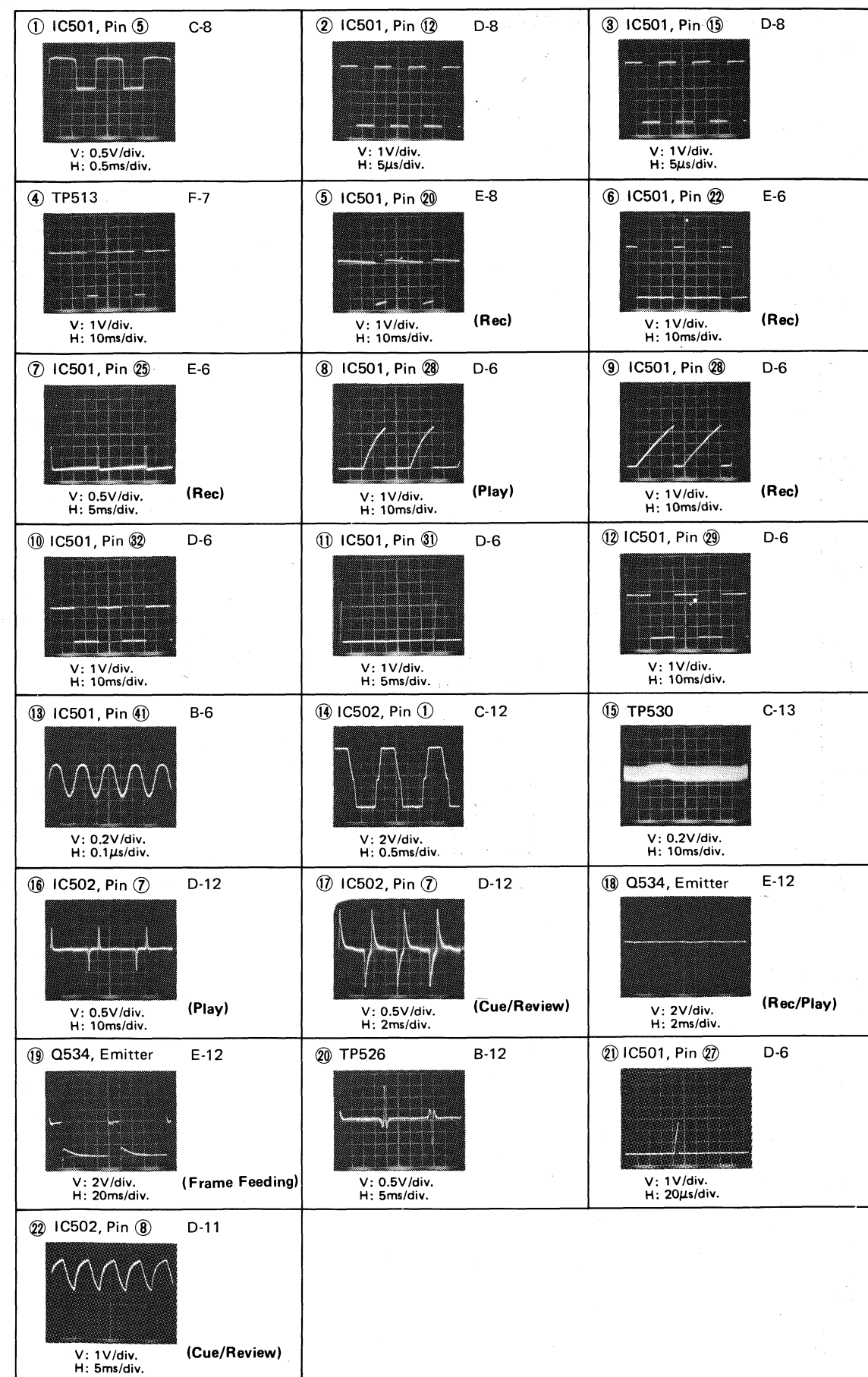
Symbol No.	Voltage(Unit:V)			Loca- tion
	E	C	B	
Q505	0	7.41(7.41)	0.01(0.01)	D-5
Q506	0	7.41(7.41)	0.01(0.01)	D-6
Q507	7.27(7.27)	7.41(7.41)	7.22(7.20)	D-6
Q508	0	0	0.4(5.04)	C-4
Q509	6.35(6.36)	2.53(2.52)	6.74(6.72)	D-6
Q510	0	7.22(7.20)	0.06(0.05)	D-5
Q511	0	5.12(0.01)	0.04(5.05)	C-4
Q512	0	2.53(3.58)	3.14(3.15)	D-5
Q513	0	0.01(2.38)	11.97(0.51)	C-4
Q514	0	3.63(3.61)	2.06(2.06)	E-4
Q516	4.59(5.10)	0.01(5.10)	5.12(0.01)	C-4
Q517	6.4(6.4)	1.8(1.8)	6.4(6.4)	D-6
Q533	3.95(3.92)	13.54(13.56)	5.18(5.04)	C-7
Q534	6.79(6.79)	13.56(13.56)	7.39(7.39)	E-6

V:REC
(V):PLAY

Symbol No.	Location
IC501	D-5
IC502	D-7
IC503	C-6

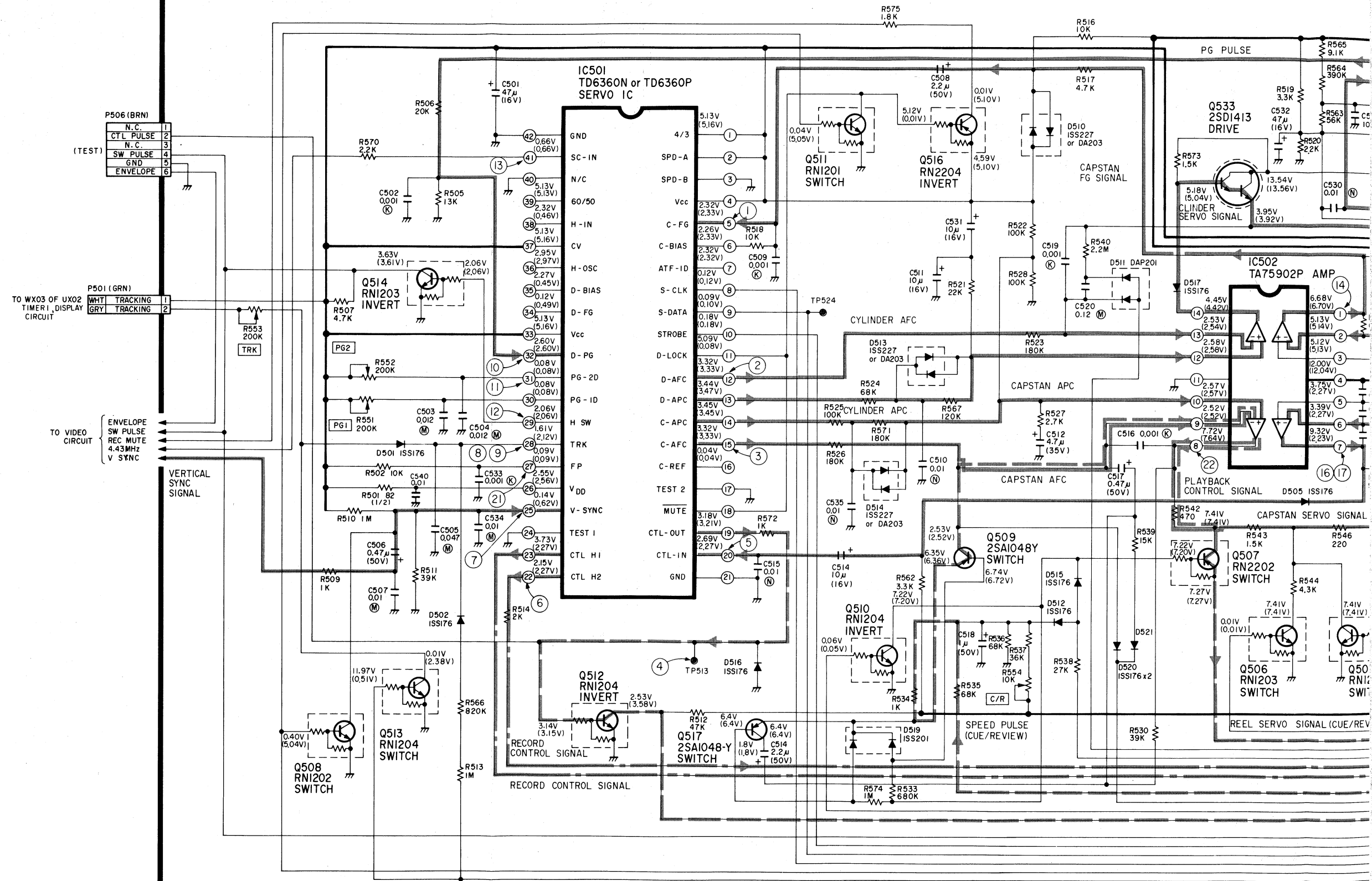
Symbol No.	Location
D501	D-4
D502	D-4
D505	E-6
D507	E-6
D508	E-7
D510	D-7
D511	D-6
D512	D-5
D513	C-5
D514	D-5
D515	D-5
D516	D-5
D517	C-7
D519	D-6
D520	C-6
D521	C-6

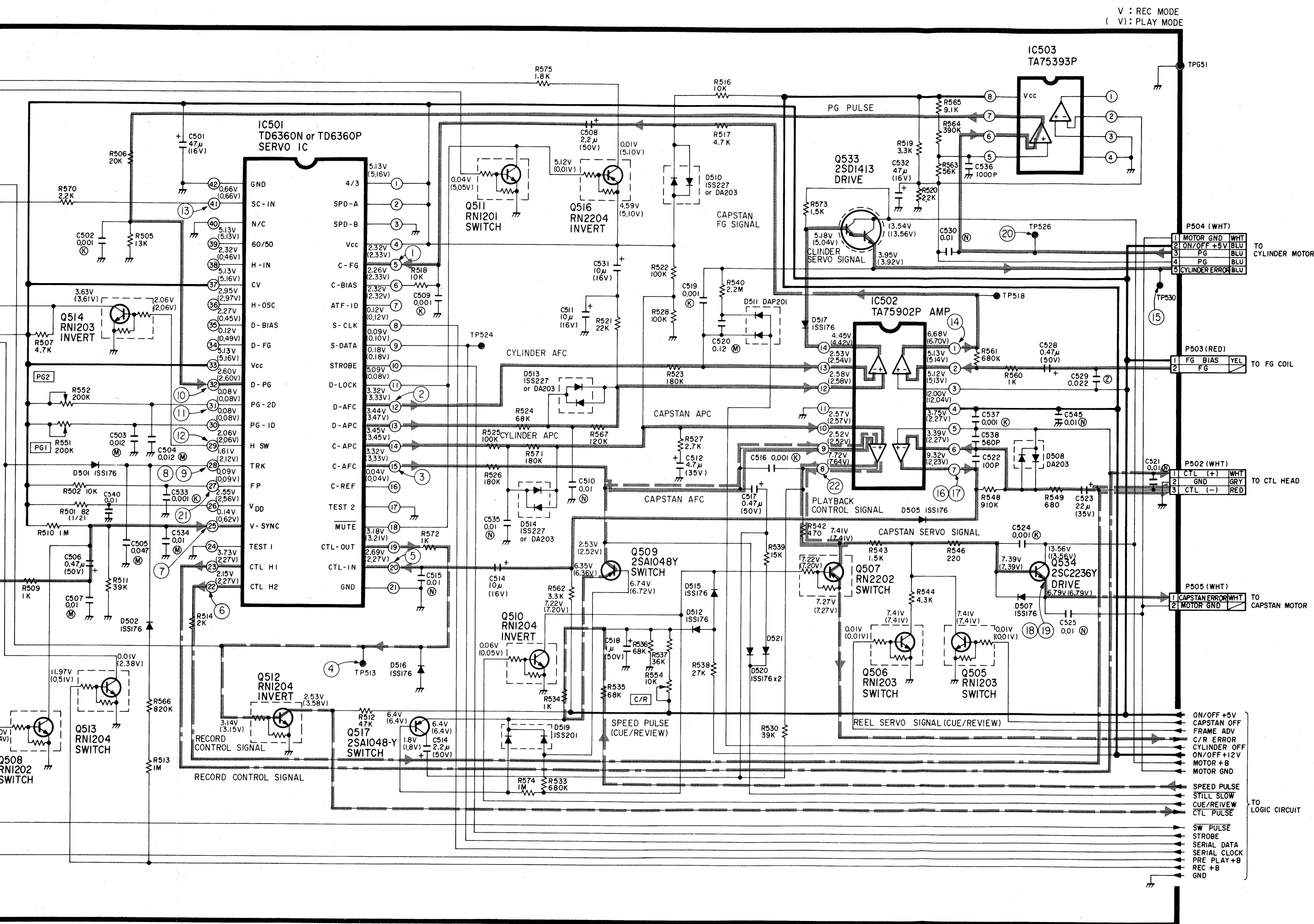
Symbol No.	Location
R551	C-4
R552	C-4
R553	D-4
R554	E-6



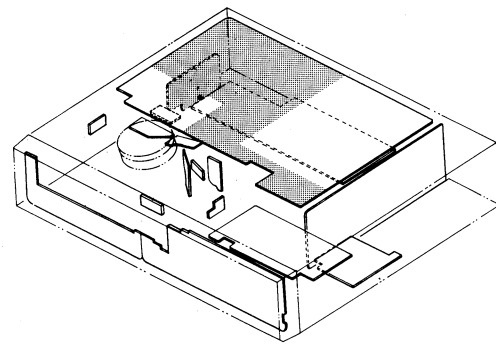
12-3. Servo Circuit

U202 SERVO





13-2. Video PC Board



U202 Video PC Board

To H002 RF Modulator
PC Board, P203

P204

1	—	7
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To U001 PIF PC Board, W303

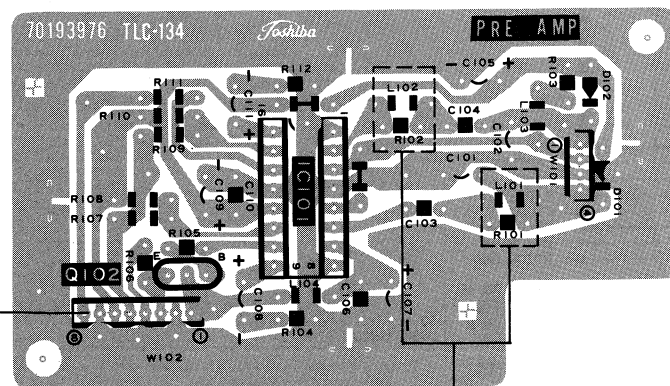
P205

1	2
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To UX02 Timer 1,
Display PC Board,
WX03

U101 Pre Amp PC Board



Note: L101, L102, R101, R102
are not used in V-81/83G.

Location of IC's

Symbol No.	Location
IC101	F-2
IC121	C-3
IC122	D-4
IC201	C-5
IC202	C-7
IC401	E-6
IC402	F-7
IC481	F-4

Location of Diodes

Symbol No.	Location
D101	F-3
D102	F-3
D121	D-6
D201	G-11
D202	D-5
D203	B-7
D204	C-7
D205	D-7
D206	C-8
D208	B-6
D209	B-6
D402	F-7
D403	G-6
D481	E-5

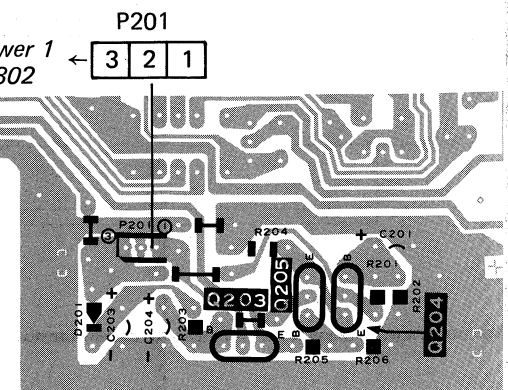
Location of VR's

Symbol No.	Location
R251	D-5
R252	C-5
R253	C-5
R254	D-5
R256	B-6
R259	D-3
R451	D-6
R453	F-6

Voltage and Location of Transistors

Symbol No.	Voltage(V)	
	E	C
Q102	0(2.0)	0(4.8)
Q124	1.2(0)	4.6(0.2)
Q125	0.9(0)	4.6(0.2)
Q126	4.0(0)	7.0(0.2)
Q127	0(0.4)	0.3(2.8)
Q128	0(0.4)	5.0(0.3)
Q129	0	0
Q130	5.0	0(0)
Q131	7.0(0.3)	9.7(12.0)
Q203	5.0	7.4
Q204	4.3	12.0
Q205	4.3	6.3
Q206	3.0(3.0)	5.0(5.0)
Q207	2.01(2.01)	4.70(4.70)
Q208	1.51(1.48)	0
Q209	0(0)	0.3(5.0)
Q210	0	0(0)
Q211	0	0.3(0.1)
Q212	0	0.3(5.0)
Q213	5.0	0.3(5.0)
Q214	5.0(5.0)	5.0(0)
Q215	5.0	—
Q216	5.0(5.0)	0.3(5.0)
Q217	0	5.0(0)
Q218	3.80(3.80)	1.80(1.76)
Q219	3.80(3.80)	1.80(1.76)
Q220	3.83(3.83)	2.67(2.69)
Q221	2.43(2.43)	0
Q403	0.8(0)	4.3(3.1)
Q404	0(0.8)	4.3(3.1)
Q405	0.8(0)	4.0(0)
Q406	1.5(0)	0
Q407	2.1(1.9)	0
Q408	1.5(1.5)	5.0
Q409	0	2.5(2.5)
Q410	1.5(1.5)<2.5>[2.5]	0.5(0.6)<0.3>[3.2][[3.2]
Q411	0	0(0.3)
Q412	2.3	5.0
Q413	1.8(1.8)	4.8(4.8)
Q414	5.0(5.0)	0(0)
Q482	—	—

To U802 Power 1
PC Board, P802

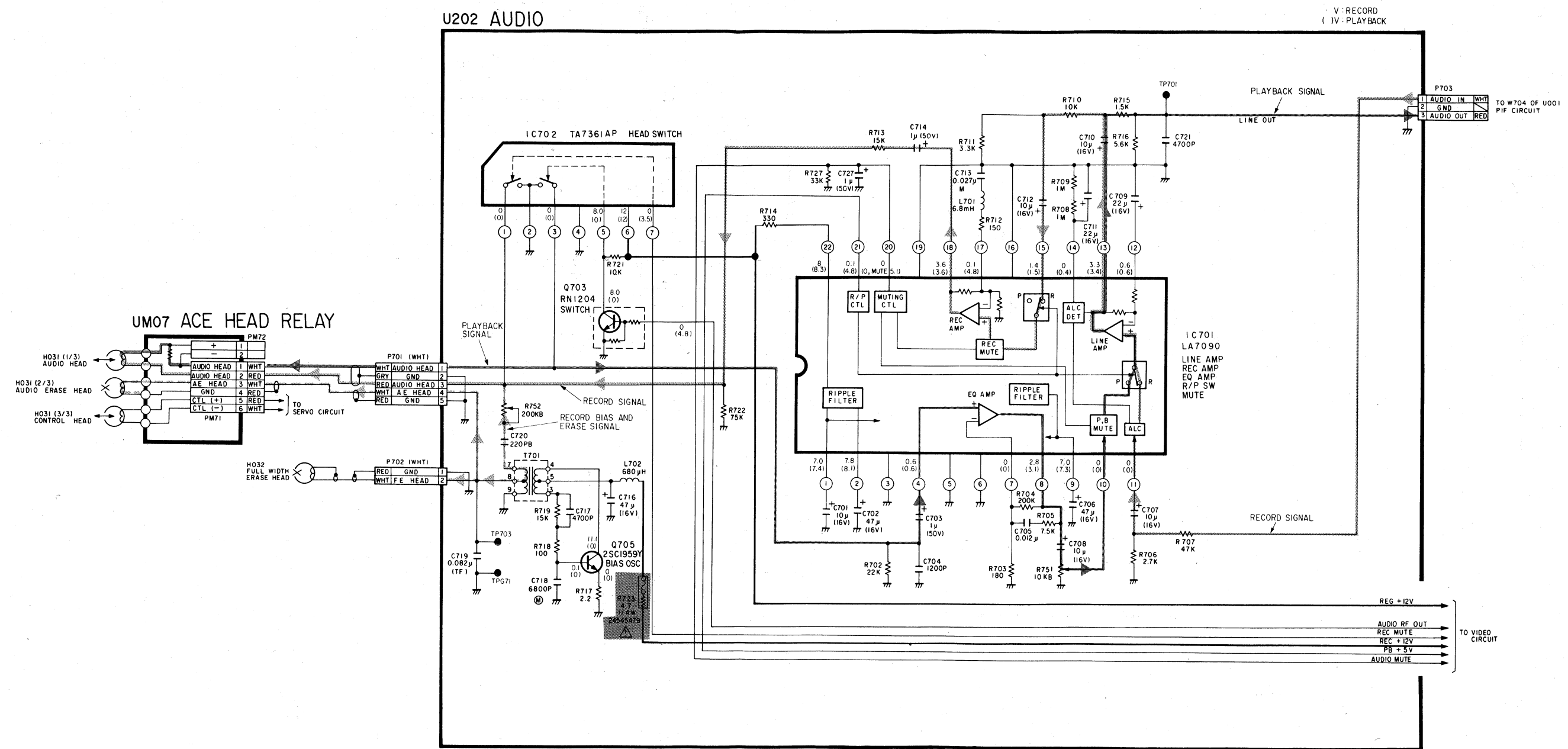
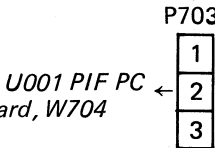
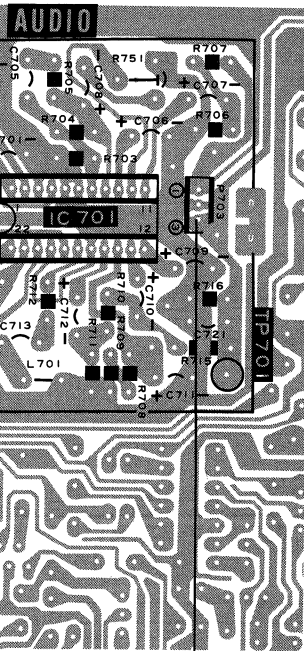


: PAL REC Mode (V)	PLAY Y SIGNAL	REC. Y SIGNAL
() : PAL PLAY Mode (V)		
< > : SECAM REC Mode (V)	PLAY C SIGNAL	REC. C SIGNAL
« » : SECAM PLAY Mode (V)		

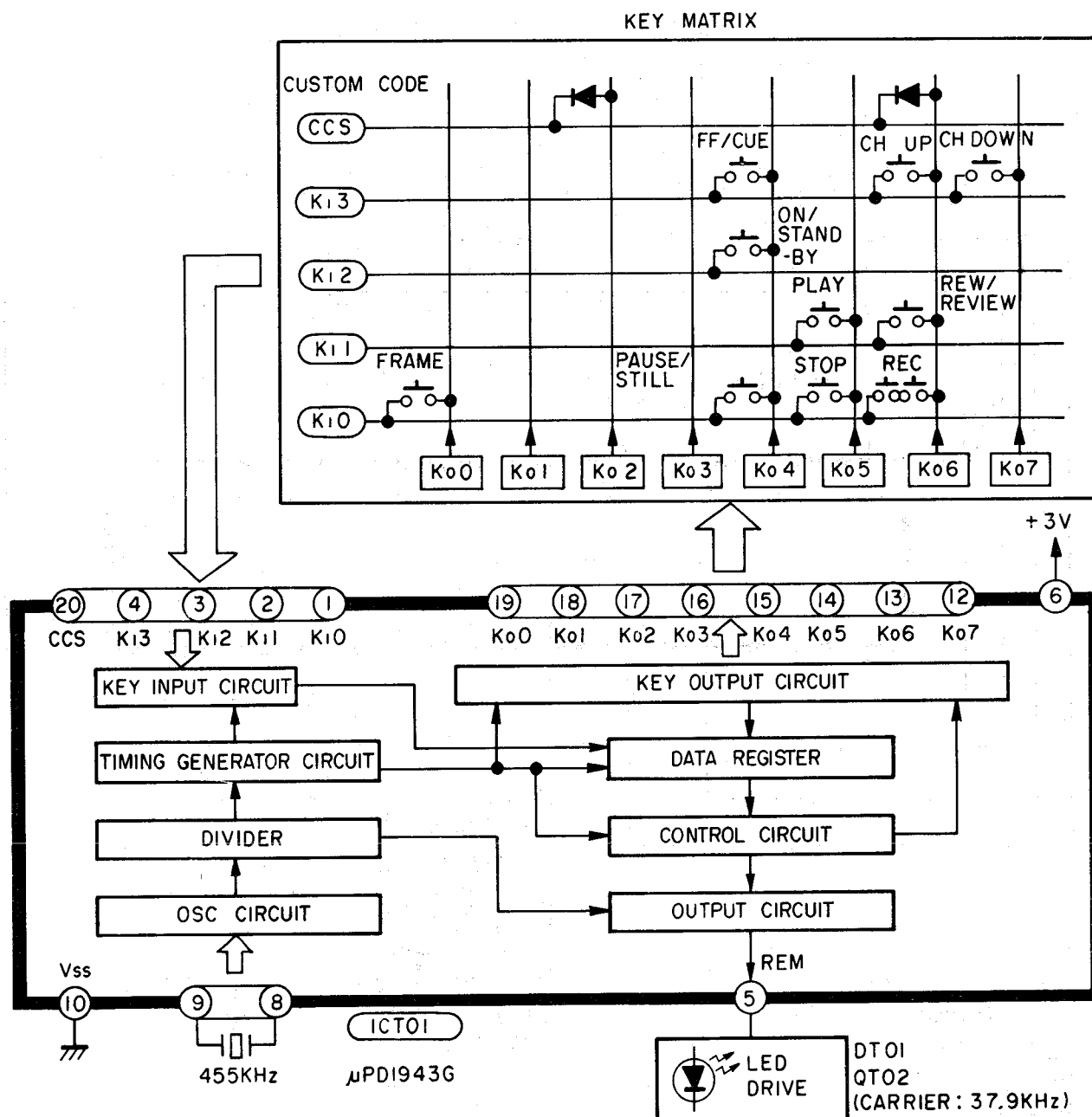


14-3. Audio Circuit

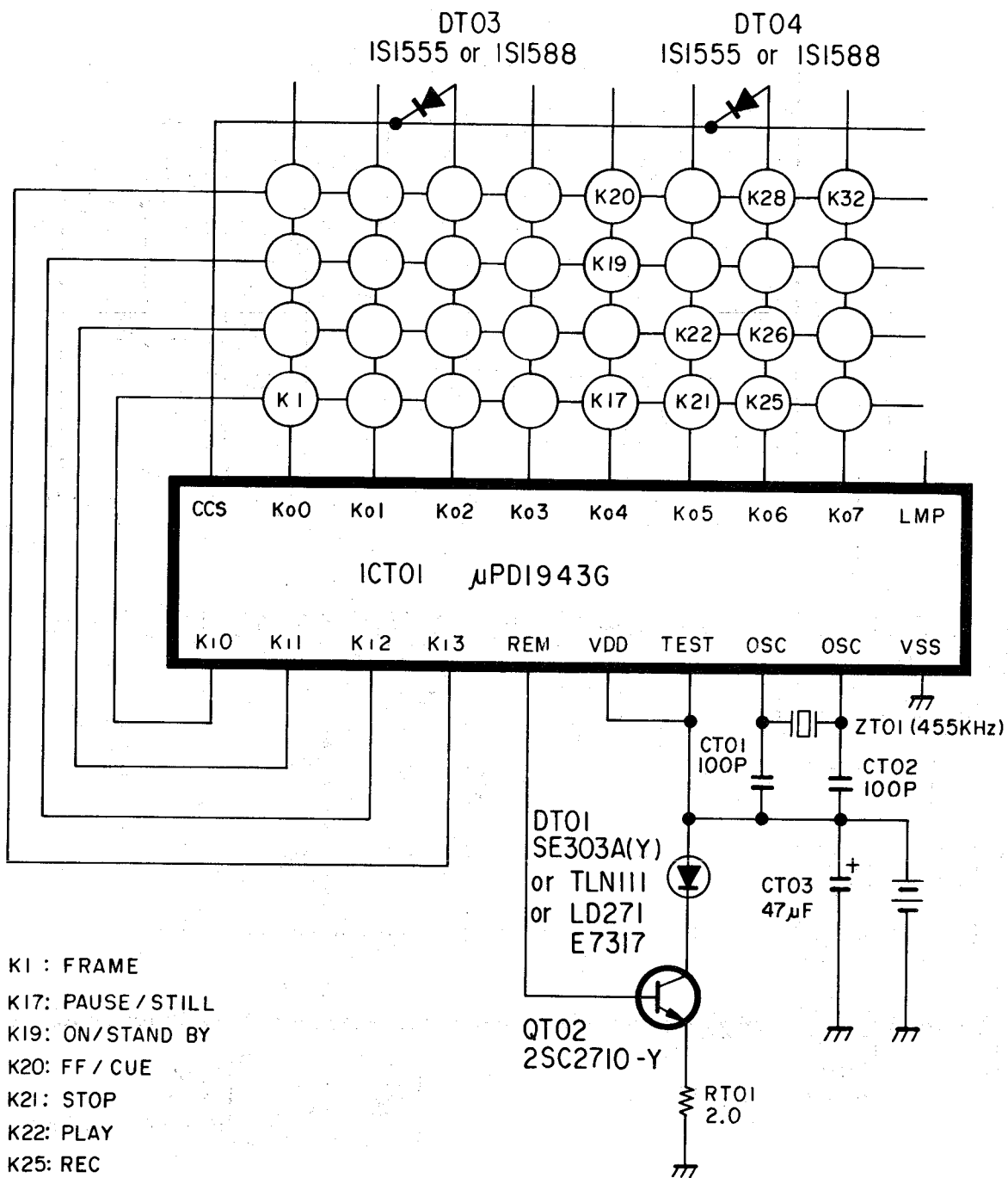
C Board



15-1. Remote Control Block Diagram

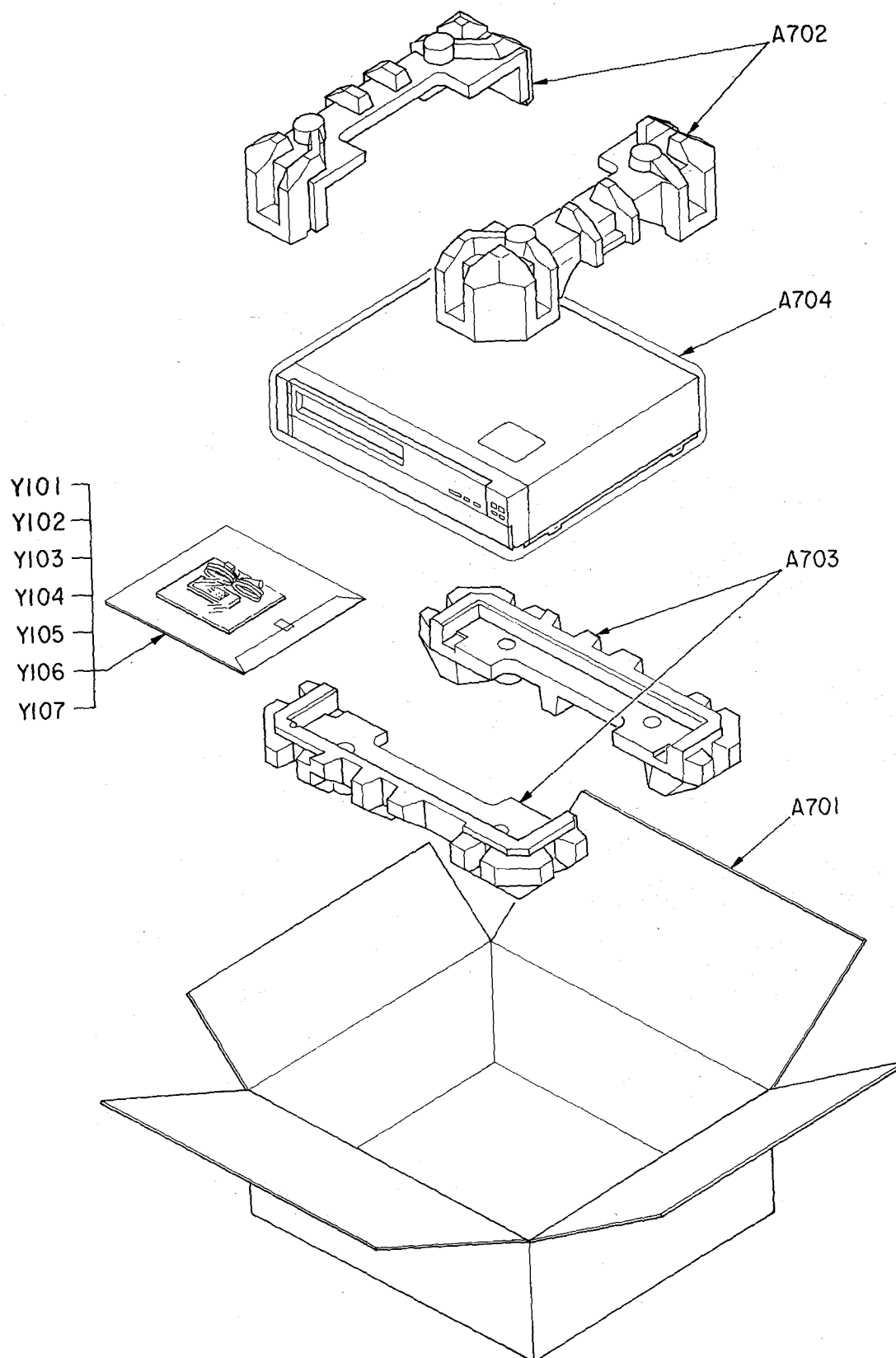


15-2. Remote Control Circuit

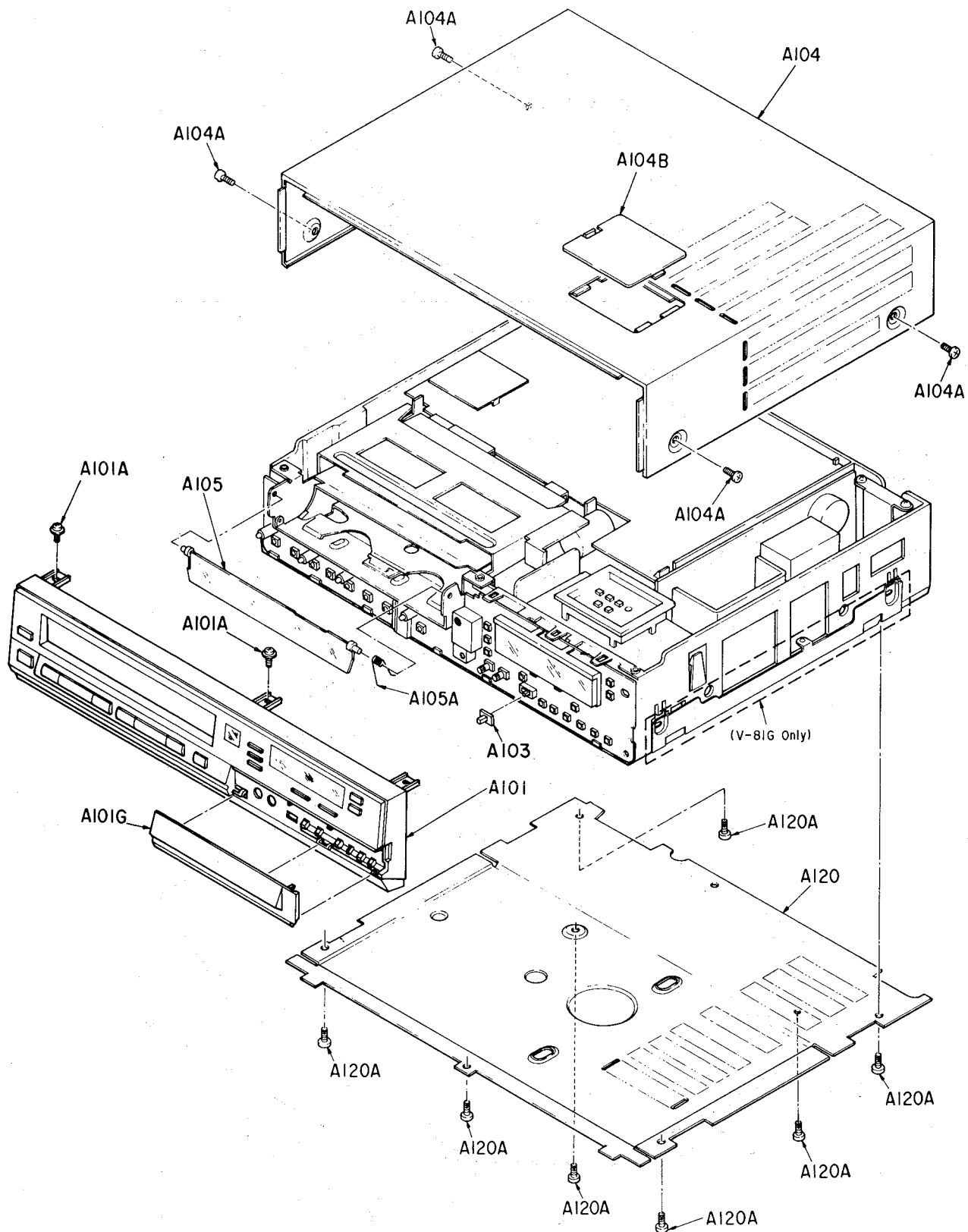


1.Exploded Views

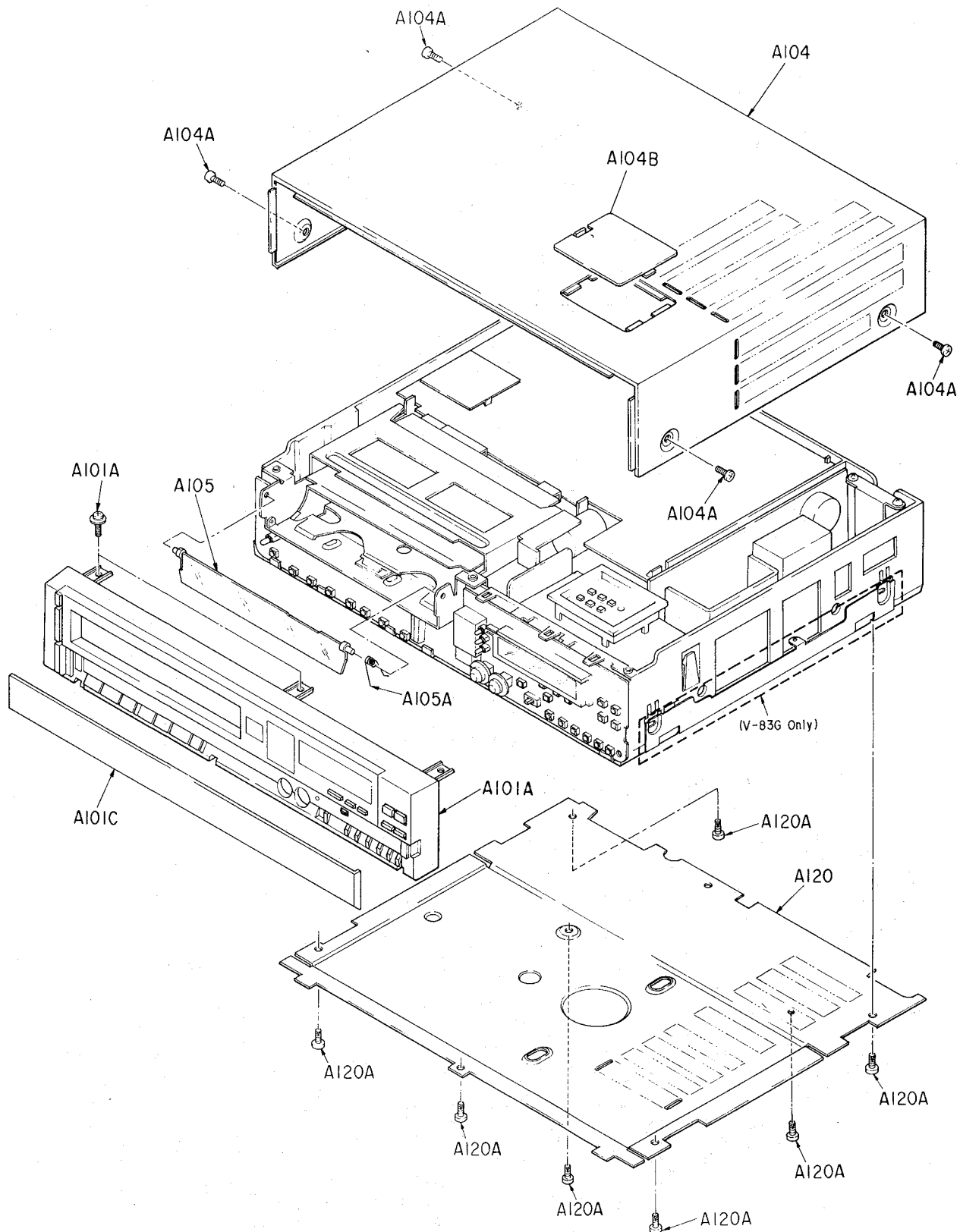
(1) Packing Assembly



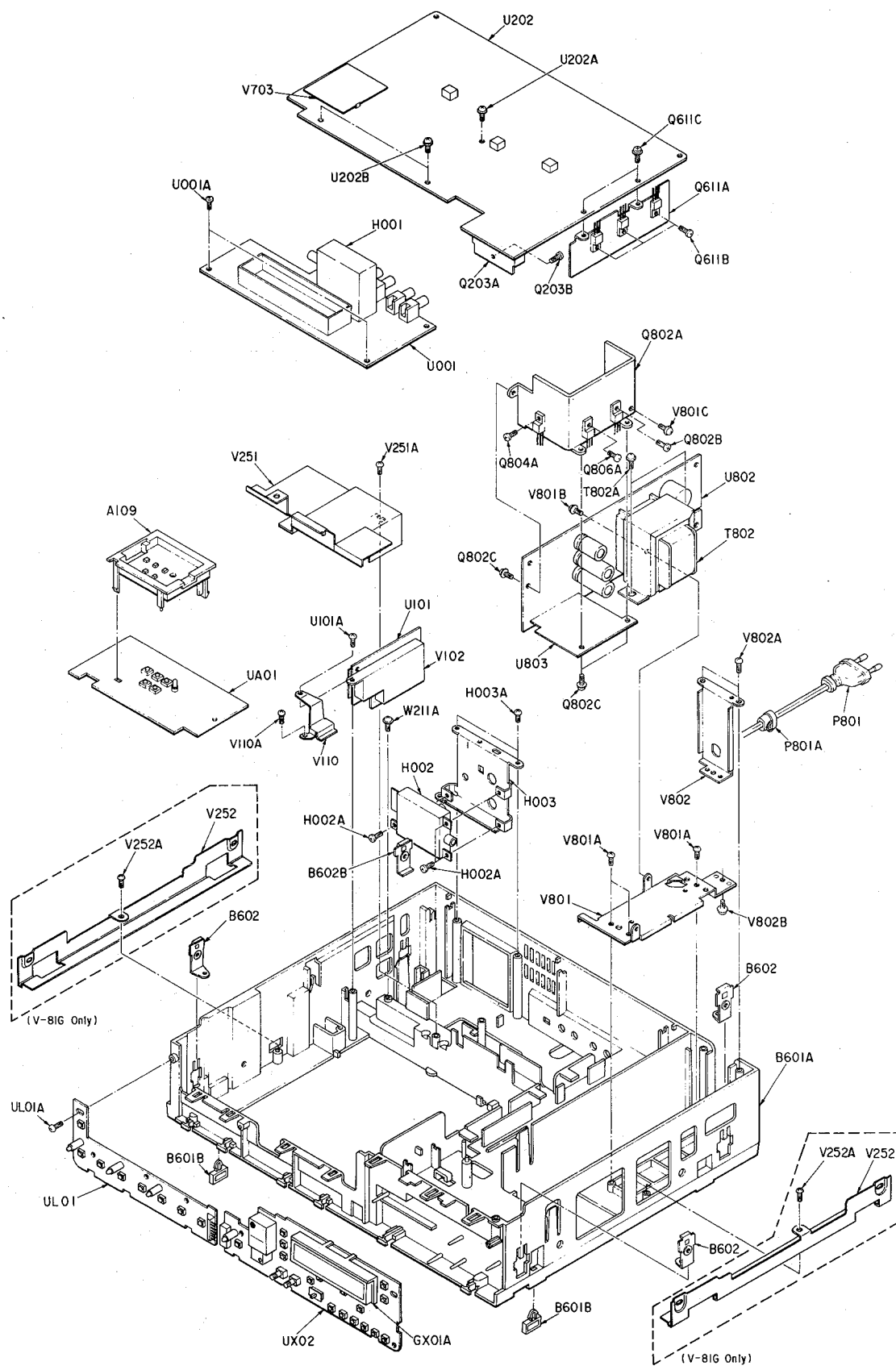
(2) Cabinet Assembly (V-81G/W)



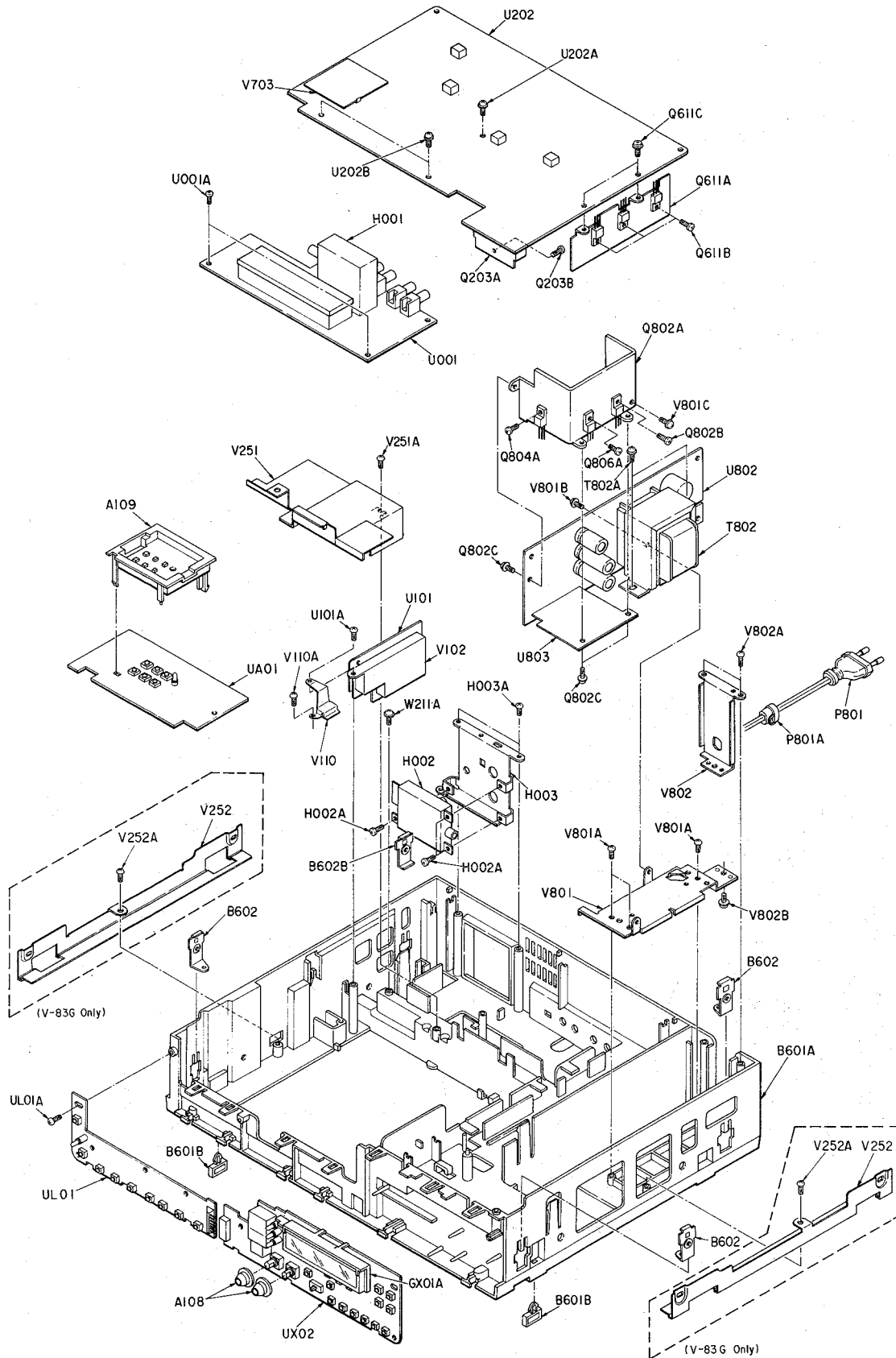
Cabinet Assembly (V-83G/W)



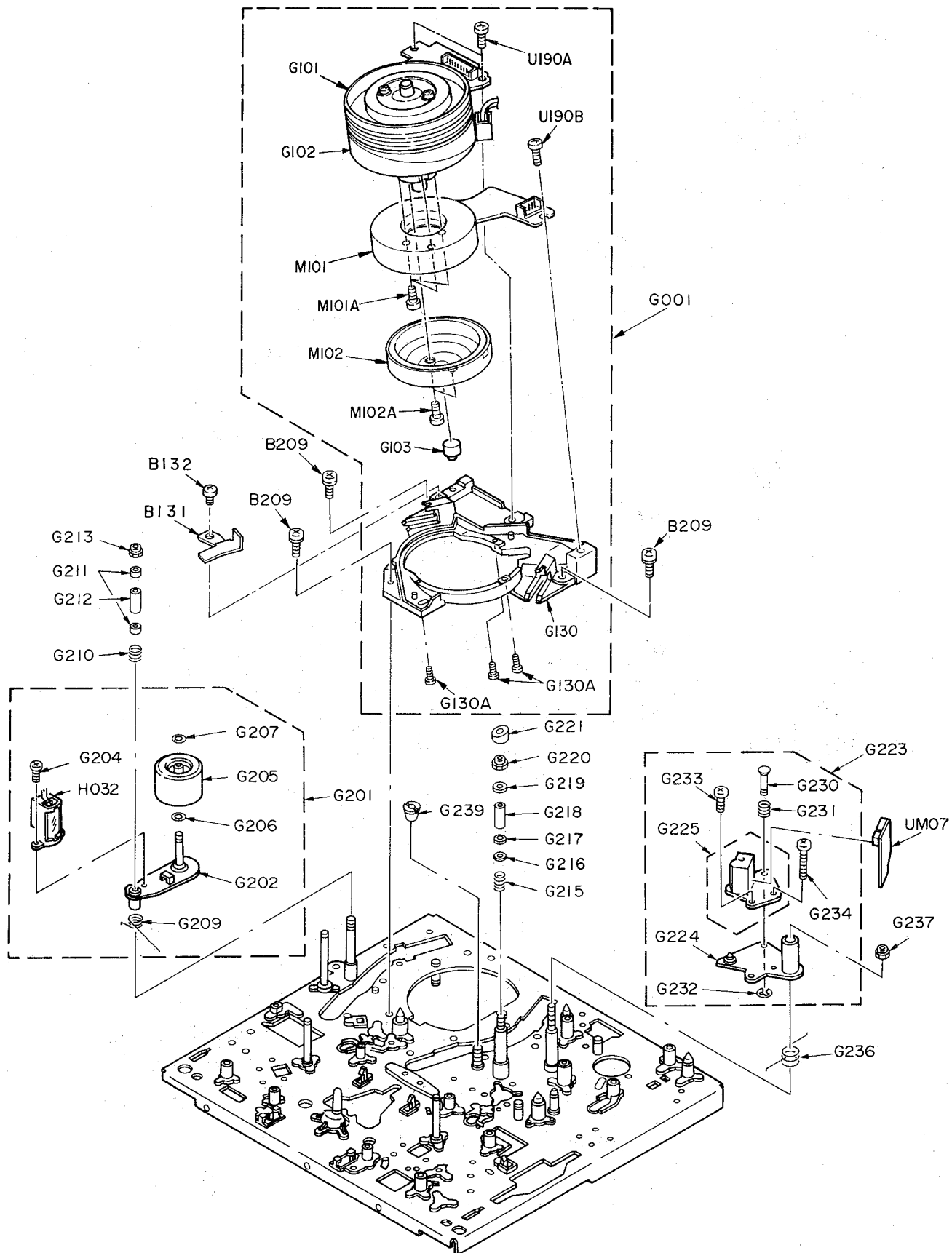
(3) Chassis Assembly (V-81G/W)



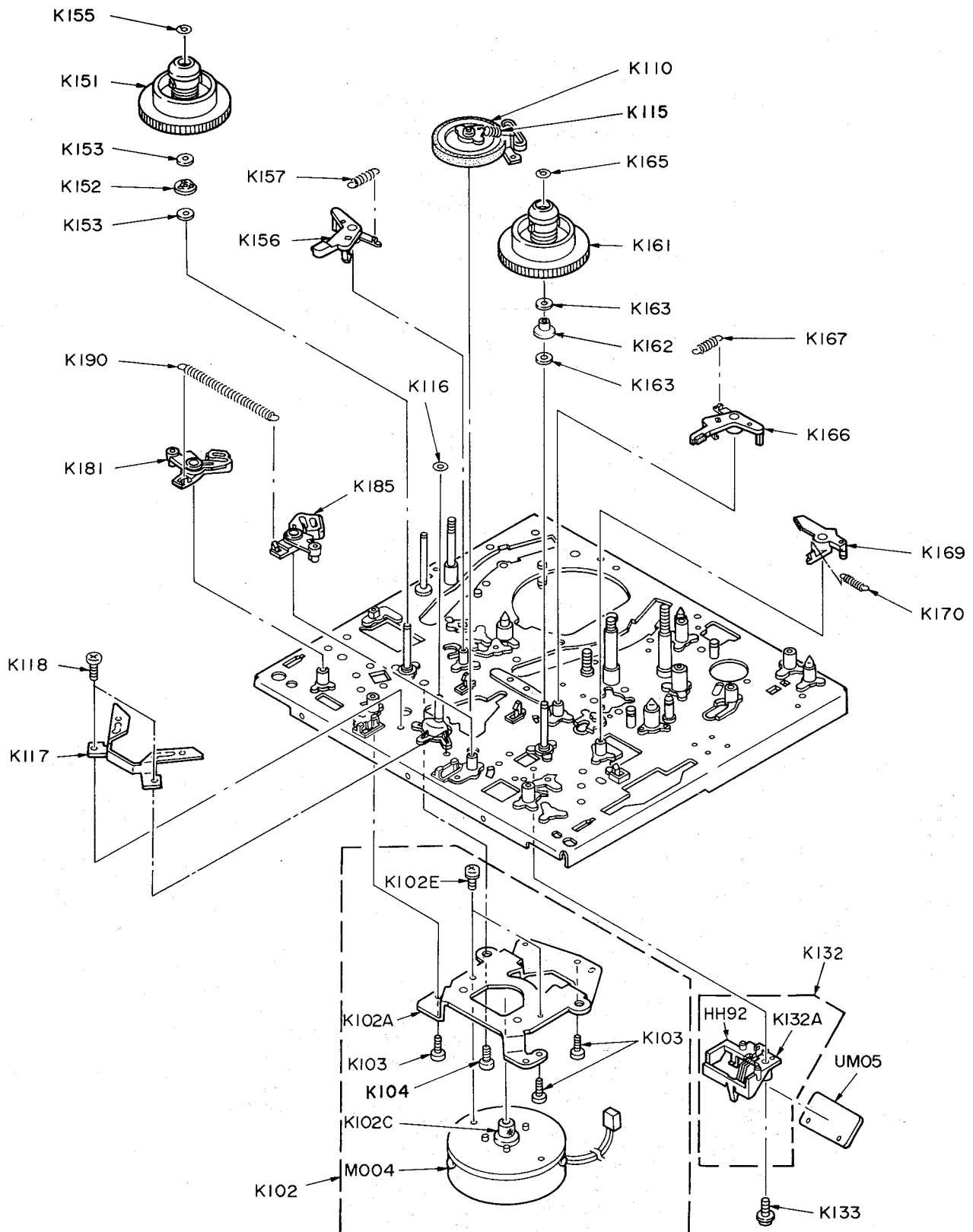
Chassis Assembly (V-83G/W)



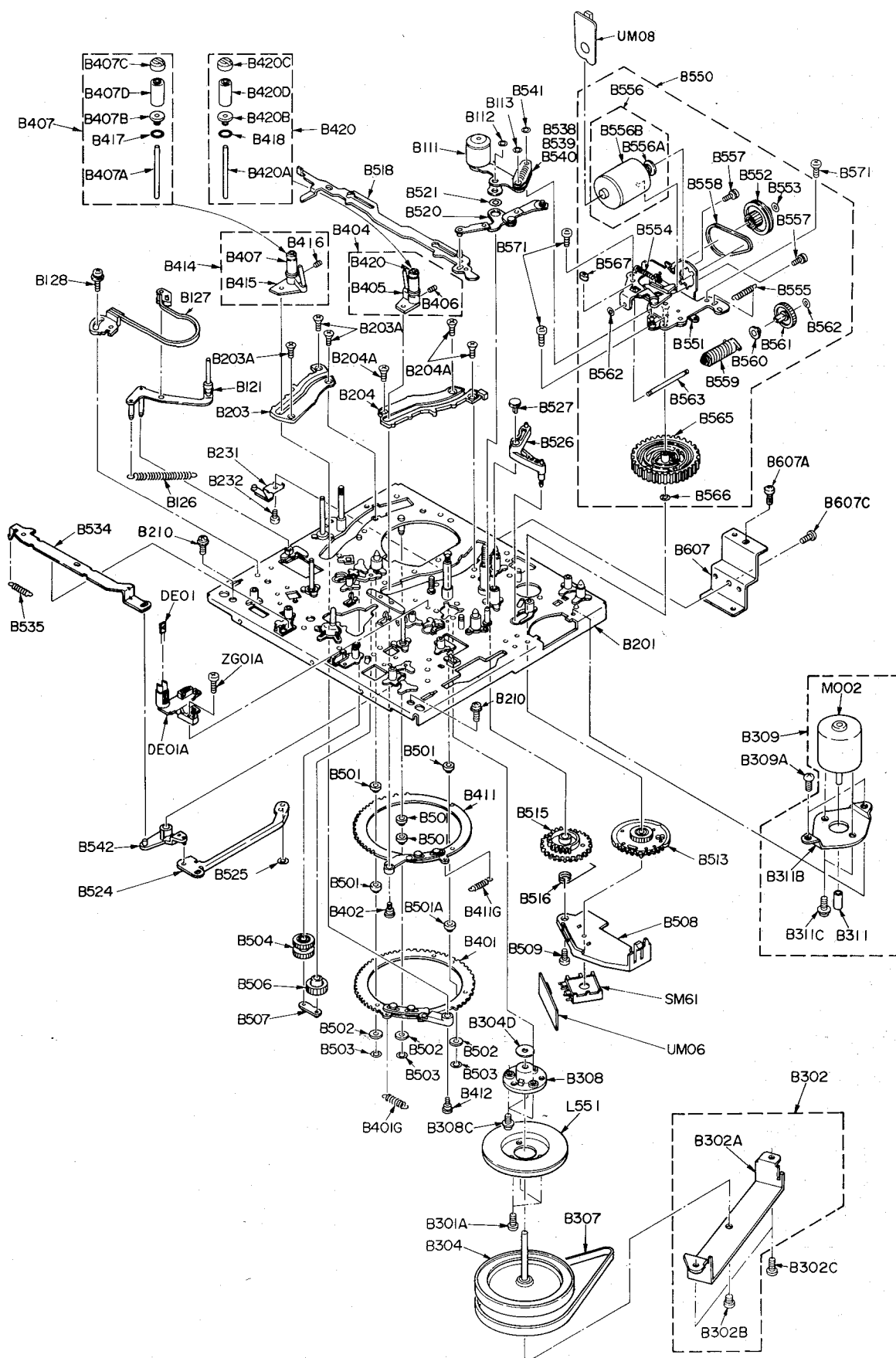
(5) Mechanical Parts (1)



(6) Mechanical Parts (2)



(7) Mechanical Parts (3)



2.Mechanical Parts List

NOTICE:The part number must be used when ordering parts. in order to assist in processing, be sure to include the model number and description.

LOCATION NUMBER	PART NUMBER	DESCRIPTION
A101	70812513	Front Panel,V-83G
A101	70812540	Front Panel,V-83W
A101	70812536	Front Panel,V-81G
A101	70812545	Front Panel,V-81W
A101C	70863571	Door,V-83G
A101C	70863524	Door,V-83W
A101G	70863584	Door,V-81W
A101G	70863596	Door,V-81G
A103	70826418	Knob,V-81W
A103	70816850	Knob,V-81G
A104	70824236	Top Cover,V-81/83G
A104	70824233	Top Cover,V-81/83W
A104B	70863573	Door,V-81/83G
A104B	70863598	Door,V-81/83W
A105	70863575	Door
A105A	70351679	Spring
A108	70816978	Knob,V-83G/W
A109	70843229	Cover,V-81/83G
A109	70843185	Cover,V-81/83W
A120	70815125	Bottom Cover,V-81/83G
A120	70815118	Bottom Cover,V-81/83W
A701	70913531	Case,V-81G
A701	70913609	Case,V-81W
A701	70913511	Case,V-83G
A701	70913533	Case,V-83W
A702	70921193	Packing (U)
A703	70921194	Packing (L)
B111	70323310	Pinch Roller Assy
B112	70396196	Washer,Fl 3. 6x8x 0. 5mm
B113	70396193	Washer,Fl 2. 6x6x 0. 5mm
B121	70328319	Tension Lever Assy
B126	70351687	Spring
B127	70321842	Band Brake Assy
B132	70391349	Screw, 2. 6x3mm
B210	70391081	Screw, 4x12mm
B231	70321858	Earth Brush Assy
B232	70391345	Screw, 3x3mm
B302B	70338038	Ball Bearing
B302C	70391049	Screw, 3x8mm
B304	70335057	Capstan Flywheel Assy
B304D	70396186	Capstan Sleeve CAP
B307	70342125	Capstan Belt
B309	70320152	Motor Assy
B309A	70391049	Screw, 3x8mm
B311C	23718001	Screw, 2. 6x4mm
B405	70322354	T Slider Sub Assy
B406	70391361	Screw, 2. 6x3mm
B407	70322353	S Guide Roller Assy
B415	70322333	S Slider Sub Assy
B416	70391361	Screw, 2. 6x3mm
B417	70353115	O-ring
B418	70353115	O-ring
B420	70322352	T Guide Roller Assy
B503	70396196	Washer,Fl 3. 6x8x 0. 5mm
B504	70333198	Loading Ring Gear(A)
B506	70333199	Loading Ring Gear(B)
B507	70368116	Double Cap
B513	70333195	Phase Gear
B515	70333196	Loading Drive Gear
B516	70351676	Spring
B521	70347034	Polislider 4. 1x 6. 5x 0. 50mm
B525	70396193	Washer,Fl 2. 6x6x 0. 5mm
B526	70323304	Cam Lever Assy
B527	70368122	Stopper
B535	70351683	Spring
B541	70396193	Washer,Fl 2. 6x6x 0. 5mm
B542	70363305	Lever
B550	70312180	Drive Assy
B553	70396064	Washer,5. 0x 2. 1x 0. 5mm

LOCATION NUMBER	PART NUMBER	DESCRIPTION
B554	70351641	Spring
B556	70312179	Loading Motor Assy
B556B	70125069	DC Motor,12V
B557	23723264	Screw, 2. 6x4mm
B558	70342123	Loading Belt
B562	70396191	Washer,2. 1x5x0.5mm
B565	70333197	Cam Gear
B566	70396193	Washer,Fl 2. 6x6x 0. 5mm
B607A	70391081	Screw, 4x12mm
DE01	70115406	Diode,LED CL450V
G001	70311328	Cylinder Assy
G101	70321968	Upper Cylinder Assy
G102	70321890	Lower Cylinder Assy
G103	70321601	Ground Cap Assy
G204	70391351	Screw, 2. 6x8mm
G205	70346035	Impedance Roller Assy
G206	70396050	Washer,3. 9x 2. 1x 0. 5mm
G207	70396190	Washer,Fl 1. 6x6x 0. 5mm
G209	70351694	Spring
G213	70393025	NUT, 3x3mm
G220	70393025	NUT, 3x3mm
G224	70328323	ACE Base T Assy
G225	70182056	ACE Sub Base Assy
G234	70391322	Adjust Screw
G236	70351666	Spring
G237	70393026	NUT, 3x4. 5mm
G239	70392015	Taper Nut
H001	70121061	Tuner,EG414X1
H001	70121057	Tuner,EG615X1
H002	70123075	RF Modulator,MMD151
H002	70123090	RF Modulator,MMD151X1
H003A	70391081	Screw, 4x12mm
H032	70183032	FE Head
HH92	A8090130	Hall Sensor,THS103A
K102	70326539	Reel Motor Assy
K110	70326538	Idler Assy
K115	70351703	Spring
K116	70396224	Polyslider,3. 6x7. 5x0. 5mm
K118	23723264	Screw, 2. 6x4mm
K132	70316142	T Sensor Assy
K151	70317042	S Reel Table Assy
K152	70338075	Bearing
K153	70394153	Spacer
K155	70396193	Washer,Fl 2. 6x6x 0. 5mm
K156	70363300	Lever
K157	70351700	Spring
K161	70317039	T Reel Table Assy
K162	70338100	Thrust Washer
K163	70394153	Spacer
K165	70396193	Washer,Fl 2. 6x6x 0. 5mm
K166	70326535	Lever Assy
K167	70351685	Spring
K169	70326533	Reverse Brake Assy
K170	70351706	Spring
K181	70326536	S Brake Assy
K185	70326537	T Brake Assy
K190	70351684	Spring
K301	70314236	Front Loading Assy
K301A	70391049	Screw, 3x8mm
K305	70396151	Washer,Fl 2. 6
K310	23723204	Screw, 2x4mm
K319	70396187	Washer,Fl 3. 6x12x0. 5mm
K321C	23723310	Screw, 3x10mm
K322A	70396195	Washer,Fl 3. 6x6x 0. 5mm
K323	70324321	Worm Gear Assy
K323C	70396152	Washer,Fl 1. 6
K323D	70396050	Washer,3. 9x 2. 1x 0. 5mm
K324	70324323	Motor Assy
K327	70338073	Bearing

3. Electrical Parts List

NOTICE: The part number must be used when ordering parts, in order to assist in processing, be sure to include the model number and description.

LOCATION NUMBER	PART NUMBER	DESCRIPTION		
PIF BOARD (V-81/83G)				
U001	70194960	P C Board Assy.PIF		
INTEGRATED CIRCUITS				
IC002	B0354710	IC	TA7607AP	
IC006	B0325290	IC	TA7337P	
TRANSISTORS				
Q001	A6708871	Transistor	2SC388ATM	
Q003	A6048370	Transistor.FET	2SK30ATMGR	
Q004	A6317440	Transistor	2SC1815-Y	
Q005	A6332430	Transistor	2SC2458-Y	
Q007	A6002060	Transistor	RN1206	
Q008	A6332430	Transistor	2SC2458-Y	
Q009	A6534430	Transistor	2SA1048-Y	
Q010	A6332440	Transistor	2SC2458-GR	
Q011	A6002020	Transistor	RN1202	
Q012	A6002020	Transistor	RN1202	
Q013	A6002020	Transistor	RN1202	
Q014	A6012020	Transistor	RN2202	
Q015	A6012020	Transistor	RN2202	
Q016	A6012020	Transistor	RN2202	
Q017	A6534430	Transistor	2SA1048-Y	
Q018	A6534430	Transistor	2SA1048-Y	
Q019	A6534430	Transistor	2SA1048-Y	
Q020	A6332440	Transistor	2SC2458-GR	
Q021	A6332430	Transistor	2SC2458-Y	
Q022	A6534430	Transistor	2SA1048-Y	
Q023	A6002020	Transistor	RN1202	
Q024	A6002020	Transistor	RN1202	
Q025	A6332430	Transistor	2SC2458-Y	
Q026	A6002040	Transistor	RN1204	
Q027	A6002040	Transistor	RN1204	
Q028	A6332430	Transistor	2SC2458-Y	
Q029	A6048370	Transistor.FET	2SK30ATMGR	
Q030	A6002020	Transistor	RN1202	
Q301	A6533240	Transistor	2SA966-Y	
Q302	A6332430	Transistor	2SC2458-Y	
Q303	A6332430	Transistor	2SC2458-Y	
DIODES				
D001	A7160570	Diode	1SS176	
D002	A7160570	Diode	1SS176	
D003	A7160570	Diode	1SS176	
D004	A7160570	Diode	1SS176	
COILS				
L002	23261985	Coil.Choke	TRF9221	
L003	23262856	Coil.Fixed	TRF1452	
L004	23237986	Coil.Peaking	TRF4120AC	
L005	23238921	Coil.Peaking	TRF4120AC	
L051	23262853	Coil.PIF	TRF1454	
L052	23262852	Coil.AFT	TRF1455	
L053	70256001	Coil.Discr	LCA01	
L054	23262782	Coil.IF	TRF1108	
L055	23262781	Coil.IF	TRF1109	
L056	23262781	Coil.IF	TRF1109	
L301	23238932	Coil.Peaking	TP4159AC	
CAPACITORS				
C001	24474103	Cap.Ceramic	0. 01MF	N 50V
C002	24474103	Cap.Ceramic	0. 01MF	N 50V
C003	24232103	Cap.Ceramic	0. 01MF	Z 50V
C004	24474103	Cap.Ceramic	0. 01MF	N 50V
C005	24474102	Cap.Ceramic	1000PF	K 50V
C006	24636478	Cap.Electrolytic	0. 47MF	M 50V
C007	24436010	Cap.Ceramic	1PF	J 50V
C008	24436159	Cap.Ceramic	1. 5PF	J 50V
C009	24436160	Cap.Ceramic	16PF	J 50V
C010	24794470	Cap.Electrolytic	47MF	M 16V
C011	24232103	Cap.Ceramic	0. 01MF	Z 50V
C012	24636339	Cap.Electrolytic	3. 3MF	M 50V
C013	24636339	Cap.Electrolytic	3. 3MF	M 50V

LOCATION NUMBER	PART NUMBER	DESCRIPTION		
C014	24636479	Cap. Electrolytic	4. 7MF	M 50V
C015	24436181	Cap. Ceramic	180PF	J 50V
C016	24797220	Cap. Electrolytic	22MF	M 50V
C017	24473470	Cap. Ceramic	47PF	J 50V
C018	24473470	Cap. Ceramic	47PF	J 50V
C019	24474103	Cap. Ceramic	0. 01MF	N 50V
C020	24636100	Cap. Electrolytic	10MF	M 50V
C021	24340300	Cap. Ceramic	30PF	J 50V
C022	24591682	Cap. Plastic	6800PF	J 50V
C023	24636100	Cap. Electrolytic	10MF	M 50V
C024	24436020	Cap. Ceramic	2PF	J 50V
C025	24232223	Cap. Ceramic	0. 022MF	Z 50V
C026	24232103	Cap. Ceramic	0. 01MF	Z 50V
C027	24232223	Cap. Ceramic	0. 022MF	Z 50V
C028	24591223	Cap. Plastic	0. 022MF	J 50V
C029	24636010	Cap. Electrolytic	1MF	M 50V
C030	24636010	Cap. Electrolytic	1MF	M 50V
C031	24232223	Cap. Ceramic	0. 022MF	Z 50V
C033	24353150	Cap. Ceramic	15PF	J 50V
C039	24636479	Cap. Electrolytic	4. 7MF	M 50V
C723	24436220	Cap. Ceramic	22PF	J 50V
RESISTORS				
R001	24366101	Res. Carbon	100	J 1/6W
R002	24366221	Res. Carbon	220	J 1/6W
R003	24366123	Res. Carbon	12K	J 1/6W
R004	24366471	Res. Carbon	470	J 1/6W
R005	24366202	Res. Carbon	2K	J 1/6W
R006	24366270	Res. Carbon	27	J 1/6W
R007	24366182	Res. Carbon	1. 8K	J 1/6W
R008	24366392	Res. Carbon	3. 9K	J 1/6W
R009	24366913	Res. Carbon	91K	J 1/6W
R010	24366271	Res. Carbon	270	J 1/6W
R011	24366824	Res. Carbon	820K	J 1/6W
R012	24366202	Res. Carbon	2K	J 1/6W
R013	24366471	Res. Carbon	470	J 1/6W
R014	24366103	Res. Carbon	10K	J 1/6W
R015	24366821	Res. Carbon	820	J 1/6W
R016	24366241	Res. Carbon	240	J 1/6W
R017	24366241	Res. Carbon	240	J 1/6W
R018	24366910	Res. Carbon	91	J 1/6W
R019	24366103	Res. Carbon	10K	J 1/6W
R020	24366202	Res. Carbon	2K	J 1/6W
R021	24366102	Res. Carbon	1K	J 1/6W
R022	24366102	Res. Carbon	1K	J 1/6W
R023	24366153	Res. Carbon	15K	J 1/6W
R024	24366242	Res. Carbon	2. 4K	J 1/6W
R025	24366182	Res. Carbon	1. 8K	J 1/6W
R026	24366105	Res. Carbon	1M	J 1/6W
R027	24366103	Res. Carbon	10K	J 1/6W
R028	24366474	Res. Carbon	470K	J 1/6W
R029	24366154	Res. Carbon	150K	J 1/6W
R030	24366164	Res. Carbon	160K	J 1/6W
R031	24366622	Res. Carbon	6. 2K	J 1/6W
R032	24366474	Res. Carbon	470K	J 1/6W
R033	24366363	Res. Carbon	36K	J 1/6W
R034	24366302	Res. Carbon	3K	J 1/6W
R035	24366242	Res. Carbon	2. 4K	J 1/6W
R036	24366512	Res. Carbon	5. 1K	J 1/6W
R037	24366333	Res. Carbon	33K	J 1/6W
R038	24366333	Res. Carbon	33K	J 1/6W
R039	24366164	Res. Carbon	160K	J 1/6W
R040	24366164	Res. Carbon	160K	J 1/6W
R041	24366683	Res. Carbon	68K	J 1/6W
R042	24366623	Res. Carbon	62K	J 1/6W
R043	24366184	Res. Carbon	180K	J 1/6W
R044	24366622	Res. Carbon	6. 2K	J 1/6W
R045	24366103	Res. Carbon	10K	J 1/6W
R046	24366474	Res. Carbon	470K	J 1/6W
R047	24366333	Res. Carbon	33K	J 1/6W

LOCATION NUMBER	PART NUMBER	DESCRIPTION			
R048	24366332	Res.Carbon	3. 3K	J 1/6W	
R049	24366151	Res.Carbon	150	J 1/6W	
R051	24066947	Res.Variable	500K		
R052	24066953	Res.Variable	100K		
R060	24366270	Res.Carbon	27	J 1/6W	
R061	24366103	Res.Carbon	10K	J 1/6W	
R062	24366331	Res.Carbon	330	J 1/6W	
R063	24366331	Res.Carbon	330	J 1/6W	
R064	24366101	Res.Carbon	100	J 1/6W	
R065	24366104	Res.Carbon	100K	J 1/6W	
R066	24366104	Res.Carbon	100K	J 1/6W	
R067	24366914	Res.Carbon	910K	J 1/6W	
R068	24366224	Res.Carbon	220K	J 1/6W	
R069	24366105	Res.Carbon	1M	J 1/6W	
R301	24366750	Res.Carbon	75	J 1/6W	
R302	24366103	Res.Carbon	10K	J 1/6W	
R303	24366202	Res.Carbon	2K	J 1/6W	
R304	24366223	Res.Carbon	22K	J 1/6W	
R305	24366223	Res.Carbon	22K	J 1/6W	
R306	24366223	Res.Carbon	22K	J 1/6W	
R307	24366202	Res.Carbon	2K	J 1/6W	
R725	24366152	Res.Carbon	1. 5K	J 1/6W	
R726	24366152	Res.Carbon	1. 5K	J 1/6W	
MISCELLANEOUS					
P301	23363526	Phono Jack			
P302	23363525	Phono Jack			
P710	23363254	Phono Jack			
P711	23363253	Phono Jack			
S301	23145436	Slide Switch. 2C2P			
Z001	A5611192	Filter. PIF. F1037C			
Z002	23107972	Video Trap. 5. 5MHz			
Z003	23107947	Filter. SIF. 5. 5MHz			
PIF BOARD (V-81/83W)					
U001	70194932	P C Board Assy. PIF			
INTEGRATED CIRCUITS					
IC002	B0354710	IC	TA7607AP		
IC005	B0325290	IC	TA7337P		
TRANSISTORS					
Q001	A6708871	Transistor	2SC388ATM		
Q003	A6317440	Transistor	2SC1815-Y		
Q006	A6002060	Transistor	RN1206		
Q007	A6332430	Transistor	2SC2458-Y		
Q008	A6332430	Transistor	2SC2458-Y		
Q009	A6534430	Transistor	2SA1048-Y		
Q061	A6048350	Transistor. FET	2SK30ATM		
Q062	A6332430	Transistor	2SC2458-Y		
Q063	A6002020	Transistor	RN1202		
Q064	A6002020	Transistor	RN1202		
Q065	A6002020	Transistor	RN1202		
Q066	A6012020	Transistor	RN2202		
Q067	A6012020	Transistor	RN2202		
Q068	A6332430	Transistor	2SC2458-Y		
Q069	A6332440	Transistor	2SC2458-GR		
Q070	A6332440	Transistor	2SC2458-GR		
Q071	A6534430	Transistor	2SA1048-Y		
Q072	A6048370	Transistor. FET	2SK30ATMGR		
Q073	A6534430	Transistor	2SA1048-Y		
Q074	A6534430	Transistor	2SA1048-Y		
Q075	A6534430	Transistor	2SA1048-Y		
Q076	A6002020	Transistor	RN1202		
Q077	A6002020	Transistor	RN1202		
Q078	A6534440	Transistor	2SA1048-GR		
Q301	A6533240	Transistor	2SA966-Y		
Q302	A6332430	Transistor	2SC2458-Y		
Q303	A6332430	Transistor	2SC2458-Y		
DIODES					
D001	A7160570	Diode	1SS176		
D002	A7160570	Diode	1SS176		
D061	A7160570	Diode	1SS176		
D062	A7160570	Diode	1SS176		
D063	A7160570	Diode	1SS176		
COILS					
L001	23261983	Coil. Choke	TRF9223		
L002	23261985	Coil. Choke	TRF9221		

LOCATION NUMBER	PART NUMBER	DESCRIPTION			
L003	23262856	Coil. Fixed	TRF1452		
L004	23237986	Coil. Peaking	TRF4120AC		
L005	23238921	Coil. Peaking	TRF4120AC		
L051	23262853	Coil. PIF	TRF1454		
L052	23262852	Coil. AFT	TRF1455		
L053	70256001	Coil. Discr	LCA01		
L301	23238932	Coil. Peaking	TRF4159AC		
CAPACITORS					
C001	24474103	Cap. Ceramic	0. 01MF	N 50V	
C002	24474103	Cap. Ceramic	0. 01MF	N 50V	
C003	24474103	Cap. Ceramic	0. 01MF	N 50V	
C004	24474103	Cap. Ceramic	0. 01MF	N 50V	
C005	24474102	Cap. Ceramic	1000PF	K 50V	
C006	24636478	Cap. Electrolytic	0. 47MF	M 50V	
C007	24436159	Cap. Ceramic	1. 5PF	J 50V	
C008	24436010	Cap. Ceramic	1PF	J 50V	
C009	24436160	Cap. Ceramic	16PF	J 50V	
C010	24794470	Cap. Electrolytic	47MF	M 16V	
C011	24232103	Cap. Ceramic	0. 01MF	Z 50V	
C014	24636479	Cap. Electrolytic	4. 7MF	M 50V	
C015	24436820	Cap. Ceramic	82PF	J 50V	
C017	24473470	Cap. Ceramic	47PF	J 50V	
C018	24473470	Cap. Ceramic	47PF	J 50V	
C019	24474103	Cap. Ceramic	0. 01MF	N 50V	
C020	24636100	Cap. Electrolytic	10MF	M 50V	
C021	24340430	Cap. Ceramic	43PF	J 50V	
C022	24591682	Cap. Plastic	6800PF	J 50V	
C023	24636100	Cap. Electrolytic	10MF	M 50V	
C030	24232223	Cap. Ceramic	0. 022MF	Z 50V	
C031	24797220	Cap. Electrolytic	22MF	M 50V	
C032	24636478	Cap. Electrolytic	0. 47MF	M 50V	
C033	24794470	Cap. Electrolytic	47MF	M 16V	
C061	24232103	Cap. Ceramic	0. 01MF	Z 50V	
C062	24636339	Cap. Electrolytic	3. 3MF	M 50V	
C063	24636339	Cap. Electrolytic	3. 3MF	M 50V	
C723	24436220	Cap. Ceramic	22PF	J 50V	
RESISTORS					
R001	24366750	Res. Carbon	75	J 1/6W	
R002	24366301	Res. Carbon	300	J 1/6W	
R003	24366562	Res. Carbon	5. 8K	J 1/6W	
R004	24366471	Res. Carbon	470	J 1/6W	
R005	24366102	Res. Carbon	1K	J 1/6W	
R006	24366270	Res. Carbon	27	J 1/6W	
R007	24366821	Res. Carbon	820	J 1/6W	
R008	24366392	Res. Carbon	3. 9K	J 1/6W	
R009	24366683	Res. Carbon	68K	J 1/6W	
R010	24366221	Res. Carbon	220	J 1/6W	
R011	24366824	Res. Carbon	820K	J 1/6W	
R012	24366512	Res. Carbon	5. 1K	J 1/6W	
R013	24366151	Res. Carbon	150	J 1/6W	
R014	24366202	Res. Carbon	2K	J 1/6W	
R015	24366821	Res. Carbon	820	J 1/6W	
R016	24366241	Res. Carbon	240	J 1/6W	
R017	24366241	Res. Carbon	240	J 1/6W	
R018	24366111	Res. Carbon	110	J 1/6W	
R021	24366102	Res. Carbon	1K	J 1/6W	
R022	24366102	Res. Carbon	1K	J 1/6W	
R023	24366103	Res. Carbon	10K	J 1/6W	
R024	24366202	Res. Carbon	2K	J 1/6W	
R025	24366202	Res. Carbon	2K	J 1/6W	
R030	24366622	Res. Carbon	6. 2K	J 1/6W	
R031	24366103	Res. Carbon	10K	J 1/6W	
R032	24366202	Res. Carbon	2K	J 1/6W	
R034	24366821	Res. Carbon	820	J 1/6W	
R035	24366561	Res. Carbon	560	J 1/6W	
R036	24366911	Res. Carbon	910	G 1/6W	
R037	24366824	Res. Carbon	820K	J 1/6W	
R038	24366182	Res. Carbon	1. 8K	J 1/6W	
R039	24366152	Res. Carbon	1. 5K	J 1/6W	
R040	24366333	Res. Carbon	33K	J 1/6W	
R041	24366333	Res. Carbon	33K	J 1/6W	
R051	24066947	Res. Variable	500K		
R052	24066953	Res. Variable	100K		
R061	24366105	Res. Carbon	1M	J 1/6W	
R062	24366203	Res. Carbon	20K	J 1/6W	

LOCATION NUMBER	PART NUMBER	DESCRIPTION		
R063	24366204	Res. Carbon	200K	J 1/6W
R064	24366363	Res. Carbon	36K	J 1/6W
R065	24366154	Res. Carbon	150K	J 1/6W
R066	24366154	Res. Carbon	150K	J 1/6W
R068	24366273	Res. Carbon	27K	J 1/6W
R069	24366432	Res. Carbon	4. 3K	J 1/6W
R070	24366562	Res. Carbon	5. 6K	J 1/6W
R071	24366562	Res. Carbon	5. 6K	J 1/6W
R072	24366513	Res. Carbon	51K	J 1/6W
R073	24366513	Res. Carbon	51K	J 1/6W
R074	24366105	Res. Carbon	1M	J 1/6W
R075	24366204	Res. Carbon	200K	J 1/6W
R076	24366204	Res. Carbon	200K	J 1/6W
R077	24366154	Res. Carbon	150K	J 1/6W
R078	24366154	Res. Carbon	150K	J 1/6W
R079	24366563	Res. Carbon	56K	J 1/6W
R080	24366623	Res. Carbon	62K	J 1/6W
R081	24366154	Res. Carbon	150K	J 1/6W
R082	24366244	Res. Carbon	240K	J 1/6W
R083	24366684	Res. Carbon	680K	J 1/6W
R084	24366684	Res. Carbon	680K	J 1/6W
R085	24366474	Res. Carbon	470K	J 1/6W
R301	24366750	Res. Carbon	75	J 1/6W
R302	24366103	Res. Carbon	10K	J 1/6W
R303	24366202	Res. Carbon	2K	J 1/6W
R304	24366223	Res. Carbon	22K	J 1/6W
R305	24366223	Res. Carbon	22K	J 1/6W
R306	24366223	Res. Carbon	22K	J 1/6W
R307	24366202	Res. Carbon	2K	J 1/6W
R725	24366152	Res. Carbon	1. 5K	J 1/6W
R726	24366152	Res. Carbon	1. 5K	J 1/6W
MISCELLANEOUS				
P301	23363526	Phono Jack		
P302	23363252	Phono Jack		
P710	23363254	Phono Jack		
P711	23363253	Phono Jack		
S301	23145436	Slide Switch. 2C2P		
Z001	A5611110	Filter. F1034. 38. 9MHz		
Z002	23107972	Video Trap. 5. 5MHz		
Z003	23107947	Filter. SIF. 5. 5MHz		
MAIN BOARD				
U202	70194961	P C Board Assy. MAIN		
INTEGRATED CIRCUITS				
IC121	B0379070	IC	TA8607P	
IC122	B0324050	IC	TA7302P	
IC201	B0379050	IC	TA8605N	
IC202	B0379060	IC	TA8606N	
IC401	70119508	IC	BA7267S	
IC402	70119509	IC	BU2763S	
IC481	70119487	IC	BA7025L	
IC501	B0272620	IC	TD6360P	
IC502	B0351500	IC	TA75902P	
IC503	B0349260	IC	TA75393P	
IC601	70119561	IC	TMP4746N5759P	
IC602	B0320635	IC	TA7288P	
IC603	B0320440	IC	TA7267P	
IC604	B0349260	IC	TA75393P	
IC605	70119577	IC	PST520D	
IC701	70119518	IC	LA7090	
IC702	B0325536	IC	TA7361AP	
TRANSISTORS				
Q123	A6332430	Transistor	2SC2458-Y	
Q124	A6332430	Transistor	2SC2458-Y	
Q125	A6332430	Transistor	2SC2458-Y	
Q126	A6332430	Transistor	2SC2458-Y	
Q127	A6332430	Transistor	2SC2458-Y	
Q128	A6332430	Transistor	2SC2458-Y	
Q129	A6002020	Transistor	RN1202	
Q130	A6012030	Transistor	RN2203	
Q131	A6325540	Transistor	SC2236-Y	
Q132	A6012020	Transistor	RN2202	
Q203	A6868350	Transistor	2SD1413	
Q204	A6332430	Transistor	2SC2458-Y	
Q205	A6332430	Transistor	2SC2458-Y	
Q206	A6332430	Transistor	2SC2458-Y	

LOCATION NUMBER	PART NUMBER	DESCRIPTION		
Q207	A6332430	Transistor	2SC2458-Y	
Q208	A6534430	Transistor	2SA1048-Y	
Q209	A6332430	Transistor	2SC2458-Y	
Q210	A6332430	Transistor	2SC2458-Y	
Q211	A6332430	Transistor	2SC2458-Y	
Q212	A6332430	Transistor	2SC2458-Y	
Q213	A6012030	Transistor	RN2203	
Q214	A6012040	Transistor	RN2204	
Q215	A6012040	Transistor	RN2204	
Q216	A6534430	Transistor	2SA1048-Y	
Q217	A6002010	Transistor	RN1201	
Q218	A6534430	Transistor	2SA1048-Y	
Q219	A6534430	Transistor	2SA1048-Y	
Q220	A6534430	Transistor	2SA1048-Y	
Q221	A6534430	Transistor	2SA1048-Y	
Q403	A6332430	Transistor	2SC2458-Y	
Q404	A6332430	Transistor	2SC2458-Y	
Q405	A6332430	Transistor	2SC2458-Y	
Q406	A6534430	Transistor	2SA1048-Y	
Q407	A6534430	Transistor	2SA1048-Y	
Q408	A6332430	Transistor	2SC2458-Y	
Q409	A6002020	Transistor	RN1202	
Q410	A6012040	Transistor	RN2204	
Q411	A6332430	Transistor	2SC2458-Y	
Q412	A6332430	Transistor	2SC2458-Y	
Q413	A6332430	Transistor	2SC2458-Y	
Q414	A6534430	Transistor	2SA1048-Y	
Q482	A6332430	Transistor	2SC2458-Y	
Q505	A6002020	Transistor	RN1202	
Q506	A6002030	Transistor	RN1203	
Q507	A6012020	Transistor	RN2202	
Q508	A6002020	Transistor	RN1202	
Q509	A6534430	Transistor	2SA1048-Y	
Q510	A6002040	Transistor	RN1204	
Q511	A6002010	Transistor	RN1201	
Q512	A6002040	Transistor	RN1204	
Q513	A6002040	Transistor	RN1204	
Q514	A6002030	Transistor	RN1203	
Q516	A6012040	Transistor	RN2204	
Q517	A6534430	Transistor	2SA1048-Y	
Q533	A6868350	Transistor	2SD1413	
Q534	A6325540	Transistor	SC2236-Y	
Q610	A6012010	Transistor	RN2201	
Q611	A6868350	Transistor	2SD1413	
Q613	A6002030	Transistor	RN1203	
Q615	A6534430	Transistor	2SA1048-Y	
Q616	A6533240	Transistor	2SA966-Y	
Q617	A6534430	Transistor	2SA1048-Y	
Q618	A6002060	Transistor	RN1206	
Q619	A6002060	Transistor	RN1206	
Q620	A6325540	Transistor	SC2236-Y	
Q621	A6002050	Transistor	RN1205	
Q623	A6002060	Transistor	RN1206	
Q624	A6002040	Transistor	RN1204	
Q625	A6639320	Transistor	2SB1015V	
Q626	A6332430	Transistor	2SC2458-Y	
Q630	A6002020	Transistor	RN1202	
Q631	A6332430	Transistor	2SC2458-Y	
Q632	A6332430	Transistor	2SC2458-Y	
Q703	A6002040	Transistor	RN1204	
Q705	A6319300	Transistor	2SC1959-Y	
DIODES				
D121	A7160570	Diode	1SS176	
D201	A7160570	Diode	1SS176	
D202	A7160570	Diode	1SS176	
D203	A7160570	Diode	1SS176	
D204	A7160570	Diode	1SS176	
D205	A7160570	Diode	1SS176	
D206	A7160570	Diode	1SS176	
D208	A7160570	Diode	1SS176	
D209	A7160570	Diode	1SS176	
D401	A7160570	Diode	1SS176	
D402	A7160570	Diode	1SS176	
D403	A7160570	Diode	1SS176	
D481	A7160570	Diode	1SS176	

LOCATION NUMBER	PART NUMBER	DESCRIPTION	
D501	A7160570	Diode	1SS176
D502	A7160570	Diode	1SS176
D505	A7160570	Diode	1SS176
D507	A7160570	Diode	1SS176
D508	70115304	Diode	DA203
D510	A7152800	Diode	1SS227
D511	70115303	Diode	DAP201
D512	A7160570	Diode	1SS176
D513	A7152800	Diode	1SS227
D514	A7152800	Diode	1SS227
D515	A7160570	Diode	1SS176
D516	A7160570	Diode	1SS176
D517	A7160570	Diode	1SS176
D519	A7151500	Diode	1SS201
D520	A7160570	Diode	1SS176
D521	A7160570	Diode	1SS176
D601	A7110076	Diode,Zener	05Z6.2Y
D602	70115303	Diode	DAP201
D604	A7160570	Diode	1SS176
D605	A7160570	Diode	1SS176
D606	A7160570	Diode	1SS176
D607	A7160570	Diode	1SS176
D611	A7160570	Diode	1SS176
COILS			
L121	23238703	Coil,Peaking	TRF4820AJ
L122	23238911	Coil,Peaking	TRF4820AC
L123	23237973	Coil,Peaking	TRF4151AC
L126	23237975	Coil,Peaking	TRF4101AC
L127	23237981	Coil,Peaking	TRF4330AC
L128	23237987	Coil,Peaking	TRF4100AC
L130	23238703	Coil,Peaking	TRF4820AJ
L131	23238768	Coil,Peaking	TRF4681AC
L132	23238768	Coil,Peaking	TRF4681AC
L133	23238906	Coil,Peaking	TRF4221AC
L136	23238756	Coil,Peaking	TRF4222AC
L137	23237813	Coil,Peaking	TRF4102AC
L202	23237985	Coil,Peaking	TRF4150AC
L203	23238918	Coil,Peaking	TRF4220AC
L204	23237969	Coil,Peaking	TRF4331AC
L205	23238904	Coil,Peaking	TRF4331AC
L207	23238904	Coil,Peaking	TRF4331AC
L208	23237968	Coil,Peaking	TRF4391AC
L401	23237982	Coil,Peaking	TRF4270AC
L402	23237973	Coil,Peaking	TRF4151AC
L403	23237982	Coil,Peaking	TRF4270AC
L404	23237985	Coil,Peaking	TRF4150AC
L405	23238912	Coil,Peaking	TRF4680AC
L451	70272005	Coil,Resonant	LAA02
L601	23238921	Coil,Peaking	TRF4120AC
L701	23238723	Coil,Peaking	TRF4682AC
L702	23237817	Coil,Peaking	TRF4681AC
CAPACITORS			
C121	24633220	Cap.Electrolytic	22MF M 16V
C123	24232103	Cap.Ceramic	0. 01MF Z 50V
C124	24473470	Cap.Ceramic	47PF J 50V
C125	24436181	Cap.Ceramic	180PF J 50V
C126	24436151	Cap.Ceramic	150PF J 50V
C127	24636010	Cap.Electrolytic	1MF M 50V
C128	24474103	Cap.Ceramic	0. 01MF N 16V
C129	24474103	Cap.Ceramic	0. 01MF N 16V
C130	24474103	Cap.Ceramic	0. 01MF N 16V
C131	24474103	Cap.Ceramic	0. 01MF N 16V
C132	24436511	Cap.Ceramic	510PF J 50V
C133	24436070	Cap.Ceramic	7PF J 50V
C134	24436150	Cap.Ceramic	15PF J 50V
C135	24474103	Cap.Ceramic	0. 01MF N 50V
C136	24474103	Cap.Ceramic	0. 01MF N 50V
C137	24436101	Cap.Ceramic	100PF J 50V
C138	24632470	Cap.Electrolytic	47MF M 10V
C139	24232103	Cap.Ceramic	0. 01MF Z 50V
C140	24474102	Cap.Ceramic	1000PF K 50V
C141	24474103	Cap.Ceramic	0. 01MF N 50V
C142	24436180	Cap.Ceramic	18PF J 50V
C143	24474103	Cap.Ceramic	0. 01MF N 50V
C144	24473560	Cap.Ceramic	56PF J 50V

LOCATION NUMBER	PART NUMBER	DESCRIPTION	
C145	24473120	Cap.Ceramic	12PF J 50V
C146	24474103	Cap.Ceramic	0. 01MF N 50V
C147	24436560	Cap.Ceramic	56PF J 50V
C148	24473130	Cap.Ceramic	13PF J 50V
C149	24474103	Cap.Ceramic	0. 01MF N 50V
C161	24538104	Cap.Plastic	0. 1MF J 50V
C162	24436471	Cap.Ceramic	470PF J 50V
C163	24436820	Cap.Ceramic	82PF J 50V
C164	24474103	Cap.Ceramic	0. 01MF N 50V
C165	24636010	Cap.Electrolytic	1MF M 50V
C166	24474103	Cap.Ceramic	0. 01MF N 50V
C167	24474103	Cap.Ceramic	0. 01MF N 50V
C168	24474103	Cap.Ceramic	0. 01MF N 50V
C169	24474103	Cap.Ceramic	0. 01MF N 50V
C170	24633330	Cap.Electrolytic	33MF M 16V
C171	24232103	Cap.Ceramic	0. 01MF Z 50V
C172	24851104	Cap.Ceramic	0. 1MF K 25V
C173	24436181	Cap.Ceramic	180PF J 50V
C201	24633220	Cap.Electrolytic	22MF M 16V
C203	24633330	Cap.Electrolytic	33MF M 16V
C204	24794470	Cap.Electrolytic	47MF M 16V
C205	24793101	Cap.Electrolytic	100MF M 10V
C206	24473560	Cap.Ceramic	56PF J 50V
C207	24793101	Cap.Electrolytic	100MF M 10V
C208	24851104	Cap.Ceramic	0. 1MF K 25V
C209	24353101	Cap.Ceramic	100PF J 50V
C210	24591103	Cap.Plastic	0. 01MF J 50V
C211	24591822	Cap.Plastic	8200PF J 50V
C212	24436221	Cap.Ceramic	220PF J 50V
C213	24436151	Cap.Ceramic	150PF J 50V
C214	24632470	Cap.Electrolytic	47MF M 10V
C215	24232103	Cap.Ceramic	0. 01MF Z 50V
C216	24636478	Cap.Electrolytic	0. 47MF M 50V
C217	24636479	Cap.Electrolytic	4. 7MF M 50V
C218	24636010	Cap.Electrolytic	1MF M 50V
C219	24636479	Cap.Electrolytic	4. 7MF M 50V
C220	24474102	Cap.Ceramic	1000PF K 50V
C221	24793101	Cap.Electrolytic	100MF M 10V
C222	24232103	Cap.Ceramic	0. 01MF Z 50V
C223	24474103	Cap.Ceramic	0. 01MF N 50V
C224	24474103	Cap.Ceramic	0. 01MF N 50V
C225	24436820	Cap.Ceramic	82PF J 50V
C226	24473180	Cap.Ceramic	18PF J 50V
C227	24591562	Cap.Plastic	5600PF J 50V
C228	24436331	Cap.Ceramic	330PF J 50V
C229	24473100	Cap.Ceramic	10PF J 50V
C230	24474103	Cap.Ceramic	0. 01MF N 50V
C231	24474103	Cap.Ceramic	0. 01MF N 50V
C232	24633100	Cap.Electrolytic	10MF M 16V
C233	24474103	Cap.Ceramic	0. 01MF N 50V
C234	24632470	Cap.Electrolytic	47MF M 10V
C235	24636479	Cap.Electrolytic	4. 7MF M 50V
C236	24473120	Cap.Ceramic	12PF J 50V
C237	24474103	Cap.Ceramic	0. 01MF N 50V
C238	24636010	Cap.Electrolytic	1MF M 50V
C239	24636010	Cap.Electrolytic	1MF M 50V
C241	24473330	Cap.Ceramic	33PF J 50V
C242	24474103	Cap.Ceramic	0. 01MF N 50V
C243	24851223	Cap.Ceramic	0. 022MF K 25V
C244	24591432	Cap.Plastic	4300PF J 50V
C245	24591392	Cap.Plastic	3900PF J 50V
C246	24436221	Cap.Ceramic	220PF J 50V
C247	24792471	Cap.Electrolytic	470MF M 6.3V
C248	24591512	Cap.Plastic	5100PF J 50V
C249	24851223	Cap.Ceramic	0. 022MF K 25V
C261	24632470	Cap.Electrolytic	47MF M 10V
C262	24632470	Cap.Electrolytic	47MF M 10V
C263	24436560	Cap.Ceramic	56PF J 50V
C264	24436621	Cap.Ceramic	620PF J 50V
C401	24232103	Cap.Ceramic	0. 01MF Z 50V
C402	24232103	Cap.Ceramic	0. 01MF Z 50V
C403	24474103	Cap.Ceramic	0. 01MF N 50V
C404	24474103	Cap.Ceramic	0. 01MF N 50V
C405	24436820	Cap.Ceramic	82PF J 50V
C406	24474103	Cap.Ceramic	0. 01MF N 50V

LOCATION NUMBER	PART NUMBER	DESCRIPTION			
C407	24436471	Cap.Ceramic	470PF	J	50V
C408	24632470	Cap.Electrolytic	47MF	M	10V
C409	24474103	Cap.Ceramic	0. 01MF	N	50V
C410	24473270	Cap.Ceramic	27PF	J	50V
C411	24474102	Cap.Ceramic	1000PF	K	50V
C412	24474103	Cap.Ceramic	0. 01MF	N	50V
C413	24538104	Cap.Plastic	0. 1MF	J	50V
C414	24591223	Cap.Plastic	0. 022MF	J	50V
C415	24206478	Cap.Electrolytic	0. 47MF	M	50V
C416	24202470	Cap.Electrolytic	47MF	M	10V
C417	24474103	Cap.Ceramic	0. 01MF	N	50V
C418	24474103	Cap.Ceramic	0. 01MF	N	50V
C419	24474103	Cap.Ceramic	0. 01MF	N	50V
C420	24202101	Cap.Electrolytic	100MF	M	10V
C421	24591102	Cap.Plastic	1000PF	J	50V
C422	24206010	Cap.Electrolytic	1MF	M	50V
C423	24202470	Cap.Electrolytic	47MF	M	10V
C424	24353150	Cap.Ceramic	15PF	J	50V
C425	24353080	Cap.Ceramic	8PF	J	50V
C426	24212472	Cap.Ceramic	4700PF	K	50V
C427	24436470	Cap.Ceramic	47PF	J	50V
C429	24212102	Cap.Ceramic	1000PF	K	50V
C430	24232103	Cap.Ceramic	0. 01MF	Z	50V
C431	24232103	Cap.Ceramic	0. 01MF	Z	50V
C433	24632470	Cap.Electrolytic	47MF	M	10V
C434	24232103	Cap.Ceramic	0. 01MF	Z	50V
C435	24212102	Cap.Ceramic	1000PF	K	50V
C436	24206229	Cap.Electrolytic	2. 2MF	M	50V
C437	24591103	Cap.Plastic	0. 01MF	J	50V
C438	24232103	Cap.Ceramic	0. 01MF	Z	50V
C439	24538473	Cap.Plastic	0. 047MF	J	50V
C440	24436030	Cap.Ceramic	3PF	J	50V
C441	24206229	Cap.Electrolytic	2. 2MF	M	50V
C455	24093986	Cap.Variable	2. 3MF		
C481	24212102	Cap.Ceramic	1000PF	K	50V
C482	24633330	Cap.Electrolytic	33MF	M	16V
C483	24206478	Cap.Electrolytic	0. 47MF	M	50V
C484	24212102	Cap.Ceramic	1000PF	K	50V
C485	24591223	Cap.Plastic	0. 022MF	J	50V
C486	24202470	Cap.Electrolytic	47MF	M	10V
C487	24203330	Cap.Electrolytic	33MF	M	16V
C501	24794470	Cap.Electrolytic	47MF	M	16V
C502	24474102	Cap.Ceramic	1000PF	K	50V
C503	24591123	Cap.Plastic	0.012MF	J	50V
C504	24591123	Cap.Plastic	0.012MF	J	50V
C505	24591473	Cap.Plastic	0. 047MF	J	50V
C506	24636478	Cap.Electrolytic	0. 47MF	M	50V
C507	24591103	Cap.Plastic	0. 01MF	J	50V
C508	24636229	Cap.Electrolytic	2. 2MF	M	50V
C509	24474102	Cap.Ceramic	1000PF	K	50V
C510	24474103	Cap.Ceramic	0. 01MF	N	50V
C511	24633100	Cap.Electrolytic	10MF	M	16V
C512	24635479	Cap.Electrolytic	4. 7MF	M	35V
C514	24633100	Cap.Electrolytic	10MF	M	16V
C515	24474103	Cap.Ceramic	0. 01MF	N	50V
C516	24474102	Cap.Ceramic	1000PF	K	50V
C517	24636478	Cap.Electrolytic	0. 47MF	M	50V
C518	24636010	Cap.Electrolytic	1MF	M	50V
C519	24474102	Cap.Ceramic	1000PF	K	50V
C520	24538823	Cap.Plastic	0. 082MF	J	50V
C521	24474103	Cap.Ceramic	0. 01MF	N	50V
C522	24436101	Cap.Ceramic	100PF	J	50V
C523	24796220	Cap.Electrolytic	22MF	M	35V
C524	24474102	Cap.Ceramic	1000PF	K	50V
C525	24474103	Cap.Ceramic	0. 01MF	N	50V
C528	24636478	Cap.Electrolytic	0. 47MF	M	50V
C529	24232223	Cap.Ceramic	0. 022MF	Z	50V
C530	24474103	Cap.Ceramic	0. 01MF	N	50V
C531	24633100	Cap.Electrolytic	10MF	M	16V
C532	24794470	Cap.Electrolytic	47MF	M	16V
C533	24474102	Cap.Ceramic	1000PF	K	50V
C534	24591103	Cap.Plastic	0. 01MF	J	50V
C535	24474103	Cap.Ceramic	0. 01MF	N	50V
C536	24474102	Cap.Ceramic	1000PF	K	50V
C537	24474102	Cap.Ceramic	1000PF	K	50V

LOCATION NUMBER	PART NUMBER	DESCRIPTION			
C538	24212561	Cap.Ceramic	560PF	K	50V
C540	24474103	Cap.Ceramic	0. 01MF	N	50V
C541	24636229	Cap.Electrolytic	2. 2MF	M	50V
C545	24474103	Cap.Ceramic	0. 01MF	N	50V
C601	24793101	Cap.Electrolytic	100MF	M	10V
C602	24636010	Cap.Electrolytic	1MF	M	50V
C603	24794470	Cap.Electrolytic	47MF	M	16V
C604	24473470	Cap.Ceramic	47PF	J	50V
C605	24473470	Cap.Ceramic	47PF	J	50V
C608	24794470	Cap.Electrolytic	47MF	M	16V
C609	24636479	Cap.Electrolytic	4. 7MF	M	50V
C610	24794470	Cap.Electrolytic	47MF	M	16V
C611	24633100	Cap.Electrolytic	10MF	M	16V
C612	24474103	Cap.Ceramic	0. 01MF	N	50V
C613	24474103	Cap.Ceramic	0. 01MF	N	50V
C614	24474103	Cap.Ceramic	0. 01MF	N	50V
C615	24232223	Cap.Ceramic	0. 022MF	Z	50V
C620	24232223	Cap.Ceramic	0. 022MF	Z	50V
C621	24232223	Cap.Ceramic	0. 022MF	Z	50V
C622	24232223	Cap.Ceramic	0. 022MF	Z	50V
C623	24538104	Cap.Plastic	0. 1MF	J	50V
C631	24538474	Cap.Plastic	0. 47MF	J	50V
C632	24538474	Cap.Plastic	0. 47MF	J	50V
C701	24633100	Cap.Electrolytic	10MF	M	16V
C702	24794470	Cap.Electrolytic	47MF	M	16V
C703	24636010	Cap.Electrolytic	1MF	M	50V
C704	24591122	Cap.Plastic	1200PF	J	50V
C705	24591123	Cap.Plastic	0.012MF	J	50V
C706	24794470	Cap.Electrolytic	47MF	M	16V
C707	24633100	Cap.Electrolytic	10MF	M	16V
C708	24633100	Cap.Electrolytic	10MF	M	16V
C709	24633220	Cap.Electrolytic	22MF	M	16V
C710	24633100	Cap.Electrolytic	10MF	M	16V
C711	24633220	Cap.Electrolytic	22MF	M	16V
C712	24633100	Cap.Electrolytic	10MF	M	16V
C713	24591273	Cap.Plastic	0.027MF	J	50V
C714	24636010	Cap.Electrolytic	1MF	M	50V
C716	24794470	Cap.Electrolytic	47MF	M	16V
C717	24212472	Cap.Ceramic	4700PF	K	50V
C718	24591682	Cap.Plastic	6800PF	J	50V
C719	24538823	Cap.Plastic	0. 082MF	J	50V
C720	24214221	Cap.Ceramic	220PF	K	500V
C721	24212472	Cap.Ceramic	4700PF	K	50V
C727	24636010	Cap.Electrolytic	1MF	M	50V
R E S I S T O R S					
R121	24366821	Res.Carbon	820	J	1/6W
R122	24366152	Res.Carbon	1. 5K	J	1/6W
R123	24366332	Res.Carbon	3. 3K	J	1/6W
R124	24366271	Res.Carbon	270	J	1/6W
R125	24366152	Res.Carbon	1. 5K	J	1/6W
R126	24366391	Res.Carbon	390	J	1/6W
R127	24366162	Res.Carbon	1. 6K	G	1/6W
R128	24366562	Res.Carbon	5. 6K	J	1/6W
R129	24366222	Res.Carbon	2. 2K	J	1/6W
R130	24366431	Res.Carbon	430	J	1/6W
R131	24366561	Res.Carbon	560	J	1/6W
R132	24366561	Res.Carbon	560	J	1/6W
R133	24366681	Res.Carbon	680	J	1/6W
R134	24366122	Res.Carbon	1. 2K	J	1/6W
R135	24366271	Res.Carbon	270	J	1/6W
R136	24366122	Res.Carbon	1. 2K	J	1/6W
R137	24366102	Res.Carbon	1K	J	1/6W
R138	24366151	Res.Carbon	150	J	1/6W
R139	24366102	Res.Carbon	1K	J	1/6W
R140	24366101	Res.Carbon	100	J	1/6W
R141	24366511	Res.Carbon	510	J	1/6W
R142	24366182	Res.Carbon	1. 8K	J	1/6W
R145	24366561	Res.Carbon	560	J	1/6W
R146	24366821	Res.Carbon	820	J	1/6W
R147	24366182	Res.Carbon	1. 8K	J	1/6W
R148	24366272	Res.Carbon	2. 7K	J	1/6W
R149	24366561	Res.Carbon	560	J	1/6W
R160	24366272	Res.Carbon	2. 7K	J	1/6W
R161	24366101	Res.Carbon	100	J	1/6W
R162	24366102	Res.Carbon	1K	J	1/6W

LOCATION NUMBER	PART NUMBER	DESCRIPTION		
R163	24366102	Res. Carbon	1K	J 1/6W
R164	24366332	Res. Carbon	3. 3K	J 1/6W
ARI165	24531220	Res. Fusible	22	J 1/2W
R166	24366390	Res. Carbon	39	J 1/6W
R167	24366102	Res. Carbon	1K	J 1/6W
R168	24366223	Res. Carbon	22K	J 1/6W
R201	24367682	Res. Carbon	6. 8K	G 1/6W
R202	24367472	Res. Carbon	4. 7K	G 1/6W
R203	24366272	Res. Carbon	2. 7K	J 1/6W
R204	24366102	Res. Carbon	1K	J 1/6W
R205	24366302	Res. Carbon	3K	J 1/6W
R206	24366154	Res. Carbon	150K	J 1/6W
R207	24367102	Res. Carbon	1K	G 1/6W
R208	24366272	Res. Carbon	2. 7K	J 1/6W
R209	24367102	Res. Carbon	1K	G 1/6W
R210	24366623	Res. Carbon	62K	J 1/6W
R211	24366823	Res. Carbon	82K	J 1/6W
R212	24366621	Res. Carbon	620	J 1/6W
R213	24366274	Res. Carbon	270K	J 1/6W
R214	24366103	Res. Carbon	10K	J 1/6W
R215	24366103	Res. Carbon	10K	J 1/6W
R216	24366822	Res. Carbon	8. 2K	J 1/6W
R217	24367331	Res. Carbon	330	G 1/6W
R218	24366564	Res. Carbon	560K	J 1/6W
R219	24366474	Res. Carbon	470K	J 1/6W
R220	24366680	Res. Carbon	68	J 1/6W
R221	24366472	Res. Carbon	4. 7K	J 1/6W
R222	24366392	Res. Carbon	3. 9K	J 1/6W
R223	24366123	Res. Carbon	12K	J 1/6W
R224	24367911	Res. Carbon	910	G 1/6W
R225	24367102	Res. Carbon	1K	G 1/6W
R226	24366122	Res. Carbon	1. 2K	J 1/6W
R227	24366101	Res. Carbon	100	J 1/6W
R228	24366331	Res. Carbon	330	J 1/6W
R229	24366150	Res. Carbon	15	J 1/6W
R230	24366222	Res. Carbon	2. 2K	J 1/6W
R231	24366202	Res. Carbon	2K	J 1/6W
R232	24366183	Res. Carbon	18K	J 1/6W
R233	24366823	Res. Carbon	82K	J 1/6W
R234	24366222	Res. Carbon	2. 2K	J 1/6W
R236	24366562	Res. Carbon	5. 6K	J 1/6W
R237	24366222	Res. Carbon	2. 2K	J 1/6W
R238	24366102	Res. Carbon	1K	J 1/6W
R239	24366392	Res. Carbon	3. 9K	J 1/6W
R240	24366821	Res. Carbon	820	J 1/6W
R241	24366332	Res. Carbon	3. 3K	J 1/6W
R242	24366682	Res. Carbon	6. 8K	J 1/6W
R243	24366103	Res. Carbon	10K	J 1/6W
R244	24366222	Res. Carbon	2. 2K	J 1/6W
R245	24366563	Res. Carbon	56K	J 1/6W
R246	24366472	Res. Carbon	4. 7K	J 1/6W
R247	24366823	Res. Carbon	82K	J 1/6W
R248	24366273	Res. Carbon	27K	J 1/6W
R249	24366472	Res. Carbon	4. 7K	J 1/6W
R251	24066952	Res. Variable	10K	
R252	24066952	Res. Variable	10K	
R253	24066952	Res. Variable	10K	
R254	24066953	Res. Variable	100K	
R256	24066953	Res. Variable	100K	
R259	24066954	Res. Variable	2K	
R260	24366683	Res. Carbon	68K	J 1/6W
R261	24366103	Res. Carbon	10K	J 1/6W
R262	24366393	Res. Carbon	39K	J 1/6W
R263	24366103	Res. Carbon	10K	J 1/6W
R264	24366103	Res. Carbon	10K	J 1/6W
R265	24366472	Res. Carbon	4. 7K	J 1/6W
R266	24366103	Res. Carbon	10K	J 1/6W
R267	24366102	Res. Carbon	1K	J 1/6W
R268	24366302	Res. Carbon	3K	J 1/6W
R269	24366471	Res. Carbon	470	J 1/6W
R270	24366823	Res. Carbon	82K	J 1/6W
R271	24366332	Res. Carbon	3. 3K	J 1/6W
R272	24366562	Res. Carbon	5. 6K	J 1/6W
R273	24366152	Res. Carbon	1. 5K	J 1/6W
R274	24366911	Res. Carbon	910	G 1/6W

LOCATION NUMBER	PART NUMBER	DESCRIPTION		
R275	24366432	Res. Carbon	4. 3K	J 1/6W
R276	24366221	Res. Carbon	220	J 1/6W
R277	24366155	Res. Carbon	1.5M	G 1/6W
R278	24366474	Res. Carbon	470K	J 1/6W
R279	24366681	Res. Carbon	680	J 1/6W
R280	24366112	Res. Carbon	1. 1K	J 1/6W
R281	24366112	Res. Carbon	1. 1K	J 1/6W
R282	24367911	Res. Carbon	910	G 1/6W
R283	24367162	Res. Carbon	1. 6K	G 1/6W
R284	24366821	Res. Carbon	820	J 1/6W
R285	24366112	Res. Carbon	1. 1K	J 1/6W
R286	24366683	Res. Carbon	68K	J 1/6W
R289	24366513	Res. Carbon	51K	J 1/6W
R290	24366333	Res. Carbon	33K	J 1/6W
R291	24366122	Res. Carbon	1. 2K	J 1/6W
R292	24366102	Res. Carbon	1K	J 1/6W
R293	24366271	Res. Carbon	270	J 1/6W
R294	24366105	Res. Carbon	1M	J 1/6W
R401	24366183	Res. Carbon	18K	J 1/6W
R402	24366472	Res. Carbon	4. 7K	J 1/6W
R403	24366102	Res. Carbon	1K	J 1/6W
R404	24366102	Res. Carbon	1K	J 1/6W
R405	24366471	Res. Carbon	470	J 1/6W
R406	24366470	Res. Carbon	47	J 1/6W
R407	24366183	Res. Carbon	18K	J 1/6W
R408	24366822	Res. Carbon	8. 2K	J 1/6W
R409	24366222	Res. Carbon	2. 2K	J 1/6W
R410	24366471	Res. Carbon	470	J 1/6W
R411	24366102	Res. Carbon	1K	J 1/6W
R412	24366471	Res. Carbon	470	J 1/6W
R413	24366183	Res. Carbon	18K	J 1/6W
R414	24366822	Res. Carbon	8. 2K	J 1/6W
R415	24366102	Res. Carbon	1K	J 1/6W
R416	24366561	Res. Carbon	560	J 1/6W
R417	24366102	Res. Carbon	1K	J 1/6W
R418	24366182	Res. Carbon	1. 8K	J 1/6W
R420	24366271	Res. Carbon	270	J 1/6W
R421	24366122	Res. Carbon	1. 2K	J 1/6W
R422	24366333	Res. Carbon	33K	J 1/6W
R423	24366273	Res. Carbon	27K	J 1/6W
R424	24366821	Res. Carbon	820	J 1/6W
R425	24366104	Res. Carbon	100K	J 1/6W
R426	24366102	Res. Carbon	1K	J 1/6W
R427	24366105	Res. Carbon	1M	J 1/6W
R428	24366682	Res. Carbon	6. 8K	J 1/6W
R429	24366562	Res. Carbon	5. 6K	J 1/6W
R430	24366822	Res. Carbon	8. 2K	J 1/6W
R431	24366183	Res. Carbon	18K	J 1/6W
R432	24366222	Res. Carbon	2. 2K	J 1/6W
R433	24366822	Res. Carbon	8. 2K	J 1/6W
R434	24366102	Res. Carbon	1K	J 1/6W
R435	24366822	Res. Carbon	8. 2K	J 1/6W
R436	24366682	Res. Carbon	6. 8K	J 1/6W
R437	24366102	Res. Carbon	1K	J 1/6W
R438	24366102	Res. Carbon	1K	J 1/6W
R439	24366470	Res. Carbon	47	J 1/6W
R440	24366272	Res. Carbon	2. 7K	J 1/6W
R441	24366223	Res. Carbon	22K	J 1/6W
R442	24366333	Res. Carbon	33K	J 1/6W
R443	24366472	Res. Carbon	4. 7K	J 1/6W
R444	24366222	Res. Carbon	2. 2K	J 1/6W
R445	24366470	Res. Carbon	47	J 1/6W
R446	24366273	Res. Carbon	27K	J 1/6W
R447	24366223	Res. Carbon	22K	J 1/6W
R448	24366333	Res. Carbon	33K	J 1/6W
R449	24366103	Res. Carbon	10K	J 1/6W
R451	24066955	Res. Variable	1K	
R453	24066951	Res. Variable	20K	
R461	24366273	Res. Carbon	27K	J 1/6W
R462	24366102	Res. Carbon	1K	J 1/6W
R463	24366562	Res. Carbon	5. 6K	J 1/6W
R464	24366123	Res. Carbon	12K	J 1/6W
R465	24366104	Res. Carbon	100K	J 1/6W
R466	24366104	Res. Carbon	100K	J 1/6W
R467	24366181	Res. Carbon	180	J 1/6W

LOCATION	PART	DESCRIPTION			
NUMBER	NUMBER				
POWER 1 BOARD (V-81/83W)					
U802	70194937	P C Board Assy. POWER 1			
TRANSISTORS					
Q801	A6841900	Transistor	2SD549		
DIODES					
AD801	23118977	Diode	ERC01-02FL		
AD802	23118977	Diode	ERC01-02FL		
AD803	A7568521	Diode	1S1885FA		
AD804	A7568521	Diode	1S1885FA		
AD805	A7568521	Diode	1S1885FA		
AD806	A7568521	Diode	1S1885FA		
D807	23118976	Diode	ERA12-02		
D808	23118976	Diode	ERA12-02		
CAPACITORS					
AC801	24095831	Cap. Plastic	0. 1MF	M 250V	
C803	24232103	Cap. Ceramic	0. 01MF	Z 50V	
C804	24232103	Cap. Ceramic	0. 01MF	Z 50V	
AC805	24796222	Cap. Electrolytic	2200MF	M 35V	
AC806	24796222	Cap. Electrolytic	2200MF	M 35V	
AC807	24794332	Cap. Electrolytic	3300MF	M 16V	
C808	24798470	Cap. Electrolytic	47MF	M 100V	
C809	24798470	Cap. Electrolytic	47MF	M 100V	
C810	24636100	Cap. Electrolytic	10MF	M 50V	
C813	24634220	Cap. Electrolytic	22MF	M 25V	
RESISTORS					
AR801	24531220	Res. Fusible	22	J 1/2W	
R803	24366473	Res. Carbon	47K	J 1/6W	
R804	24366472	Res. Carbon	4. 7K	J 1/6W	
R805	24366222	Res. Carbon	2. 2K	J 1/6W	
R851	24066985	Res. Variable	1K		
MISCELLANEOUS					
AF801	23144129	Fuse, 2A			
AF802	23144959	Fuse, 3.15A			
AF803	23144164	Fuse, 250V, 1.25A			
AF801A	23165102	Fuse Holder			
AF802A	23165102	Fuse Holder			
AF803A	23165102	Fuse Holder			
AT801	23211997	Linefilter	TRE3004C		
POWER 2 BOARD (V-81/83W)					
U803	70194938	P C Board Assy. POWER 2			
TRANSISTORS					
Q802	A6868450	Transistor	2SD1415		
Q803	A6332430	Transistor	2SC2458-Y		
Q804	A6868450	Transistor	2SD1415		
Q805	A6332430	Transistor	2SC2458-Y		
Q806	A6868020	Transistor	2SD1406-Y		
Q807	A6325825	Transistor	2SC2240GR		
Q808	A6002020	Transistor	RN1202		
Q809	A6533625	Transistor	2SA970GR		
Q810	A6002010	Transistor	RN1201		
DIODES					
D809	A7110115	Diode, Zener	05Z 6. 8V		
D810	A7110635	Diode, Zener	05Z 20Z		
D814	A7160570	Diode	1SS176		
D815	A7110017	Diode, Zener	05Z 5. 6V		
D816	A7160570	Diode	1SS176		
D817	A7110412	Diode, Zener	05Z12Z		
D818	A7160570	Diode	1SS176		
D819	A7110016	Diode, Zener	05Z 5. 6X		
D820	A7160570	Diode	1SS176		
D821	A7160570	Diode	1SS176		
D822	A7160570	Diode	1SS176		
CAPACITORS					
C811	24634220	Cap. Electrolytic	22MF	M 25V	
C812	24591103	Cap. Plastic	0. 01MF	J 50V	
C814	24634220	Cap. Electrolytic	22MF	M 25V	
C815	24634100	Cap. Electrolytic	10MF	M 25V	
C817	24798479	Cap. Electrolytic	4. 7MF	M 100V	
C818	24636229	Cap. Electrolytic	2. 2MF	M 50V	
C822	24591103	Cap. Plastic	0. 01MF	J 50V	
RESISTORS					
R802	24383222	Res. Oxide	2. 2K	J 2W	
R811	24366163	Res. Carbon	16K	J 1/6W	
R812	24366122	Res. Carbon	1. 2K	J 1/6W	

LOCATION NUMBER	PART NUMBER	DESCRIPTION			
R813	24366152	Res. Carbon	1. 5K	J 1/6W	
R814	24366162	Res. Carbon	1. 6K	G 1/6W	
R815	24366222	Res. Carbon	2. 2K	J 1/6W	
AR816	24531100	Res. Fusible	10	J 1/2W	
R817	24552751	Res. Oxide Metal	750	J 1/2W	
R818	24366153	Res. Carbon	15K	J 1/6W	
R819	24366123	Res. Carbon	12K	J 1/6W	
R820	24366362	Res. Carbon	3. 6K	J 1/6W	
R822	24552103	Res. Oxide Metal	10K	J 1/2W	
R824	24366822	Res. Carbon	8. 2K	J 1/6W	
R825	24366123	Res. Carbon	12K	J 1/6W	
R826	24366103	Res. Carbon	10K	J 1/6W	
R827	24366223	Res. Carbon	22K	J 1/6W	
R828	24366103	Res. Carbon	10K	J 1/6W	
R829	24366103	Res. Carbon	10K	J 1/6W	
CAM SWITCH BOARD					
UM06	70197081	P C Board Assy. Cam SW			
MISCELLANEOUS					
SM61	23145424	Cam Switch			
PRE AMP BOARD (V-81/83W)					
U101	70197092	P C Board Assy. PRE AMP, V-81W			
U101	70194936	P C Board Assy. PRE AMP, V-83W			
INTEGRATED CIRCUITS					
IC101	B0358220	IC	TA7772P		
TRANSISTORS					
Q102	A6332430	Transistor	2SC2458-Y		
DIODES					
D101	A7160570	Diode	1SS176		
D102	A7160570	Diode	1SS176		
COILS					
L101	23239835	Coil, Peaking	TRF4109AJ		
L102	23239835	Coil, Peaking	TRF4109AJ		
L103	23238718	Coil, Peaking	TRF4479AJ		
L104	23238710	Coil, Peaking	TRF4220AJ		
CAPACITORS					
C101	24436120	Cap. Ceramic	12PF	J 50V	
C102	24436430	Cap. Ceramic	43PF	J 50V	
C103	24474103	Cap. Ceramic	0. 01MF	N 50V	
C104	24474103	Cap. Ceramic	0. 01MF	N 50V	
C105	24202330	Cap. Electrolytic	33MF	M 10V	
C106	24474103	Cap. Ceramic	0. 01MF	N 50V	
C107	24201470	Cap. Electrolytic	47MF	M 6.3V	
C108	24206010	Cap. Electrolytic	1MF	M 50V	
C109	24202330	Cap. Electrolytic	33MF	M 10V	
C110	24474103	Cap. Ceramic	0. 01MF	N 50V	
C111	24206010	Cap. Electrolytic	1MF	M 50V	
RESISTORS					
R101	24366821	Res. Carbon	820	J 1/6W	
R102	24366821	Res. Carbon	820	J 1/6W	
R103	24366361	Res. Carbon	360	J 1/6W	
R104	24366331	Res. Carbon	330	J 1/6W	
R105	24366102	Res. Carbon	1K	J 1/6W	
R106	24366102	Res. Carbon	1K	J 1/6W	
R107	24366272	Res. Carbon	2. 7K	J 1/6W	
R108	24366152	Res. Carbon	1. 5K	J 1/6W	
R109	24366272	Res. Carbon	2. 7K	J 1/6W	
R110	24366152	Res. Carbon	1. 5K	J 1/6W	
R111	24366103	Res. Carbon	10K	J 1/6W	
R112	24366471	Res. Carbon	470	J 1/6W	
PRE AMP BOARD (V-81/83G)					
U101	70197041	P C Board Assy. PRE AMP, V-81G			
U101	70194968	P C Board Assy. PRE AMP, V-83G			
INTEGRATED CIRCUITS					
IC101	B0358220	IC	TA7772P		
TRANSISTORS					
Q102	A6332430	Transistor	2SC2458-Y		
DIODES					
D101	A7160570	Diode	1SS176		
D102	A7160570	Diode	1SS176		
COILS					
L103	23238718	Coil, Peaking	TRF4479AJ		
L104	23238710	Coil, Peaking	TRF4220AJ		

LOCATION NUMBER	PART NUMBER	DESCRIPTION			
CAPACITORS					
C101	24436120	Cap.Ceramic	12PF	J	50V
C102	24436430	Cap.Ceramic	43PF	J	50V
C103	24474103	Cap.Ceramic	0. 01MF	N	50V
C104	24474103	Cap.Ceramic	0. 01MF	N	50V
C105	24202330	Cap.Electrolytic	33MF	M	10V
C106	24474103	Cap.Ceramic	0. 01MF	N	50V
C107	24201470	Cap.Electrolytic	47MF	M	6.3V
C108	24206010	Cap.Electrolytic	1MF	M	50V
C109	24202330	Cap.Electrolytic	33MF	M	10V
C110	24474103	Cap.Ceramic	0. 01MF	N	50V
C111	24206010	Cap.Electrolytic	1MF	M	50V
RESISTORS					
R103	24366361	Res.Carbon	360	J	1/6W
R104	24366331	Res.Carbon	330	J	1/6W
R105	24366102	Res.Carbon	1K	J	1/6W
R106	24366102	Res.Carbon	1K	J	1/6W
R107	24366272	Res.Carbon	2. 7K	J	1/6W
R108	24366152	Res.Carbon	1. 5K	J	1/6W
R109	24366272	Res.Carbon	2. 7K	J	1/6W
R110	24366152	Res.Carbon	1. 5K	J	1/6W
R111	24366103	Res.Carbon	10K	J	1/6W
R112	24366471	Res.Carbon	470	J	1/6W
SELECTOR BOARD (V-81/83G)					
UA01	70197040	P C Board Assy.SELECTOR.V-81G			
UA01	70194963	P C Board Assy.SELECTOR.V-83G			
INTEGRATED CIRCUITS					
ICA01	70119579	IC	M50430-085SP		
ICA02	70119517	IC	M58659P		
ICL10	70119413	IC	PST520C		
TRANSISTORS					
QA03	A6332430	Transistor	2SC2458-Y		
QA04	A6012020	Transistor	RN2202		
QA05	A6002040	Transistor	RN1204		
QA06	A6332430	Transistor	2SC2458-Y		
QA07	A6332430	Transistor	2SC2458-Y		
QL11	A6533240	Transistor	2SA966-Y		
QL12	A6002060	Transistor	RN1206		
DIODES					
DA01	23115922	Diode.Zener	UPC574J		
DA02	A8600606	Diode.LED	TLR113AD-FA		
DA03	A7160590	Diode	1SS177		
DA04	A7160590	Diode	1SS177		
DL10	A7110017	Diode.Zener	05Z 5. 6V		
DL11	A7110725	Diode.Zener	05Z30Y		
DL12	A7160590	Diode	1SS177		
DL13	A7160590	Diode	1SS177		
CAPACITORS					
CA01	24636100	Cap.Electrolytic	10MF	M	50V
CA02	24474151	Cap.Ceramic	150PF	K	50V
CA03	24538104	Cap.Plastic	0. 1MF	J	50V
CA04	24538104	Cap.Plastic	0. 1MF	J	50V
CA05	24538104	Cap.Plastic	0. 1MF	J	50V
CA06	24591473	Cap.Plastic	0. 047MF	J	50V
CA07	24794470	Cap.Electrolytic	47MF	M	16V
CA08	24473470	Cap.Ceramic	47PF	J	50V
CA09	24473470	Cap.Ceramic	47PF	J	50V
CA10	24636100	Cap.Electrolytic	10MF	M	50V
CA11	24636229	Cap.Electrolytic	2. 2MF	M	50V
CL10	24793222	Cap.Electrolytic	2200MF	M	10V
CL11	24635101	Cap.Electrolytic	100MF	M	35V
CL12	24636010	Cap.Electrolytic	1MF	M	50V
RESISTORS					
RA01	24366303	Res.Carbon	30K	J	1/6W
RA02	24366103	Res.Carbon	10K	J	1/6W
RA03	24366333	Res.Carbon	33K	J	1/6W
RA04	24366153	Res.Carbon	15K	J	1/6W
RA05	24366103	Res.Carbon	10K	J	1/6W
RA06	24366153	Res.Carbon	15K	J	1/6W
RA07	24366203	Res.Carbon	20K	J	1/6W
RA08	24366203	Res.Carbon	20K	J	1/6W
RA09	24366203	Res.Carbon	20K	J	1/6W
RA10	24366203	Res.Carbon	20K	J	1/6W
RA11	24366472	Res.Carbon	4. 7K	J	1/6W

LOCATION NUMBER	P A R T NUMBER	DESCRIPTION			
RA12	24366472	Res.Carbon	4. 7K	J	1/6W
RA13	24366472	Res.Carbon	4. 7K	J	1/6W
RA16	24366271	Res.Carbon	270	J	1/6W
RA17	24366433	Res.Carbon	43K	J	1/6W
RA18	24366153	Res.Carbon	15K	J	1/6W
RA19	24366101	Res.Carbon	100	J	1/6W
RA20	24366102	Res.Carbon	1K	J	1/6W
RA21	24366102	Res.Carbon	1K	J	1/6W
RA22	24366471	Res.Carbon	470	J	1/6W
RA23	24366471	Res.Carbon	470	J	1/6W
RA24	24366103	Res.Carbon	10K	J	1/6W
RA25	24366103	Res.Carbon	10K	J	1/6W
RA26	24366103	Res.Carbon	10K	J	1/6W
RL10	24366301	Res.Carbon	300	J	1/6W
RL11	24366301	Res.Carbon	300	J	1/6W
RL12	24366473	Res.Carbon	47K	J	1/6W
RL13	24366391	Res.Carbon	390	J	1/6W
RL14	24366152	Res.Carbon	1. 5K	J	1/6W
RL15	24366103	Res.Carbon	10K	J	1/6W
RL16	24552391	Res.Oxide Metal	390	J	1/2W
RL17	24383302	Res.Oxide Metal	3K	J	2W
RL18	24383332	Res.Oxide Metal	3.3K	J	2W
RL19	24366472	Res.Carbon	4. 7K	J	1/6W
MISCELLANEOUS					
SA01	23145509	Push Switch.IC1P			
SA02	23145509	Push Switch.IC1P			
SA03	23145509	Push Switch.IC1P			
SA04	23145509	Push Switch.IC1P			
SA05	23145509	Push Switch.IC1P			
SA06	23145509	Push Switch.IC1P			
ZA01	23153949	Ceramic Resonator	TCR1003.4MHz		
SELECTOR BOARD (V-81/83W)					
UA01	70197091	P C Board Assy.SELECTOR.V-81W			
UA01	70194934	P C Board Assy.SELECTOR.V-83W			
INTEGRATED CIRCUITS					
ICA01	70119516	IC	M50430081SP		
ICA02	70119517	IC	M58659P		
ICL10	70119413	IC	PST520C		
TRANSISTORS					
QA03	A6332430	Transistor	2SC2458-Y		
QA04	A6012020	Transistor	RN2202		
QA05	A6002040	Transistor	RN1204		
QA06	A6332430	Transistor	2SC2458-Y		
QA07	A6332430	Transistor	2SC2458-Y		
QL11	A6533240	Transistor	2SA966-Y		
QL12	A6002060	Transistor	RN1206		
DIODES					
DA01	23115922	Diode.Zener	UPC574J		
DA02	A8600606	Diode.LED	TLR113AD-FA		
DA03	A7160590	Diode	1SS177		
DA04	A7160590	Diode	1SS177		
DL10	A7110017	Diode.Zener	05Z 5. 6V		
DL11	A7110725	Diode.Zener	05Z30Y		
DL12	A7160590	Diode	1SS177		
DL13	A7160590	Diode	1SS177		
CAPACITORS					
CA01	24636100	Cap.Electrolytic	10MF	M	50V
CA02	24474151	Cap.Ceramic	150PF	K	50V
CA03	24538104	Cap.Plastic	0. 1MF	J	50V
CA04	24538104	Cap.Plastic	0. 1MF	J	50V
CA05	24538104	Cap.Plastic	0. 1MF	J	50V
CA06	24591473	Cap.Plastic	0. 047MF	J	50V
CA07	24794470	Cap.Electrolytic	47MF	M	16V
CA08	24473470	Cap.Ceramic	47PF	J	50V
CA09	24473470	Cap.Ceramic	47PF	J	50V
CA10	24636100	Cap.Electrolytic	10MF	M	50V
CA11	24636229	Cap.Electrolytic	2. 2MF	M	50V
CL10	24793222	Cap.Electrolytic	2200MF	M	10V
CL11	24635101	Cap.Electrolytic	100MF	M	35V
CL12	24636010	Cap.Electrolytic	1MF	M	50V
RESISTORS					
RA01	24366303	Res.Carbon	30K	J	1/6W
RA02	24366103	Res.Carbon	10K	J	1/6W
RA03	24366333	Res.Carbon	33K	J	1/6W

LOCATION NUMBER	PART NUMBER	DESCRIPTION			
RA04	24366153	Res.Carbon	15K	J	1/6W
RA05	24366103	Res.Carbon	10K	J	1/6W
RA06	24366153	Res.Carbon	15K	J	1/6W
RA07	24366203	Res.Carbon	20K	J	1/6W
RA08	24366203	Res.Carbon	20K	J	1/6W
RA09	24366203	Res.Carbon	20K	J	1/6W
RA10	24366203	Res.Carbon	20K	J	1/6W
RA11	24366472	Res.Carbon	4. 7K	J	1/6W
RA16	24366271	Res.Carbon	270	J	1/6W
RA17	24366433	Res.Carbon	43K	J	1/6W
RA18	24366153	Res.Carbon	15K	J	1/6W
RA19	24366101	Res.Carbon	100	J	1/6W
RA20	24366102	Res.Carbon	1K	J	1/6W
RA21	24366102	Res.Carbon	1K	J	1/6W
RA24	24366103	Res.Carbon	10K	J	1/6W
RA25	24366103	Res.Carbon	10K	J	1/6W
RA26	24366103	Res.Carbon	10K	J	1/6W
RL10	24366301	Res.Carbon	300	J	1/6W
RL11	24366301	Res.Carbon	300	J	1/6W
RL12	24366473	Res.Carbon	47K	J	1/6W
RL13	24366391	Res.Carbon	390	J	1/6W
RL14	24366152	Res.Carbon	1. 5K	J	1/6W
RL15	24366103	Res.Carbon	10K	J	1/6W
RL16	24552391	Res.Oxide Metal	390	J	1/2W
RL17	24383302	Res.Oxide Metal	3K	J	2W
RL18	24383332	Res.Oxide Metal	3. 3K	J	2W
RL19	24366472	Res.Carbon	4. 7K	J	1/6W
MISCELLANEOUS					
SA01	23145509	Push Switch.1C1P			
SA02	23145509	Push Switch.1C1P			
SA03	23145509	Push Switch.1C1P			
SA04	23145509	Push Switch.1C1P			
SA05	23145509	Push Switch.1C1P			
SA06	23145509	Push Switch.1C1P			
ZA01	23153949	Ceramic Resonator TCR1003.4MHz			
LOGIC CTL BOARD (V-81G/W)					
UL01	70197039	P C Board Assy.LOGIC CTL.V-81G			
UL01	70197090	P C Board Assy.LOGIC CTL.V-81W			
DIODES					
DL05	A8690640	Diode.LED	TLUG163		
DL07	A8690640	Diode.LED	TLUG163		
DX16	A7160590	Diode	1SS177		
DX17	A7160590	Diode	1SS177		
DX18	A8690640	Diode.LED	TLUG163		
RESISTORS					
RX09	24366271	Res.Carbon	270	J	1/6W
MISCELLANEOUS					
SL03	23145509	Push Switch.1C1P			
SL04	23145509	Push Switch.1C1P			
SL05	23145509	Push Switch.1C1P			
SL06	23145509	Push Switch.1C1P			
SL07	23145509	Push Switch.1C1P			
SL08	23145509	Push Switch.1C1P			
SL09	23145509	Push Switch.1C1P			
SX19	23145509	Push Switch.1C1P			
LOGIC CTL BOARD (V-83G/W)					
UL01	70194964	P C Board Assy.LOGIC CTL.V-83G			
UL01	70194935	P C Board Assy.LOGIC CTL.V-83W			
DIODES					
DX15	A7160590	Diode	1SS177		
DX16	A7160590	Diode	1SS177		
DX17	A7160590	Diode	1SS177		
DX18	A8605671	Diode.LED	TLG113A(FA)		
RESISTORS					
RX09	24366271	Res.Carbon	270	J	1/6W
MISCELLANEOUS					
SL02	23145510	Push Switch.1C1P			
SL03	23145510	Push Switch.1C1P			
SL04	23145510	Push Switch.1C1P			
SL05	23145510	Push Switch.1C1P			
SL06	23145510	Push Switch.1C1P			
SL07	23145510	Push Switch.1C1P			
SL08	23145510	Push Switch.1C1P			

LOCATION NUMBER	PART NUMBER	DESCRIPTION			
SL09	23145510	Push Switch.1C1P			
SX19	23145510	Push Switch.1C1P			
TIMER BOARD (V-83G/W)					
UX02	70194962	P C Board Assy.TIMER.V-83G			
UX02	70194933	P C Board Assy.TIMER.V-83W			
INTEGRATED CIRCUITS					
ICR01	23119566	IC	UPC1474HA		
ICX01	70119578	IC	TMP47C410AN6775Z		
TRANSISTORS					
QX02	A6332430	Transistor	2SC2458-Y		
QX04	A6002010	Transistor	RN1201		
DIODES					
DL02	A8600606	Diode.LED	TLR113AD-FA		
DL05	A8605671	Diode.LED	TLG113A(FA)		
DL07	A8605671	Diode.LED	TLG113A(FA)		
DR01	23115800	Diode.Photo	PH-302		
DX01	A7160590	Diode	1SS177		
DX02	A7160590	Diode	1SS177		
DX03	A7160590	Diode	1SS177		
DX04	A7160590	Diode	1SS177		
DX07	A7160590	Diode	1SS177		
DX09	A7160590	Diode	1SS177		
DX12	A7160590	Diode	1SS177		
DX13	A7160590	Diode	1SS177		
DX14	A7160590	Diode	1SS177		
DX27	A7152800	Diode	1SS227		
DX28	A7152800	Diode	1SS227		
DX29	A7160570	Diode	1SS176		
COILS					
LR01	23238722	Coil.Peaking	TRF4822A1		
CAPACITORS					
CR01	24202330	Cap.Electrolytic	33MF	M	10V
CR02	24203100	Cap.Electrolytic	10MF	M	16V
CR03	24203100	Cap.Electrolytic	10MF	M	16V
CR04	24593222	Cap.Plastic	2200PF	J	50V
CR05	24538683	Cap.Plastic	0. 068MF	J	50V
CR06	24501222	Cap.Plastic	2200PF	J	50V
CR07	24202470	Cap.Electrolytic	47MF	M	10V
CX01	24793101	Cap.Electrolytic	100MF	M	10V
CX02	24473470	Cap.Ceramic	47PF	J	50V
CX03	24473470	Cap.Ceramic	47PF	J	50V
CX04	24474103	Cap.Ceramic	0. 01MF	N	50V
CX05	24474103	Cap.Ceramic	0. 01MF	N	50V
CX07	24474103	Cap.Ceramic	0. 01MF	N	50V
CX08	24474103	Cap.Ceramic	0. 01MF	N	50V
CX10	24591102	Cap.Plastic	1000PF	J	50V
RESISTORS					
R258	24069645	Res.Variable	10K		
R556	24069640	Res.Variable	500K		
RR01	24366222	Res.Carbon	2. 2K	J	1/6W
RR02	24366100	Res.Carbon	10	J	1/6W
RR03	24366103	Res.Carbon	10K	J	1/6W
RR04	24366223	Res.Carbon	22K	J	1/6W
RX01	24366473	Res.Carbon	47K	J	1/6W
RX02	24366223	Res.Carbon	22K	J	1/6W
RX04	24366123	Res.Carbon	12K	J	1/6W
RX05	24366123	Res.Carbon	12K	J	1/6W
RX06	24366123	Res.Carbon	12K	J	1/6W
RX07	24366123	Res.Carbon	12K	J	1/6W
RX08	24366123	Res.Carbon	12K	J	1/6W
RX10	24366222	Res.Carbon	2. 2K	J	1/6W
RX11	24366223	Res.Carbon	22K	J	1/6W
RX12	24366223	Res.Carbon	22K	J	1/6W
RX13	24366223	Res.Carbon	22K	J	1/6W
RX14	24366223	Res.Carbon	22K	J	1/6W
RX15	24366223	Res.Carbon	22K	J	1/6W
RX16	24366223	Res.Carbon	22K	J	1/6W
RX25	24366102	Res.Carbon	1K	J	1/6W
RX30	24366221	Res.Carbon	220	J	1/6W
RX31	24366221	Res.Carbon	220	J	1/6W
RX32	24366221	Res.Carbon	220	J	1/6W
RX33	24366511	Res.Carbon	510	J	1/6W
RX34	24366511	Res.Carbon	510	J	1/6W
MISCELLANEOUS					

SECTION 4

PARTS LIST

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SAFETY PRECAUTION

The parts identified by Δ mark are critical for safety. Replace only with part number specified.
The mounting position of replacement is to be identical with originals. The substitute replacement parts which do not have the same safety characteristics as specified in the parts list may create shock, fire or other hazards.

ABBREVIATIONS

1. Integrated circuit (IC)

2. Capacitor (Cap)

MF.....microfarad
PP.....picofarad(micro-microfarad)

3. Resistor (Res)

All resistance values are in ohms.
KKilo(1000)
MMega(1000000)
WWatt

4. Tolerance

Symbol	G	J	K	M	N	Z	P	A
%	± 2	± 5	± 10	± 20	± 30	+80 -20	+100 -0	+100 -10